### Hierarchical Topic Models

#### Andrew Leverentz

Research Examination, Fall Quarter 2017 UC San Diego, Dept. of Computer Science and Engineering

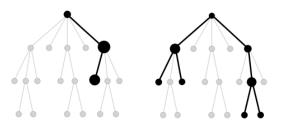


Image Source: Paisley et al [16]

lacktriangle Internet and digital archives ightarrow large collections of text data

- lacktriangle Internet and digital archives ightarrow large collections of text data
- ▶ How can we navigate these collections efficiently?

- lacktriangle Internet and digital archives ightarrow large collections of text data
- ▶ How can we navigate these collections efficiently?
- Typical task: find sets of documents that share the same topic or subject matter

- ▶ Internet and digital archives → large collections of text data
- ▶ How can we navigate these collections efficiently?
- ► Typical task: find sets of documents that share the same topic or subject matter
- ▶ Natural language can be both redundant and ambiguous

- ightharpoonup Internet and digital archives ightarrow large collections of text data
- How can we navigate these collections efficiently?
- Typical task: find sets of documents that share the same topic or subject matter
- Natural language can be both redundant and ambiguous
- Superficial attributes of documents aren't enough

- ightharpoonup Internet and digital archives ightarrow large collections of text data
- How can we navigate these collections efficiently?
- Typical task: find sets of documents that share the same topic or subject matter
- Natural language can be both redundant and ambiguous
- Superficial attributes of documents aren't enough
- ▶ We need a notion of *latent semantics*, or underlying meaning

 General approach: documents are mixtures of topics, which are distributions over the vocabulary

- General approach: documents are mixtures of topics, which are distributions over the vocabulary
- Probability provides a natural framework for this

- General approach: documents are mixtures of topics, which are distributions over the vocabulary
- Probability provides a natural framework for this
- ► Topics can exist at different levels of abstraction (e.g., baseball and basketball are distinct subtopics under sports)

- General approach: documents are mixtures of topics, which are distributions over the vocabulary
- Probability provides a natural framework for this
- Topics can exist at different levels of abstraction (e.g., baseball and basketball are distinct subtopics under sports)
- ► Can we learn a hierarchy of topics based on a particular corpus?

- General approach: documents are mixtures of topics, which are distributions over the vocabulary
- Probability provides a natural framework for this
- Topics can exist at different levels of abstraction (e.g., baseball and basketball are distinct subtopics under sports)
- ► Can we learn a hierarchy of topics based on a particular corpus?
- Similar to the Dewey Decimal System or Library of Congress Classification

Topics: 
$$heta_1= ext{"sports"}$$
  $heta_2= ext{"medicine"}$   $heta_2= ext{"document 1"}$   $heta_2= ext{"document 2"}$ 

Topics: 
$$\theta_1$$
 = "sports"  $\frac{}{}_{\text{team}}$  player injury illness  $\theta_2$  = "medicine"  $\frac{}{}_{\text{team}}$  player injury illness

Documents:  $\phi_1$  = "document 1"

 $\phi_2$  = "document 2"

Topics: 
$$\theta_1$$
 = "sports" 
$$\theta_2$$
 = "medicine" 
$$\frac{1}{\text{team player injury illness}}$$
Documents:  $\phi_1$  = "document 1" 
$$\phi_2$$
 = "document 2"

Topics: 
$$\theta_1$$
 = "sports" 
$$\theta_2$$
 = "medicine" 
$$\frac{1}{\text{team}} \frac{1}{\text{player}} \frac{1}{\text{injury}} \frac{1}{\text{illness}}$$
Documents:  $\phi_1$  = "document 1" 
$$\phi_2$$
 = "document 2" 
$$\frac{1}{\text{topic 1}} \frac{1}{\text{topic 2}}$$

# "Flat" Topic Models

Idea: frequencies of words in documents determined by probabilities

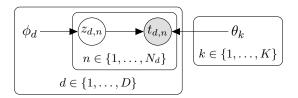
- Idea: frequencies of words in documents determined by probabilities
- ▶ There are K latent topics, and each  $\theta_k$  is a distribution over words in the vocabulary

- Idea: frequencies of words in documents determined by probabilities
- ▶ There are K latent topics, and each  $\theta_k$  is a distribution over words in the vocabulary
- For document d, the vector  $\phi_d$  is a distribution over topics

- Idea: frequencies of words in documents determined by probabilities
- ▶ There are K latent topics, and each  $\theta_k$  is a distribution over words in the vocabulary
- ▶ For document d, the vector  $\phi_d$  is a distribution over topics
- For the  $n^{\text{th}}$  word in document d:

Select a topic:  $z_{d,n} \sim \mathsf{Categorical}(\phi_d)$ 

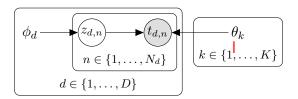
Select a word:  $t_{d,n} \sim \mathsf{Categorical}(\theta_{z_{d,n}})$ 



- Idea: frequencies of words in documents determined by probabilities
- ▶ There are K latent topics, and each  $\theta_k$  is a distribution over words in the vocabulary
- ▶ For document d, the vector  $\phi_d$  is a distribution over topics
- For the  $n^{\text{th}}$  word in document d:

Select a topic:  $z_{d,n} \sim \mathsf{Categorical}(\phi_d)$ 

Select a word:  $t_{d,n} \sim \mathsf{Categorical}(\theta_{z_{d,n}})$ 



▶ Infer values of  $\theta_k$ ,  $\phi_d$  using maximum likelihood

Extension to PLSA: assume topic mixtures  $\phi_d$  and topic vectors  $\theta_k$  are drawn from Dirichlet distributions

- Extension to PLSA: assume topic mixtures  $\phi_d$  and topic vectors  $\theta_k$  are drawn from Dirichlet distributions
- Dirichlet is a distribution over discrete probability distributions; density over simplex:

$$\mathsf{Dirichlet}(\vec{x} \mid \vec{\alpha}) \propto \prod_{k=1}^{\mathsf{len}(\vec{\alpha})} x_i^{\alpha_i - 1}$$

- Extension to PLSA: assume topic mixtures  $\phi_d$  and topic vectors  $\theta_k$  are drawn from Dirichlet distributions
- Dirichlet is a distribution over discrete probability distributions; density over simplex:

$$\mathsf{Dirichlet}(\vec{x} \mid \vec{\alpha}) \propto \prod_{k=1}^{\mathsf{len}(\vec{\alpha})} x_i^{\alpha_i - 1}$$

Dirichlet distribution acts as a regularizer, reduces overfitting

- Extension to PLSA: assume topic mixtures  $\phi_d$  and topic vectors  $\theta_k$  are drawn from Dirichlet distributions
- Dirichlet is a distribution over discrete probability distributions; density over simplex:

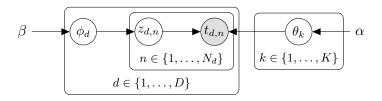
$$\mathsf{Dirichlet}(\vec{x} \mid \vec{\alpha}) \propto \prod_{k=1}^{\mathsf{len}(\vec{\alpha})} x_i^{\alpha_i - 1}$$

- Dirichlet distribution acts as a regularizer, reduces overfitting
- Allows Bayesian posterior inference

