The Cauchy-Kowalevski Theorem and Its Consequences

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Sofya Vasilyevna Kovalevskaya (1850-1891)

We assume the historical figure of Augustin-Louis Cauchy is well-known.

Kowalevski was:

Introduction

- a Russian mathematician and student of Weierstrass
- the first woman to earn a doctorate (3 theses dating back to 1874) and to obtain a chair in Europe (in mathematics)

literature and cinema. The most notable are:

Introduction

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- An accurate biography: Little Sparrow: A Portrait of Sophia Kovalevsky (1983), Don H. Kennedy
- A short story: Too Much Happiness (2009), Alice Munro

Guiding Questions

Introduction

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Is it possible for an analytical solution of a PDE system with Cauchy conditions to exist? The answer is affirmative, so we already ask:

- under what assumptions?
- is the solution unique?
- is the problem well-posed?
- what are the consequences of the obtained results?

Types of Equations (and Operators)

Equations of order k:

Linear	$\sum_{ \alpha \le k} a_{\alpha} D^{\alpha} u = f$
Quasi-linear	$\sum_{ \alpha =k} a_{\alpha}(x, D^{\beta}u) D^{\alpha}u + a_{0}(x, D^{\beta}u) = f,$
	$ \beta < k$
Non-linear	$F(x, D^{\alpha}u) = 0, \alpha \le k$
In normal form	$D_t^k u = G(x, D_x^{\alpha} D_t^j u), \alpha + j \le k, j < k$

Tools

- Characteristic surfaces
- Method of characteristics
- Cauchy problems
- Power series

Characteristic Surfaces for Linear Operators

L linear differential operator.

Definizione 2.1

Characteristic form of L:

$$\chi_L(x,\xi) = \sum_{|\alpha|=k} a_{\alpha}(x) \, \xi^{\alpha}$$
 with $x,\xi \in \mathbb{R}^n$

Definizione 2.2

Characteristic variety of L at x:

$$char_x(L) = \{ \xi \neq 0 : \chi_L(x, \xi) = 0 \}$$



 Γ characteristic surface for L at $x \iff \nu(x) \in \operatorname{char}_x(L)$

Osservazione

Case of 1st order operator: $A = (a_1, \ldots, a_n)$ tangent to Γ . Useful for further generalizations.

Meaning

$$\xi \in \operatorname{char}_x(L)$$

at x L is not "properly" of order k in the direction ξ .

 Γ non-characteristic

given $D_{\nu}^{i}u\left(i < k\right)$ of a solution u on Γ it is possible to calculate all its partial derivatives on Γ .

1st Order Quasi-linear Operators

- $\blacksquare u = \phi \text{ on } \Gamma \text{ Cauchy data}$

Definizione 2.4

 Γ non-characteristic at $x_0 = \gamma(s_0)$

$$\iff \det \underbrace{\begin{bmatrix} D_{s_1} \gamma_1 & \cdots & D_{s_{n-1}} \gamma_1 \\ \vdots & & \vdots \\ D_{s_1} \gamma_n & \cdots & D_{s_{n-1}} \gamma_n \end{bmatrix}}_{\text{span of the tangent plane}} \underbrace{a_1(\gamma, \phi(\gamma))}_{a_1(\gamma, \phi(\gamma))} (s_0) \neq 0$$

Method of Characteristics

The following problems¹ are **equivalent**.

$$PDE: \begin{cases} \sum a_j(x, u) D_{x_j} u = b(x, u) \\ u = \phi \text{ on } \Gamma \end{cases}$$
 (1)

$$ODE: \begin{cases} D_{t} x = A(x, y)^{2} \\ D_{t} y = b(x, y) \\ x(0) = x_{0} \\ y(0) = \phi(x_{0}) \quad \forall x_{0} \in \Gamma \end{cases}$$
 (2)

Where y = u(x) and $A(x, y) = [a_1(x, y), \dots, a_n(x, y)].$

¹it can be generalized to the nonlinear case (1st order!)

