

Preliminary Definitions

Definition. A matrix, $A \in \mathbb{R}^{m \times n}$ is positive semidefinite if:

$$\forall x \in \mathbb{R}^n, x^T A x \geq 0$$

Definition. A function f is affine if

$$f(v) = Av + b$$

for some matrix A and some vector b .

Definition. For some minimisation problem with objective function $f : \mathbb{R}^n \rightarrow \mathbb{R}$ and inequality constraints $g_i : \mathbb{R}^n \rightarrow \mathbb{R}$ and equality constraints $h_j : \mathbb{R}^n \rightarrow \mathbb{R}$ that are continuously differentiable at the optimal solution x^* the KKT conditions are (providing some constraints hold): $\exists \mu_i$ and λ_i such that

$$\begin{aligned} \nabla f(x^*) + \sum_{i=1}^m \mu_i \nabla g_i(x^*) + \sum_{j=1}^l \lambda_j \nabla h_j(x^*) &= 0 \quad (\text{stationarity}) \\ g_i(x^*) &\leq 0 \quad (\text{Primal Feasibility}) \\ h_j(x^*) &= 0 \quad (\text{Primal Feasibility}) \\ \mu_i &\geq 0 \quad (\text{Dual Feasibility}) \\ \mu_i g_i(x^*) &= 0 \quad (\text{Complementary Slackness}) \end{aligned}$$

Definition. A point $x \in \mathbb{R}^n$ is a critical point of some $f : \mathbb{R}^{n \times m} \rightarrow \mathbb{R}$ if:

$$\nabla f(x) = \mathbf{0}$$

Theorem. Fermat's Theorem (critical points): If $x \in \mathbb{R}^n$ is a local minima of some function $f : \mathbb{R}^n \rightarrow \mathbb{R}$ then:

$$\nabla f(x) = \mathbf{0}$$

Definition. The ball of size $R > 0$ around a point $x \in \mathbb{R}^n$, written $B(x, R)$, is the set of all points $y \in \mathbb{R}^n$ such that:

$$\|y - x\| < R$$

Definition. An point, $x \in \mathbb{R}^n$ of some set $C \subseteq \mathbb{R}^n$ is an interior point if there exists an $R > 0$ such that:

$$B(x, R) \subseteq C$$

Theorem. 2nd Order Taylor's Approximation: If $f : U \rightarrow \mathbb{R}$ is a twice differentiable function over an open set $U \subseteq \mathbb{R}^n$ and $x \in U$ select some $r > 0$ such that $B(x, r) \subseteq U$. Then for any $y \in B(x, r)$

$$f(y) = f(x) + \nabla f(x)^T (y - x) + \frac{1}{2} (y - x)^T \nabla^2 f(x) (y - x) + o(\|y - x\|^2)$$

Definition. A linear program is an optimisation of the form:

$$\begin{aligned} &\underset{x}{\text{maximise}} \quad \mathbf{c}^T \mathbf{x} \\ &\text{such that} \quad \mathbf{A} \mathbf{x} \leq \mathbf{b} \\ &\text{and} \quad \mathbf{x} \geq \mathbf{0} \end{aligned}$$

$A \in \mathbb{R}^{m \times n}$, $c \in \mathbb{R}^n$, $b \in \mathbb{R}^m$ and $x \in \mathbb{R}^n$