

# Instance-based learning: Support Vector Machines



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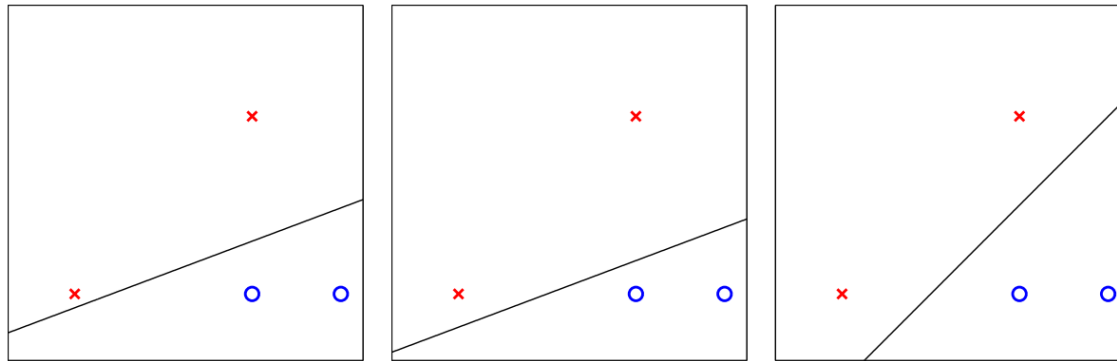
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i Informàtica

**11752 Aprendizaje Automático**  
**11752 Machine Learning**  
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en Sistemas Inteligentes

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# Review on hyperplanes

- One can find several hyperplanes to separate the 2D toy dataset below:



$$g(x) = w^T x + w_0$$

$$g(x_i) > 0 \Rightarrow x_i \rightarrow \omega_1$$

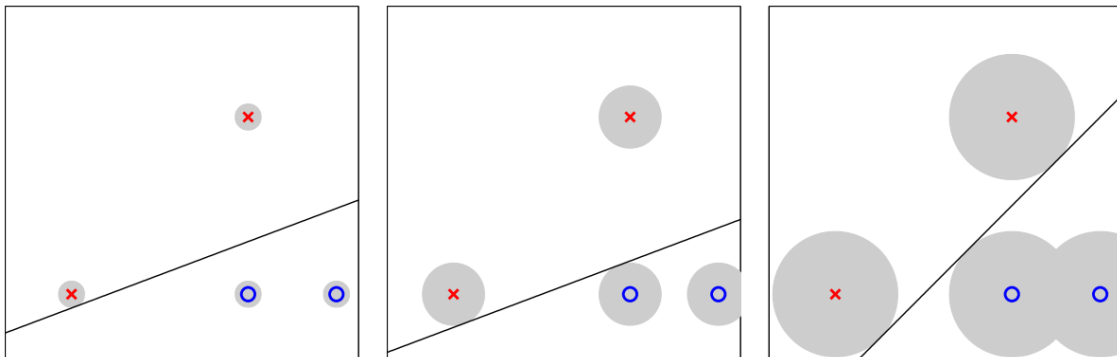
$$g(x_i) < 0 \Rightarrow x_i \rightarrow \omega_2$$

which could be the result of e.g. the perceptron algorithm:

$$w^+(t+1) = w^+(t) - \rho_t \sum_{x_i^+ \in \mathcal{Y}} \delta_{x_i} x_i^+, \text{ with } \delta_{x_i} = -1 \text{ if } x_i \in \omega_1, +1 \text{ if } x_i \in \omega_2$$

$$w^+ = (w, w_0), \quad x_i^+ = (x_i, 1)$$

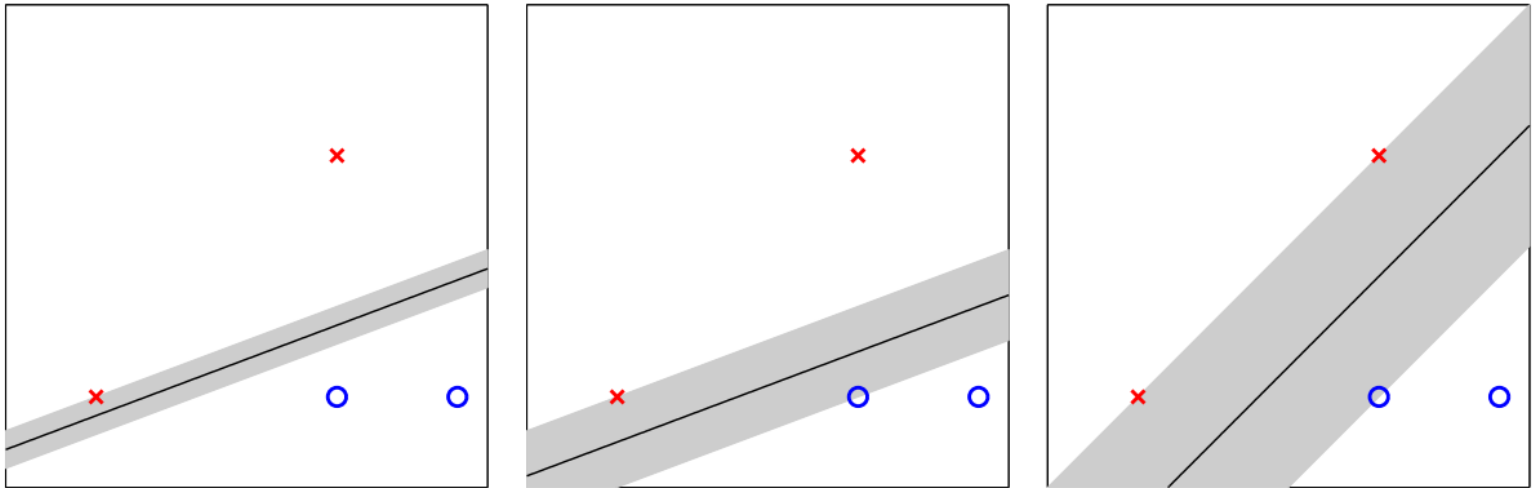
- Do we have any reason to choose one solution against the others?



← the rightmost one seems more robust to data noise, i.e. the model would keep valid even if the “true” samples were anywhere within their tolerance hypervolumes

# Review on hyperplanes

- We can also quantify noise tolerance from the viewpoint of the separator, defining a “cushion” on each side of the separator, the largest one we can define:

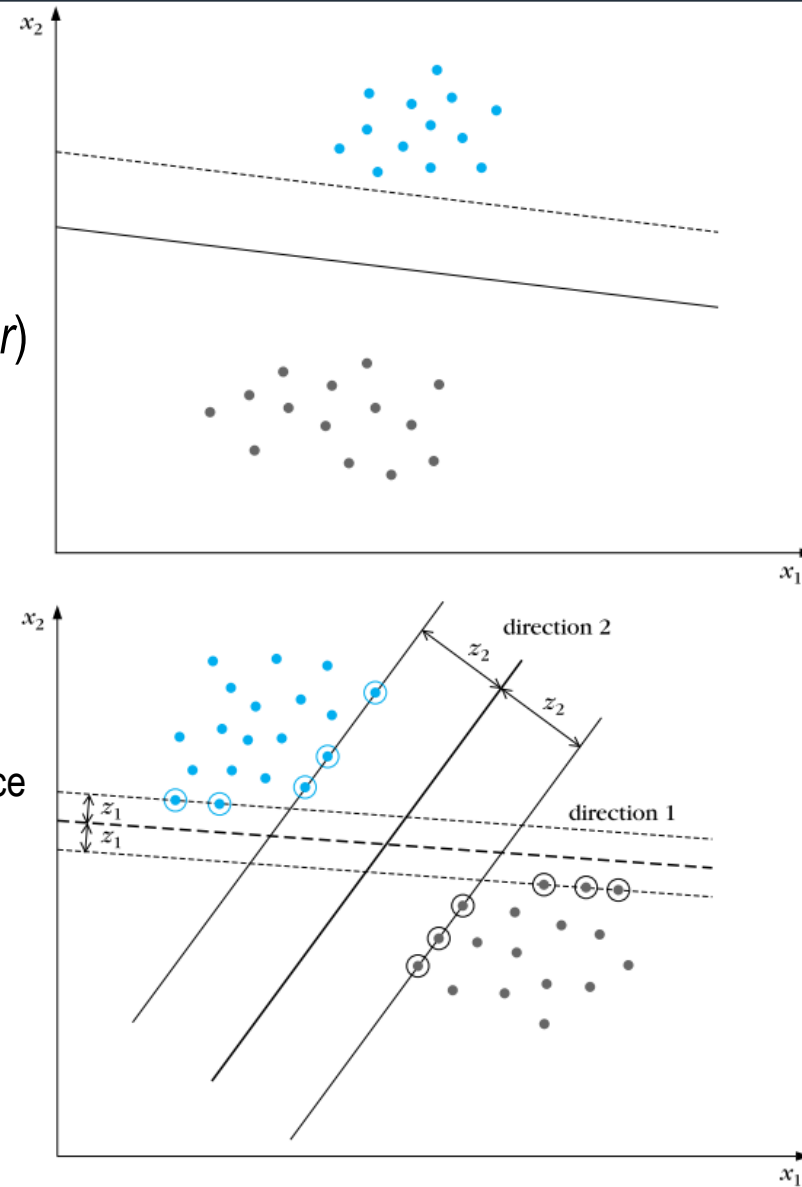


- We call such a “cushion” as the **margin** of the separator, so that the thicker the larger is the noise margin of the separator
- In this lecture we will address several points in this regard:
  - Can we efficiently find the **largest margin** hyperplane?
  - What can we do if the data is **not linearly separable**?

- Formulation of the SVM problem for linearly separable classes
- SVM training for linearly separable classes
- Non-linearly separable classes
- Non-linear SVM
- Numerical examples
- Final remarks

# Formulation of the SVM problem

- Let  $\mathbf{x}_i$ ,  $i = 1, \dots, N$ , be the feature vectors of the training set  $\mathbf{X}$ , which belong to one of two **linearly separable** classes  $\omega_1$  and  $\omega_2$
- The goal is to find the separating hyperplane with the largest **margin** (*max. margin classifier*)
  - We expect that the larger the margin the **better** the **generalization** of the classifier
  - If we do not want to give preference to one class over the other, we look for the hyperplane that is at the **same orthogonal distance** to the nearest samples from  $\omega_1$  and  $\omega_2$   
 $\Rightarrow$  determine the  $(\mathbf{w}, w_0)$  that leads to the **maximum margin**, i.e. maximum orthogonal distance
- **Support Vectors**  $\equiv$  nearest samples (most informative for classification)
- **SVM**  $\equiv$  optimum hyperplane

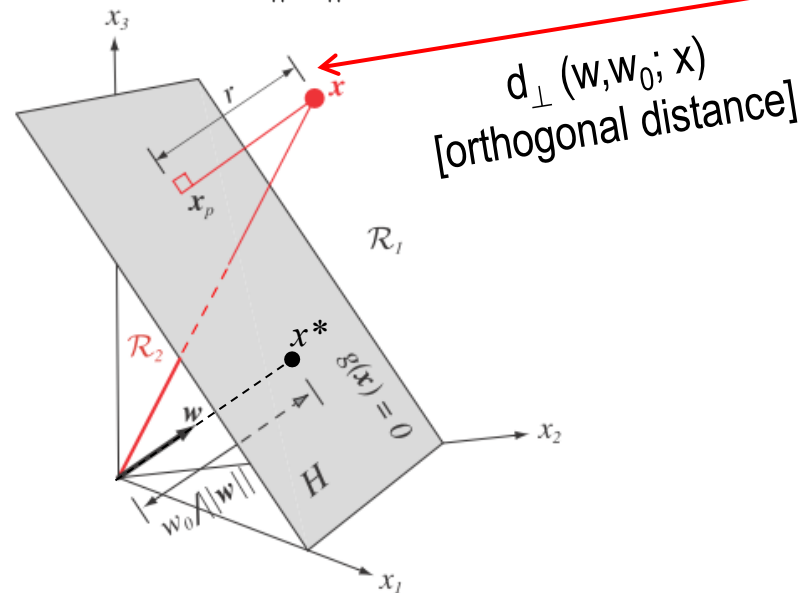


# Formulation of the SVM problem

- An additional fact about classification rules based on hyperplanes, i.e.  $g(\mathbf{x}) = \mathbf{w}^T \mathbf{x} + w_0$

$$\mathbf{x} = \mathbf{x}_p + r \frac{\mathbf{w}}{\|\mathbf{w}\|} \Rightarrow \mathbf{x}_p = \mathbf{x} - r \frac{\mathbf{w}}{\|\mathbf{w}\|}$$

$$g(\mathbf{x}_p) = \mathbf{w}^T \left( \mathbf{x} - r \frac{\mathbf{w}}{\|\mathbf{w}\|} \right) + w_0 = \mathbf{w}^T \mathbf{x} + w_0 - r \frac{\mathbf{w}^T \mathbf{w}}{\|\mathbf{w}\|} = g(\mathbf{x}) - r \|\mathbf{w}\| = 0 \Rightarrow r = \frac{g(\mathbf{x})}{\|\mathbf{w}\|}$$



**FIGURE 5.2.** The linear decision boundary  $H$ , where  $g(\mathbf{x}) = \mathbf{w}^T \mathbf{x} + w_0 = 0$ , separates the feature space into two half-spaces  $\mathcal{R}_1$  (where  $g(\mathbf{x}) > 0$ ) and  $\mathcal{R}_2$  (where  $g(\mathbf{x}) < 0$ ). From: Richard O. Duda, Peter E. Hart, and David G. Stork, *Pattern Classification*. Copyright © 2001 by John Wiley & Sons, Inc.

