

# Formal Languages and Compilers - Exercises

## Lecture 7-8

### Scoping and Subprograms

17/04/2012

# Outline

1 Environment

2 GE and LE

3 SLE and DLE

4 Static scoping

5 Semantics

6 Implementation

7 SCP

8 Call

# Data control

How to provide data to operations and subprograms?

Or, similarly, what is the “environment” of the reference by name?

Two major problems

- 1 one name can denote different objects (e.g. local variables)
- 2 one object can be denoted by several names (e.g. passing parameters)

To solve these problems the environments were proposed.

Environment

Binding between the names (Ide) and values:

$$\text{Env} : \text{Ide} \longrightarrow \text{Loc} \cup \text{Val}$$

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Operations in programming language that affect the environment:

**1 Creation of binding** `<name, object>`

Example: declarations, parameters... in the beginning of execution and when entering the subprograms

**2 Use of the environment**

Example: reference to the identifier (variables, names of subprograms)

**3 Deactivation the binding**

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# Blocks and local variables

## Blocks

A block consists of local declarations and commands:

```
begin
    D    -> local declarations
    C    -> commands
end
```

## Example

A block is like a procedure without parameters

```
x := 5;
{
    int x;
    x := 7;
    printf("%d", x);    -> 7
}
printf("%d", x);        -> 5
```

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# Scoping

“Scoping” solves the problem of determining

- when a particular binding  $\langle \text{name}, \text{object} \rangle$  is active
- which bindings are valid in a particular moment of execution
- which is the environment?

## Different environments

*LE*: local environment. All bindings created/activated in a block/subprogram

*NLE*: non-local environment. All bindings used (active) but not local

*GE*: global environment. All bindings shared by all blocks/subprograms. *GE* can be considered:

- as a subset of *NLE*
- separately from *NLE*

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# Global Environment (*GE*)

## Example (C)

```
int a[20];  
float b[5];  
struct { int i; char n[10]; } c, d;  
...  
int main() {...}
```

- Contains also all the identifiers (constants, functions, etc.) predefined in the language
- Common table for all the subprograms (including main)
- Concrete implementation:
  - treat *GE* as a record
  - names are compiled as fields of the record
  - in the code, it's sufficient to know the base address of *GE*

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# Local Environment ( $LE$ ) - 1

## Notation

- $P \Downarrow Q$ : procedure  $P$  calls  $Q$
- $P \Uparrow Q$ : procedure  $P$  terminates and returns the control to the caller  $Q$

Let's consider the computation

$$P \Downarrow Q \Downarrow R \Uparrow Q \Uparrow P$$

what happens to the local environment of  $Q$ ?

## The simple way

$Q \Downarrow R$  when control is passed to  $R$ ,  $LE$  becomes deactivated

$R \Uparrow Q$  when control is passed back to  $Q$ , its  $LE$  become reactivated

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# Local Environment ( $LE$ ) - 2

The management of environment in Q

$$P \Downarrow Q \text{ and } Q \Uparrow P$$

is more delicate.

*DLE*: Dynamic Local Environment

$P \Downarrow Q$  *LE* of  $Q$  is created

$Q \Uparrow P$  *LE* of  $Q$  is destroyed

*SLE*: Static Local Environment

$P \Downarrow Q$  *LE* of  $Q$  is reactivated

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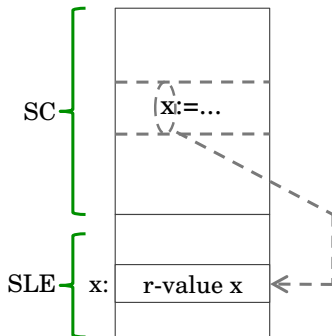
# Static Local Environment

Example: static option in C creates static local environment

```
void f()  
{  
    static int x = 0;  
    x++;  
    printf("%d", x);  
    f();  
}  
...  
while (1) { f(); } → 1,2,3,4,5,
```

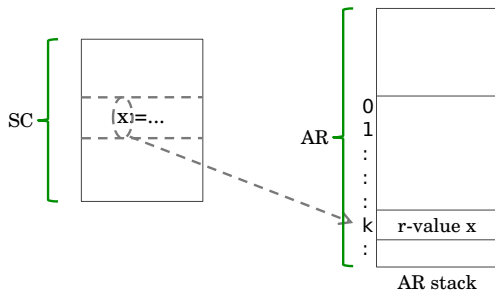
What happens without static?

