Tock Embedded OS Training

SOSP 2017

Please make sure you have completed all of the tutorial pre-requisites. If you prefer, you can download a virtual machine image with all the pre-requisites already installed.

https://github.com/helena-project/tock/tree/master/doc/courses/sosp/README.md

aka

https://goo.gl/s17fy8

Tock

A secure operating system for microcontrollers

- Kernel components in Rust
- ► Type-safe API for safe driver development
- ► Hardware isolated processes for application code

Microcontrollers

System-on-a-chip with integrated flash, SRAM, CPU and a bunch of hardware controllers.

Typically:

- Communication: UART, SPI, I2C, USB, CAN...
- External I/O: GPIO, external interrupt, ADC, DAC
- ► Timers: RTC, countdown timers

Maybe...

- Radio (Bluetooth, 15.4)
- Cryptographic accelerators
- Other specialized hardware...

Low Resource

- 10's of μA average power draw
- ▶ 10's of kBs of RAM
- Moderate clock speeds

Use cases

- Security applications (e.g. authentication keys)
- Sensor networks
- Programmable wearables
- ► PC/phone peripherals
- ► Home/industrial automation
- ▶ Flight control

Two types of components: capsules and processes

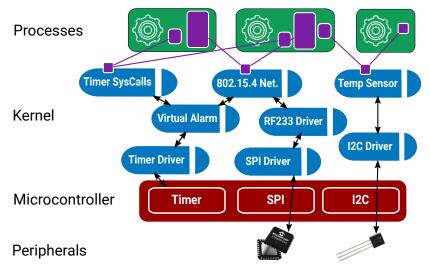


Figure 1

Two types of scheduling: cooperative and preemptive

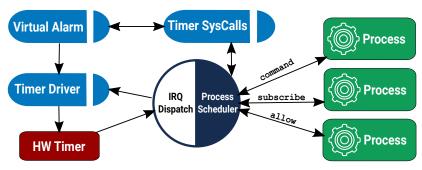


Figure 2

Agenda Today

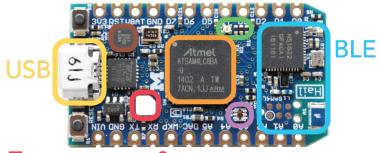
- 1. Intro to hardware, tools and development environment
- 2. Write an end-to-end Bluetooth Low Energy environment sensing application
- 3. Add functionality to the Tock kernel

Part 1: Hardware, tools and development

environment

Hail

SAM4L Accelerometer MCU RGB LED



Temperature & Humidity

Light Sensor

Binaries on-board

Bootloader

Kernel

Processes

Tools

- make (just instrumenting xargo)
- Rust (nightly for asm!, compiling core, etc)
- xargo to automate compiling base libraries
- arm-none-eabi GCC/LD to link binaries
- tockloader to interact with Hail and the bootloader

Tools: tockloader

Write a binary to a particular address in flash

\$ tockloader flash --address 0x1000 \
 target/thumbv7em-none-eabi/release/hail.bin

Program a process in Tock Binary Format¹:

\$ tockloader install myapp.tab

Restart the board and connect to the debug console:

\$ tockloader listen

¹TBFs are relocatable process binaries prefixed with headers like the package name. .tab is a tarball of TBFs for different architectures as well as a metadata file for tockloader.

Check your understanding

- 1. What kinds of binaries exist on a Tock board? Hint: There are three, and only two can be programmed using tockloader.
- 2. Can you point to the chip on the Hail that runs the Tock kernel? How about the processes?
- 3. What steps would you follow to program a processes onto Hail? What about to replace the kernel?

Hands-on: Set-up development environment

- 1. Compile and flash the kernel
- 2. (Optional) Familiarize yourself with tockloader commands
 - ▶ uninstall
 - ▶ list
 - erase-apps
- 3. (Optional) Add some other apps from the repo, like blink and sensors
- Head to http://bit.ly/2lniNt6 to get started!
- (github.com/helena-project/tock/blob/master/doc/courses/sosp/environment.md)

Part 2: User space

System calls

| Call | Target | Description |
|-----------|---------|----------------------------------|
| command | Capsule | Invoke an operation on a capsule |
| allow | Capsule | Share memory with a capsule |
| subscribe | Capsule | Register an upcall |
| memop | Core | Modify memory break |
| yield | Core | Block until next upcall is ready |

C System Calls: command & allow

C System Calls: subscribe

C System Calls: yield & yield_for

```
void yield(void);

void yield_for(bool *cond) {
  while (!*cond) {
    yield();
  }
}
```

Example: printing to the debug console

```
static void putstr_cb(int _x, int _y, int _z, void* ud) {
  putstr data t* data = (putstr data t*)ud;
  data->done = true:
int putnstr(const char *str, size t len) {
  putstr_data_t data;
  data.buf = str;
  data.done = false;
  allow(DRIVER NUM CONSOLE, 1, str, len);
  subscribe(DRIVER_NUM_CONSOLE, 1, putstr_cb, &data);
  command(DRIVER_NUM_CONSOLE, 1, len, 0);
  yield for(&data.done);
  return ret;
}
```

Inter Process Communication (IPC)

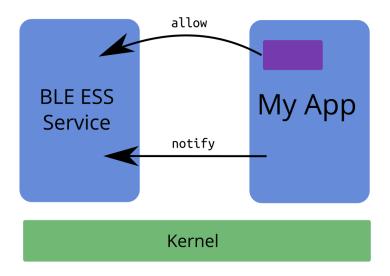


Figure 4

Tock Inter Process Communication Overview

Servers

- Register as an IPC service
- Call notify to trigger callback in connected client
- Receive a callback when a client calls notify

Clients

- Discover IPC services by application name
- ▶ Able to share a buffer with a connected service
- Call notify to trigger callback in connected service
- Receive a callback when service calls notify

Inter Process Communication API

```
// discover IPC service by name
// returns error code or PID for service
int ipc discover(const char* pkg name);
// shares memory slice at address with IPC service
int ipc_share(int pid, void* base, int len);
// register for callback on server `notify`
int ipc_register_client_cb(int pid, subscribe_cb cb,
                           void* userdata);
// trigger callback in service
int ipc_notify_svc(int pid);
// trigger callback in a client
int ipc notify client(int pid);
```

Check your understanding

- How does a process perform a blocking operation? Can you draw the flow of operations when a process calls delay_ms(1000)?
- 2. How would you write an IPC service to print to the console? Which functions would the client need to call?