# Formulation of the SVM problem

- Let us define class indicators  $\mathbf{y}_i$  for every sample  $\mathbf{x}_i$

$$y_i = \begin{cases} +1 & x_i \in \omega_1 \\ -1 & x_i \in \omega_2 \end{cases} \Rightarrow \text{search for } (w, w_0) \text{ such that } y_i g(x_i) = y_i (w^T x_i + w_0) \geq 0, i = 1, \dots, N$$

- To solve the SVM problem, we need to maximize the margin for the  $\mathbf{x}_i$ 's closest to the separating hyperplane:

$$\arg \max_{w, w_0} \left\{ \min_i d_{\perp}(w, w_0; x_i) \right\} \equiv \arg \max_{w, w_0} \left\{ \min_i \left[ \frac{y_i (w^T x_i + w_0)}{\|w\|} \right] \right\}$$

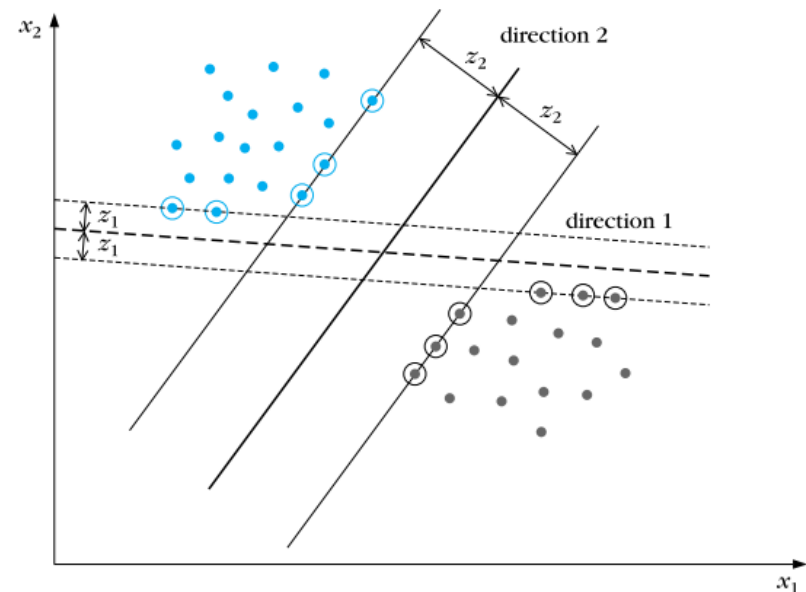
- Let us suppose now  $\|w\| = 1$  and that final opposite support vectors are at a distance  $2z$  from each other.

Then:

$$y_i (w^T x_i + w_0) \geq z, i = 1, \dots, N$$

$\Downarrow$

$$y_i \left( \left( \frac{w}{z} \right)^T x_i + \frac{w_0}{z} \right) \geq 1, i = 1, \dots, N$$



# Formulation of the SVM problem

- We can solve for  $\mathbf{w}^* = \mathbf{w} / \mathbf{z}$  and  $\mathbf{w}_0^* = \mathbf{w}_0 / \mathbf{z} = \mathbf{w}^T \mathbf{x}_0 / \mathbf{z}$  and free us from the scale factor of  $(\mathbf{w}, \mathbf{w}_0)$  [  $\mathbf{w}^T(\mathbf{x} - \mathbf{x}_0) = \mathbf{w}^T \mathbf{x} + \mathbf{w}_0 = 0 = (\mathbf{w}^*)^T \mathbf{x} + \mathbf{w}_0^*$  ] when maximizing

$$d_{\perp}(w, w_0; x_i) = \frac{y_i(w^T x_i + w_0)}{\|w\|} = \frac{y_i \left( \left( \frac{w}{z} \right)^T x_i + \frac{w_0}{z} \right)}{\sqrt{\left( \frac{w}{z} \right)^T \frac{w}{z}}} = \frac{y_i \left( (w^*)^T x_i + w_0^* \right)}{\|w^*\|}$$

- For appropriately scaled  $(\mathbf{w}, \mathbf{w}_0)$ , we have  $\forall x_i, y_i g(x_i) = y_i(w^T x_i + w_0) \geq 1$  and support vectors lie on hyperplanes  $y_i g(x_i) = y_i(w^T x_i + w_0) = 1$

- From this, we can write  $\max_w \left\{ \min_i \frac{y_i g(x_i)}{\|w\|} \right\} = \max_w \frac{1}{\|w\|} \equiv \min_w \|w\|$

- According to all the aforementioned, the **SVM problem** finally becomes into a quadratic optimization problem with linear constraints/inequalities:

$$\min J(w) = \frac{1}{2} w^T w$$

$$\text{subject to } y_i(w^T x_i + w_0) \geq 1, i = 1, \dots, N$$



- Formulation of the SVM problem for linearly separable classes
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- To solve the quadratic optimization problem with linear inequality constraints

$$\min J(w) = \frac{1}{2}w^T w$$

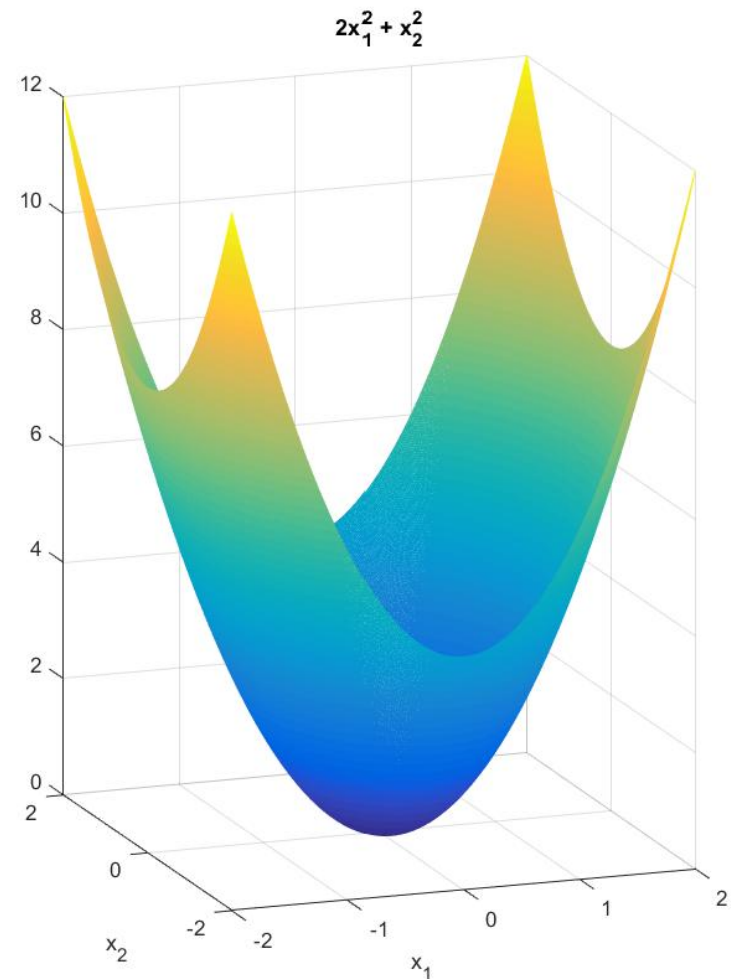
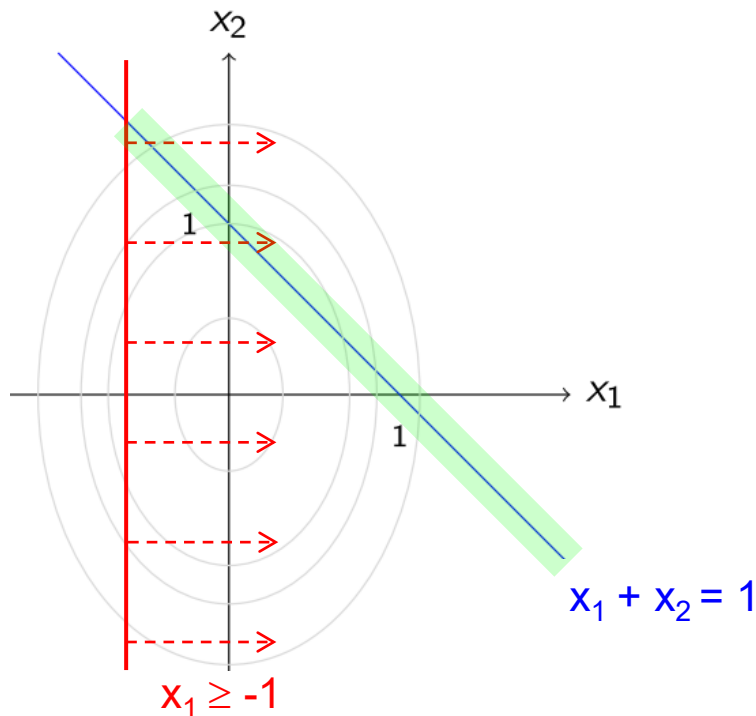
$$\text{subject to } y_i(w^T x_i + w_0) \geq 1, i = 1, \dots, N$$

we have to resort to the **Lagrangian** function and the **Karush-Kuhn-Tucker** (KKT) conditions (necessary conditions for function extrema in problems constrained by inequalities).

# Function optimization with constraints

- We want to solve this kind of optimization problems:

$$\begin{aligned} \min f(x) &= 2x_1^2 + x_2^2 \\ \text{subject to } x_1 + x_2 &= 1 \\ x_1 + 1 &\geq 0 \end{aligned}$$



# Function optimization with constraints

- In general:
$$\begin{aligned} &\min f(x) && [\max f(x) \equiv \min -f(x)] \\ &\text{subject to } g_j(x) = 0, \quad j = 1, \dots, n \\ & && h_k(x) \leq 0, \quad k = 1, \dots, m \quad [h_k(x) \geq 0 \rightarrow -h_k(x) \leq 0] \end{aligned}$$

requires the definition of the so-called **Lagrangian function**:

$$L(x, \lambda, \mu) = f(x) + \sum_{j=1}^n \lambda_j g_j(x) + \sum_{k=1}^m \mu_k h_k(x) \quad [\min f(x)]$$

$$L(x, \lambda, \mu) = -f(x) + \sum_{j=1}^n \lambda_j g_j(x) + \sum_{k=1}^m \mu_k h_k(x) \quad [\max f(x)]$$

where  $\{\lambda_j\}$  and  $\{\mu_k\}$  are the **Karush-Kuhn-Tucker multipliers**  
(Lagrange multipliers if there are no inequalities)

- The solution to the optimization problem is among the solutions of the **KKT conditions**

$$(1) \frac{\partial L}{\partial x_i} = 0, (2) \frac{\partial L}{\partial \lambda_j} = 0, (3) \mu_k h_k(x) = 0, (4) \mu_k \geq 0$$

- They are **necessary conditions** for locating function extrema in problems constrained by equalities and/or inequalities

# Function optimization with constraints

- Example:  $\min f(x) = 2x_1^2 + x_2^2$   
**subject to**  $x_1 + x_2 = 1$   
 $x_1 + 1 \geq 0$

$$\begin{aligned} \min f(x) &= 2x_1^2 + x_2^2 \\ \text{subject to } g(x) &= x_1 + x_2 - 1 = 0 \\ h(x) &= -(x_1 + 1) \leq 0 \end{aligned}$$

$$L(x, \lambda, \mu) = f(x) + \sum_{j=1}^n \lambda_j g_j(x) + \sum_{k=1}^m \mu_k h_k(x)$$



$$L(x, \lambda, \mu) = 2x_1^2 + x_2^2 + \lambda(x_1 + x_2 - 1) + \mu(-x_1 - 1)$$

$$\frac{\partial L}{\partial x_1} = 4x_1 + \lambda - \mu = 0$$

$$\frac{\partial L}{\partial x_2} = 2x_2 + \lambda = 0$$

$$\frac{\partial L}{\partial \lambda} = x_1 + x_2 - 1 = 0$$

$$\mu(-(x_1 + 1)) = 0, \mu \geq 0$$

$$\mu = 0$$

$$4x_1 + \lambda = 0 \Rightarrow x_1 = -\lambda/4 = \textcolor{red}{1/3}$$

$$2x_2 + \lambda = 0 \Rightarrow x_2 = -\lambda/2 = \textcolor{red}{2/3}$$

$$x_1 + x_2 - 1 = 0 \Rightarrow \lambda = -4/3$$

$$\mu(-(x_1 + 1)) = 0, \mu \geq 0$$

$$x_1 + 1 = 0 \Rightarrow x_1 = -1$$

$$-4 + \lambda - \mu = 0 \Rightarrow \mu = \textcolor{red}{-8}$$

$$2x_2 + \lambda = 0 \Rightarrow \lambda = \textcolor{red}{-4}$$

$$-1 + x_2 - 1 = 0 \Rightarrow x_2 = 2$$

$$\mu = \textcolor{red}{-8} \not\geq 0, \text{ NOT a solution}$$

- A **first** solution to the quadratic optimization problem associated to SVM training

$$\min J(w) = \frac{1}{2} w^T w$$

$$\text{subject to } y_i(w^T x_i + w_0) \geq 1, i = 1, \dots, N$$

**PRIMAL  
PROBLEM**

is obtained by means of the corresponding **Lagrangian** function

$$L(w, w_0, \lambda) = \frac{1}{2} w^T w - \sum_{i=1}^N \lambda_i [y_i(w^T x_i + w_0) - 1]$$

and the **Karush-Kuhn-Tucker** (KKT) conditions:

$$\frac{\partial L}{\partial w} = 0$$

$$\frac{\partial L}{\partial w_0} = 0$$

$$\lambda_i [y_i(w^T x_i + w_0) - 1] = 0, i = 1, \dots, N$$

$$\lambda_i \geq 0, i = 1, 2, \dots, N$$

$$\Rightarrow \begin{cases} w - \sum_{i=1}^N \lambda_i y_i x_i = 0 \Rightarrow w = \sum_{i=1}^N \lambda_i y_i x_i \\ \sum_{i=1}^N \lambda_i y_i = 0 \\ \lambda_i [y_i(w^T x_i + w_0) - 1] = 0, i = 1, \dots, N \\ \lambda_i \geq 0, i = 1, \dots, N \end{cases}$$

- **Remarks:**

- 1)  $\mathbf{w}$  is a linear combination of the feature vectors for which  $\lambda_i \neq 0$ :

$$\mathbf{w} = \sum_{i=1}^N \lambda_i y_i \mathbf{x}_i = \sum_{i|\lambda_i \neq 0} \lambda_i y_i \mathbf{x}_i$$

- 2) Regarding  $\lambda_i [y_i(\mathbf{w}^T \mathbf{x}_i + w_0) - 1] = 0$ , when  $\lambda_i \neq 0$ , the corresponding constraint is called **active**, and makes the corresponding  $\mathbf{x}_i$  lie on either of the two hyperplanes  $\mathbf{w}^T \mathbf{x}_i + w_0 = \pm 1$ .

