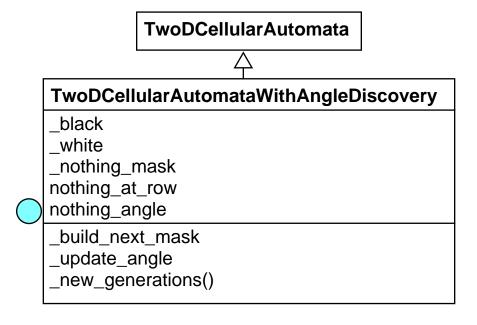
automata = TwoDCellularAutomataWithAngleDiscovery(
 generations=200,
 machine_cls=Rule30,
 wall_cls=WallLeftWhiteRightWhite,
 cells_per_generation=50)



adjacent = self.nothing_at_row - self.cells_per_generation / 2.0
opposite = self.cells_per_generation
self.nothing_angle = math.degrees(math.atan(opposite/adjacent))

