

Terminal window showing ROS2 interface commands and output:

```
yahboom@VM: ~/roscourse_ws

yahboom@VM:~/roscourse_ws$ ros2 interface show turtle_interfaces/srv/SetColor
string color
---
int8 ret
yahboom@VM:~/roscourse_ws$ ros2 interface show turtle_interfaces/srv/SetPose
geometry_msgs/PoseStamped turtle_pose
---
int8 ret
yahboom@VM:~/roscourse_ws$
```

Terminal window showing ROS2 run commands and output:

```
yahboom@VM: ~/roscourse_ws

[INFO] [1708114484.652970642] [turtleClient]: Turtlebot Client Started!
^Z
[3]+  Stopped                  ros2 run python_turtle turtlebot_client
yahboom@VM:~/roscourse_ws$ ros2 run python_turtle turtlebot_client
[INFO] [1708114980.175234456] [turtleClient]: Turtlebot Client Started!
^Z
[4]+  Stopped                  ros2 run python_turtle turtlebot_client
yahboom@VM:~/roscourse_ws$ ros2 interface show turtle_interfaces/srv/SetColor
string color
---
int8 ret
yahboom@VM:~/roscourse_ws$
```

Terminal window showing ROS2 run commands and output:

```
yahboom@VM: ~/roscourse_ws

[INFO] [1708114487.752838980] [turtleServer]: Turtle color set: red
^Z
[1]+  Stopped                  ros2 run python_turtle turtlebot_server = python_t
urtle.turtlebot_server:mainturtlebot_client
yahboom@VM:~/roscourse_ws$ ros2 run python_turtle service_client
[INFO] [1708114983.001226011] [service_client]: Turtlebot Client Started!
[INFO] [1708114983.005057944] [service_client]: Server call success: 1
yahboom@VM:~/roscourse_ws$ ros2 interface show turtle_interfaces/msg/TurtleMsg
string name
geometry_msgs/Pose turtle_pose
string color
yahboom@VM:~/roscourse_ws$
```

System tray at the bottom shows the time 3:32 PM on 2/16/2024, along with various icons for applications and system status.