$\mathbf{x}_i$  such that  $\lambda_i \neq 0$  are, thus, the **support vectors** and constitute the critical elements of the training set.

Feature vectors corresponding to  $\lambda_i = 0$  can either lie outside the **class separation band**, defined as the region between the two hyperplanes, or they can also lie on one of these hyperplanes (degenerate cases).

- 3) The resulting hyperplane is **insensitive to the number and position of the non-support vectors**, provided they do not cross the class separation band.

- **Remarks:**

4)  $\mathbf{w}_0$  can be deduced from the active constraints:

$$\begin{aligned}\lambda_i [y_i(w^T x_i + w_0) - 1] &= 0 \stackrel{\lambda_i \neq 0}{\Rightarrow} y_i(w^T x_i + w_0) = 1 \\ &\Rightarrow w^T x_i + w_0 = \frac{1}{y_i} = y_i \text{ (since } y_i = \pm 1) \\ &\Rightarrow w_0 = y_i - w^T x_i \\ &\Rightarrow w_0 = y_i - \left( \sum_{j|\lambda_j \neq 0} \lambda_j y_j x_j^T \right) x_i\end{aligned}$$

In practice,  $\mathbf{w}_0$  is computed as an average value obtained from all  $N_\lambda$  active constraints (it is numerically safer):

$$\begin{aligned}w_0 &= \frac{1}{N_\lambda} \sum_{i|\lambda_i \neq 0} \left( y_i - \left( \sum_{j|\lambda_j \neq 0} \lambda_j y_j x_j^T \right) x_i \right) \\ &= \frac{1}{N_\lambda} \sum_{i|\lambda_i \neq 0} y_i - \frac{1}{N_\lambda} \sum_{i,j|\lambda_i, \lambda_j \neq 0} \lambda_j y_j x_j^T x_i\end{aligned}$$

5) Due to the nature of the cost function (convex) and the constraints (linear), the SVM is guaranteed to be **unique**.



- We have yet to determine the  $\lambda_i$ . To this end,  $\mathbf{w}$  and  $\mathbf{w}_0$  are substituted in the Lagrangian using the equality constraints from the 1<sup>st</sup> solution (**Wolfe dual repres.**)

$$L(w, w_0, \lambda) = \frac{1}{2} w^T w - \sum_{i=1}^N \lambda_i [y_i (w^T x_i + w_0) - 1] \quad \Rightarrow$$

$w = \sum_{i=1}^N \lambda_i y_i x_i,$

$\sum_{i=1}^N \lambda_i y_i = 0$

$$L(\lambda) = \frac{1}{2} \left( \sum_{i=1}^N \lambda_i y_i x_i \right)^T \left( \sum_{j=1}^N \lambda_j y_j x_j \right) - \sum_{i=1}^N \lambda_i y_i \left( \sum_{j=1}^N \lambda_j y_j x_j \right)^T x_i - w_0 \sum_{i=1}^N \lambda_i y_i + \sum_{i=1}^N \lambda_i$$

$$= \sum_{i=1}^N \lambda_i - \frac{1}{2} \sum_{i=1}^N \sum_{j=1}^N \lambda_i \lambda_j y_i y_j x_i^T x_j$$

- The optimization problem becomes again into a **quadratic optimization problem**, to solve for  $\lambda_i$

$$\max L(\lambda) = \sum_{i=1}^N \lambda_i - \frac{1}{2} \sum_{i=1}^N \sum_{j=1}^N \lambda_i \lambda_j y_i y_j x_i^T x_j$$

$$\sum_{i=1}^N \lambda_i y_i = 0$$

$$\lambda_i \geq 0, i = 1, \dots, N$$

DUAL  
PROBLEM

- Given: 
$$\max L(\lambda) = \sum_{i=1}^N \lambda_i - \frac{1}{2} \sum_{i=1}^N \sum_{j=1}^N \lambda_i \lambda_j y_i y_j x_i^T x_j$$
$$\sum_{i=1}^N \lambda_i y_i = 0, \quad \lambda_i \geq 0, i = 1, \dots, N$$

DUAL  
PROBLEM

the solution by means of the KKT conditions turns out to be:

$$L(\lambda_i, \mu, \delta_i) = \overbrace{\frac{1}{2} \sum_{i=1}^N \sum_{j=1}^N \lambda_i \lambda_j y_i y_j x_i^T x_j}^{-f(x)} - \sum_{i=1}^N \lambda_i + \mu \sum_{i=1}^N \lambda_i y_i - \overbrace{\sum_{i=1}^N \delta_i \lambda_i}^{-\lambda_i \leq 0}$$

$$\frac{\partial L}{\partial \lambda_i} = \sum_{j=1}^N \lambda_j y_i y_j x_i^T x_j - 1 + \mu y_i - \delta_i = 0$$

$$\frac{\partial L}{\partial \mu} = \sum_{i=1}^N \lambda_i y_i = 0$$

$$\delta_i \lambda_i = 0, \quad \delta_i \geq 0, \quad i = 1, \dots, N$$

- In matrix form, we can write:

$$\begin{aligned} \frac{\partial L}{\partial \Lambda} = 0 &\Rightarrow H\Lambda + \mu Y - \Delta = \mathbf{1} & \Lambda &= \begin{bmatrix} \lambda_1 \\ \lambda_2 \\ \vdots \\ \lambda_N \end{bmatrix}, Y = \begin{bmatrix} y_1 \\ y_2 \\ \vdots \\ y_N \end{bmatrix}, \Delta = \begin{bmatrix} \delta_1 \\ \delta_2 \\ \vdots \\ \delta_N \end{bmatrix}, \mathbf{1} = \begin{bmatrix} 1 \\ 1 \\ \vdots \\ 1 \end{bmatrix} \\ \frac{\partial L}{\partial \mu} = 0 &\Rightarrow \sum_{i=1}^N \lambda_i y_i = 0 \\ \delta_i \lambda_i = 0, \delta_i \geq 0, i = 1, \dots, N & & H &= \begin{bmatrix} y_1 y_1 x_1^T x_1 & y_1 y_2 x_1^T x_2 & \dots & y_1 y_N x_1^T x_N \\ y_2 y_1 x_2^T x_1 & y_2 y_2 x_2^T x_2 & \dots & y_2 y_N x_2^T x_N \\ \vdots & \vdots & \ddots & \vdots \\ y_N y_1 x_N^T x_1 & y_N y_2 x_N^T x_2 & \dots & y_N y_N x_N^T x_N \end{bmatrix} \end{aligned}$$

- Although the hyperplane is unique, there is no guarantee of the uniqueness of the associated Lagrange multipliers  $\lambda_i$  and by extension of the expansion of  $\mathbf{w}$  in terms of support vectors
- Because of the size of this problem when  $\mathbf{N}$  is large, a number of efficient solutions have been developed (e.g. Platt's **Sequential Minimal Optimization** – SMO)

- **SVM algorithm:**

- Solve for the  $\lambda_i, i = 1, \dots, N$

$$H\Lambda + \mu Y - \Delta = \mathbf{1}$$

$$\sum_{i=1}^N \lambda_i y_i = 0$$

$$\delta_i \lambda_i = 0, \delta_i \geq 0, i = 1, \dots, N$$

$$\Lambda = \begin{bmatrix} \lambda_1 \\ \lambda_2 \\ \vdots \\ \lambda_N \end{bmatrix}, Y = \begin{bmatrix} y_1 \\ y_2 \\ \vdots \\ y_N \end{bmatrix}, \Delta = \begin{bmatrix} \delta_1 \\ \delta_2 \\ \vdots \\ \delta_N \end{bmatrix}, \mathbf{1} = \begin{bmatrix} 1 \\ 1 \\ \vdots \\ 1 \end{bmatrix}$$

$$H = \begin{bmatrix} y_1 y_1 x_1^T x_1 & y_1 y_2 x_1^T x_2 & \dots & y_1 y_N x_1^T x_N \\ y_2 y_1 x_2^T x_1 & y_2 y_2 x_2^T x_2 & \dots & y_2 y_N x_2^T x_N \\ \vdots & \vdots & \ddots & \vdots \\ y_N y_1 x_N^T x_1 & y_N y_2 x_N^T x_2 & \dots & y_N y_N x_N^T x_N \end{bmatrix}$$

- Solve for  $\mathbf{w}$ :

$$\mathbf{w} = \sum_{i|\lambda_i \neq 0} \lambda_i y_i x_i$$

- Solve for  $\mathbf{w}_0$ :

$$w_0 = \frac{1}{N_\lambda} \sum_{i|\lambda_i \neq 0} (y_i - \mathbf{w}^T x_i)$$

- An even **higher-level** view:

$$\begin{aligned} \min \quad & J(w, w_0) = \frac{1}{2} w^T w \\ \text{s.t.} \quad & y_i(w^T x_i + w_0) \geq 1, \quad i = 1, \dots, N \end{aligned}$$



*Wolfe dual representation*

$$\begin{aligned} \max \quad & L(\lambda) = \sum_{i=1}^N \lambda_i - \frac{1}{2} \sum_{i=1}^N \sum_{j=1}^N \lambda_i \lambda_j y_i y_j x_i^T x_j \\ \text{s.t.} \quad & \sum_{i=1}^N \lambda_i y_i = 0 \\ & \lambda_i \geq 0, \quad i = 1, \dots, N \end{aligned}$$

(1) solve for  $\lambda$

$$(2) \quad w = \sum_{i|\lambda_i \neq 0} \lambda_i y_i x_i$$

$$(3) \quad w_0 = \frac{1}{N_\lambda} \sum_{i|\lambda_i \neq 0} y_i - \sum_{i,j|\lambda_i, \lambda_j \neq 0} \lambda_j y_j x_j^T x_i$$

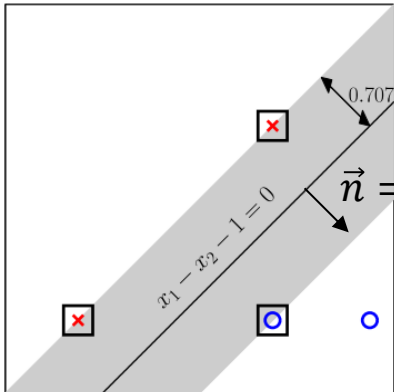
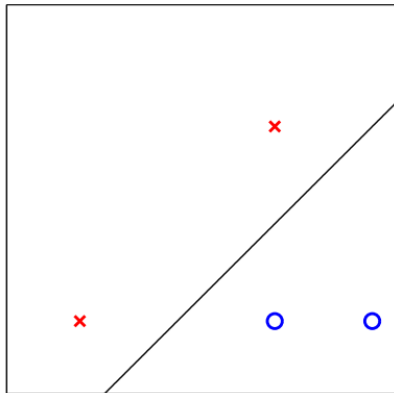
classify:  $\text{sign}(w^T x + w_0) \equiv$

$$\text{sign} \left( \sum_{i|\lambda_i \neq 0} \lambda_i y_i x_i^T x + w_0 \right)$$

# Numerical examples

- Example 1(a)

$$X = \begin{bmatrix} 0 & 0 \\ 2 & 2 \\ 2 & 0 \\ 3 & 0 \end{bmatrix} \quad y = \begin{bmatrix} -1 \\ -1 \\ +1 \\ +1 \end{bmatrix}$$



$$\min J(w) = \frac{1}{2} w^T w = \frac{1}{2} (w_1^2 + w_2^2)$$

$$\text{subject to } y_i(w^T x_i + w_0) \geq 1, i = 1, \dots, N$$

$$i) -1(0 \cdot w_1 + 0 \cdot w_2 + w_0) \geq 1 \Rightarrow -w_0 \geq 1$$

$$ii) -1(2 \cdot w_1 + 2 \cdot w_2 + w_0) \geq 1 \Rightarrow -(2w_1 + 2w_2 + w_0) \geq 1$$

$$iii) +1(2 \cdot w_1 + 0 \cdot w_2 + w_0) \geq 1 \Rightarrow 2w_1 + w_0 \geq 1$$

$$iv) +1(3 \cdot w_1 + 0 \cdot w_2 + w_0) \geq 1 \Rightarrow 3w_1 + w_0 \geq 1$$

$$i) : w_0 \leq -1$$

$$i) \text{ and } iii) : 2w_1 - 1 \geq 2w_1 + w_0 \geq 1 \Rightarrow w_1 \geq 1$$

$$ii) \text{ and } iii) : 1 + 2w_2 \leq 2w_1 + 2w_2 + w_0 \leq -1 \Rightarrow w_2 \leq -1$$

$$\Rightarrow \min J(=1) \text{ for } w_1 = 1 \text{ and } w_2 = -1$$

$$\forall \text{ support vector } x_i, y_i(w^T x_i + w_0) = 1$$

$$w_0 : -(0 \cdot w_1 + 0 \cdot w_2 + w_0) = 1 \Rightarrow w_0 = -1$$

$$: -(2 \cdot w_1 + 2 \cdot w_2 + w_0) = 1 \Rightarrow w_0 = -1$$

$$: +(2 \cdot w_1 + 0 \cdot w_2 + w_0) = 1 \Rightarrow w_0 = -1$$

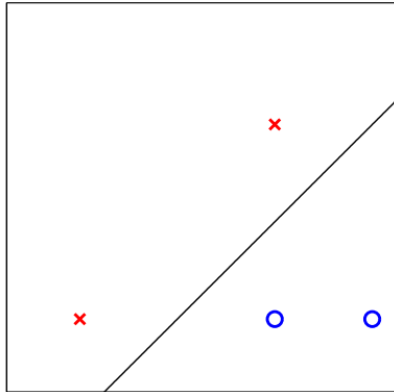
$$\text{hyperplane: } (w_1 = 1, w_2 = -1, w_0 = -1) \rightarrow x_1 - x_2 - 1 = 0$$

$$\text{margin: } 1/\|w\| = 0.7071$$

# Numerical examples

- Example 1(b)