# Static Local environment - Implementation



- The table of static local environment: it's memorized only once and divided by all the calls of subprogram
- SLE is simply a sequence of r-value
- The names are offset inside the SLE

# Dynamic Local environment - Implementation



- The local environment is a part of the activation record (AR): different calls of subprogram correspond to different instances of the local environment
- Again, the local names in the subprogram are compiled as offset, but this time inside the AR

# Non local references

## Example

```
procedure Q()  
  begin  
    ...  
    x  
    ...  
  end
```

If  $x$  is not local, which binding is used for  $x$ ?

**Answer:** rules of scoping

**Dynamic scoping:** rules of visibility are related to the execution  
(e.g., Lisp)

**Static scoping:** rules of visibility are related to the syntax of the  
program (e.g., C, Java, Pascal, ML...)

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# Static scoping - 1

## Definition

Every identifier has a declaration that statically binds it. This binding is *constant at runtime*.

- The type of the identifier is known at compile time
- The location for the value of identifier can change at runtime (dynamic local environment) or not (static local environment)

# Static scoping - 2

## Scoping tree

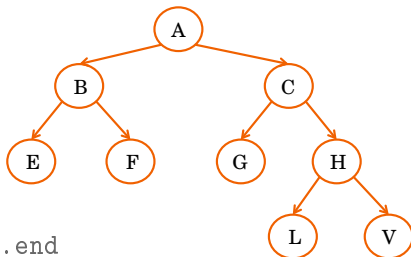
For more rigorous analysis, for every program let's associate a tree called **scoping tree**:

- we give different names to blocks (the subprograms already have different names)
- nodes of the tree → names of the blocks and subprograms
- Q is a child of P if
  - Q is a direct block of P
  - Q is a subprogram declared in P



# Scoping tree example

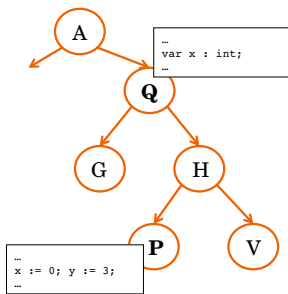
```
A: begin
  proc B;
    begin
      E: begin...end
      F: begin...end
    end {B}
  C: begin
    G: begin...end
    proc H;
      begin
        L: begin...end
        V: begin...end
      end {H}
    end {C}
  end {A}
```



# Rule of static scoping - 1

If  $x$  occurs in non local reference in the subprogram/block  $P$

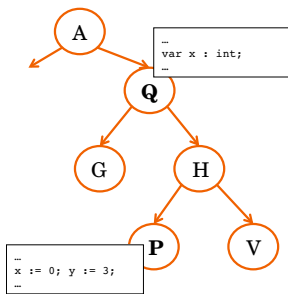
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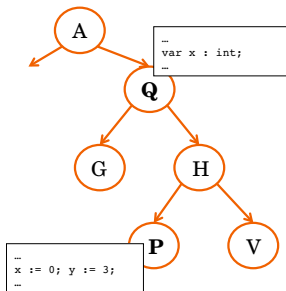
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## Rule of static scoping - 2

If the language defines a global environment outside of subprograms/blocks

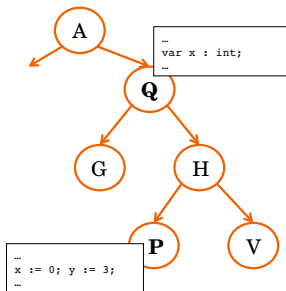
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## Rule of static scoping - 2