### Latent Dirichlet Allocation: The Model

 $egin{aligned} heta_k &\sim \mathsf{Dirichlet}(lpha) \ \phi_d &\sim \mathsf{Dirichlet}(eta) \ z_{d,n} &\sim \mathsf{Categorical}(\phi_d) \ t_{d,n} &\sim \mathsf{Categorical}( heta_{z_{d,n}}) \end{aligned}$ 

for each topic k for each document d for the  $n^{\rm th}$  word in document d for the  $n^{\rm th}$  word in document d



# Bayesian Inference Algorithms

► Latent-variable models contain *observed* and *latent* random variables

- ► Latent-variable models contain *observed* and *latent* random variables
- Model specifies:
  - lacktriangleright Likelihood:  $p(\text{data} \mid \text{latent variables}, \text{fixed parameters})$

- ► Latent-variable models contain *observed* and *latent* random variables
- Model specifies:
  - ightharpoonup *Likelihood*:  $p(\text{data} \mid \text{latent variables}, \text{fixed parameters})$
  - ▶ *Prior*: p(latent variables | fixed parameters)

- Latent-variable models contain observed and latent random variables
- Model specifies:
  - ightharpoonup *Likelihood*: p(data | latent variables, fixed parameters)
  - ▶ *Prior*: *p*(latent variables | fixed parameters)
- ► Goal: try to estimate the *posterior* via Bayes' rule

$$\begin{split} p(\text{latent variables} \mid \text{data}, \text{fixed parameters}) \\ &= \frac{\text{Likelihood} \times \text{Prior}}{p(\text{data} \mid \text{fixed parameters})} \end{split}$$

- Latent-variable models contain observed and latent random variables
- Model specifies:
  - ightharpoonup *Likelihood*: p(data | latent variables, fixed parameters)
  - ▶ *Prior*: *p*(latent variables | fixed parameters)
- ▶ Goal: try to estimate the *posterior* via Bayes' rule

$$\begin{split} p(\text{latent variables} \mid \text{data}, \text{fixed parameters}) \\ &= \frac{\text{Likelihood} \times \text{Prior}}{p(\text{data} \mid \text{fixed parameters})} \end{split}$$

Denominator: marginalization is often intractable

- Latent-variable models contain observed and latent random variables
- Model specifies:
  - Likelihood: p(data | latent variables, fixed parameters)
  - ▶ *Prior.* p(latent variables | fixed parameters)
- ▶ Goal: try to estimate the *posterior* via Bayes' rule

$$\begin{split} p(\text{latent variables} \mid \text{data}, \text{fixed parameters}) \\ &= \frac{\text{Likelihood} \times \text{Prior}}{p(\text{data} \mid \text{fixed parameters})} \end{split}$$

- Denominator: marginalization is often intractable
- Need approximate inference methods

## Gibbs Sampling

Markov Chain Monte Carlo (MCMC) method

- Markov Chain Monte Carlo (MCMC) method
  - Monte Carlo: Estimate a quantity by drawing samples from a random distribution

- Markov Chain Monte Carlo (MCMC) method
  - Monte Carlo: Estimate a quantity by drawing samples from a random distribution
  - Markov Chain: Find stationary distribution of a stochastic process where update rules depend only on previous state

- Markov Chain Monte Carlo (MCMC) method
  - Monte Carlo: Estimate a quantity by drawing samples from a random distribution
  - Markov Chain: Find stationary distribution of a stochastic process where update rules depend only on previous state
- ▶ State vector  $\vec{z}$ ; each component corresponds to a latent variable

- Markov Chain Monte Carlo (MCMC) method
  - Monte Carlo: Estimate a quantity by drawing samples from a random distribution
  - Markov Chain: Find stationary distribution of a stochastic process where update rules depend only on previous state
- ▶ State vector  $\vec{z}$ ; each component corresponds to a latent variable
- ▶ Repeatedly update  $\vec{z}$  by iterating through latent variables, updating  $z_k$  by sampling from its *complete conditional*:

$$p(z_k \mid \vec{z}_{-k}, \vec{x})$$

Here,  $\vec{z}_{-k}$  denotes all components of  $\vec{z}$  except  $z_k$ 

- Markov Chain Monte Carlo (MCMC) method
  - Monte Carlo: Estimate a quantity by drawing samples from a random distribution
  - Markov Chain: Find stationary distribution of a stochastic process where update rules depend only on previous state
- ▶ State vector  $\vec{z}$ ; each component corresponds to a latent variable
- ▶ Repeatedly update  $\vec{z}$  by iterating through latent variables, updating  $z_k$  by sampling from its *complete conditional*:

$$p(z_k \mid \vec{z}_{-k}, \vec{x})$$

Here,  $\vec{z}_{-k}$  denotes all components of  $\vec{z}$  except  $z_k$ 

▶ The distribution of the samples  $\vec{z}$  approaches the true posterior  $p(\vec{z} \mid \vec{x})$ 

# Collapsed Gibbs Sampling

► For some models, we can eliminate some latent variables by marginalization

## Collapsed Gibbs Sampling

- ► For some models, we can eliminate some latent variables by marginalization
- ► For the remaining latent variables, we compute a modified form of the complete conditionals:

$$p(z_k \mid \vec{z}_{\mathsf{subset}-k}, \vec{x})$$

## Collapsed Gibbs Sampling

- ► For some models, we can eliminate some latent variables by marginalization
- ► For the remaining latent variables, we compute a modified form of the complete conditionals:

$$p(z_k \mid \vec{z}_{\mathsf{subset}-k}, \vec{x})$$

 Running Gibbs sampling based on these distributions yields an estimate for

$$p(\vec{z}_{\mathsf{subset}} \mid \vec{x})$$

 Approximation technique: select an approximating family of distributions and search for best approximation

- Approximation technique: select an approximating family of distributions and search for best approximation
- ▶ Measure closeness using reversed Kullback-Leibler divergence

$$\mathsf{KL}(q,\,p(\cdot\,|\,\vec{x})) = E_{\vec{z} \sim q}[\log q(\vec{z}) - \log p(\vec{z}\,|\,\vec{x})]$$

- Approximation technique: select an approximating family of distributions and search for best approximation
- Measure closeness using reversed Kullback-Leibler divergence

$$\mathsf{KL}(q, \, p(\cdot \,|\, \vec{x})) = E_{\vec{z} \sim q}[\log q(\vec{z}) - \log p(\vec{z} \,|\, \vec{x})]$$

Mean-field approximation: consider parameterized functions which factor cleanly:

$$q(\vec{z}) = \prod_{k} q_k(z_k; \nu_k)$$

- Approximation technique: select an approximating family of distributions and search for best approximation
- Measure closeness using reversed Kullback-Leibler divergence

$$\mathsf{KL}(q,\,p(\cdot\,|\,\vec{x})) = E_{\vec{z} \sim q}[\log q(\vec{z}) - \log p(\vec{z}\,|\,\vec{x})]$$

