

# Numerics (Part III)

## [Lecture 1] Triangular Linear Systems

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# Matrix Representation of a Linear System

$$\hat{A} = \begin{bmatrix} 1 & -1 & 2 \\ 2 & -1 & -1 \\ 1 & 1 & 1 \end{bmatrix} \quad \vec{x} = \begin{bmatrix} x_1 \\ x_2 \\ x_3 \end{bmatrix} \quad \vec{b} = \begin{bmatrix} 2 \\ 0 \\ 3 \end{bmatrix}$$

$$\begin{cases} x_1 - x_2 + 2x_3 = 2 \\ 2x_1 - x_2 - x_3 = 0 \\ x_1 + x_2 + x_3 = 3 \end{cases} \quad \hat{A} \cdot \vec{x} = \vec{b}$$

## Matrix Representation of a Triangular System

$$\hat{A} = \begin{bmatrix} 1 & -1 & 2 \\ 0 & -1 & -1 \\ 0 & 0 & 1 \end{bmatrix} \quad \vec{x} = \begin{bmatrix} x_1 \\ x_2 \\ x_3 \end{bmatrix} \quad \vec{b} = \begin{bmatrix} 2 \\ 0 \\ 3 \end{bmatrix}$$

$$\begin{cases} x_1 - x_2 + 2x_3 = 2 \\ -x_2 - x_3 = 0 \\ x_3 = 3 \end{cases} \quad \begin{cases} x_1 = 2 + x_2 - 2x_3 = 2 - 3 - 6 = -7 \\ x_2 = -x_3 = -3 \\ x_3 = 3 \end{cases}$$

## Solving by Substitution

- INPUT: triangular system  $\hat{\mathbf{A}}, \vec{b}$  ( $\hat{\mathbf{A}}$  triangular)
- OUTPUT: solution  $\vec{x}^*$  such that  $\hat{\mathbf{A}} \cdot \vec{x}^* = \vec{b}$

Bottom-up substitution + right-left  
(stop just before the diagonal)

n matrix dimension

*solution vector  $\vec{x}^*$*

for i=n .. 1

*obtained by starting from the*

for j=n .. i

*last element*

x(i)= ...

end

end

## Manual $5 \times 5$ in Python ...

```
x[4] = b[4]/A[4][4]
```

```
tmp = A[3][4]*x[4]
```

```
x[3] = (b[3]-tmp)/A[3][3]
```

```
tmp = A[2][4]*x[4] + A[2][3]*x[3]
```

```
x[2] = (b[2]-tmp)/A[2][2]
```

```
tmp = A[1][4]*x[4] + A[1][3]*x[3] + A[1][2]*x[2]
```

```
x[1] = (b[1]-tmp)/A[1][1]
```

```
tmp = A[0][4]*x[4] + A[0][3]*x[3] + A[0][2]*x[2] + A[0][1]*x[1]
```

```
x[0] = (b[0]-tmp)/A[0][0]
```

## Substitution in Python ...

```
def triangular_solver(A,b):  
  
    n = len(b)  
    x = numpy.array([0.0 for _ in range(n)])  
    for i in range(n-1,-1,-1):  
        tmp = 0.0  
        for j in range(n-1,i,-1):  
            tmp += A[i][j]*x[j]  
        x[i] = (b[i]-tmp)/A[i][i]  
    return x
```

# Computational Complexity of Substitution

- One division for each equation ( $n$  divisions)
- One subtraction and one multiplication for each upper-diagonal element
- Upper-diagonal Elements =  $\frac{n^2-n}{2}$
- Number of Basic Operations =  $n + 2 \cdot \frac{n^2-n}{2} = n^2$
- Quadratic Complexity  $O(n^2)$