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# Static scoping: semantics - 1

## Environment 2.0

An environment a *sequence* of local environments:

$$\text{Env} = \text{List}(\text{Ide} \rightarrow \text{DVal})$$

$$r = [r_0, r_1, \dots, r_k]$$

$$\text{DVal} = (\text{Val} \cup \text{Loc} \cup \text{Com})$$

## Rule of scoping

$r(x)$  is defined as follows:

- if  $r_k(x)$  is defined, then  $r_k(x)$ , otherwise:
- if  $r_{k-1}(x)$  is defined, then  $r_{k-1}(x)$ , otherwise:
- ...
- if  $r_0(x)$  is defined, then  $r_0(x)$ , otherwise:
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# Static scoping: semantics - 2

$$D \parallel \text{const } v = n \parallel [r_0, \dots, r_k]s = [r_0, \dots, r_{k+1}]s \quad \text{where}$$

$$r_{k+1}(y) = \begin{cases} r_k(y) & \text{if } y \neq v \\ n, & \text{if } y = v \end{cases}$$

$$D \parallel \text{var } v := n \parallel [r_0, \dots, r_k]s = [r_0, \dots, r_{k+1}]s' \quad \text{where}$$

$$r_{k+1}(y) = \begin{cases} r_k(y) & \text{if } y \neq v \\ l = \text{newmem } s, & \text{if } y = v \end{cases} \quad s'(x) = \begin{cases} s(x) & \text{if } x \neq l \\ n, & \text{if } x = l \end{cases}$$

$$D \parallel \text{proc } P = C \parallel [r_0, \dots, r_k]s = [r_0, \dots, r_{k+1}]s \quad \text{where}$$

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## Problem

The Activation Record stack provides a temporal order between local environments (useless for static scoping), but gives no indication on the structure of the program.

## Solution

- To each AR the *static chain pointer* (SCP) is added. The “static” information on the syntactic structure (scoping tree) is implemented through the SCP.
- A subprogram/block Q is parent of subprogram/block P in the scoping tree. Then, the SCP of an AR of P points to AR of Q according to the rule of static scoping.

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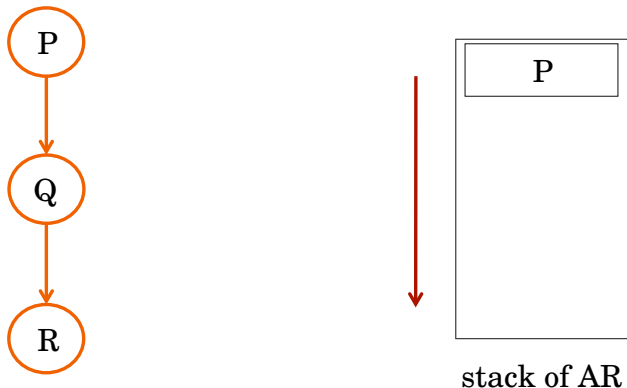
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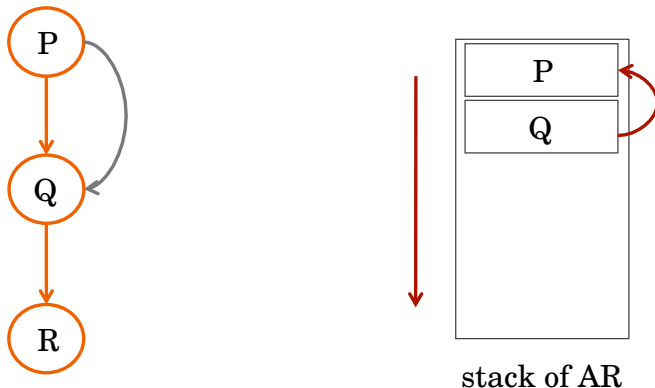
Suppose that  $Q \Downarrow R$ ; then, the AR of P is pushed in the stack of AR



R is a child of Q but in the stack there are several occurrences of Q.