Mean-field approximation: consider parameterized functions which factor cleanly:

$$q(\vec{z}) = \prod_{k} q_k(z_k; \nu_k)$$

Minimizing reversed KL corresponds to maximizing evidence lower bound (ELBO):

$$\mathsf{ELBO} = E_q[\log p(\vec{z}, \vec{x})] - E_q[\log q(\vec{z})]$$

 Coordinate ascent: optimize one latent variable's parameters at a time

- Coordinate ascent: optimize one latent variable's parameters at a time
- Works best for exponential-family models, where conditional distributions can be written as

$$p(x \mid \theta) = h(x) \exp(\eta(\theta) \cdot T(x) - a(\theta))$$

- Coordinate ascent: optimize one latent variable's parameters at a time
- Works best for exponential-family models, where conditional distributions can be written as

$$p(x \mid \theta) = h(x) \exp(\eta(\theta) \cdot T(x) - a(\theta))$$

 $(\eta(\theta) = natural parameters, T(x) = sufficient statistics)$ 

- Coordinate ascent: optimize one latent variable's parameters at a time
- Works best for exponential-family models, where conditional distributions can be written as

$$p(x \mid \theta) = h(x) \exp(\eta(\theta) \cdot T(x) - a(\theta))$$

 $(\eta(\theta) = \text{natural parameters}, T(x) = \text{sufficient statistics})$ 

- Coordinate ascent: optimize one latent variable's parameters at a time
- Works best for exponential-family models, where conditional distributions can be written as

$$p(x \mid \theta) = h(x) \exp(\eta(\theta) \cdot T(x) - a(\theta))$$

 $(\eta(\theta) = \text{natural parameters}, T(x) = \text{sufficient statistics})$ 

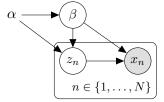
lacktriangle For exponential-family models, the update rule for  $z_k$  is

$$\nu_k = E_q[\eta_k(\vec{z}_{-k}, \vec{x})]$$

where  $\eta_k$  denotes the natural parameters of the complete conditional of  $z_k$ 

### Stochastic Variational Inference: Context

Generic model with local (per-observation) and global variables:



 $x_n$ : observed data

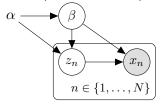
 $z_n$ : local variables (one per observation)

 $\beta$ : global variable (shared for all observations)

 $\alpha$ : fixed parameters

### Stochastic Variational Inference: Context

► Generic model with local (per-observation) and global variables:



 $x_n$ : observed data

 $z_n$ : local variables (one per observation)

 $\beta$ : global variable (shared for all observations)

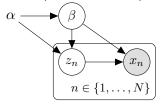
 $\alpha$ : fixed parameters

► Complete conditional for local variables simplifies:

$$p(z_n \mid \alpha, \beta, z_{-n}, x_{1:N}) = p(z_n \mid \alpha, \beta, x_n)$$

### Stochastic Variational Inference: Context

► Generic model with local (per-observation) and global variables:



 $x_n$ : observed data

 $z_n$ : local variables (one per observation)

 $\beta$ : global variable (shared for all observations)

 $\alpha$ : fixed parameters

Complete conditional for local variables simplifies:

$$p(z_n \mid \alpha, \beta, z_{-n}, x_{1:N}) = p(z_n \mid \alpha, \beta, x_n)$$

▶ Complete conditional for global variable requires full dataset:

$$p(\beta \mid \alpha, z_{1:N}, x_{1:N})$$

 Euclidean distance on variational parameters may not reflect "true" distance between distributions

- Euclidean distance on variational parameters may not reflect "true" distance between distributions
- ▶ Rather than standard gradient of the objective function  $(\nabla \mathcal{L})$ , use natural gradient  $G^{-1}\nabla \mathcal{L}$

- Euclidean distance on variational parameters may not reflect "true" distance between distributions
- ▶ Rather than standard gradient of the objective function  $(\nabla \mathcal{L})$ , use natural gradient  $G^{-1}\nabla \mathcal{L}$
- ► *G* is a matrix (*metric tensor*) that encodes local information about "true" distances

- ► Euclidean distance on variational parameters may not reflect "true" distance between distributions
- ▶ Rather than standard gradient of the objective function  $(\nabla \mathcal{L})$ , use natural gradient  $G^{-1}\nabla \mathcal{L}$
- ► *G* is a matrix (*metric tensor*) that encodes local information about "true" distances
- ▶ With a symmetric version of KL divergence and a model with exponential-family distributions, *G* cancels cleanly:

$$G^{-1}\nabla \mathcal{L} = E_q[\eta] - \nu$$

where u is the current value of the local variational params

- ► Euclidean distance on variational parameters may not reflect "true" distance between distributions
- ▶ Rather than standard gradient of the objective function  $(\nabla \mathcal{L})$ , use natural gradient  $G^{-1}\nabla \mathcal{L}$
- ► *G* is a matrix (*metric tensor*) that encodes local information about "true" distances
- ▶ With a symmetric version of KL divergence and a model with exponential-family distributions, *G* cancels cleanly:

$$G^{-1}\nabla \mathcal{L} = E_q[\eta] - \nu$$

where  $\nu$  is the current value of the local variational params

► For local variables, the update rule is the same as in CAVI:

$$\nu^{\mathsf{local}} = E_q[\eta^{\mathsf{local}}]$$

► For global variables, repeatedly draw *mini-batches* b containing S observations

- ► For global variables, repeatedly draw *mini-batches b* containing S observations
- ▶ Compute an *unbiased estimate* of the natural gradient  $G^{-1}\nabla \mathcal{L}$  for each batch:

$$\mu = E_q[\eta_b^{\mathsf{global}}] - \nu^{\mathsf{global}}$$

- ► For global variables, repeatedly draw *mini-batches b* containing S observations
- ▶ Compute an *unbiased estimate* of the natural gradient  $G^{-1}\nabla \mathcal{L}$  for each batch:

$$\mu = E_q[\eta_b^{\mathsf{global}}] - \nu^{\mathsf{global}}$$

Here,  $\eta_b^{\rm global}$  denotes the natural parameters of the complete conditional of the global variable, but with the true dataset replaced by N/S copies of the mini-batch b

- ► For global variables, repeatedly draw *mini-batches b* containing S observations
- ▶ Compute an *unbiased estimate* of the natural gradient  $G^{-1}\nabla \mathcal{L}$  for each batch:

$$\mu = E_q[\eta_b^{\mathsf{global}}] - \nu^{\mathsf{global}}$$

Here,  $\eta_b^{\rm global}$  denotes the natural parameters of the complete conditional of the global variable, but with the true dataset replaced by N/S copies of the mini-batch b

▶ Update according to a decaying schedule of step sizes  $\rho_t$ :

$$u^{\mathsf{global}} \leftarrow \nu^{\mathsf{global}} + \rho_t \, \mu$$

- ► For global variables, repeatedly draw *mini-batches b* containing S observations
- ▶ Compute an *unbiased estimate* of the natural gradient  $G^{-1}\nabla \mathcal{L}$  for each batch:

$$\mu = E_q[\eta_b^{\mathsf{global}}] - \nu^{\mathsf{global}}$$

Here,  $\eta_b^{\rm global}$  denotes the natural parameters of the complete conditional of the global variable, but with the true dataset replaced by N/S copies of the mini-batch b

▶ Update according to a decaying schedule of step sizes  $\rho_t$ :

$$\begin{split} \nu^{\mathsf{global}} &\leftarrow \nu^{\mathsf{global}} + \rho_t \, \mu \\ &= (1 - \rho_t) \nu^{\mathsf{global}} + \rho_t \, E_q[\eta_b^{\mathsf{global}}] \end{split}$$