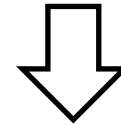
$$X = \begin{bmatrix} 0 & 0 \\ 2 & 2 \\ 2 & 0 \\ 3 & 0 \end{bmatrix} \quad y = \begin{bmatrix} -1 \\ -1 \\ +1 \\ +1 \end{bmatrix}$$



$$\max L(\lambda) = \sum_{i=1}^N \lambda_i - \frac{1}{2} \sum_{i=1}^N \sum_{j=1}^N \lambda_i \lambda_j y_i y_j x_i^T x_j$$

$$\text{s.t. } \sum_{i=1}^N \lambda_i y_i = 0$$

$$\lambda_i \geq 0, \quad i = 1, \dots, N$$



$$H\Lambda + \mu Y - \Delta = \mathbf{1}$$

$$\sum_{i=1}^N \lambda_i y_i = 0$$

$$\delta_i \lambda_i = 0, \quad \delta_i \geq 0, \quad i = 1, \dots, N$$

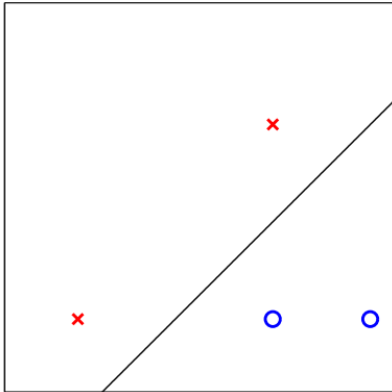
$$\Lambda = \begin{bmatrix} \lambda_1 \\ \lambda_2 \\ \vdots \\ \lambda_N \end{bmatrix}, \quad Y = \begin{bmatrix} y_1 \\ y_2 \\ \vdots \\ y_N \end{bmatrix}, \quad \Delta = \begin{bmatrix} \delta_1 \\ \delta_2 \\ \vdots \\ \delta_N \end{bmatrix}, \quad \mathbf{1} = \begin{bmatrix} 1 \\ 1 \\ \vdots \\ 1 \end{bmatrix}$$

$$H = \begin{bmatrix} y_1 y_1 x_1^T x_1 & y_1 y_2 x_1^T x_2 & \dots & y_1 y_N x_1^T x_N \\ y_2 y_1 x_2^T x_1 & y_2 y_2 x_2^T x_2 & \dots & y_2 y_N x_2^T x_N \\ \vdots & \vdots & \ddots & \vdots \\ y_N y_1 x_N^T x_1 & y_N y_2 x_N^T x_2 & \dots & y_N y_N x_N^T x_N \end{bmatrix}$$

# Numerical examples

- Example 1(b)

$$X = \begin{bmatrix} 0 & 0 \\ 2 & 2 \\ 2 & 0 \\ 3 & 0 \end{bmatrix} \quad y = \begin{bmatrix} -1 \\ -1 \\ +1 \\ +1 \end{bmatrix}$$



$$H\Lambda + \mu Y - \Delta = \mathbf{1}$$

$$\sum_{i=1}^N \lambda_i y_i = 0$$

$$\delta_i \lambda_i = 0, \delta_i \geq 0, i = 1, \dots, N$$

$$\Lambda = \begin{bmatrix} \lambda_1 \\ \lambda_2 \\ \vdots \\ \lambda_N \end{bmatrix}, Y = \begin{bmatrix} y_1 \\ y_2 \\ \vdots \\ y_N \end{bmatrix}, \Delta = \begin{bmatrix} \delta_1 \\ \delta_2 \\ \vdots \\ \delta_N \end{bmatrix}, \mathbf{1} = \begin{bmatrix} 1 \\ 1 \\ \vdots \\ 1 \end{bmatrix}$$

$$H = \begin{bmatrix} y_1 y_1 x_1^T x_1 & y_1 y_2 x_1^T x_2 & \dots & y_1 y_N x_1^T x_N \\ y_2 y_1 x_2^T x_1 & y_2 y_2 x_2^T x_2 & \dots & y_2 y_N x_2^T x_N \\ \vdots & \vdots & \ddots & \vdots \\ y_N y_1 x_N^T x_1 & y_N y_2 x_N^T x_2 & \dots & y_N y_N x_N^T x_N \end{bmatrix}$$

$$\begin{bmatrix} 0 & 0 & 0 & 0 \\ 0 & +8 & -4 & -6 \\ 0 & -4 & +4 & +6 \\ 0 & -6 & +6 & +9 \end{bmatrix} \begin{bmatrix} \lambda_1 \\ \lambda_2 \\ \lambda_3 \\ \lambda_4 \end{bmatrix} + \mu \begin{bmatrix} -1 \\ -1 \\ +1 \\ +1 \end{bmatrix} - \begin{bmatrix} \delta_1 \\ \delta_2 \\ \delta_3 \\ \delta_4 \end{bmatrix} = \begin{bmatrix} 1 \\ 1 \\ 1 \\ 1 \end{bmatrix}$$

$$-\lambda_1 - \lambda_2 + \lambda_3 + \lambda_4 = 0$$

$$\delta_1 \lambda_1 = 0, \delta_2 \lambda_2 = 0, \delta_3 \lambda_3 = 0, \delta_4 \lambda_4 = 0$$

$$\delta_1 \geq 0, \delta_2 \geq 0, \delta_3 \geq 0, \delta_4 \geq 0$$

$$\text{p.e. } \delta_1 = \delta_2 = \delta_3 = 0 \text{ and } \delta_4 > 0 \Rightarrow \lambda_4 = 0$$

$$-\mu = 1 \Rightarrow \mu = -1$$

$$8\lambda_2 - 4\lambda_3 - \mu = 1 \Rightarrow \lambda_3 = 2\lambda_2$$

$$-4\lambda_2 + 4\lambda_3 + \mu = 1 \Rightarrow -4\lambda_2 + 8\lambda_2 = 2 \Rightarrow \lambda_2 = 0.5, \lambda_3 = 1$$

$$-6\lambda_2 + 6\lambda_3 + \mu - \delta_4 = 1 \Rightarrow \delta_4 = 1$$

$$-\lambda_1 - \lambda_2 + \lambda_3 = 0 \Rightarrow \lambda_1 = \lambda_3 - \lambda_2 = 0.5$$

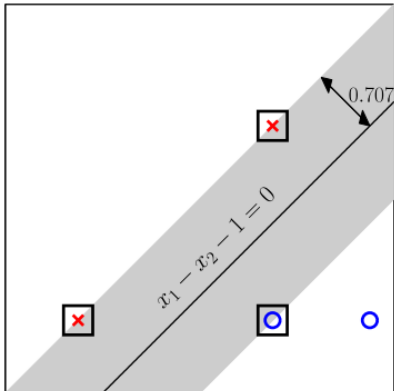
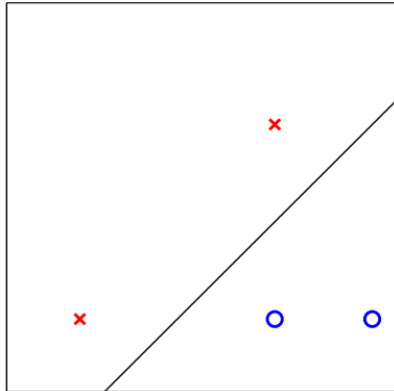
$$\Rightarrow L = 1$$



# Numerical examples

- Example 1(b)

$$X = \begin{bmatrix} 0 & 0 \\ 2 & 2 \\ 2 & 0 \\ 3 & 0 \end{bmatrix} \quad y = \begin{bmatrix} -1 \\ -1 \\ +1 \\ +1 \end{bmatrix}$$



$$\begin{bmatrix} 0 & 0 & 0 & 0 \\ 0 & +8 & -4 & -6 \\ 0 & -4 & +4 & +6 \\ 0 & -6 & +6 & +9 \end{bmatrix} \begin{bmatrix} \lambda_1 \\ \lambda_2 \\ \lambda_3 \\ \lambda_4 \end{bmatrix} + \mu \begin{bmatrix} -1 \\ -1 \\ +1 \\ +1 \end{bmatrix} - \begin{bmatrix} \delta_1 \\ \delta_2 \\ \delta_3 \\ \delta_4 \end{bmatrix} = \begin{bmatrix} 1 \\ 1 \\ 1 \\ 1 \end{bmatrix}$$

$$-\lambda_1 - \lambda_2 + \lambda_3 + \lambda_4 = 0$$

$$\delta_1 \lambda_1 = 0, \delta_2 \lambda_2 = 0, \delta_3 \lambda_3 = 0, \delta_4 \lambda_4 = 0$$

$$\delta_1 \geq 0, \delta_2 \geq 0, \delta_3 \geq 0, \delta_4 \geq 0$$

$\delta_1$	$\delta_2$	$\delta_3$	$\delta_4$	$\lambda_1$	$\lambda_2$	$\lambda_3$	$\lambda_4$	$\mu$	$L$
+0.00	+0.00	+0.00	+0.00	—	—	—	—	—	—
+0.00	+0.00	+0.00	+1.00	+0.50	+0.50	+1.00	+0.00	-1.00	+1.00
+0.00	+0.00	-0.67	+0.00	+0.11	+0.33	+0.00	+0.44	-1.00	—
+0.00	+0.00	-2.00	-2.00	+0.00	+0.00	+0.00	+0.00	-1.00	—
+0.00	—	+0.00	+0.00	—	+0.00	—	—	—	—
+0.00	-2.00	+0.00	+1.00	+0.50	+0.00	+0.50	+0.00	-1.00	—
+0.00	-1.33	-0.67	+0.00	+0.22	+0.00	+0.00	+0.22	-1.00	—
+0.00	+0.00	-2.00	-2.00	+0.00	+0.00	+0.00	+0.00	-1.00	—
-2.00	+0.00	+0.00	+0.00	+0.00	+0.50	+0.50	+0.00	+1.00	—
-2.00	+0.00	+0.00	+0.00	+0.00	+0.50	+0.50	+0.00	+1.00	—
-0.80	+0.00	-0.40	+0.00	+0.00	+0.40	+0.00	+0.40	-0.20	—
+0.00	+0.00	-2.00	-2.00	+0.00	+0.00	+0.00	+0.00	-1.00	—
-2.00	-2.00	+0.00	+0.00	+0.00	+0.00	+0.00	+0.00	+1.00	—
-2.00	-2.00	+0.00	+0.00	+0.00	+0.00	+0.00	+0.00	+1.00	—
-2.00	-2.00	+0.00	+0.00	+0.00	+0.00	+0.00	+0.00	+1.00	—
-1.00	-1.00	-1.00	-1.00	+0.00	+0.00	+0.00	+0.00	+0.00	—

$$w = \sum_{i|\lambda_i \neq 0} \lambda_i y_i x_i = 0.5(-1) \begin{bmatrix} 0 \\ 0 \end{bmatrix} + 0.5(-1) \begin{bmatrix} 2 \\ 2 \end{bmatrix} + 1(+1) \begin{bmatrix} 2 \\ 0 \end{bmatrix} = \begin{bmatrix} 1 \\ -1 \end{bmatrix}$$

$$w_0 = \frac{1}{N_\lambda} \sum_{i|\lambda_i \neq 0} (y_i - w^T x_i) = \frac{-1 - 1 - 1}{3} = -1$$

# Numerical examples

- Example 1(c)

$$X = \begin{bmatrix} 0 & 0 \\ 2 & 2 \\ 2 & 0 \\ 3 & 0 \end{bmatrix} \quad y = \begin{bmatrix} -1 \\ -1 \\ +1 \\ +1 \end{bmatrix}$$

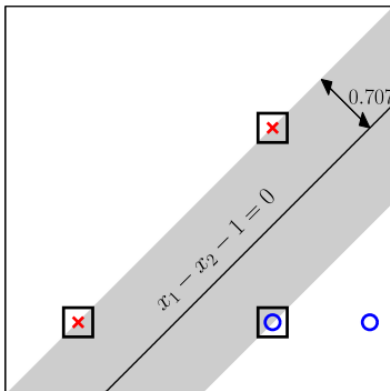
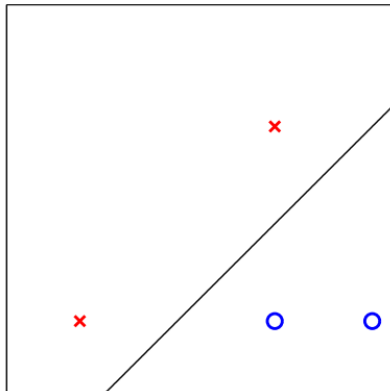
$$\max L(\lambda) = \sum_{i=1}^N \lambda_i - \frac{1}{2} \sum_{i=1}^N \sum_{j=1}^N \lambda_i \lambda_j y_i y_j x_i^T x_j$$

$$\text{s.t. } \sum_{i=1}^N \lambda_i y_i = 0$$

$$\lambda_i \geq 0, \quad i = 1, \dots, N$$

Using a QP solver, e.g. **cvxpy**:

*pip install cvxpy*  
or *conda install -c conda-forge cvxpy*



```
import cvxpy as cp
X = np.array([[0.,0.],[2.,2.],[2.,0.],[3.,0.]])
N = X.shape[0]
y = np.array([-1.,-1.,1.,1.]).reshape((N,1))
P = build_H(X,y)
G = np.identity(N)
h = np.zeros((N,1))
A = y.reshape((1,N))
b = 0.0

z = cp.Variable((N,1))
P = P + (1e-8) * np.identity(N) # for numerical stability
prob = cp.Problem(cp.Maximize(cp.sum(z) - 0.5*cp.quad_form(z,P)),
                  [G @ z >= h, A @ z == b])
prob.solve()
lm = z.value # lm = [0.5, 0.5, 1.0, 0.0]
```

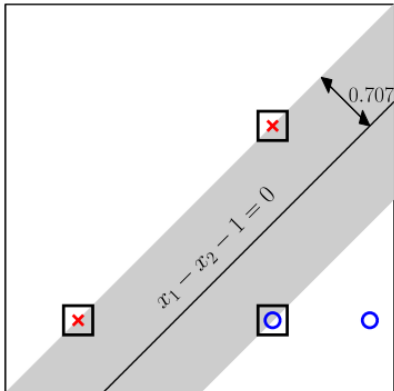
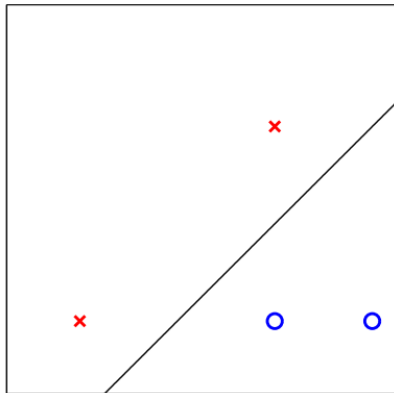
$$w = \sum_{i|\lambda_i \neq 0} \lambda_i y_i x_i = 0.5(-1) \begin{bmatrix} 0 \\ 0 \end{bmatrix} + 0.5(-1) \begin{bmatrix} 2 \\ 2 \end{bmatrix} + 1(+1) \begin{bmatrix} 2 \\ 0 \end{bmatrix} = \begin{bmatrix} 1 \\ -1 \end{bmatrix}$$

$$w_0 = \frac{1}{N_\lambda} \sum_{i|\lambda_i \neq 0} (y_i - w^T x_i) = \frac{-1 - 1 - 1}{3} = -1$$

# Numerical examples

- Example 1(d)

$$X = \begin{bmatrix} 0 & 0 \\ 2 & 2 \\ 2 & 0 \\ 3 & 0 \end{bmatrix} \quad y = \begin{bmatrix} -1 \\ -1 \\ +1 \\ +1 \end{bmatrix}$$



$$\max L(\lambda) = \sum_{i=1}^N \lambda_i - \frac{1}{2} \sum_{i=1}^N \sum_{j=1}^N \lambda_i \lambda_j y_i y_j x_i^T x_j$$

$$\text{s.t. } \sum_{i=1}^N \lambda_i y_i = 0$$

$$\lambda_i \geq 0, \quad i = 1, \dots, N$$

**Solve the primal problem**

$$\min J(w) = \frac{1}{2} w^T w$$

$$\text{subject to } y_i(w^T x_i + w_0) \geq 1, \forall i$$

Using a QP solver, e.g. **cvxpy**:

*pip install cvxpy*

or *conda install -c conda-forge cvxpy*

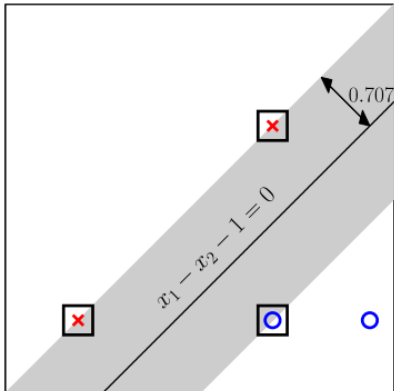
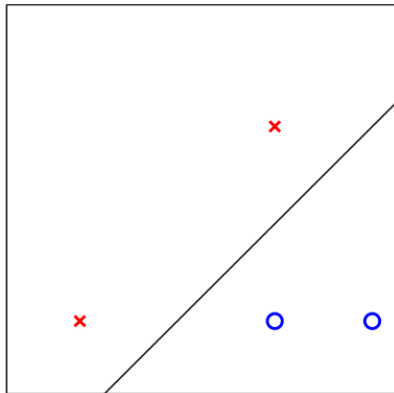
```
import cvxpy as cp
X = np.array([[0.,0.],[2.,2.],[2.,0.],[3.,0.]])
N = X.shape[0]
y = np.array([-1.,-1.,1.,1.]).reshape((N,1))
w = cp.Variable((2,1))
w0 = cp.Variable()
loss = cp.Minimize(0.5 * cp.square(cp.norm(w)))
constr = []
for i in range(N):
    xi, yi = X[i,:], y[i]
    constr += [yi @ (xi @ w + w0) >= 1]
prob = cp.Problem(loss, constr)
prob.solve()
print(w.value, w0.value) # w = [1.0, -1.0], w0 = -1.0
```

care with this formulation, since  
one does not have access to the  $\lambda$ 's

# Numerical examples

- Example 1(e)

$$X = \begin{bmatrix} 0 & 0 \\ 2 & 2 \\ 2 & 0 \\ 3 & 0 \end{bmatrix} \quad y = \begin{bmatrix} -1 \\ -1 \\ +1 \\ +1 \end{bmatrix}$$



$$\min J(w, w_0) = \frac{1}{2} w^T w$$

$$\text{s.t. } y_i(w^T x_i + w_0) \geq 1, \quad i = 1, \dots, N$$

Using **scikit-learn**:

```
from sklearn import svm

X = np.array([[0.,0.],[2.,2.],[2.,0.],[3.,0.]])
N = X.shape[0]
y = np.array([-1.,-1.,1.,1.]).reshape((N,1))
clf = svm.SVC(C = 1e16, kernel = 'linear')
clf.fit(X, y)
sv = clf.support_vectors_
w = clf.coef_.flatten()
w0 = clf.intercept_
lm = clf.dual_coeff_.flatten()

# sv = [[0.,0.], [2.,2.], [2.,0.]]
# w = [1.0, -1.0], w0 = -1.0
# lm = [-0.5, -0.5, 1] # y_i * lambda_i
```

# Multi-class problems

- **M-class problems**

1) Transform it into  $M$  two-class problems (*one-versus-rest* [**OVR**], *one-versus-all* [OVA])

$$g_i(x), i = 1, \dots, M \mid g_i(x) > 0 \text{ if } x \in \omega_i \text{ and } g_i(x) < 0 \text{ if } x \notin \omega_i$$

- It is an unbalanced problem since the negative class can comprise far more samples than the positive class

2) Transform it into  $M(M - 1)/2$  two-class problems (*one-versus-one* [**OVO**])

$$g_{ij}(x), i, j = 1, \dots, M, i \neq j \mid g_{ij}(x) > 0 \text{ if } x \in \omega_i$$

$g_{12}(x)$	$g_{13}(x)$	$g_{23}(x)$	class	$g_{12}(x)$	$g_{13}(x)$	$g_{23}(x)$	class
$< 0$ $\omega_2$	$< 0$ $\omega_3$	$< 0$ $\omega_3$	$\rightarrow \omega_3$	$> 0$ $\omega_1$	$< 0$ $\omega_3$	$< 0$ $\omega_3$	$\rightarrow \omega_3$
$< 0$ $\omega_2$	$< 0$ $\omega_3$	$> 0$ $\omega_2$	$\rightarrow \omega_2$	$> 0$ $\omega_1$	$< 0$ $\omega_3$	$> 0$ $\omega_2$	?
$< 0$ $\omega_2$	$> 0$ $\omega_1$	$< 0$ $\omega_3$	?	$> 0$ $\omega_1$	$> 0$ $\omega_1$	$< 0$ $\omega_3$	$\rightarrow \omega_1$
$< 0$ $\omega_2$	$> 0$ $\omega_1$	$> 0$ $\omega_2$	$\rightarrow \omega_2$	$> 0$ $\omega_1$	$> 0$ $\omega_1$	$> 0$ $\omega_2$	$\rightarrow \omega_1$

- Sort of a voting scheme
- Training and inference can be slow for  $N, M$  large

$g_{12}(x)$	$> 0$	$< 0$	
$g_{13}(x)$	$> 0$		$< 0$
$g_{23}(x)$		$> 0$	$< 0$
	$\omega_1$	$\omega_2$	$\omega_3$

- Formulation of the SVM problem for linearly separable classes
- SVM training for linearly separable classes
- Non-linearly separable classes
- Non-linear SVM
- Numerical examples
- Final remarks

# Non-linearly separable classes

- When the classes are not linearly separable, the original setup is **no longer valid**

- Any attempt to draw a hyperplane will never end up with a class separation band

$$w^T x + w_0 = \pm 1$$

with no data points inside it

- For this case, we have the following classes of samples:

- 1) Points that fall outside the band, at the correct side ( $\bullet$ ,  $\bullet$ ):

$$y_i(w^T x_i + w_0) \geq 1$$

- 2) Points that fall inside the band, also at the correct side ( $\square$ ,  $\square$ ):

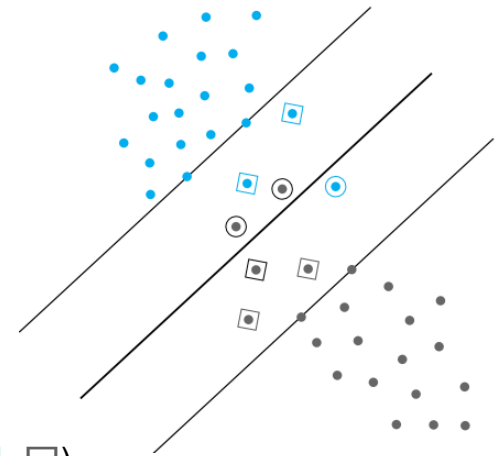
$$0 \leq y_i(w^T x_i + w_0) < 1$$

- 3) Points that are missclassified ( $\odot$ ,  $\odot$ ):

$$y_i(w^T x_i + w_0) < 0$$

- This can be summarized by introducing a new set of variables  $\xi_i$  (**slack variables**) such that  $y_i(w^T x_i + w_0) \geq 1 - \xi_i$

- In this way:
  - (1)  $\xi_i = 0$
  - (2)  $0 < \xi_i \leq 1$
  - (3)  $\xi_i > 1$



# Non-linearly separable classes

- The **goal** is now
  - to make the margin as large as possible, but at the same time
  - to keep the number of samples with  $\xi_i > 0$  as small as possible

$$\min J(w, w_0, \xi) = \frac{1}{2} w^T w + C \sum_{i=1}^N \xi_i$$

$$\text{subject to} \quad y_i(w^T x_i + w_0) \geq 1 - \xi_i, \quad i = 1, \dots, N$$
$$\xi_i \geq 0, \quad i = 1, \dots, N$$

**SOFT MARGIN** problem  
versus  
**HARD MARGIN** problem

where  $C$  is a positive constant that controls the relative influence of the  $\xi$  term

- The problem is solved by a **Lagrangian** and the **Karush-Kuhn-Tucker conditions**:

$$L(w, w_0, \xi, \lambda, \mu) = \frac{1}{2} w^T w + C \sum_{i=1}^N \xi_i - \sum_{i=1}^N \lambda_i [y_i(w^T x_i + w_0) - 1 + \xi_i] - \sum_{i=1}^N \mu_i \xi_i$$

$$\frac{\partial L}{\partial w} = 0 \Rightarrow w = \sum_{i=1}^N \lambda_i y_i x_i$$

$$\frac{\partial L}{\partial w_0} = 0 \Rightarrow \sum_{i=1}^N \lambda_i y_i = 0$$

$$\frac{\partial L}{\partial \xi_i} = 0 \Rightarrow C - \mu_i - \lambda_i = 0, \quad i = 1, \dots, N$$

$$\lambda_i [y_i(w^T x_i + w_0) - 1 + \xi_i] = 0, \quad i = 1, \dots, N$$

$$\mu_i \xi_i = 0, \quad i = 1, \dots, N$$

$$\lambda_i \geq 0, \quad \mu_i \geq 0, \quad i = 1, \dots, N$$



# Non-linearly separable classes

- The corresponding **Wolfe dual representation** is obtained from the primal problem:

$$\min L(w, w_0, \xi, \lambda, \mu) = \frac{1}{2} w^T w + C \sum_{i=1}^N \xi_i - \sum_{i=1}^N \lambda_i [y_i (w^T x_i + w_0) - 1 + \xi_i] - \sum_{i=1}^N \mu_i \xi_i$$

subject to

$$\begin{aligned} w &= \sum_{i=1}^N \lambda_i y_i x_i \\ \sum_{i=1}^N \lambda_i y_i &= 0 \\ C - \mu_i - \lambda_i &= 0, \quad i = 1, \dots, N \\ \lambda_i &\geq 0, \quad \mu_i \geq 0, \quad i = 1, \dots, N \end{aligned}$$

The constraints are grouped into two sets: a green box containing the first two constraints, and a red box containing the third and fourth constraints. A green arrow points from the green box to the first two terms of the dual problem, and a red arrow points from the red box to the third and fourth terms of the dual problem.

... substituting the above equality constraints into the Lagrangian to end up with:

$$\begin{aligned} \max L(\lambda) &= \sum_{i=1}^N \lambda_i - \frac{1}{2} \sum_{i=1}^N \sum_{j=1}^N \lambda_i \lambda_j y_i y_j x_i^T x_j \\ &\quad \sum_{i=1}^N \lambda_i y_i = 0 \text{ and } 0 \leq \lambda_i \leq C, \quad i = 1, \dots, N \end{aligned}$$

- The only difference with the linearly-separable case is the bound  $C$  on  $\lambda_i$ .

