Tabell1

| Project | Priority | Prio 3 | Duration | Users | Platform | Status | End date |
|-----------------------------|----------|--------|----------|---|-------------------------|-----------------------------|----------|
| Cyberlab stereo setup | 0 | | | Catherine | Cyberlab | | |
| Servo for Andreas | 1 | | 10 | Andreas | Arduino | Final fix, find bugs | |
| Level 2 & 3 | | | | | | | |
| Finger pushing | 3 | 2 | 40 | Hiske | Shadow box | New material needed | |
| Force monitoring | 3 | | | Giovanni, Claudio | Arduino | Need feedback | New |
| Cyberlab API rc1 | 2 | | | | OpenGL/Firewire | | 12-05-31 |
| - Magic box | 2 | 2 | | Giovanni | - | Order TV | 13-01-30 |
| - Multi camera | 2 | 3 | | | Magic box | | |
| - Framepackaging | 2 | 1 | | | Stereo vision on screen | Test with Bino | |
| Split vision | 3 | | | Arvid | | | |
| GUI for force-servo setup | 3 | | | Andreas | Python | Might be useful | |
| Thermometer | 4 | ? | | Hiske | LabJack | Debugging - non ros version | |
| Discontinue? | | | | | | | |
| Pan/tilt unit | 4 | ? | | Björn | ROS | See ki-ros-pkg | |
| AD converter analog cameras | 3 | | | | ImagineSource | | |
| Heart rate monitor | 3 | ? | | Björn/Loretxu | Polar | | |
| ROS PsychoPy | 3 | ? | | All | Mac/Linux | Keep in mind | |
| Finished | | | | | | | |
| Example project | 3 | | | | | | |
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| Urgent | 0 | | | Ongoing experiments | s, needing fix | | |
| Top priority | 1 | | | Only one project can have this staus | | | |
| Status quo | 2 | | | Keep everything floating, but not urget (administration) | | | |
| Nice to have | 3 | | | Includes things that eventually must be done, and things that might never happen. | | | |
| Low | 4 | | | Low but keep in mi | | | |