# Learning Topic Hierarchies

▶ Goal: extend LDA model so that:

- ► Goal: extend LDA model so that:
  - ▶ Topics are arranged in a tree (root  $\rightarrow$  abstract; leaves  $\rightarrow$  concrete)

- Goal: extend LDA model so that:
  - ▶ Topics are arranged in a tree (root  $\rightarrow$  abstract; leaves  $\rightarrow$  concrete)
  - ► The size and structure of the tree can be determined in a data-driven way

- Goal: extend LDA model so that:
  - ► Topics are arranged in a tree (root  $\rightarrow$  abstract; leaves  $\rightarrow$  concrete)
  - ► The size and structure of the tree can be determined in a data-driven way
- Documents can combine topics, but in a more constrained way

- Goal: extend LDA model so that:
  - ▶ Topics are arranged in a tree (root  $\rightarrow$  abstract; leaves  $\rightarrow$  concrete)
  - ► The size and structure of the tree can be determined in a data-driven way
- Documents can combine topics, but in a more constrained way
  - If a document draws words from one node, then it should also be somewhat likely to draw words from ancestor nodes

# Topic Modeling with Hierarchies

- Goal: extend LDA model so that:
  - ▶ Topics are arranged in a tree (root → abstract; leaves → concrete)
  - ► The size and structure of the tree can be determined in a data-driven way
- Documents can combine topics, but in a more constrained way
  - If a document draws words from one node, then it should also be somewhat likely to draw words from ancestor nodes
- ▶ We'll discuss two main models:

# Topic Modeling with Hierarchies

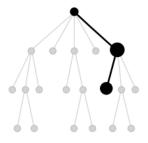
- Goal: extend LDA model so that:
  - ► Topics are arranged in a tree (root  $\rightarrow$  abstract; leaves  $\rightarrow$  concrete)
  - ► The size and structure of the tree can be determined in a data-driven way
- Documents can combine topics, but in a more constrained way
  - ▶ If a document draws words from one node, then it should also be somewhat likely to draw words from ancestor nodes
- We'll discuss two main models:
  - Nested Chinese Restaurant Process

# Topic Modeling with Hierarchies

- Goal: extend LDA model so that:
  - ▶ Topics are arranged in a tree (root  $\rightarrow$  abstract; leaves  $\rightarrow$  concrete)
  - ► The size and structure of the tree can be determined in a data-driven way
- Documents can combine topics, but in a more constrained way
  - ▶ If a document draws words from one node, then it should also be somewhat likely to draw words from ancestor nodes
- We'll discuss two main models:
  - Nested Chinese Restaurant Process
  - Nested Hierarchical Dirichlet Process

#### Nested Chinese Restaurant Process

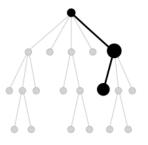
▶ Idea: Each document samples a path from an infinite tree



Source: Paisley et al [16]

#### Nested Chinese Restaurant Process

- ▶ Idea: Each document samples a path from an infinite tree
- Within each document, we can only select nodes (ie, topics)
   from the sampled path



Source: Paisley et al [16]

How to define distributions over paths in an infinite (or arbitrarily large) tree?

How to define distributions over paths in an infinite (or arbitrarily large) tree?
Nested Chinese Restaurant Process

- How to define distributions over paths in an infinite (or arbitrarily large) tree?
  Nested Chinese Restaurant Process
- ▶ How to define distributions over arbitrarily large partitions?

- How to define distributions over paths in an infinite (or arbitrarily large) tree?
  Nested Chinese Restaurant Process
- How to define distributions over arbitrarily large partitions? Chinese Restaurant Process

► Analogy: Sequence of customers entering a restaurant

- Analogy: Sequence of customers entering a restaurant
- ▶ Infinitely many tables, each with infinite capacity

- Analogy: Sequence of customers entering a restaurant
- Infinitely many tables, each with infinite capacity
- First customer always sits at first table

- Analogy: Sequence of customers entering a restaurant
- Infinitely many tables, each with infinite capacity
- ► First customer always sits at first table
- ▶ When  $n \ge 1$  customers have been seated, the next customer follows these rules:

- Analogy: Sequence of customers entering a restaurant
- Infinitely many tables, each with infinite capacity
- First customer always sits at first table
- ▶ When  $n \ge 1$  customers have been seated, the next customer follows these rules:
  - ▶ If the first k tables are occupied, with the  $i^{\text{th}}$  table containing  $m_i$  customers, sit at table i with probability  $\frac{m_i}{n+\alpha}$

- Analogy: Sequence of customers entering a restaurant
- Infinitely many tables, each with infinite capacity
- First customer always sits at first table
- ▶ When  $n \ge 1$  customers have been seated, the next customer follows these rules:
  - ▶ If the first k tables are occupied, with the  $i^{\text{th}}$  table containing  $m_i$  customers, sit at table i with probability  $\frac{m_i}{n+\alpha}$
  - Sit at the next empty table with probability  $\frac{n}{n+\alpha}$

- Analogy: Sequence of customers entering a restaurant
- ▶ Infinitely many tables, each with infinite capacity
- First customer always sits at first table
- ▶ When  $n \ge 1$  customers have been seated, the next customer follows these rules:
  - ▶ If the first k tables are occupied, with the  $i^{\text{th}}$  table containing  $m_i$  customers, sit at table i with probability  $\frac{m_i}{n+\alpha}$
  - Sit at the next empty table with probability  $\frac{n}{n+\alpha}$



- Analogy: Sequence of customers entering a restaurant
- ▶ Infinitely many tables, each with infinite capacity
- First customer always sits at first table
- ▶ When  $n \ge 1$  customers have been seated, the next customer follows these rules:
  - ▶ If the first k tables are occupied, with the  $i^{\text{th}}$  table containing  $m_i$  customers, sit at table i with probability  $\frac{m_i}{n+\alpha}$
  - Sit at the next empty table with probability  $\frac{\alpha}{n+\alpha}$



- Analogy: Sequence of customers entering a restaurant
- Infinitely many tables, each with infinite capacity
- First customer always sits at first table
- ▶ When  $n \ge 1$  customers have been seated, the next customer follows these rules:
  - ▶ If the first k tables are occupied, with the  $i^{\text{th}}$  table containing  $m_i$  customers, sit at table i with probability  $\frac{m_i}{n+\alpha}$
  - Sit at the next empty table with probability  $\frac{n}{n+\alpha}$



- Analogy: Sequence of customers entering a restaurant
- Infinitely many tables, each with infinite capacity
- ▶ First customer always sits at first table
- ▶ When  $n \ge 1$  customers have been seated, the next customer follows these rules:
  - ▶ If the first k tables are occupied, with the  $i^{\text{th}}$  table containing  $m_i$  customers, sit at table i with probability  $\frac{m_i}{n+\alpha}$
  - Sit at the next empty table with probability  $\frac{n}{n+\alpha}$



- Analogy: Sequence of customers entering a restaurant
- ▶ Infinitely many tables, each with infinite capacity
- First customer always sits at first table
- ▶ When  $n \ge 1$  customers have been seated, the next customer follows these rules:
  - ▶ If the first k tables are occupied, with the  $i^{\text{th}}$  table containing  $m_i$  customers, sit at table i with probability  $\frac{m_i}{n+\alpha}$
  - Sit at the next empty table with probability  $\frac{n}{n+\alpha}$