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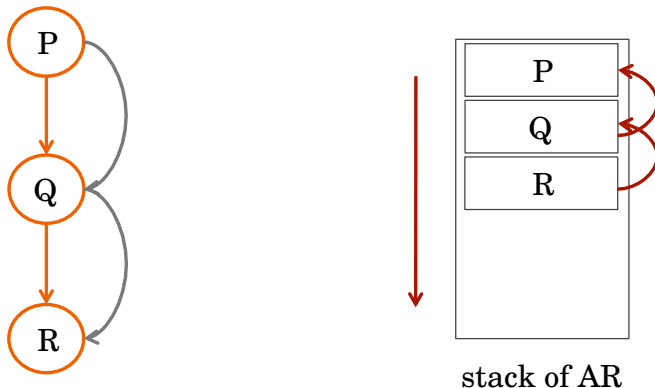
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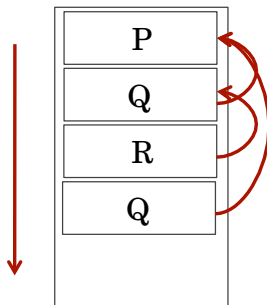
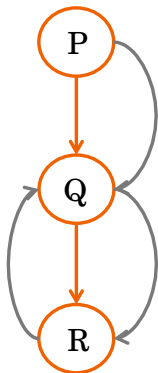
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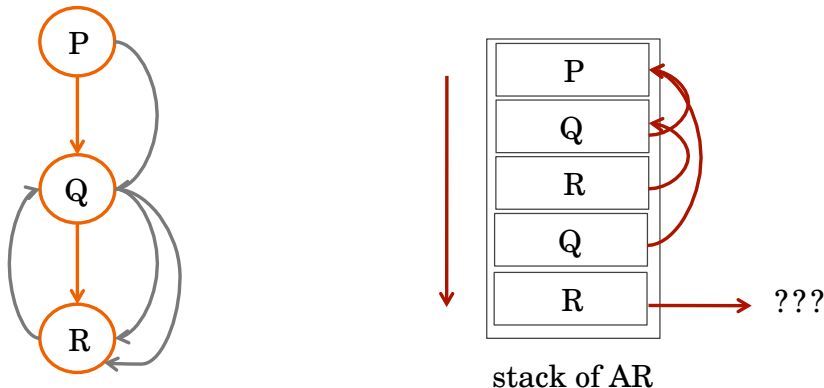
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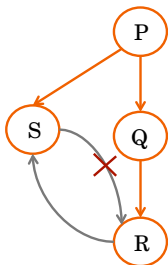
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# Algorithm to determine SCP

- Suppose  $\alpha$  and  $\beta$  are nodes of the scoping tree, and suppose that  $\alpha \Downarrow \beta$
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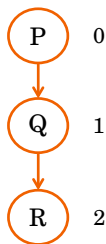


```

P: begin
  proc S; begin...end {S}
  proc Q;
    begin
      proc R; begin...end {R}
    end {Q}
  end {P}
  
```

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- Then, the parent of  $\beta$  should be an ancestor of  $\alpha$  (otherwise  $\beta$  would not be visible from  $\alpha$ )
- Let's define  $(\alpha, \beta) = \text{depth}(\alpha) - \text{depth}(\text{parent}(\beta))$