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Нр	Problem (1) $a_j, b, \phi, \Gamma \in C^1$ Γ non-characteristic
Ts	$\exists !$ unique C^1 solution in a neighborhood of Γ
oof	using the local existence and uniqueness theorem for ODEs

Cauchy Problem

- Often used when the data surface is **not** a boundary.
- It also requires the **normal derivatives** $(D^j_{\nu}u)$ of the solution on the surface to uniquely determine it.
- It carries the risk of being **overdetermined** (good for uniqueness but less for the existence of the solution).



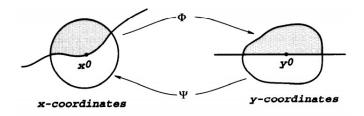
General Problem

$$\begin{cases} F^*(x, D^{\alpha}u^*) = 0 & |\alpha| \le k, F^* \text{ at least } C^1 \\ D^j_{\nu}u^* = \phi^*_j & \text{on } \Gamma^* \text{ for } j < k \end{cases}$$

Mapping at t = 0

Let γ^* be the local parametrization of Γ^* , we apply the map:

$$\Phi(x) = [x_1 \quad \cdots \quad x_{n-1} \mid x_n - \gamma^*(x_1, \dots, x_{n-1})]$$



L. C. Evans, Partial Differential Equations

Select a privileged variable and call it "time":

$$t \leftarrow x_n \\ x \leftarrow (x_1, \dots, x_{n-1})$$

- 2 Call $\Gamma_0 = \{t = 0\}.$
- Indicate the derivatives as follows: $D_r^{\alpha} D_t^j u$.
- 4 Obtain the problem $(u^* = u(\Phi))$:

$$\begin{cases} F(x, t, D_x^{\alpha} D_t^j u) = 0 & |\alpha| + j \le k \\ D_t^j u(x, 0) = \phi_j(x) & \text{for } j < k \end{cases}$$



Non-characteristic Surfaces in General

Definizione 2.5

 Γ^* (or Γ_0) is non-characteristic \iff the equation on Γ_0 can be rewritten in **normal form** with respect to t.

Osservazione

It is shown to be consistent with previous definitions.

Osservazione

- Linear case \rightarrow condition on the coefficients.
- Non-linear case \rightarrow validity of implicit function theorem hypotheses on F.



Remarkable Power Series

Definizione 2.6

Majorizing function:

$$\mathcal{M}_{Cr}(x) = \frac{Cr}{r - (x_1 + \dots + x_n)}$$

Osservazione

By the multinomial theorem, if |x| < r/n we have that

$$\frac{Cr}{r - (x_1 + \ldots + x_n)} = C \sum_{\alpha} \frac{|\alpha|!}{\alpha! \, r^{|\alpha|}} x^{\alpha}.$$



Teorema 2.2 (utility of the majorant)

$$\begin{cases} g_{\alpha} \ge |f_{\alpha}| \\ \sum g_{\alpha} x^{\alpha} \text{ has a radius of conv. } R \end{cases} \implies \sum_{\text{has a radius at least } R} f_{\alpha} x^{\alpha}$$

In this case, we write: $\sum g_{\alpha}x^{\alpha} \gg \sum f_{\alpha}x^{\alpha}$.



 $\sum f_{\alpha}x^{\alpha}$ has radius $R \implies \exists r < R, C > 0$ such that

$$|f_{\alpha}| \le C \frac{1}{r^{|\alpha|}} \le C \frac{|\alpha|!}{\alpha! \, r^{|\alpha|}}$$

Outline of the Approach

Following the chronological order of discovery, we proceed by **progressive generalizations**:

- 1 ODEs
- 2 Quasi-linear PDEs
- 3 PDEs in normal form



$$A \subseteq \mathbb{C}, B \subseteq \mathbb{C}^n \text{ open}$$

$$\Omega \subseteq A \text{ open, connected}$$

$$f: A \times B \to \mathbb{C}^n \text{ holomorphic}$$

$$Pb: \begin{cases} y' = f(x, y) & \forall x \in \Omega \\ y(x_0) = y_0 \end{cases}$$

Ts

locally there exists a unique holomorphic solution

Radius Estimate

Teorema 3.2

Hp Assumptions of the previous theorem
$$\exists \overline{B_a(x_0)} \subseteq A, \overline{B_b(y_0)} \subseteq B$$