- Analogy: Sequence of customers entering a restaurant
- ▶ Infinitely many tables, each with infinite capacity
- First customer always sits at first table
- ▶ When  $n \ge 1$  customers have been seated, the next customer follows these rules:
  - ▶ If the first k tables are occupied, with the  $i^{\text{th}}$  table containing  $m_i$  customers, sit at table i with probability  $\frac{m_i}{n+\alpha}$
  - Sit at the next empty table with probability  $\frac{n}{n+\alpha}$



- Analogy: Sequence of customers entering a restaurant
- Infinitely many tables, each with infinite capacity
- First customer always sits at first table
- ▶ When  $n \ge 1$  customers have been seated, the next customer follows these rules:
  - ▶ If the first k tables are occupied, with the  $i^{\text{th}}$  table containing  $m_i$  customers, sit at table i with probability  $\frac{m_i}{n+\alpha}$
  - Sit at the next empty table with probability  $\frac{n}{n+\alpha}$



- Analogy: Sequence of customers entering a restaurant
- Infinitely many tables, each with infinite capacity
- First customer always sits at first table
- ▶ When  $n \ge 1$  customers have been seated, the next customer follows these rules:
  - ▶ If the first k tables are occupied, with the  $i^{\text{th}}$  table containing  $m_i$  customers, sit at table i with probability  $\frac{m_i}{n+\alpha}$
  - Sit at the next empty table with probability  $\frac{n}{n+\alpha}$



- Analogy: Sequence of customers entering a restaurant
- Infinitely many tables, each with infinite capacity
- First customer always sits at first table
- ▶ When  $n \ge 1$  customers have been seated, the next customer follows these rules:
  - ▶ If the first k tables are occupied, with the  $i^{\text{th}}$  table containing  $m_i$  customers, sit at table i with probability  $\frac{m_i}{n+\alpha}$
  - Sit at the next empty table with probability  $\frac{n}{n+\alpha}$



- Analogy: Sequence of customers entering a restaurant
- ► Infinitely many tables, each with infinite capacity
- First customer always sits at first table
- ▶ When  $n \ge 1$  customers have been seated, the next customer follows these rules:
  - ▶ If the first k tables are occupied, with the  $i^{\text{th}}$  table containing  $m_i$  customers, sit at table i with probability  $\frac{m_i}{n+\alpha}$
  - Sit at the next empty table with probability  $\frac{n}{n+\alpha}$



- Analogy: Sequence of customers entering a restaurant
- ▶ Infinitely many tables, each with infinite capacity
- ► First customer always sits at first table
- ▶ When  $n \ge 1$  customers have been seated, the next customer follows these rules:
  - ▶ If the first k tables are occupied, with the  $i^{\text{th}}$  table containing  $m_i$  customers, sit at table i with probability  $\frac{m_i}{n+\alpha}$
  - Sit at the next empty table with probability  $\frac{n}{n+\alpha}$



- Analogy: Sequence of customers entering a restaurant
- ▶ Infinitely many tables, each with infinite capacity
- ▶ First customer always sits at first table
- ▶ When  $n \ge 1$  customers have been seated, the next customer follows these rules:
  - ▶ If the first k tables are occupied, with the  $i^{\text{th}}$  table containing  $m_i$  customers, sit at table i with probability  $\frac{m_i}{n+\alpha}$
  - Sit at the next empty table with probability  $\frac{n}{n+\alpha}$



- Analogy: Sequence of customers entering a restaurant
- Infinitely many tables, each with infinite capacity
- ▶ First customer always sits at first table
- ▶ When  $n \ge 1$  customers have been seated, the next customer follows these rules:
  - ▶ If the first k tables are occupied, with the  $i^{\text{th}}$  table containing  $m_i$  customers, sit at table i with probability  $\frac{m_i}{n+\alpha}$
  - Sit at the next empty table with probability  $\frac{n}{n+\alpha}$



▶ Parameter  $\alpha$ : As  $\alpha \to \infty$ , number of occupied tables increases

▶ Stick-breaking construction:

- Stick-breaking construction:
  - ▶ Draw infinite sequence of beta-distributed variables:

$$V_k \sim \mathsf{Beta}(1,\alpha)$$
 for  $k \ge 1$ 

- Stick-breaking construction:
  - ▶ Draw infinite sequence of beta-distributed variables:

$$V_k \sim \mathsf{Beta}(1,\alpha)$$
 for  $k \ge 1$ 

 $\blacktriangleright$  Draw table index k with probability  $\pi_k = V_k \prod_{j=1}^{k-1} (1-V_j)$ 

- ► Stick-breaking construction:
  - ▶ Draw infinite sequence of beta-distributed variables:

$$V_k \sim \mathsf{Beta}(1, \alpha) \qquad \mathsf{for} \ k \geq 1$$

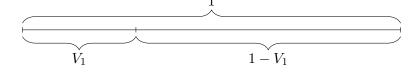
 $\blacktriangleright$  Draw table index k with probability  $\pi_k = V_k \prod_{j=1}^{k-1} (1-V_j)$ 



- Stick-breaking construction:
  - ▶ Draw infinite sequence of beta-distributed variables:

$$V_k \sim \mathsf{Beta}(1,\alpha)$$
 for  $k \ge 1$ 

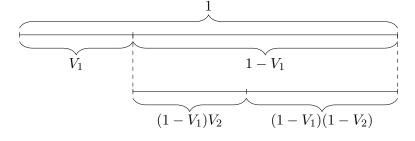
 $\blacktriangleright$  Draw table index k with probability  $\pi_k = V_k \prod_{j=1}^{k-1} (1-V_j)$ 



- Stick-breaking construction:
  - ▶ Draw infinite sequence of beta-distributed variables:

$$V_k \sim \mathsf{Beta}(1,\alpha)$$
 for  $k \ge 1$ 

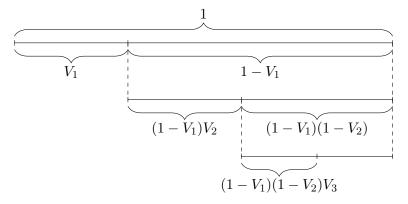
▶ Draw table index k with probability  $\pi_k = V_k \prod_{j=1}^{k-1} (1-V_j)$ 



- Stick-breaking construction:
  - ▶ Draw infinite sequence of beta-distributed variables:

$$V_k \sim \mathsf{Beta}(1,\alpha)$$
 for  $k \ge 1$ 

▶ Draw table index k with probability  $\pi_k = V_k \prod_{j=1}^{k-1} (1 - V_j)$ 



#### Nested CRP: Distribution Over Paths

► Analogy: Infinitely many restaurants, arranged in a tree

- ► Analogy: Infinitely many restaurants, arranged in a tree
- ▶ Customers enter the "root" restaurant and select a table

- ► Analogy: Infinitely many restaurants, arranged in a tree
- Customers enter the "root" restaurant and select a table
- Once seated, customers move to a restaurant indicated by a card at their table

- ► Analogy: Infinitely many restaurants, arranged in a tree
- Customers enter the "root" restaurant and select a table
- Once seated, customers move to a restaurant indicated by a card at their table
- ► This process repeats indefinitely at new restaurants

► A single draw from the NCRP is a distribution over infinite paths (finite-depth variant also exists)