$$Q \Downarrow R \text{ then } (Q, R) = 1 - 1 = 0$$

$$R \Downarrow Q \text{ then } (R, Q) = 2 - 0 = 2$$

# Algorithm to determine SCP

If  $P \Downarrow Q$  then

- 1 The AR of  $Q$  ( $AR_Q$ ) is put in the stack
- 2 The distance  $(P, Q)$  is calculated
- 3 The address  $a$  is reached by making  $(P, Q)$  steps starting from SCP of AR of the caller  $P$ ; this is the address of an AR corresponding to a subprogram/block  $T$  that declares  $Q$ .
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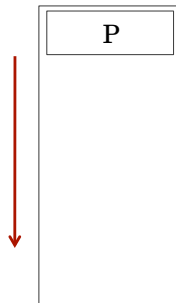
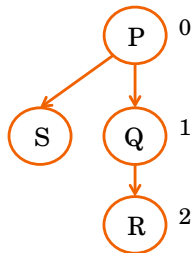
If  $P \Downarrow Q$  then

- 1 The AR of  $Q$  ( $AR_Q$ ) is put in the stack
- 2 The distance  $(P, Q)$  is calculated
- 3 The address  $a$  is reached by making  $(P, Q)$  steps starting from SCP of AR of the caller  $P$ ; this is the address of an AR corresponding to a subprogram/block  $T$  that declares  $Q$ .
- 4 SCP of  $AR_Q$  has value  $a$



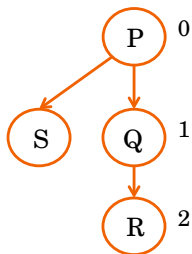
# Determining SCP: Example

$P$

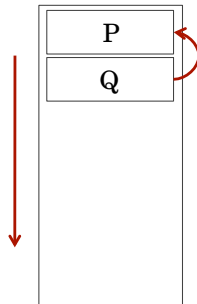


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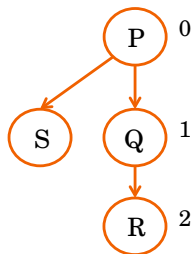
$$P \Downarrow Q$$



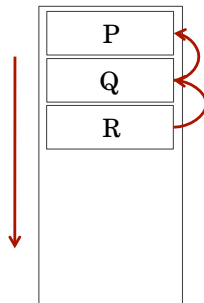
$$(P, Q) = 0$$



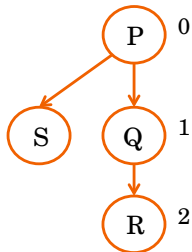
# Determining SCP: Example

$$P \Downarrow Q \Downarrow R$$


$$(P, Q) = 0$$

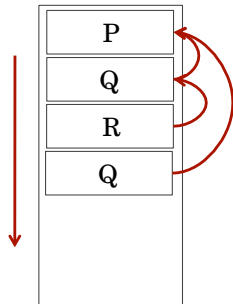
$$(Q, R) = 0$$


# Determining SCP: Example

$$P \Downarrow Q \Downarrow R \Downarrow Q$$


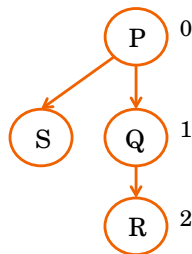
$$(P, Q) = 0$$

$$(Q, R) = 0$$

$$(R, Q) = 2$$


# Determining SCP: Example

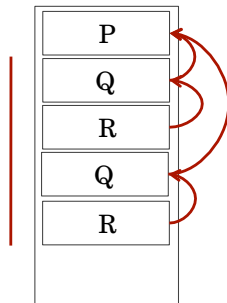
$P \Downarrow Q \Downarrow R \Downarrow Q \Downarrow R$



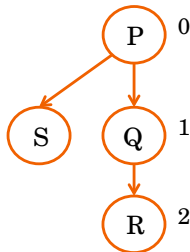
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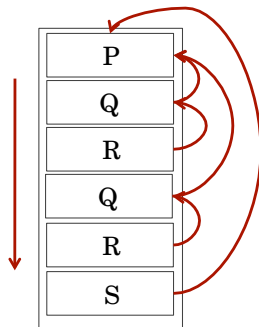
$$P \Downarrow Q \Downarrow R \Downarrow Q \Downarrow R \Downarrow S$$


