

# Linguaggi di programmazione: semantica

Scoping statico e dinamico

## 1

$d_1$      $\text{var } z : \text{int} = 2;$   
 $d_2$      $\text{procedure inc( var } x : \text{int)}$   
 $c_1$          $z := x + 1;$   
 $d_3$      $\text{var } z : \text{int} = 3;$   
 $c_2$      $\text{while } z=3 \text{ do}$   
 $c_3$          $\text{inc}(z);$

### 1.1 Semantica statica

$$\frac{\emptyset \vdash_{\emptyset} 2 : \text{int}}{\emptyset \vdash_{\emptyset} d_1 : [z = \text{intloc}]}$$

$$\Delta_1 = [z = \text{intloc}]$$

$$I_1 = \{z\}$$

$$\frac{\frac{\Delta_1[x = \text{intloc}] \vdash_{I_1 \cup \{x\}} x : \text{int} \quad \Delta_1[x = \text{intloc}] \vdash_{I_1 \cup \{x\}} 1 : \text{int}}{\Delta_1[x = \text{intloc}] \vdash_{I_1 \cup \{x\}} x + 1 : \tau_+(\text{int}, \text{int})}}{\frac{\text{var } x : \text{int} : [x = \text{intloc}] \quad \Delta_1[x = \text{intloc}] \vdash_{I_1 \cup \{x\}} c_1}{\Delta_1 \vdash_{I_1} d_2 : [\text{inc} = \text{intproc}]}}$$

$$\Delta_2 = \Delta_1[\text{inc} = \text{intproc}]$$

$$I_2 = I_1 \cup \{p\}$$

$$\frac{\Delta_2 \vdash_{I_2} 3 : \text{int}}{\Delta_2 \vdash_{I_2} d_3 : [z = \text{intloc}]}$$

$$\frac{\frac{\frac{\Delta_2 \vdash_{I_2} z : \text{int} \quad \Delta_2 \vdash_{I_2} 3 : \text{int}}{\Delta_2 \vdash_{I_2} z = 3 : \tau_=(\text{int}, \text{int}) = \text{bool}} \quad \frac{\Delta_2 \vdash_{I_2} x : \text{int}}{\Delta_2 \vdash_{I_2} c_3} \Delta_2(\text{inc}) = \text{intproc}}{\frac{\emptyset \vdash_{\emptyset} d_1; d_2; d_3 : \Delta_2 \quad \Delta_2 \vdash_{I_2} c_2}{\emptyset \vdash_{\emptyset} d_1; d_2; d_3; c_2}}$$

## 1.2 Semantica dinamica: scoping statico

$$\begin{array}{lcl}
& < d_1; d_2; d_3; c_2, \emptyset > \\
\frac{(1)}{\rightarrow} & < \rho_1 = [z = l_z]; d_2; d_3; c_2, [l_z = 2] > \\
\frac{(2)}{\rightarrow} & < \rho_1; \rho_2 = [inc = \lambda \text{var } x : \text{int}. [z = l_z]; c_1]; d_3; c_2, [l_z = 2] > \\
\frac{(3)}{\rightarrow} & < \rho_1; \rho_2; \rho_3 = [z = l'_z]; c_2, [l_z = 2, l'_z = 3] > \\
\frac{(4-5)}{\rightarrow} & < \rho = [inc = \lambda \text{var } x : \text{int}. [z = l_z]; c_1, z = l'_z]; c_2, [l_z = 2, l'_z = 3] > \\
\frac{(6)}{\rightarrow} & < \rho; c_3; c_2, [l_z = 2, l'_z = 3] > \\
\frac{(7)}{\rightarrow} & < \rho; (\text{var } x : \text{int} = z; [z = l_z]; c_1); c_2, [l_z = 2, l'_z = 3] > \\
\frac{(8)}{\rightarrow} & < \rho; (\text{var } x : \text{int} = 3; [z = l_z]; c_1); c_2, [l_z = 2, l'_z = 3] > \\
\frac{(9)}{\rightarrow} & < \rho; ([x = l_x]; [z = l_z]; c_1); c_2, [l_z = 2, l'_z = 3, l_x = 3] > \\
\frac{(10-11)}{\rightarrow} & < \rho; ([x = l_x, z = l_z]; c_1); c_2, [l_z = 2, l'_z = 3, l_x = 3] > \\
\frac{(12)}{\rightarrow} & < \rho; c_2, [l_z = 4, l'_z = 3, l_x = 3] >
\end{array}$$