- ➤ A single draw from the NCRP is a distribution over infinite paths (finite-depth variant also exists)
- ▶ Stick-breaking construction:  $T \sim NCRP(\alpha)$  denotes:

- ► A single draw from the NCRP is a distribution over infinite paths (finite-depth variant also exists)
- ▶ Stick-breaking construction:  $T \sim NCRP(\alpha)$  denotes:

 $V_r \sim \mathsf{Beta}(1, \alpha)$  for any finite-length path r

- ➤ A single draw from the NCRP is a distribution over infinite paths (finite-depth variant also exists)
- ▶ Stick-breaking construction:  $T \sim NCRP(\alpha)$  denotes:

$$V_r \sim \mathrm{Beta}(1,\alpha) \qquad \text{for any finite-length path } r$$
 
$$V_{()} = 1$$

- A single draw from the NCRP is a distribution over infinite paths (finite-depth variant also exists)
- ▶ Stick-breaking construction:  $T \sim NCRP(\alpha)$  denotes:

$$V_r \sim {\sf Beta}(1, lpha)$$
 for any finite-length path  $r$   $V_{()} = 1$   $\pi_{()} = 1$ 

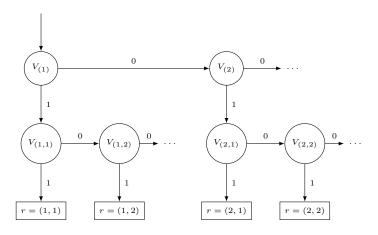
- A single draw from the NCRP is a distribution over infinite paths (finite-depth variant also exists)
- ▶ Stick-breaking construction:  $T \sim NCRP(\alpha)$  denotes:

$$\begin{split} V_r &\sim \text{Beta}(1,\alpha) &\quad \text{for any finite-length path } r \\ V_{()} &= 1 \\ \pi_{()} &= 1 \\ \pi_{r[1:\ell]} &= \pi_{r[1:\ell-1]} \cdot \left( V_{r[1:\ell]} \prod_{j=1}^{r[\ell]-1} (1 - V_{r[1:\ell-1],j}) \right) \end{split}$$

- A single draw from the NCRP is a distribution over infinite paths (finite-depth variant also exists)
- ▶ Stick-breaking construction:  $T \sim NCRP(\alpha)$  denotes:

$$\begin{split} V_r &\sim \text{Beta}(1,\alpha) &\quad \text{for any finite-length path } r \\ V_{()} &= 1 \\ \pi_{()} &= 1 \\ \pi_{r[1:\ell]} &= \pi_{r[1:\ell-1]} \cdot \left( V_{r[1:\ell]} \prod_{j=1}^{r[\ell]-1} (1 - V_{r[1:\ell-1],j}) \right) \\ T &= \sum_{r: \text{infinite path}} \pi_r \delta_r \end{split}$$

# Nested CRP: A Finite-Depth Example



▶ Draw an infinite tree of topics,  $\theta_r \sim \mathsf{Dirichlet}(\alpha^{(\theta)})$ 

- ▶ Draw an infinite tree of topics,  $\theta_r \sim \mathsf{Dirichlet}(\alpha^{(\theta)})$
- ▶ Draw a global distribution over paths,  $T \sim \text{NCRP}(\alpha^{(V)})$

- ▶ Draw an infinite tree of topics,  $\theta_r \sim \mathsf{Dirichlet}(\alpha^{(\theta)})$
- ▶ Draw a global distribution over paths,  $T \sim \mathsf{NCRP}(\alpha^{(V)})$
- ► For each document *d*:

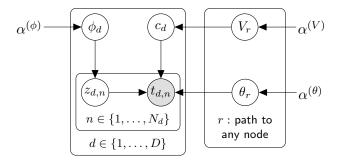
- ▶ Draw an infinite tree of topics,  $\theta_r \sim \mathsf{Dirichlet}(\alpha^{(\theta)})$
- ▶ Draw a global distribution over paths,  $T \sim \mathsf{NCRP}(\alpha^{(V)})$
- ► For each document d:
  - ▶ Draw a path  $c_d \sim T$

- ▶ Draw an infinite tree of topics,  $\theta_r \sim \mathsf{Dirichlet}(\alpha^{(\theta)})$
- ▶ Draw a global distribution over paths,  $T \sim \text{NCRP}(\alpha^{(V)})$
- ► For each document *d*:
  - ▶ Draw a path  $c_d \sim T$
  - lacktriangle Draw a stick-breaking distribution over depths  $\phi_d$

- ▶ Draw an infinite tree of topics,  $\theta_r \sim \mathsf{Dirichlet}(\alpha^{(\theta)})$
- ▶ Draw a global distribution over paths,  $T \sim \text{NCRP}(\alpha^{(V)})$
- ► For each document *d*:
  - ▶ Draw a path  $c_d \sim T$
  - lacktriangle Draw a stick-breaking distribution over depths  $\phi_d$
  - ► For each word-slot *n*:

- ▶ Draw an infinite tree of topics,  $\theta_r \sim \mathsf{Dirichlet}(\alpha^{(\theta)})$
- ▶ Draw a global distribution over paths,  $T \sim NCRP(\alpha^{(V)})$
- ▶ For each document d:
  - ▶ Draw a path  $c_d \sim T$
  - lacktriangle Draw a stick-breaking distribution over depths  $\phi_d$
  - ▶ For each word-slot *n*:
    - Draw a depth  $z_{d,n} \sim \mathsf{Categorical}(\phi_d)$

- ▶ Draw an infinite tree of topics,  $\theta_r \sim \mathsf{Dirichlet}(\alpha^{(\theta)})$
- ▶ Draw a global distribution over paths,  $T \sim \mathsf{NCRP}(\alpha^{(V)})$
- ► For each document d:
  - ▶ Draw a path  $c_d \sim T$
  - lacktriangle Draw a stick-breaking distribution over depths  $\phi_d$
  - ▶ For each word-slot n:
    - ▶ Draw a depth  $z_{d,n} \sim \mathsf{Categorical}(\phi_d)$
    - ▶ Draw a vocabulary word  $t_{d,n} \sim \mathsf{Categorical}(\theta[c_d[1:z_{d,n}]])$



# NCRP Topic Model: Gibbs Sampling

▶ Collapsed Gibbs sampling (marginalize out depth proportions  $\phi_d$  and topic vectors  $\theta_r$ )

# NCRP Topic Model: Gibbs Sampling

- ▶ Collapsed Gibbs sampling (marginalize out depth proportions  $\phi_d$  and topic vectors  $\theta_r$ )
- ► Griffiths et al [11]: Finite depth, uses order-dependent "restaurant analogy" formulation to avoid tracking infinitely many paths; each sampling step may grow or shrink the tree

# NCRP Topic Model: Gibbs Sampling

- ▶ Collapsed Gibbs sampling (marginalize out depth proportions  $\phi_d$  and topic vectors  $\theta_r$ )
- ▶ Griffiths et al [11]: Finite depth, uses order-dependent "restaurant analogy" formulation to avoid tracking infinitely many paths; each sampling step may grow or shrink the tree
- ▶ Blei et al [3]: Uses lazy evaluation; if final layer is ever sampled, then start tracking one extra layer