Ts The solution converges with at least radius³
$$\widetilde{r} = a \left[1 - \exp\left(-\frac{b}{aM(n+1)}\right) \right]$$



 $^{^{3}}M = \max_{B_{a}(x_{0}), B_{b}(y_{0})} |f|$

Quasi-linear PDEs

Teorema 3.3

Hp
$$\begin{cases} A_j, \ B \text{ analytic} \\ \text{Pb: } \begin{cases} D_t \ y = \sum\limits_{j=1}^{n-1} A_j(x,y) D_{x_j} y + B(x,y) \\ y = 0 \quad \text{on } \Gamma_0 \end{cases}$$
Ts
$$\begin{cases} \exists! \ y(x,t) : \mathbb{R}^n \to \mathbb{R}^m \text{ analytic solution} \\ \text{in a neighborhood of the origin} \end{cases}$$

Invariant Version 0000000000000

- 1 Assume $y_h = \sum c_h^{\alpha j} x^{\alpha} t^j$
- 2 Inserting the series of y, A_j , B we get:

$$c_h^{\alpha j} = Q_h^{\alpha j}$$
 (coeff. of series of A_j , B)

Q polynomial with non-negative coefficients

- $\widetilde{A}_i \gg A_i, \widetilde{B} \gg B \implies \widetilde{y} \gg y$ thanks to Q
- 4 Choose \widetilde{A}_i , \widetilde{B} so that \widetilde{y} can be explicitly calculated as analytic with the method of characteristics



Majorizing System

As we already know, we majorize the series with

$$\mathcal{M}_{Cr}(x,y) \gg A_j, B$$

and solve the problem⁴:

$$\begin{cases} D_t \, \widetilde{y}_h = \mathcal{M}_{Cr} \left[\sum_{i,j} D_{x_j} \widetilde{y}_i + 1 \right] \\ \widetilde{y}_h = 0 \quad \text{on } \Gamma_0 \end{cases}$$



 $^{^{4}}$ with h = 1, ..., m

Majorant Solution

The previous system has the solution:

$$\widetilde{y}_h(x,t) = u(x_1 + \dots + x_n, t) \quad \forall h$$

with

$$u(s,t) = \frac{r - s - \sqrt{(r-s)^2 - 2tCrmn}}{mn},$$

whose radius of convergence we can study.



Radius of Convergence Estimate

Teorema 3.4

The solution of theorem 3.3 converges with radius at least

$$\widetilde{r} = \frac{1}{n-1} \frac{r}{8Cmn}$$
 with $C \ge \frac{1}{2}$

Let's observe its behavior⁵ with respect to r, knowing that:

 $r < \min\{radii \ of \ conv. \ of \ the \ coefficients \ a_{ml}^j, \ b_m\}$

$$C \ge \max \left\{ \frac{\max\limits_{j,m,l,\alpha} \left| a_{ml}^{j} \, r^{|\alpha|} \right|}{\max\limits_{m,\alpha} \left| b_{m} \, r^{|\alpha|} \right|} \right\}$$



⁵ trade-off Cr

PDE in Normal Form

Teorema 3.5

The following two problems are equivalent

$$\begin{aligned} & \text{nonlinear}: & \begin{cases} D_t^k u = G(x, D_x^\alpha D_t^j u) & |\alpha| + j \leq k, \ j < k \\ D_t^j u = \phi_j & \text{on } \Gamma_0, \ j < k \end{cases} \\ & \text{quasi-linear}: & \begin{cases} D_t \, y = \sum\limits_{j=1}^{n-1} A_j(x,y) D_{x_j} y + B(x,y) \\ y = 0 & \text{on } \Gamma_0 \end{cases} \end{aligned}$$