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# Outline

1 Environment

2 GE and LE

3 SLE and DLE

4 Static scoping

5 Semantics

6 Implementation

7 SCP

8 Call

# Calling a subprogram: semantics

Given  $r = [r_0, r_1, \dots, r_k]$ ,

$$C \parallel \text{call } P \parallel_{r_s} = C \parallel \text{Cmd} \parallel_{r'_s}$$

where

- program  $P$  is declared as  $\text{proc } P = \text{Cmd}$
- $\text{Cmd} = r(P) \in \text{Com}$
- $r' = [r_0, r_1, \dots, r_h, r_\epsilon]$  where:
  - $h = \text{depth}(r, P)$ , or  $r_h$  is the “deepest” environment where  $P$  is defined,
  - $P$  is defined in  $r_h$ ,
  - $P$  is not defined in  $r_{h+1}, r_{h+2}, \dots, r_k$
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# Non local references

- Suppose that a subprogram/block  $P$  is using a name  $n$
- Define  $(P, n) = \text{depth}(P) - \text{depth}(\text{subprg./blk that declares } n)$

## Non local references

Every non local reference  $n$  in the subprogram/block  $P$  is represented as

$$\langle x, y \rangle$$

where  $x = (P, n)$  and  $y = \text{position (offset) of } n \text{ in the template of AR of the subprogram/block that declares } n$ .

If  $x = 0$ , then  $n$  is local and is compiled simply as  $y$ .

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# Non local references: implementation

## Observation

Given a subprogram P,

- the length of the static chain when P is executing is statically fixed
- the non-local reference to a variable  $n$  is resolved always at the same point in the chain

For the reason of efficiency, the static chain is often implemented as a vector (we call it **display**)

The access to the identifier with the “coordinates”  $\langle x, y \rangle$  is calculated as:

$$\text{display}[x] + y$$



# Passing the parameters - 1

Let's assume:

- dynamic local environment
- static scoping

## Notation

`proc P(x)`:  $x$  is a formal parameter

`call P(e)`:  $e$  is an actual parameter or an argument

Formal parameters are treated as local variables (they are allocated in the activation record).

# Passing the parameters - 1

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## Example

```
proc P(x)
  begin
    int y;
    ...
  end
```

The local variables are x and y.

# Passing the parameters - 2

- Notation `call P(x  $\leftarrow_{\alpha}$  e)` means that `P` is declared as `proc P(x)` and `P` is invoked as `call P(e)`

- $\alpha$  is type of passing the parameters

Value: `call P(x  $\leftarrow_{\text{Val}}$  e)`

Value-result: `call P(x  $\leftarrow_{\text{Val-res}}$  e)`

Result: `call P(x  $\leftarrow_{\text{Res}}$  e)`

Reference: `call P(x  $\leftarrow_{\text{Ref}}$  e)`

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# Passing by value

`call P( $x \leftarrow_{\text{val}} e$ )`

- The expression  $e$  is evaluated in the environment of the caller
- In the AR of  $P$  the value  $e$  is assigned to the variable  $x$

$$C \parallel \text{call } P(x \leftarrow_{\text{val}} e) \parallel_{rs} = C \parallel \text{Cmd} \parallel_{r's'}$$

- $l = \text{newmem } s$
- $v = E \parallel e \parallel_{rs}$
- $r' = [r_0, \dots, r_{\text{depth}(r, P)}, r_P]$  with  $r_P(x) = l$
- $s' = \text{updatemem}(s, l, v)$
- $\text{Cmd} = r(P)$

Note:  $x$  is local in  $P$ !

It is already implemented in crème CAraMeL.

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Note:  $x$  is local in  $P$ !

It is already implemented in crème CAraMeL.