... nell'ambiente attuale  $z$  fa riferimento ad  $l'_z$  che non viene mai modificato da  $c_2$  per via dello scoping statico e quindi il programma non termina.

$$\begin{array}{lcl}
\frac{(1)}{\rightarrow} & & \frac{\frac{\frac{\frac{\emptyset \vdash_{\Delta_2} < d_1, \emptyset > \rightarrow_d < [z = l_z], [l_z = 2] >}{\emptyset \vdash_{\Delta_2} < d_1; d_2, \emptyset > \rightarrow_d < [z = l_z]; d_2, [l_z = 2] >}}{\emptyset \vdash_{\Delta_2} < d_1; d_2; d_3, \emptyset > \rightarrow_d < [z = l_z]; d_2; d_3, [l_z = 2] >}}{\emptyset \vdash_{\Delta_2} < d_1; d_2; d_3; c_2, \emptyset > \rightarrow_c < [z = l_z]; d_2; d_3; c_2, [l_z = 2] >} \\
\frac{(2)}{\rightarrow} & & \frac{\frac{\frac{\rho_1 \vdash_{\Delta_2} < d_2, [l_z = 2] > \rightarrow_d < [inc = \lambda \text{var } x : \text{int}. [z = l_z]; c_1], [l_z = 2] >}{\rho_1 \vdash_{\Delta_2} < d_2; d_3, [l_z = 2] > \rightarrow_d < [inc = \lambda \text{var } x : \text{int}. [z = l_z]; c_1]; d_3, [l_z = 2] >}}{\rho_1 \vdash_{\Delta_2} < d_2; d_3; c_2, [l_z = 2] > \rightarrow_c < [inc = \lambda \text{var } x : \text{int}. [z = l_z]; c_1]; d_3; c_2, [l_z = 2] >}}{\emptyset \vdash_{\Delta_2} < \rho_1; d_2; d_3; c_2, [l_z = 2] > \rightarrow_c < \rho_1; [inc = \lambda \text{var } x : \text{int}. [z = l_z]; c_1]; d_3; c_2, [l_z = 2] >} \\
\frac{(3)}{\rightarrow} & & \frac{\frac{\frac{\rho_1 \rho_2 \vdash_{\Delta_2} < d_3, [l_z = 2] > \rightarrow_d < [z = l'_z], [l_z = 2, l'_z = 3] >}{\rho_1 \rho_2 \vdash_{\Delta_2} < d_3; c_2, [l_z = 2] > \rightarrow_c < [z = l'_z]; c_2, [l_z = 2, l'_z = 3] >}}{\rho_1 \vdash_{\Delta_2} < \rho_2; d_3; c_2, [l_z = 2] > \rightarrow_c < \rho_2; [z = l'_z]; c_2, [l_z = 2, l'_z = 3] >}}{\emptyset \vdash_{\Delta_2} < \rho_1; \rho_2; d_3; c_2, [l_z = 2] > \rightarrow_c < \rho_1; \rho_2; [z = l'_z]; c_2, [l_z = 2, l'_z = 3] >} \\
\frac{(6)}{\rightarrow} & & \frac{\frac{\frac{\rho \vdash_{\Delta_2} < z = 3, [l_z = 2, l'_z = 3] > \rightarrow_e^* < tt, [l_z = 2, l'_z = 3] >}{\rho \vdash_{\Delta_2} < c_2, [l_z = 2, l'_z = 3] > \rightarrow_c < c_3; c_2, [l_z = 2, l'_z = 3] >}}{\emptyset \vdash_{\Delta_2} < \rho; c_2, [l_z = 2, l'_z = 3] > \rightarrow_c < \rho; c_3; c_2, [l_z = 2, l'_z = 3] >} \\
\frac{(9)}{\rightarrow} & & \frac{\frac{\frac{\bullet, \{l_x\} \vdash \bullet : \emptyset, \emptyset}{(3, \bullet), \emptyset \vdash \text{var } x : \text{int} = 3, \bullet : [x = l_x], [l_x = 3]}}{\rho \vdash_{\Delta_2} < \text{var } x : \text{int} = 3, [l_z = 2, l'_z = 3] > \rightarrow_d < [x = l_x], [l_z = 2, l'_z = 3, l_x = 3] >}}{\emptyset \vdash_{\Delta_2} < \rho; \text{var } x : \text{int} = 3, [l_z = 2, l'_z = 3] > \rightarrow_d < \rho; [x = l_x], [l_z = 2, l'_z = 3, l_x = 3] >}}{\emptyset \vdash_{\Delta_2} < \rho; \text{var } x : \text{int} = 3; [z = l_z]; c_1; c_2, [l_z = 2, l'_z = 3] > \rightarrow_c < \rho; [x = l_x]; [z = l_z]; c_1; c_2, [l_z = 2, l'_z = 3, l_x = 3] >}
\end{array}$$