The system is constructed so that $y_{\alpha j} = D_x^{\alpha} D_t^j u$

The matrices A_i and B will then be derived from the expressions⁶:

$$\begin{split} D_{t}y_{\alpha j} &= y_{\alpha(j+1)} & |\alpha| + j < k \\ D_{t}y_{\alpha j} &= D_{x_{i}}y_{(\alpha-1_{i})(j+1)} & |\alpha| + j = k, \ j < k \\ D_{t}y_{0k} &= D_{t}G + \sum_{|\alpha|+j < k} D_{y_{\alpha j}}Gy_{\alpha(j+1)} & \\ &+ \sum_{|\alpha|+j = k, \ j < k} D_{y_{\alpha j}}GD_{x_{i}}y_{(\alpha-1_{i})(j+1)} & \end{split}$$

The Cauchy data will be:

$$y_{\alpha j}(x,0) = D_x^{\alpha} \phi_j(x)$$
 $j < k$
$$y_{0k}(x,0) = G(x,0, D_x^{\alpha} \phi_j(x))$$
 $|\alpha| + j \le k, j < k$



 $^{^{6}}i(\alpha) = \min\{i : \alpha \neq 0\}$

- 2 removing $\phi: y(x,t) \leftarrow y(x,t) \phi(x)$
- removing t: the variable $y^0 = t$ is added (with its corresponding equation)

Holomorphic Version

As in the case of ODEs, everything extends in an **immediate** way to the complex case by assuming holomorphic data.



Examples

We now answer the questions with three examples:

- Lewy's example: importance of analyticity
- Kowalevski's example: importance of non-characteristicity
- Hadamard's example: the problem might not be well-posed



Lewy's Example

Definizione 4.1

$$\mathcal{L} = D_x + iD_y - 2i(x+iy)D_t$$

is called Lewy's operator.



Teorema 4.1

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f continuous real-valued function
  Нр
            depending only on t
            u \in C^1: \mathcal{L}u = f in a neighborhood of the origin
   T_{\rm S}
            f analytic in a neighborhood of t=0
Proof
            Schwarz reflection principle
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Teorema 4.2

$$\begin{array}{c|c} \operatorname{Hp} & A\subseteq\mathbb{R}^3 \text{ open} \\ & \exists F\in C^\infty(\mathbb{R}^3,\mathbb{R}) : \ \nexists u\in C^1(A,\mathbb{R}) \\ & \operatorname{such\ that} \begin{cases} \mathcal{L}u=F \text{ in } A \\ u_x,\ u_y,\ u_t \text{ satisfy} \\ \text{the\ H\"{o}lder\ condition} \end{cases} \end{array}$$

Proof

- Translate the problem of the previous theorem so as to reduce it to the case of a generic point (x_0, y_0, t_0) , using the function $g(x, y, t) = f(t - 2xy_0 + 2x_0y)$ as the forcing function.
- 2 Construct a function $S_a \in C^{\infty}$ for each $a \in l^{\infty}$ using a series.
- Construct closed sets $E_{i,n} \subseteq l^{\infty}$ with no interior using S_a and the Ascoli-Arzelà theorem.
- 4 Conclude the proof of the new theorem using the aforementioned lemmas to derive, by a contradiction argument, the equality $l^{\infty} = \bigcup E_{i,n}$, allowing the application of Baire's argument.



Kowalevski's Example

This problem admits no analytic solutions⁷ in a neighborhood of the origin:

$$\begin{cases} u_t - u_{xx} = 0 \\ u(x,0) = \frac{1}{1+x^2} \quad \forall x \in \mathbb{R} \end{cases}$$

Osservazione

The surface is characteristic!



⁷proof by contradiction

Hadamard's Example

$$\begin{cases} u_{xx} + u_{yy} = 0 \\ u(x,0) = 0 \\ u_y(x,0) = n\sin(nx)e^{-\sqrt{n}} \text{ with } n \in \mathbb{N} \end{cases}$$

The solution to this problem is:

$$u_n(x,y) = \sin(nx)\underbrace{\sinh(ny)e^{-\sqrt{n}}}_{\substack{n\to\infty\\ \longrightarrow \infty}}$$

Alternative Versions

Abstract Version (Ovsyannikov classes)

 $\downarrow \downarrow$

Classical Version (similar to local existence and uniqueness for ODEs)



Invariant Version (non-characteristic surfaces)