▶ Infinitely many latent variables: need additional approximations

- ▶ Infinitely many latent variables: need additional approximations
- ▶ Start with finite-depth, finite-width tree



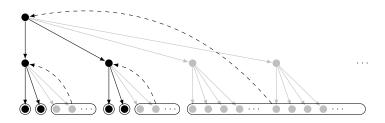
- Infinitely many latent variables: need additional approximations
- ▶ Start with finite-depth, finite-width tree
- Depth stays constant, but width may change



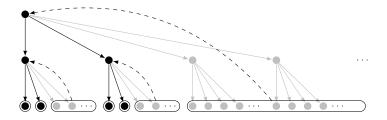
- Infinitely many latent variables: need additional approximations
- Start with finite-depth, finite-width tree
- Depth stays constant, but width may change
- Outside of the finite truncation, variational distributions are assumed constant



- Infinitely many latent variables: need additional approximations
- Start with finite-depth, finite-width tree
- Depth stays constant, but width may change
- Outside of the finite truncation, variational distributions are assumed constant
- ▶ Divide infinite set of paths into equivalence classes



- Infinitely many latent variables: need additional approximations
- Start with finite-depth, finite-width tree
- Depth stays constant, but width may change
- Outside of the finite truncation, variational distributions are assumed constant
- ▶ Divide infinite set of paths into equivalence classes
- If one equivalence class becomes sufficiently likely, add a representative path from it

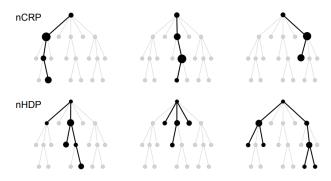


### Nested Hierarchical Dirichlet Process

▶ Idea: Global probability distribution over nodes, and each document samples a re-weighted version of that distribution

### Nested Hierarchical Dirichlet Process

- Idea: Global probability distribution over nodes, and each document samples a re-weighted version of that distribution
- Handles "hybrid" topics better than NCRP



Source: Paisley et al [16]

lacktriangle Each node in infinite tree associated with a topic vector  $heta_r$ 

- **Each** node in infinite tree associated with a topic vector  $\theta_r$
- ▶ Global distribution over paths drawn from an NCRP distribution (i.e., draw global stick-breaking proportions  $V_{r,j}^*$ )

- **Each** node in infinite tree associated with a topic vector  $\theta_r$
- ▶ Global distribution over paths drawn from an NCRP distribution (i.e., draw global stick-breaking proportions  $V_{r,i}^*$ )
- Per-document:
  - $lackbox{ Permutation of branches } z_{r,j}^d$

- **Each** node in infinite tree associated with a topic vector  $\theta_r$
- ▶ Global distribution over paths drawn from an NCRP distribution (i.e., draw global stick-breaking proportions  $V_{r,i}^*$ )
- Per-document:
  - $lackbox{ Permutation of branches } z_{r,j}^d$
  - lacktriangleright "Re-weighting" stick-breaking proportions  $V^d_{r,j}$

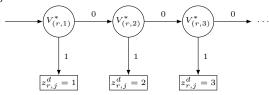
- **Each** node in infinite tree associated with a topic vector  $\theta_r$
- ▶ Global distribution over paths drawn from an NCRP distribution (i.e., draw global stick-breaking proportions  $V_{r,j}^*$ )
- Per-document:
  - lacktriangle Permutation of branches  $z_{r,j}^d$
  - lacktriangle "Re-weighting" stick-breaking proportions  $V^d_{r,j}$
  - $\,\blacktriangleright\,$  "Path-propagation" proportions  $U^d_r$

# NHDP Topic Model

- **Each** node in infinite tree associated with a topic vector  $\theta_r$
- ▶ Global distribution over paths drawn from an NCRP distribution (i.e., draw global stick-breaking proportions  $V_{r,j}^*$ )
- Per-document:
  - $\blacktriangleright \ \ {\it Permutation of branches} \ z^d_{r,j}$
  - lacktriangle "Re-weighting" stick-breaking proportions  $V^d_{r,j}$
  - lacktriangle "Path-propagation" proportions  $U_r^d$
- ▶ Together,  $z_{r,j}^d$ ,  $V_{r,j}^d$ , and  $U_r^d$  define a document-specific distribution over nodes

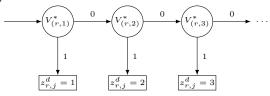
# NHDP Topic Model: Selecting Indices

▶ For each document d, for each node r, and for each  $j \ge 1$ , select  $z^d_{r,j}$ :

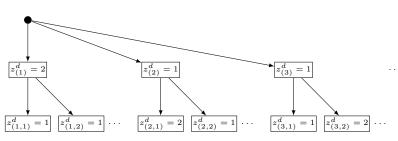


# NHDP Topic Model: Selecting Indices

▶ For each document d, for each node r, and for each  $j \ge 1$ , select  $z_{r,j}^d$ :

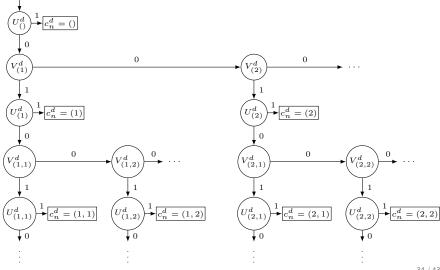


Result defines how branches are permuted and copied (per document):



# NHDP Topic Model: Path Propagation

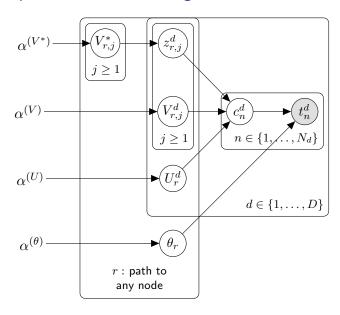
Visualizing  $V_{r,j}^d$  and  $U_r^d$ , ignoring branch permutations (i.e., assuming  $z_{r,i}^d = j$ )



# NHDP Topic Model: Conditional Distributions

$$\begin{split} \theta_r &\sim \mathsf{Dirichlet}(\alpha^{(\theta)}) \\ V_{r,j}^* &\sim \mathsf{Beta}(1,\alpha^{(V^*)}) \\ V_{r,j}^d &\sim \mathsf{Beta}(1,\alpha^{(V)}) \\ U_r^d &\sim \mathsf{Beta}(\alpha_1^{(U)},\alpha_2^{(U)}) \\ z_{r,j}^d &\sim \sum_{k\geq 1} \left(V_{r,k}^* \prod_{i=1}^{k-1} (1-V_{r,i}^*)\right) \delta_k \\ c_n^d &\sim \sum_{r:\mathsf{path}} A(r,V^d,z^d) \, B(r,U^d) \, \delta_r \\ A(r,V^d,z^d) &= \prod_{m=0}^{\mathsf{len}(r)-1} \sum_{k\geq 1} \mathbbm{1} \left[z_{r[1:m],k}^d = r[m+1]\right] \left(V_{r[1:m],k}^d \prod_{i=1}^{k-1} \left(1-V_{r[1:m],i}^d\right)\right) \\ B(r,U^d) &= U_r^d \prod_{m=0}^{\mathsf{len}(r)-1} \left(1-U_{r[1:m]}^d\right) \\ t_n^d &\sim \mathsf{Categorical}(\theta_{c_n^d}) \end{split}$$