Hands-on: Write a BLE environment sensing application

- 1. Get an application running on Hail
- 2. Print "Hello World" every second
- 3. Extend your app to sample on-board sensors
- Extend your app to report through the ble-env-sense service
- ► Head to http://bit.ly/2hgpl8n> to get started!
- (github.com/helena-project/tock/blob/master/doc/courses/sosp/application.md)

Part 3: The kernel

Trusted Computing Base (unsafe allowed)

- Hardware Abstraction Layer
- Board configuration
- Event & Process scheduler
- Rust core library
- Core Tock primitives

```
kernel/chips/
```

Capsules (unsafe not allowed)

- Virtualization
- Peripheral drivers
- ► Communication protocols (IP, USB, etc)
- Application logic

capsules/

Constraints

Small isolation units

Breaking a monolithic component into smaller ones should have low/no cost

Avoid memory exhaustion in the kernel

No heap. Everything is allocated statically.

Low communication overhead

Communicating between components as cheap as an internal function call. Ideally inlined.

Event-driven execution model

```
pub fn main<P, C>(platform: &P, chip: &mut C,
                  processes: &mut [Process]) {
    loop {
        chip.service_pending_interrupts();
        for (i, p) in processes.iter_mut().enumerate() {
            sched::do_process(platform, chip, process);
        if !chip.has pending interrupts() {
            chip.prepare for sleep();
            support::wfi();
```

Event-driven execution model

```
fn service pending interrupts(&mut self) {
    while let Some(interrupt) = get interrupt() {
        match interrupt {
            ASTALARM => ast::AST.handle_interrupt(),
            USARTO => usart::USARTO.handle_interrupt(),
            USART1 => usart::USART1.handle_interrupt(),
            USART2 => usart::USART2.handle_interrupt(),
```

Event-driven execution model

```
impl Ast {
    pub fn handle_interrupt(&self) {
        self.clear alarm();
        self.callback.get().map(|cb| { cb.fired(); });
impl time::Client for MuxAlarm {
   fn fired(&self) {
        for cur in self.virtual alarms.iter() {
            if cur.should_fire() {
                cur.armed.set(false);
                self.enabled.set(self.enabled.get() - 1);
                cur.fired();
```

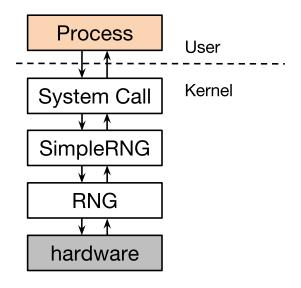


Figure 5: Capsules reference each other directly, assisting inlining

The mutable aliases problem

```
enum NumOrPointer {
  Num(u32),
  Pointer(&mut u32)
// n.b. will not compile
let external : &mut NumOrPointer;
match external {
  Pointer(internal) => {
    // This would violate safety and
    // write to memory at Oxdeadbeef
    *external = Num(Oxdeadbeef);
    *internal = 12345; // Kaboom
  },
```

Interior mutability to the rescue

| Туре | Copy-only | Mutual exclusion | Opt. | Mem Opt. |
|--------------|--------------|------------------|------|----------|
| Cell | ✓ | X | ✓ | ✓ |
| VolatileCell | \checkmark | × | X | ✓ |
| TakeCell | × | ✓ | X | ✓ |
| MapCell | X | ✓ | ✓ | X |

```
pub struct Fxos8700cq<`a> {
  i2c: &`a I2CDevice,
  state: Cell<State>,
  buffer: TakeCell<`static, [u8]>,
  callback:
    Cell<Option<&`a hil::ninedof::NineDofClient>>,
}
impl<`a> I2CClient for Fxos8700cq<`a> {
  fn cmd_complete(&self, buf: &`static mut [u8]) { ... }
impl<`a> hil::ninedof::NineDof for Fxos8700cq<`a> {
  fn read accelerometer(&self) -> ReturnCode { ... }
}
pub trait NineDofClient {
  fn callback(&self, x: usize, y: usize, z: usize);
```

Check your understanding

- What is a VolatileCell? Can you find some uses of VolatileCell, and do you understand why they are needed? Hint: look inside chips/sam4l/src.
- What is a TakeCell? When is a TakeCell preferable to a standard Cell?

Hands-on: Write and add a capsule to the kernel

- 1. Read the Hail boot sequence in boards/hail/src/main.rs
- 2. Write a new capsule that prints "Hello World" to the debug console.
- 3. Extend your capsule to print "Hello World" every second
- 4. Extend your capsule to print light readings every second
- Extra credit
- ► Head to http://bit.ly/2zLoD9W> to get started!
- (github.com/helena-project/tock/blob/master/doc/courses/sosp/capsule.md)

Stay in touch!

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https://www.tockos.org
https://github.com/helena-project/tock
tock-dev@googlegroups.com
#tock on Freenode
Quick Survey!
```

https://goo.gl/ntxsgX