# Non-linearly separable classes

- Summing up:

## Hard margin formulation

$$\begin{aligned} \min \quad & J(w, w_0) = \frac{1}{2} w^T w \\ \text{s.t.} \quad & y_i(w^T x_i + w_0) \geq 1, \quad i = 1, \dots, N \end{aligned}$$



*Wolfe dual representation*

$$\begin{aligned} \max \quad & L(\lambda) = \sum_{i=1}^N \lambda_i - \frac{1}{2} \sum_{i=1}^N \sum_{j=1}^N \lambda_i \lambda_j y_i y_j x_i^T x_j \\ \text{s.t.} \quad & \sum_{i=1}^N \lambda_i y_i = 0 \\ & \lambda_i \geq 0, \quad i = 1, \dots, N \end{aligned}$$

(1) solve for  $\lambda$

$$(2) \quad w = \sum_{i|\lambda_i \neq 0} \lambda_i y_i x_i$$

$$(3) \quad w_0 = \frac{1}{N_\lambda} \sum_{i|\lambda_i \neq 0} y_i - \sum_{i,j|\lambda_i, \lambda_j \neq 0} \lambda_j y_j x_j^T x_i$$

## Soft margin formulation

$$\begin{aligned} \min \quad & J(w, \xi) = \frac{1}{2} w^T w + C \sum_{i=1}^N \xi_i \\ \text{s.t.} \quad & y_i(w^T x_i + w_0) \geq 1 - \xi_i, \quad i = 1, \dots, N \\ & \xi_i \geq 0, \quad i = 1, \dots, N \end{aligned}$$



*Wolfe dual representation*

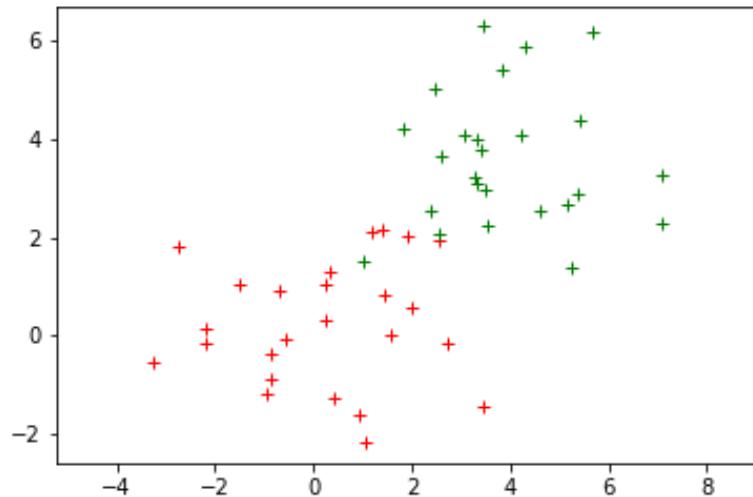
$$\begin{aligned} \max \quad & L(\lambda) = \sum_{i=1}^N \lambda_i - \frac{1}{2} \sum_{i=1}^N \sum_{j=1}^N \lambda_i \lambda_j y_i y_j x_i^T x_j \\ \text{s.t.} \quad & \sum_{i=1}^N \lambda_i y_i = 0 \\ & 0 \leq \lambda_i \leq C, \quad i = 1, \dots, N \end{aligned}$$

classify:  $\text{sign}(w^T x + w_0) \equiv$

$$\text{sign} \left( \sum_{i|\lambda_i \neq 0} \lambda_i y_i x_i^T x + w_0 \right)$$

# Numerical Examples

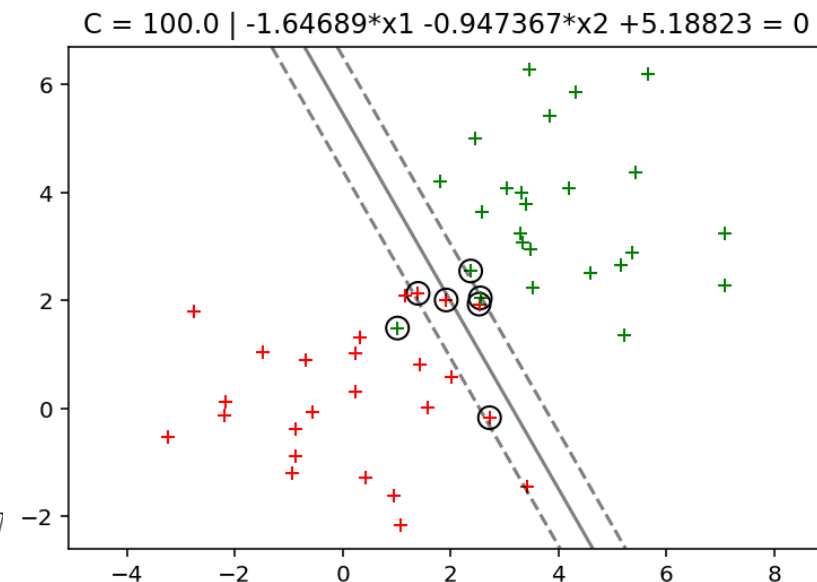
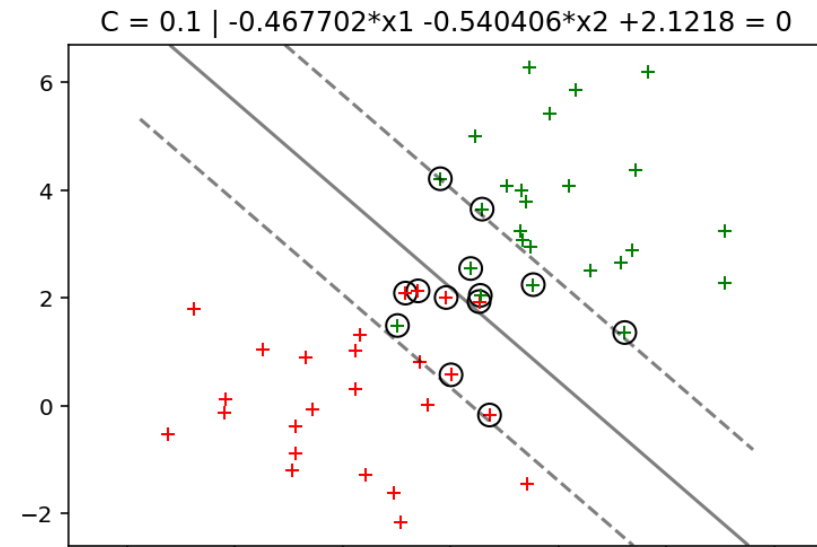
- Example 2: derive the SVM corresponding to the next non-linearly separable classif. problem



Wolfe dual representation

$$\begin{aligned} \min J(w, w_0, \xi) &= \frac{1}{2} w^T w + C \sum_{i=1}^N \xi_i \\ \text{subject to} \quad &y_i(w^T x_i + w_0) \geq 1 - \xi_i, \quad i = 1, \dots, N \\ &\xi_i \geq 0, \quad i = 1, \dots, N \end{aligned}$$

$$\begin{aligned} \max L(\lambda) &= \sum_{i=1}^N \lambda_i - \frac{1}{2} \sum_{i=1}^N \sum_{j=1}^N \lambda_i \lambda_j y_i y_j x_i^T x_j \\ &\sum_{i=1}^N \lambda_i y_i = 0 \text{ and } 0 \leq \lambda_i \leq C, \quad i = 1, \dots, N \end{aligned}$$



# Numerical Examples

- Example 2:

using a QP solver, e.g. **cvxpy**:

```
X = np.loadtxt('svm_samples.txt')
N = X.shape[0]
y = np.loadtxt('svm_labels.txt')
P = build_H(X, y)
A = y.reshape((1,N))
lb = np.zeros((N,1))
ub = C * np.ones((N,1))
z = cp.Variable((N,1))
P = P + (1e-8) * np.identity(N)
prob = cp.Problem(
    cp.Maximize(cp.sum(z) -
                 0.5*cp.quad_form(z,P)),
    [z >= lb, z <= ub, A@z == 0.0])
prob.solve(verbose=True, solver='SCS')
lm = z.value
ilm = (lm > 1e-4).flatten() # indices SV
```

Wolfe dual  
representation

$$\begin{aligned} \min J(w, w_0, \xi) &= \frac{1}{2} w^T w + C \sum_{i=1}^N \xi_i \\ \text{subject to} \quad & y_i (w^T x_i + w_0) \geq 1 - \xi_i, \quad i = 1, \dots, N \\ & \xi_i \geq 0, \quad i = 1, \dots, N \end{aligned}$$
$$\begin{aligned} \max L(\lambda) &= \sum_{i=1}^N \lambda_i - \frac{1}{2} \sum_{i=1}^N \sum_{j=1}^N \lambda_i \lambda_j y_i y_j x_i^T x_j \\ & \sum_{i=1}^N \lambda_i y_i = 0 \text{ and } 0 \leq \lambda_i \leq C, \quad i = 1, \dots, N \end{aligned}$$

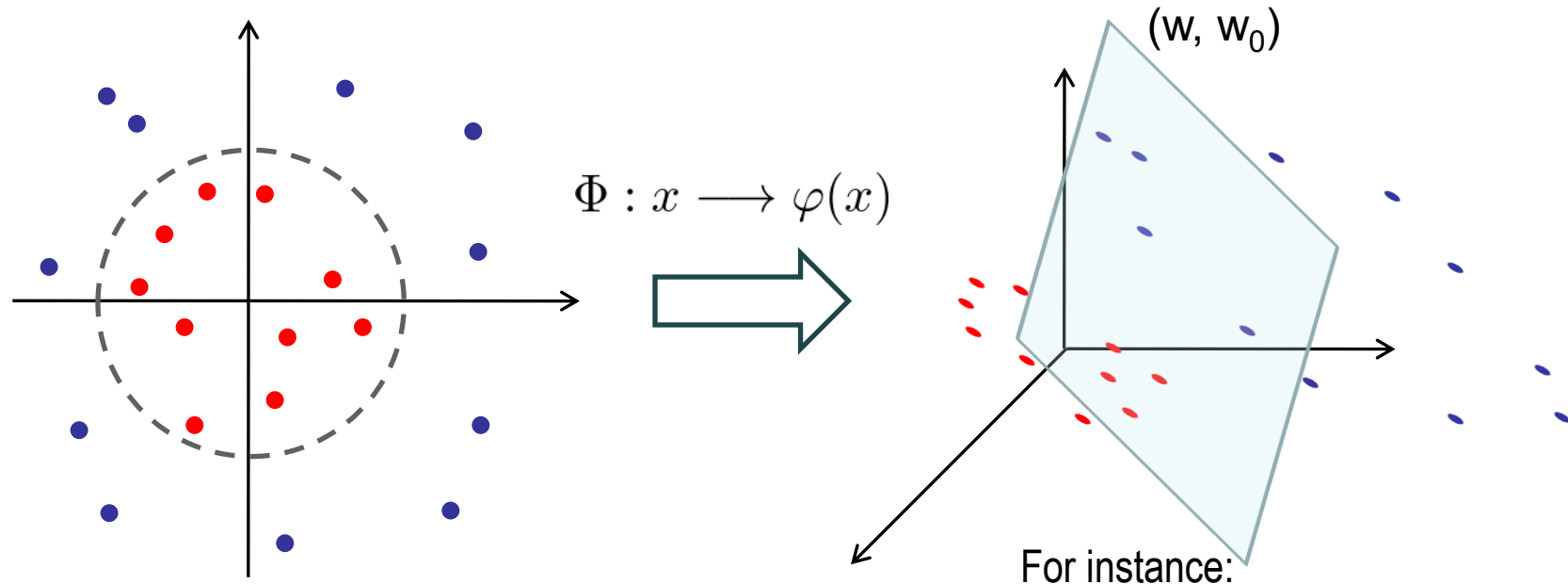
using **scikit-learn**:

```
clf = svm.SVC(C = C, kernel = 'linear')
clf.fit(X, y)
```

- Formulation of the SVM problem for linearly separable classes
- SVM training for linearly separable classes
- Non-linearly separable classes
- Non-linear SVM
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- Final remarks

# Non-linear SVM

- Non-linear classification problems can often be solved by **mapping the input feature space onto a larger dimensional space**, where the classes can be satisfactorily separated by a hyperplane:



- Thanks to the SVM formulation, the cost of working in a higher dimension is not excessive, but controlled
  - This is known as the “kernel trick”

$$\begin{aligned} \Phi : \mathcal{R}^2 &\longrightarrow \mathcal{R}^3 \\ (x_1, x_2) &\longrightarrow \begin{pmatrix} x_1^2 \\ \sqrt{2}x_1x_2 \\ x_2^2 \end{pmatrix} \end{aligned}$$

- The mapping into a higher space is incorporated in the following way:

## Hard margin formulation

$$\begin{aligned} \min J(w) &= \frac{1}{2} w^T w \\ \text{s.t. } y_i(w^T \Phi(x_i) + w_0) &\geq 1, i = 1, \dots, N \end{aligned}$$



*Wolfe dual representation*

$$\begin{aligned} \max L(\lambda) &= \sum_{i=1}^N \lambda_i - \frac{1}{2} \sum_{i=1}^N \sum_{j=1}^N \lambda_i \lambda_j y_i y_j \Phi(x_i)^T \Phi(x_j) \\ \text{s.t. } \sum_{i=1}^N \lambda_i y_i &= 0 \\ \lambda_i &\geq 0, i = 1, \dots, N \end{aligned}$$

## Soft margin formulation

$$\begin{aligned} \min J(w, \xi) &= \frac{1}{2} w^T w + C \sum_{i=1}^N \xi_i \\ \text{s.t. } y_i(w^T \Phi(x_i) + w_0) &\geq 1 - \xi_i, i = 1, \dots, N \\ \xi_i &\geq 0, i = 1, \dots, N \end{aligned}$$