# NHDP Topic Model: Plate Diagram



▶ Use a finite-depth, finite-width tree

- ▶ Use a finite-depth, finite-width tree
- lacktriangle Simplifications for document-specific indices  $z_{r,j}^d$ :

- ▶ Use a finite-depth, finite-width tree
- ▶ Simplifications for document-specific indices  $z_{r,j}^d$ :
  - Use Dirac- $\delta$  variational distributions

- ▶ Use a finite-depth, finite-width tree
- ▶ Simplifications for document-specific indices  $z_{r,j}^d$ :
  - Use Dirac- $\delta$  variational distributions
  - lackbox For any d and any r, the indices  $z_{r,j}^d$  do not repeat

- ▶ Use a finite-depth, finite-width tree
- lacktriangle Simplifications for document-specific indices  $z_{r,j}^d$ :
  - Use Dirac- $\delta$  variational distributions
  - For any d and any r, the indices  $z_{r,j}^d$  do not repeat
  - For each document, greedy algorithm selects small number of nodes to include

- ▶ Use a finite-depth, finite-width tree
- lacktriangle Simplifications for document-specific indices  $z_{r,j}^d$ :
  - Use Dirac- $\delta$  variational distributions
  - For any d and any r, the indices  $z_{r,j}^d$  do not repeat
  - For each document, greedy algorithm selects small number of nodes to include
- Greedy algorithm: start with root, add a node only if it increases ELBO by some threshold

- ▶ Use a finite-depth, finite-width tree
- lacktriangle Simplifications for document-specific indices  $z_{r,j}^d$ :
  - Use Dirac- $\delta$  variational distributions
  - For any d and any r, the indices  $z_{r,j}^d$  do not repeat
  - For each document, greedy algorithm selects small number of nodes to include
- Greedy algorithm: start with root, add a node only if it increases ELBO by some threshold
- Remainder of algorithm is a standard application of stochastic variational inference

► Scalable algorithms

- Scalable algorithms
- ► Interpreting models

- Scalable algorithms
- Interpreting models
- Incorporating human feedback

- Scalable algorithms
- Interpreting models
- Incorporating human feedback
- Moving beyond the bag-of-words model

- Scalable algorithms
- Interpreting models
- Incorporating human feedback
- Moving beyond the bag-of-words model
- Frameworks for Bayesian non-parametric inference

# Acknowledgements

Advisor: Sanjoy Dasgupta

► LANL Mentor: Kari Sentz

Research Exam Committee:

Vineet Bafna (chair), Yoav Freund, Julian McAuley

Thank You!

 Sanjeev Arora, Rong Ge, Yonatan Halpern, David Mimno, Ankur Moitra, David Sontag, Yichen Wu, and Michael Zhu.

A practical algorithm for topic modeling with provable guarantees.

In International Conference on Machine Learning, pages 280-288, 2013.

[2] David Barber.

Bayesian reasoning and machine learning.

Cambridge University Press, 2012.

Online version available at http://www.cs.ucl.ac.uk/staff/d.barber/brml/; Draft dated 2017-02-02.

[3] David M Blei, Thomas L Griffiths, and Michael I Jordan.

The nested chinese restaurant process and bayesian nonparametric inference of topic hierarchies. Journal of the ACM (JACM), 57(2):7, 2010.

[4] David M Blei, Alp Kucukelbir, and Jon D McAuliffe.

Variational inference: A review for statisticians.

Journal of the American Statistical Association, (just-accepted), 2017.

[5] David M Blei, Andrew Y Ng, and Michael I Jordan. Latent dirichlet allocation.

Journal of machine Learning research, 3(Jan):993-1022, 2003.

[6] Scott Deerwester, Susan T Dumais, George W Furnas, Thomas K Landauer, and Richard Harshman. Indexing by latent semantic analysis.

Journal of the American society for information science, 41(6):391, 1990.

Arthur P Dempster, Nan M Laird, and Donald B Rubin.
 Maximum likelihood from incomplete data via the EM algorithm.

Journal of the royal statistical society. Series B (methodological), pages 1–38, 1977.

[8] Thomas S Ferguson.

A bayesian analysis of some nonparametric problems.

The annals of statistics, pages 209-230, 1973.

 [9] Jerome Friedman, Trevor Hastie, and Robert Tibshirani. The elements of statistical learning. Springer, 2001.

[10] Samuel J Gershman and David M Blei.

A tutorial on bayesian nonparametric models.

Journal of Mathematical Psychology, 56(1):1–12, 2012.

[11] Thomas L Griffiths, Michael I Jordan, Joshua B Tenenbaum, and David M Blei. Hierarchical topic models and the nested chinese restaurant process. In Advances in neural information processing systems, pages 17–24, 2004.

[12] Thomas L Griffiths and Mark Steyvers.

Finding scientific topics.

Proceedings of the National academy of Sciences, 101(suppl 1):5228–5235, 2004.

[13] Gregor Heinrich.

Parameter estimation for text analysis.

Technical report, 2005.

[14] Matthew D Hoffman, David M Blei, Chong Wang, and John Paisley. Stochastic variational inference.

The Journal of Machine Learning Research, 14(1):1303–1347, 2013.

[15] Thomas Hofmann.

Probabilistic latent semantic analysis.

In Proceedings of the Fifteenth conference on Uncertainty in artificial intelligence, pages 289–296. Morgan Kaufmann Publishers Inc., 1999.

[16] John Paisley, Chong Wang, David M Blei, and Michael I Jordan.

Nested hierarchical dirichlet processes.

IEEE Transactions on Pattern Analysis and Machine Intelligence, 37(2):256-270, 2015.

[17]	Rajesh	Ranganath,	Sean	Gerrish,	and	David	Blei.

Black box variational inference.

In Artificial Intelligence and Statistics, pages 814-822, 2014.

### [18] Rajesh Ranganath, Dustin Tran, Jaan Altosaar, and David Blei. Operator variational inference.

In Advances in Neural Information Processing Systems, pages 496–504, 2016.

### [19] Philip Resnik and Eric Hardisty.

### Gibbs sampling for the uninitiated.

Technical report, University of Maryland, College Park, 2010.

### [20] Jayaram Sethuraman.

#### A constructive definition of dirichlet priors.

Statistica sinica, pages 639-650, 1994.

### [21] Yee W Teh, Michael I Jordan, Matthew J Beal, and David M Blei. Sharing clusters among related groups: Hierarchical dirichlet processes. In Advances in neural information processing systems, pages 1385–1392, 2005.

#### [22] Chong Wang and David M Blei.

### Variational inference for the nested chinese restaurant process.

In Advances in Neural Information Processing Systems, pages 1990-1998, 2009.

### [23] Wikipedia.

### Exponential family.

https://en.wikipedia.org/w/index.php?title=Exponential\_family&oldid=787816251. Accessed September 2017.

### [24] Wikipedia.

### Latent dirichlet allocation.

### [25] Wikipedia.

### Latent semantic analysis.

https://en.wikipedia.org/w/index.php?title=Latent\_semantic\_analysis&oldid=798597246. Accessed September 2017.

### [26] Wikipedia.

### Probabilistic latent semantic analysis.

#### https:

//en.wikipedia.org/w/index.php?title=Probabilistic\_latent\_semantic\_analysis&oldid=783155225.

Accessed September 2017.