$\xrightarrow{(12)}$

$$\frac{\frac{\frac{\rho[x = l_x, z = l_z] \vdash_{\Delta_2} < x + 1, [l_z = 2, l'_z = 3, l_x = 3] > \rightarrow_e^* < 4, [l_z = 2, l'_z = 3, l_x = 3] >}{\rho[x = l_x, z = l_z] \vdash_{\Delta_2} < z := x + 1, [l_z = 2, l'_z = 3, l_x = 3] > \rightarrow_c [l_z = 4, l'_z = 3, l_x = 3]}}{\rho \vdash_{\Delta_2} < [x = l_x, z = l_z]; z := x + 1, [l_z = 2, l'_z = 3, l_x = 3] > \rightarrow_c [l_z = 4, l'_z = 3, l_x = 3]}}{\rho \vdash_{\Delta_2} < ([x = l_x, z = l_z]; z := x + 1); c_2, [l_z = 2, l'_z = 3, l_x = 3] > \rightarrow_c \vdash_{\Delta_2} < c_2, [l_z = 4, l'_z = 3, l_x = 3] >}$$

### 1.3 Semantica dinamica: scoping dinamico

$$\begin{array}{l} < d_1; d_2; d_3; c_2, \emptyset > \\ \xrightarrow{(1)} < \rho_1 = [z = l_z]; d_2; d_3; c_2, [l_z = 2] > \\ \xrightarrow{(2)} < \rho_1; \rho_2 = [inc = \lambda \text{var } x : \text{int}.c_1]; d_3; c_2, [l_z = 2] > \\ \xrightarrow{(3)} < \rho_1; \rho_2; \rho_3 = [z = l'_z]; c_2, [l_z = 2, l'_z = 3] > \\ \xrightarrow{(4-5)} < \rho = [inc = \lambda \text{var } x : \text{int}.c_1, z = l'_z]; c_2, [l_z = 2, l'_z = 3] > \\ \xrightarrow{(6)} < \rho; c_3; c_2, [l_z = 2, l'_z = 3] > \\ \xrightarrow{(7)} < \rho; (\text{var } x : \text{int} = z; c_1); c_2, [l_z = 2, l'_z = 3] > \\ \xrightarrow{(8)} < \rho; (\text{var } x : \text{int} = 3; c_1); c_2, [l_z = 2, l'_z = 3] > \\ \xrightarrow{(9)} < \rho; ([x = l_x]; c_1); c_2, [l_z = 2, l'_z = 3, l_x = 3] > \\ \xrightarrow{(10-11)} < \rho; ([x = l_x]; c_1); c_2, [l_z = 2, l'_z = 3, l_x = 3] > \\ \xrightarrow{(12)} < \rho; c_2, [l_z = 2, l'_z = 4, l_x = 3] > \\ \xrightarrow{(13)} [l_z = 2, l'_z = 4, l_x = 3] \end{array}$$