*Wolfe dual representation*

$$\begin{aligned} \max L(\lambda) &= \sum_{i=1}^N \lambda_i - \frac{1}{2} \sum_{i=1}^N \sum_{j=1}^N \lambda_i \lambda_j y_i y_j \Phi(x_i)^T \Phi(x_j) \\ \text{s.t. } \sum_{i=1}^N \lambda_i y_i &= 0 \\ 0 \leq \lambda_i &\leq C, i = 1, \dots, N \end{aligned}$$

(1) solve for  $\lambda$

$$(2) w = \sum_{i|\lambda_i \neq 0} \lambda_i y_i \Phi(x_i)$$

$$(3) w_0 = \frac{1}{N_\lambda} \sum_{i|\lambda_i \neq 0} y_i - \sum_{i,j|\lambda_i, \lambda_j \neq 0} \lambda_j y_j \Phi(x_j)^T \Phi(x_i)$$

classify:  $\text{sign}(w^T \Phi(x) + w_0) \equiv$

$$\text{sign} \left( \sum_{i|\lambda_i \neq 0} \lambda_i y_i \Phi(x_i)^T \Phi(x) + w_0 \right)$$

- For instance:

$$\begin{aligned} \Phi : \mathcal{R}^2 &\longrightarrow \mathcal{R}^3 \\ (x_1, x_2) &\longrightarrow \begin{pmatrix} x_1^2 \\ \sqrt{2}x_1x_2 \\ x_2^2 \end{pmatrix} \end{aligned} \quad \Phi(x)^T \Phi(z) = \begin{pmatrix} x_1^2 & \sqrt{2}x_1x_2 & x_2^2 \end{pmatrix} \begin{pmatrix} z_1^2 \\ \sqrt{2}z_1z_2 \\ z_2^2 \end{pmatrix}$$

$$= x_1^2 z_1^2 + 2x_1x_2 z_1z_2 + x_2^2 z_2^2$$

$$= (x_1 z_1 + x_2 z_2)^2 = (x^T z)^2 = K_{hp}(x, z)$$

Kernel trick: one can operate in the original space (less computation) instead of operating in the larger-dimensional space, but with the advantages of the latter

- This and other functions known as **kernels** satisfy the following condition:

$$K(x, z) = \Phi(x)^T \Phi(z)$$

(Mercer's theorem characterizes these functions)

- This is the case of:

Linear kernel

$$K_{ln}(x, z) = x^T z$$

(homogeneous) Polynomial kernel

$$K_{hp}(x, z) = (x^T z)^q, \quad q > 0$$

(inhomogeneous) Polynomial kernel

$$K_{ip}(x, z) = (\gamma x^T z + r)^q, \quad q > 0, \quad r \text{ usually } 1$$

(Gaussian) Radial Basis Function kernel

$$K_{rbf}(x, z) = e^{-\frac{\|x-z\|^2}{2\sigma^2}} = e^{-\gamma\|x-z\|^2}$$

[in this last case, the higher-dimensional feature space  $\Phi(x)$  is infinite dimensional]

and others ...



- Another example:  $\Phi(x) = (1, \sqrt{2}x_1, \sqrt{2}x_2, x_1^2, x_2^2, \sqrt{2}x_1x_2)^T$

$$\Phi(x)^T \Phi(z) = (1 + x^T z)^2 = K_{ih}(x, z)$$

- In general, the **expansion** of an L-variate M-degree inhomogeneous polynomial is:  
(in the following, all coefficients are assumed 1 for simplicity)

$$\Pi^M(x_1, \dots, x_L) = 1 + \sum_{i=1}^L x_i + \sum_{\substack{i, j=1 \\ a+b=2 \\ a \geq 0, b \geq 0}}^L x_i^a x_j^b + \dots + \sum_{\substack{i, j, \dots=1 \\ a+b+\dots=M \\ a \geq 0, b \geq 0, \dots}}^L x_i^a x_j^b \dots$$

- The **number of terms** of  $\Pi^M(x)$ , and  $\Phi(x)$ , is thus:

$$\begin{aligned} 1 + \sum_{i=1}^M \text{CR}_{L,i} &= 1 + \text{CR}_{L,1} + \text{CR}_{L,2} + \dots + \text{CR}_{L,M} = \sum_{i=0}^M \binom{L+i-1}{i} \\ &= \binom{L-1}{0} + \binom{L}{1} + \binom{L+1}{2} + \dots + \binom{L+M-1}{M} = \frac{(L+M)!}{M!L!} \end{aligned}$$

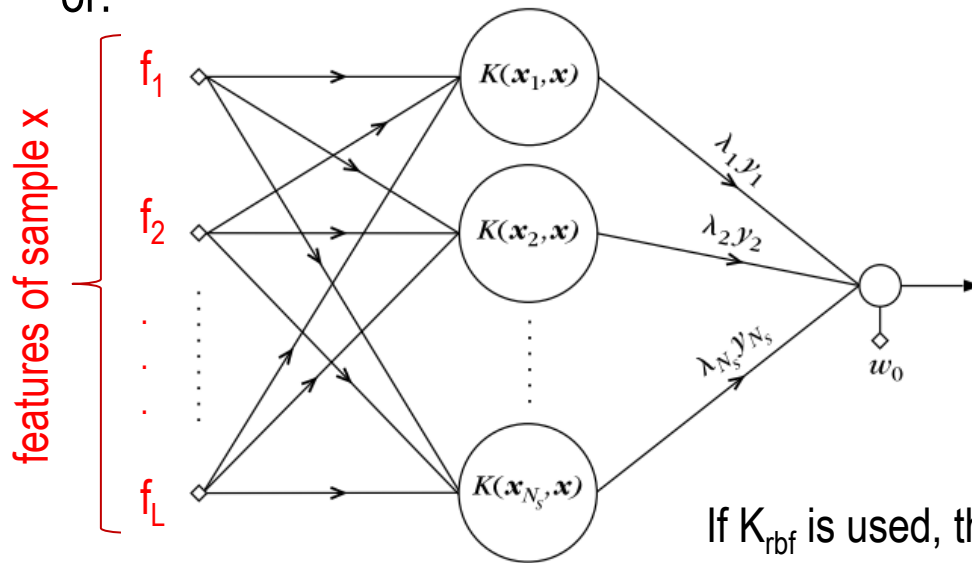
- For instance, for **L = 10** and **M = 4**,  $\Phi(x)$  dimension becomes 1001:
  - computing  $\Phi(x)^T \Phi(z)$  means a dot product involving 1001-component vectors,
  - while  $(1 + x^T z)^4$  represents a dot product involving 10-component vectors

# Non-linear SVM

- Apart from the benefits of working in a higher number of dimensions at almost no cost, with the “kernel trick” the **classification** operation becomes:

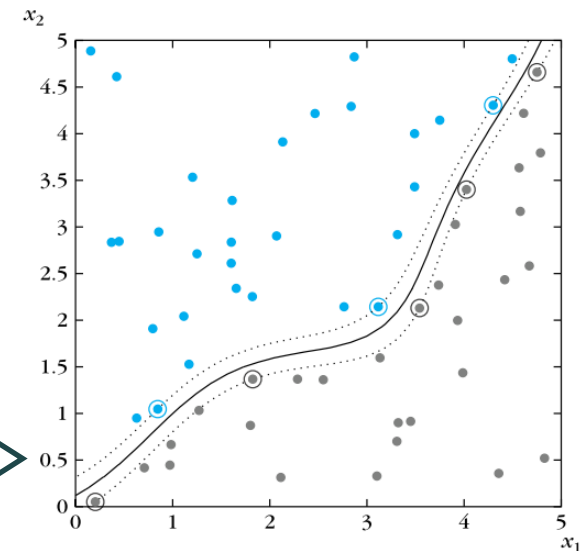
$$\text{sign} \left( \underbrace{\sum_{i|\lambda_i \neq 0} \lambda_i y_i K(x_i, x)}_{w^T \Phi(x)} + w_0 \right) > 0 (< 0) \Rightarrow x \rightarrow \omega_1 (\omega_2)$$

or:



$x = (f_1, f_2, \dots, f_L)$   
 $N_s$ : num. support vectors

If  $K_{\text{rbf}}$  is used, the classifier is known as an **RBF network**



- Formulation of the SVM problem for linearly separable classes
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# Numerical Examples

- Example 3: derive the SVM corresponding to the next 2-class classification problem

$$\omega_1 = \{ (1,1)^T, (-1,-1)^T \} (\bullet)$$

$$\omega_2 = \{ (1,-1)^T, (-1,1)^T \} (\bullet)$$

Wolfe dual representation

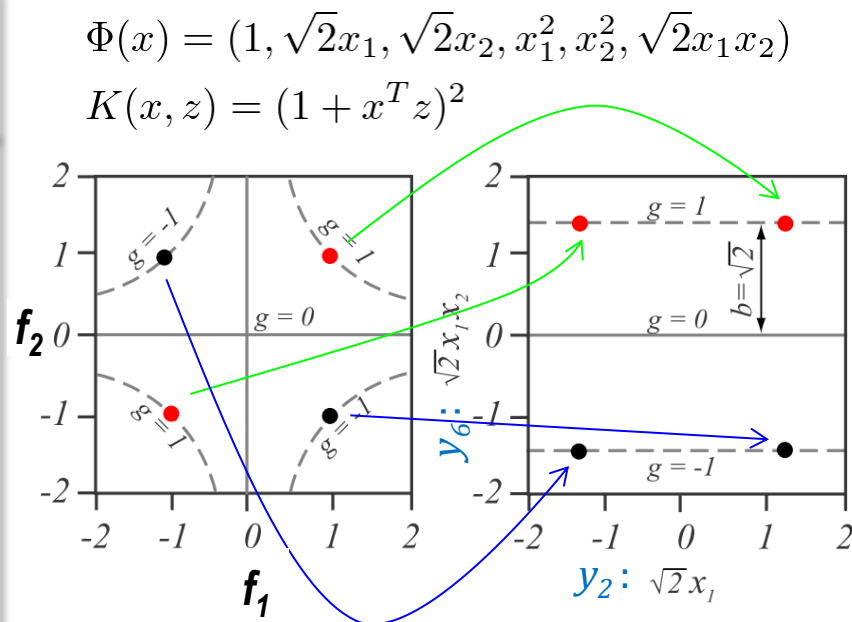
$$\min J(w, w_0) = \frac{1}{2} w^T w$$

$$\text{s.t. } y_i(w^T \Phi(x_i) + w_0) \geq 1, \quad i = 1, \dots, N$$

$$\max L(\lambda) = \sum_{i=1}^N \lambda_i - \frac{1}{2} \sum_{i=1}^N \sum_{j=1}^N \lambda_i \lambda_j y_i y_j K(x_i, x_j)$$

$$\text{s.t. } \sum_{i=1}^N \lambda_i y_i = 0$$

$$\lambda_i \geq 0, \quad i = 1, \dots, N$$



$$(1) H = \begin{bmatrix} y_1 y_1 K(x_1, x_1) & y_1 y_2 K(x_1, x_2) & \dots & y_1 y_N K(x_1, x_N) \\ y_2 y_1 K(x_2, x_1) & y_2 y_2 K(x_2, x_2) & \dots & y_2 y_N K(x_2, x_N) \\ \vdots & \vdots & \ddots & \vdots \\ y_N y_1 K(x_N, x_1) & y_N y_2 K(x_N, x_2) & \dots & y_N y_N K(x_N, x_N) \end{bmatrix} \quad (2) w = \sum_{i|\lambda_i \neq 0} \lambda_i y_i \Phi(x_i)$$

$$(3) w_0 = \frac{1}{N_\lambda} \sum_{i|\lambda_i \neq 0} (y_i - \sum_{j|\lambda_j \neq 0} \lambda_j y_j K(x_j, x_i))$$

# Numerical Examples

- Solution:**  $\omega_1 : x_1 = (1, 1)^T, x_3 = (-1, -1)^T \Rightarrow y_1 = +1, y_3 = +1$   
 $\omega_2 : x_2 = (1, -1)^T, x_4 = (-1, 1)^T \Rightarrow y_2 = -1, y_4 = -1$

$$K(x, z) = (1 + x^T z)^2$$

$$H = \begin{bmatrix} y_1 y_1 K(x_1, x_1) & y_1 y_2 K(x_1, x_2) & y_1 y_3 K(x_1, x_3) & y_1 y_4 K(x_1, x_4) \\ y_2 y_1 K(x_2, x_1) & y_2 y_2 K(x_2, x_2) & y_2 y_3 K(x_2, x_3) & y_2 y_4 K(x_2, x_4) \\ y_3 y_1 K(x_3, x_1) & y_3 y_2 K(x_3, x_2) & y_3 y_3 K(x_3, x_3) & y_3 y_4 K(x_3, x_4) \\ y_4 y_1 K(x_4, x_1) & y_4 y_2 K(x_4, x_2) & y_4 y_3 K(x_4, x_3) & y_4 y_4 K(x_4, x_4) \end{bmatrix} = \begin{bmatrix} 9 & -1 & 1 & -1 \\ -1 & 9 & -1 & 1 \\ 1 & -1 & 9 & -1 \\ -1 & 1 & -1 & 9 \end{bmatrix}$$

using a QP solver, e.g. **cvxpy** :

$$\min \frac{1}{2} z^T P z + q^T z$$

$$\text{s.t. } z \geq 0$$

$$A z = b$$

```
P = build_H_wpk(X, y, g=1, r=1, q=2)
```

```
A = y.reshape((1, 4))
```

```
z = cp.Variable((4, 1))
```

```
prob = cp.Problem(cp.Minimize(0.5 * cp.quad_form(z, P) - cp.sum(z)),  
[z >= 0, A @ z == 0])
```

```
prob.solve()
```

```
l = z.value
```

```
ilm = (lm > 1e-6).flatten()
```

$$K_{ip}(x, z) = (\gamma x^T z + r)^q$$

$$\Phi(x) = (1, \sqrt{2}x_1, \sqrt{2}x_2, x_1^2, x_2^2, \sqrt{2}x_1x_2)$$

$$K(x, z) = (1 + x^T z)^2$$

$$\Rightarrow \begin{cases} \lambda_1 = 0.125 \\ \lambda_2 = 0.125 \\ \lambda_3 = 0.125 \\ \lambda_4 = 0.125 \end{cases}$$

$$w = \sum_{i|\lambda_i \neq 0} \lambda_i y_i \Phi(x_i) = \lambda_1 \begin{bmatrix} 1 \\ \sqrt{2} \\ \sqrt{2} \\ 1 \\ 1 \\ \sqrt{2} \end{bmatrix} - \lambda_2 \begin{bmatrix} 1 \\ \sqrt{2} \\ -\sqrt{2} \\ 1 \\ 1 \\ -\sqrt{2} \end{bmatrix} + \lambda_3 \begin{bmatrix} 1 \\ -\sqrt{2} \\ -\sqrt{2} \\ 1 \\ 1 \\ \sqrt{2} \end{bmatrix} - \lambda_4 \begin{bmatrix} 1 \\ -\sqrt{2} \\ \sqrt{2} \\ 1 \\ 1 \\ -\sqrt{2} \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ \frac{1}{\sqrt{2}} \end{bmatrix}$$

$$w_0 = \underbrace{1}_{y_1} - \underbrace{\begin{bmatrix} 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ \frac{1}{\sqrt{2}} \end{bmatrix}^T \begin{bmatrix} 1 \\ \sqrt{2} \\ \sqrt{2} \\ 1 \\ 1 \\ \sqrt{2} \end{bmatrix}}_{w^T \Phi(x_1)} = 0$$