Teorema 5.1

$$\overline{\mathcal{O}}_0 \subseteq \mathcal{O}_1 \subseteq \mathbb{C}^n \text{ open connected bounded}$$

$$A_j, f, y_0 \text{ holomorphic wrt } z$$

$$A_j, f \text{ continuous wrt } t$$

$$\text{Pb: } \begin{cases} D_t y = \sum A_j(z,t) D_{z_j} y + A_0(z,t) y + f(z,t) \\ y(z,0) = y_0(z) \end{cases}$$

$$\exists \delta \in (0,T) : \exists ! y \text{ solution when } |t| < T$$

$$-\text{holomorphic wrt } z$$

$$-C^1 \text{ wrt } t \qquad \rightarrow (\neq \text{Holmgren})$$

Consequences

The consequences of this theorem can be observed in various fields, including the main ones:

- theory of differential equations
- mathematical physics: emergence of numerous questions (what happens in reality if a local analytic solution exists?)
- differential geometry
- economic theory



Impact on the theory of differential equations:

- refuting Weierstrass's conjecture
- Holmgren's theorem
- research on necessary and/or sufficient conditions for the existence of local solutions by Treves and Nirenberg
- Hörmander's theory of linear differential operators



Holmgren's Theorem

Result of uniqueness of solutions for linear PDEs.

Osservazione

Cauchy-Kowalevski theorem does not exclude the existence of other solutions that are not analytic!

Any linear equation can be reduced to a **first-order system**. We focus on this case.

Teorema 6.1

Hp
$$\begin{cases} y \text{ distribution on } (\mathcal{O}_0 \cap \mathbb{R}^n) \times (-T, T) : \\ -K \subseteq \mathcal{O}_0 \cap \mathbb{R}^n \text{ compact: } y = 0 \text{ in } \mathcal{O}_0 \cap \mathbb{R}^n \setminus K \\ -\begin{cases} D_t y = \sum A_j(z, t) D_{z_j} y + A_0(z, t) y \\ y = 0 \text{ for } t < 0 \end{cases}$$
Ts
$$\begin{cases} y = 0 \text{ in } (\mathcal{O}_0 \cap \mathbb{R}^n) \times (-T, T) \end{cases}$$

Classical Version

Teorema 6.2

$$\begin{array}{c|c} \Omega\subseteq\mathbb{R}^n \text{ open} \\ A_j \text{ analytic} \\ \text{Hp} & y\in C^1(\Omega\times(-T,T)): \\ \begin{cases} D_ty=\sum A_j(x,t)D_{x_j}y+A_0(x,t)y \\ y=0 \text{ for } t=0 \\ \end{cases} \\ \text{Ts} & y=0 \text{ in a neighborhood of } \Omega\times\{0\} \end{array}$$

Proof

It is an application of the abstract version to the function

$$\widetilde{y}(x,t) = H(t) \, y(x,t),$$

which always satisfies a system of the same type.

Cartan-Kähler Theorem

A very important theorem in differential geometry:

- on the integrability of exterior differential systems
- which is proved using the Cauchy-Kowalevski theorem
- which has an application in the economic field (I. Ekeland, P.A. Chiappori)



Quoting Ekeland regarding the paper written in 1999 with Chiappori:

This paper solves a basic problem in economic theory, which had remained open for thirty years, namely the characterization of market demand functions. The method of proof consists of reducing the problem to a system of nonlinear PDEs, for which convex solutions are sought. This is rewritten as an exterior differential system, and is solved by the Cartan-Kähler theorem, together with some algebraic manipulations to achieve convexity.

Despite the research conducted in those years

- lacktriangledown wasn't guided by immediate applications
- led to **disappointing** results compared to the expectations of Cauchy and Weierstrass

it has had a gigantic impact thanks to the understanding of solutions of PDE systems it allowed us to achieve.



In conclusion, a quote about the relationship between Weierstrass and Kowalevski:

All his life – he had difficulty saying this, as he admitted, being always wary of too much enthusiasm – all his life he had been waiting for such a student to come into this room. A student who would challenge him completely, who was not only capable of following the strivings of his own mind but perhaps of flying beyond them.

— Alice Munro, Too Much Happiness