# Passing by value-result

call  $P(x \leftarrow_{\text{val-res}} y)$

- The value of  $y$  is evaluated in the environment of the caller
- This value is assigned to the local variable  $x$  in  $P$
- When  $P$  terminates, the value of  $x$  is copied to the variable  $y$  of the caller

$$C \parallel \text{call } P(x \leftarrow_{\text{val-res}} y) \parallel_{rs} = s'''$$

- $v = E \parallel y \parallel_{rs}$
- $l = \text{newmem } s$
- $r' = [r_0, \dots, r_{\text{depth}(r, P)}, r_P]$  with  $r_P(x) = l$
- $s' = \text{updatemem}(s, l, v)$
- $\text{Cmd} = r(P)$
- $C \parallel \text{Cmd} \parallel_{r's'} = s''$
- $s''' = \text{update}(s'', \Lambda \parallel y \parallel_{rs}, s''(l))$

# Passing by value-result

call  $P(x \leftarrow_{\text{val-res}} y)$

- The value of  $y$  is evaluated in the environment of the caller
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# Passing by value-result

call  $P(x \leftarrow_{\text{val-res}} y)$

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- This value is assigned to the local variable  $x$  in  $P$
- When  $P$  terminates, the value of  $x$  is copied to the variable  $y$  of the caller

$$C \parallel \text{call } P(x \leftarrow_{\text{val-res}} y) \parallel_{rs} = s'''$$

- $v = E \parallel y \parallel_{rs}$
- $l = \text{newmem } s$
- $r' = [r_0, \dots, r_{\text{depth}(r, P)}, r_P]$  with  $r_P(x) = l$
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- $C \parallel \text{Cmd} \parallel_{r' s'} = s''$
- $s''' = \text{update}(s'', \Lambda \parallel y \parallel_{rs}, s''(l))$

# Passing by value-result

call  $P(x \leftarrow_{\text{val-res}} y)$

- The value of  $y$  is evaluated in the environment of the caller
- This value is assigned to the local variable  $x$  in  $P$
- When  $P$  terminates, the value of  $x$  is copied to the variable  $y$  of the caller

$$C \parallel \text{call } P(x \leftarrow_{\text{val-res}} y) \parallel_{rs} = s'''$$

- $v = E \parallel y \parallel_{rs}$
- $l = \text{newmem } s$
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# Passing by value-result

call  $P(x \leftarrow_{\text{val-res}} y)$

- The value of  $y$  is evaluated in the environment of the caller
- This value is assigned to the local variable  $x$  in  $P$
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# Passing by result

call  $P(x \leftarrow_{\text{Res}} y)$

- When  $P$  terminates,  $x$  is copied to the variable  $y$
- Initial value of  $x$  is not specified
- The semantics is like in passing by value-result without the evaluation of  $y$

# Passing by result

```
call P( $x \leftarrow_{\text{Res}} y$ )
```

- When P terminates, x is copied to the variable y
- Initial value of x is not specified
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`call P(x  $\leftarrow_{\text{Ref}}$  y)`

- The location  $l$  of  $y$  is evaluated in the environment of the caller
- The location of  $x$  in  $P$  is set to  $l$

$$C \parallel \text{call } P(x \leftarrow_{\text{Ref}} y) \parallel_{rs} = C \parallel \text{Cmd} \parallel_{r's}$$

- $l = \Lambda \parallel y \parallel_{rs}$
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# Passing by constant

`call P( $x \leftarrow_{\text{Const}}$  e)`

- The value of  $e$  is evaluated in the environment of the caller
- This value is assigned to the local variable  $x$  in  $P$
- Inside  $P$ , values cannot be assigned to  $x$
- It can be implemented in a similar way to the passing by reference

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# Passing by name

`call P( $x \leftarrow_{\text{Name}} y$ )`

- Create a new couple  $\langle e, r \rangle$ , where  $r$  is an environment of the caller
- Every time  $x$  should be evaluated,  $e$  is getting evaluated instead, in the environment  $r$ , and put instead of  $x$
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# Passing by name

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