# Numerical Examples

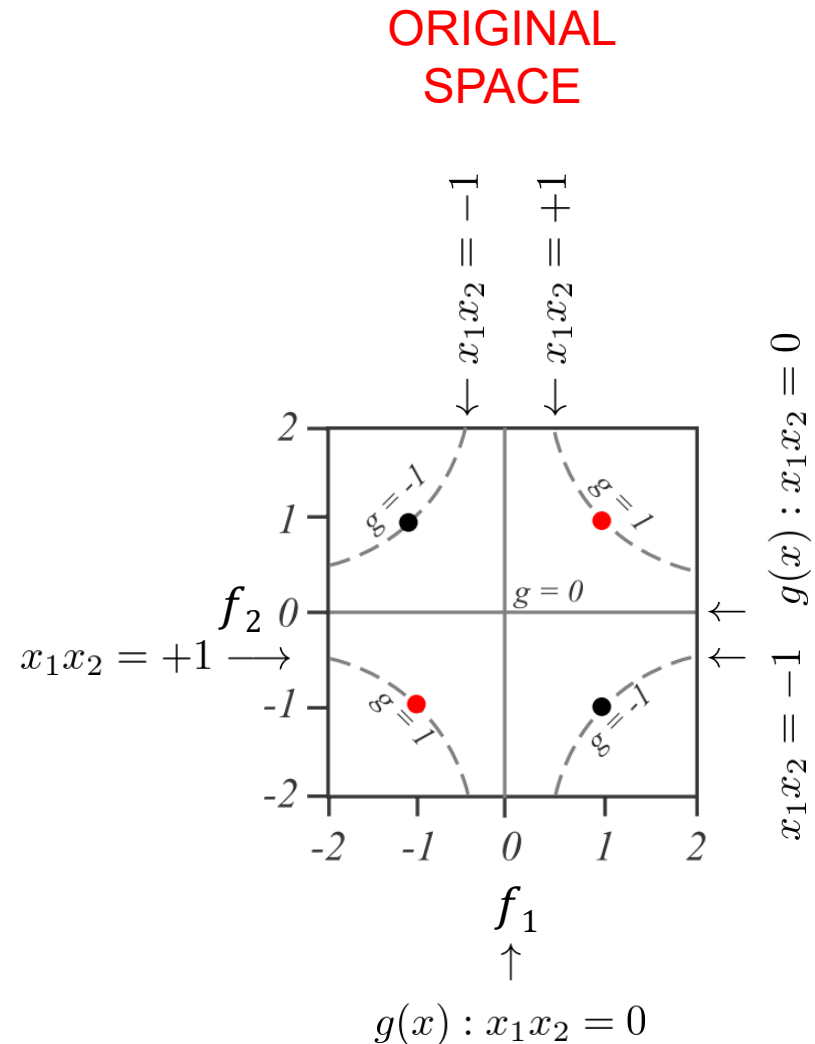
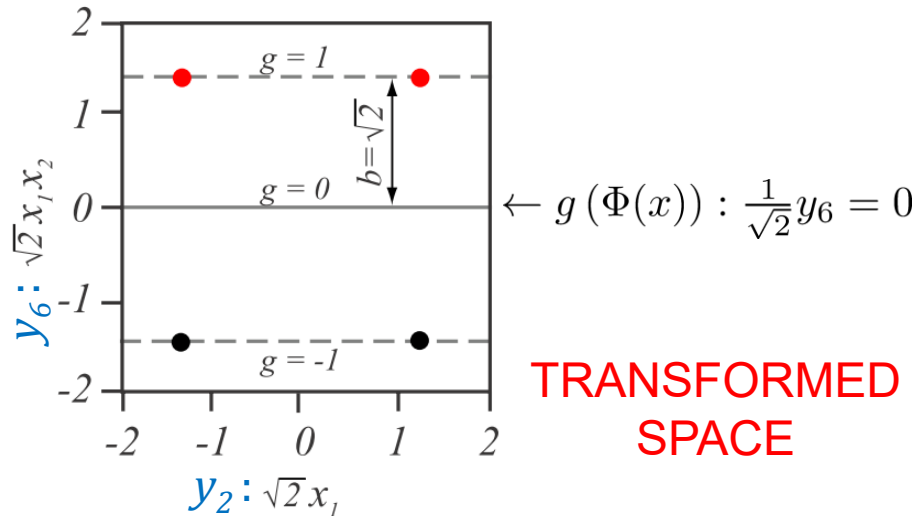
- Solution:**

$$\Phi(x) = (1, \sqrt{2}x_1, \sqrt{2}x_2, x_1^2, x_2^2, \sqrt{2}x_1x_2)$$

$$w = (0, 0, 0, 0, 0, \frac{1}{\sqrt{2}})$$

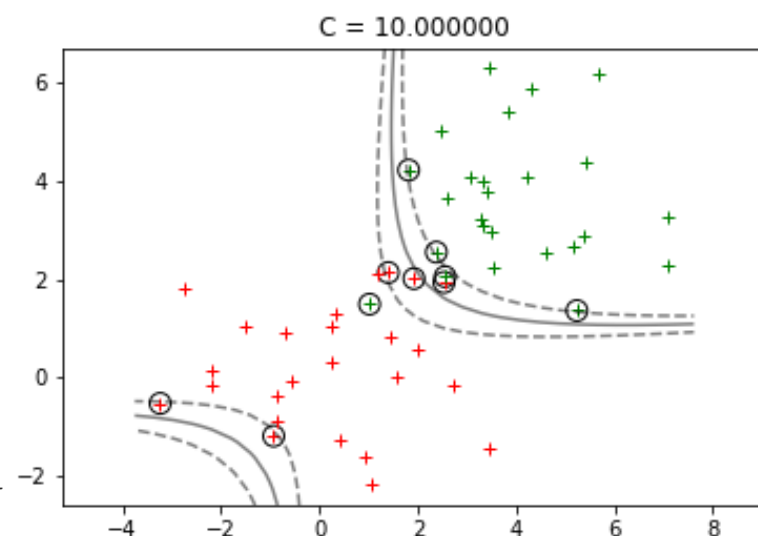
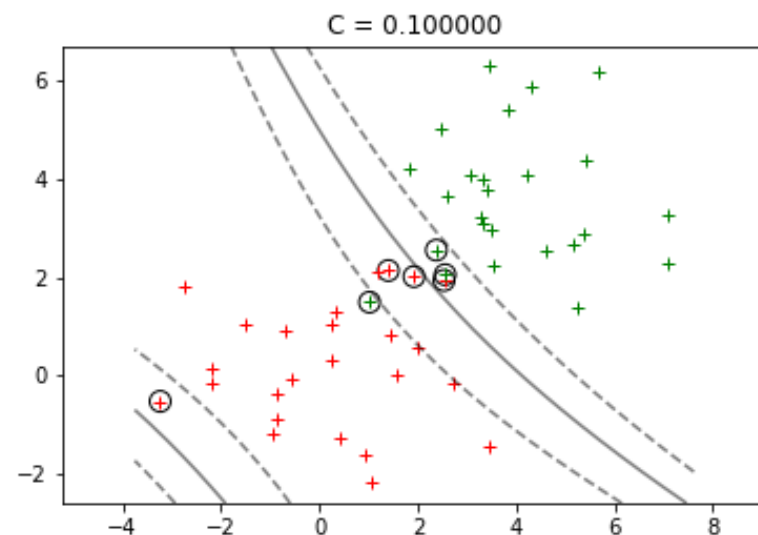
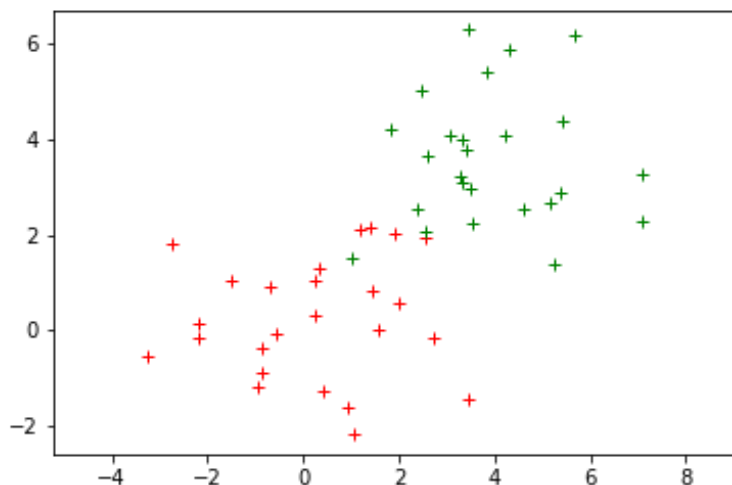
$$\Rightarrow \text{SVM} : \frac{1}{\sqrt{2}} (\sqrt{2}x_1x_2) = x_1x_2 = 0$$

and the SV lie on  $x_1x_2 = \pm 1$



# Numerical Examples

- Example 4: derive the SVM for the following classif. problem using  $K(x, z) = (1 + x^T z)^2$



Wolfe dual representation

$$\min J(w, w_0, \xi) = \frac{1}{2} w^T w + C \sum_{i=1}^N \xi_i$$

$$\text{subject to } y_i(w^T \Phi(x_i) + w_0) \geq 1 - \xi_i, \quad i = 1, \dots, N$$

$$\xi_i \geq 0, \quad i = 1, \dots, N$$

$$\max L(\lambda) = \sum_{i=1}^N \lambda_i - \frac{1}{2} \sum_{i=1}^N \sum_{j=1}^N \lambda_i \lambda_j y_i y_j K(x_i, x_j)$$

$$\sum_{i=1}^N \lambda_i y_i = 0 \text{ and } 0 \leq \lambda_i \leq C, \quad i = 1, \dots, N$$

- Example 4:

$$\min J(w, w_0, \xi) = \frac{1}{2} w^T w + C \sum_{i=1}^N \xi_i$$

$$\text{subject to} \quad y_i(w^T \Phi(x_i) + w_0) \geq 1 - \xi_i, \quad i = 1, \dots, N$$

$$\xi_i \geq 0, \quad i = 1, \dots, N$$

$$\max L(\lambda) = \sum_{i=1}^N \lambda_i - \frac{1}{2} \sum_{i=1}^N \sum_{j=1}^N \lambda_i \lambda_j y_i y_j K(x_i, x_j)$$

$$\sum_{i=1}^N \lambda_i y_i = 0 \text{ and } 0 \leq \lambda_i \leq C, \quad i = 1, \dots, N$$

using a QP solver, e.g. **cvxpy**:

```
X = np.loadtxt('svm_samples.txt')
y = np.loadtxt('svm_labels.txt')
P = build_H_wpk(X, y, g=1, r=1, q=2)
A = y.reshape((1,N))
lb = np.zeros((N,));
ub = C * np.ones((N,))
z = cp.Variable((N,1))
P = P + (1e-6) * np.identity(N)
prob = cp.Problem(
    cp.Minimize(0.5 * cp.quad_form(z, P)
                - cp.sum(z)),
    [z >= lb, z <= ub, A @ z = 0] )
prob.solve(solver='SCS')
ilm = (lm > 1e-6).flatten() # indices SV
```

standard formulation

$$\min \frac{1}{2} z^T P z + q^T z$$

$$\text{s.t. } Gz \leq h$$

$$Az = b$$

$$lb \leq z \leq ub$$

using **scikit-learn**:

```
clf = svm.SVC(C = C, kernel = 'poly',
              degree = 2, coef0 = 1, gamma = 1)
clf.fit(X, y)
```



- Formulation of the SVM problem for linearly separable classes
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- Final remarks

- SVMs tend to be **less prone to overfitting** than other methods
  - Because the classifier resulting from the SVM approach **depends only on the SV**, which are the **most significant** patterns for the classification task
  - Besides, the margin band **contributes to the generalization performance**
  - As a consequence, in general, they **exhibit good generalization performance**
- The **complexity** of the classifier depends more on the number of SV than on the dimensionality of the feature space
  - Thanks to the SVM formulation and the kernel trick, working in a higher dimension is almost at **zero cost**
- However:
  - There is not an efficient practical method for **choosing the best kernel**
  - Besides, once a kernel has been chosen, its parameters' values, **hyperparameters**, have to be selected
    - They are crucial to the generalization capabilities of the classifier
  - As a consequence, the most common procedure is to **solve the SVM task for different sets of parameters** (grid search)

# Instance-based learning: Support Vector Machines



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