

YOU__a5q4q5

December 1, 2021

1 A5-Q3Q4: DCT and JPEG Compression

```
[32]: import numpy as np
import matplotlib.pyplot as plt
from scipy.fft import fft2, ifft2
```

```
[ ]:
```

1.1 Q3: Discrete Cosine Transform

1.1.1 Some helper functions

```
[3]: def EvenExtension(f):
    '''
    fe = EvenExtension(f)

    Performs an even extension on the array f.

    Input:
    f is a 2D array

    Output:
    fe is the even extension of f

    If f has dimensions N x M, then fe has dimensions
    (2*N-2) x (2*M-2)
    and fe[n,j]=fe[-n,j] for n=0,...,N-1
    and fe[n,j]=fe[n,-j] for j=0,...,M-1

    For example, if f is 5x4, then fe has dimensions 8x6.

    IEvenExtension is the inverse of EvenExtension, so that
    IEvenExtension(EvenExtension(f)) == f
    for any matrix f.

    '''
    fe = np.concatenate((f,np.fliplr(f[:,-1])), axis=1)
```

```

    fe = np.concatenate((fe, np.flipud(fe[1:-1,:])), axis=0)

    return fe

def IEvenExtension(fe):
    '''
        f = IEvenExtension(fe)

        Reverses the action of an even extension.

        Input:
            fe is a 2D array, assumed to contain an even extension

        Output:
            f is the sub-array that was used to generate the extension

        If fe has dimensions  $K \times L$ , then f has dimensions
             $\text{ceil}((K+1)/2) \times \text{ceil}((L+1)/2)$ 
        For example, if fe is  $8 \times 6$ , then f is  $5 \times 4$ .

        IEvenExtension is the inverse of EvenExtension, so that
             $\text{IEvenExtension}(\text{EvenExtension}(f)) == f$ 
        for any matrix f.

    '''
    e_dims = np.array(np.shape(fe))
    dims = np.ceil((e_dims+1.)/2)
    dims = np.array(dims, dtype=int)
    f = fe[:dims[0], :dims[1]]
    #f = fe(1:dims(1),1:dims(2));
    return f

```

[4]: *# First, a simple 1D example.*

```

f = np.array([[1,2,3,4,5]])
fe = EvenExtension(f)
print(fe)

```

```

[[1 2 3 4 5 4 3 2]]

```

[5]: *# Define a simple 2-D array to play with*

```

f = np.array([[1,2,3,4],[5,6,7,8],[9,10,11,12]], dtype=float)
print(f)

```

```

[[ 1.  2.  3.  4.]
 [ 5.  6.  7.  8.]
 [ 9. 10. 11. 12.]]

```

```
[6]: # Even extension
fe = EvenExtension(f)
print(fe)
```

```
[[ 1.  2.  3.  4.  3.  2.]
 [ 5.  6.  7.  8.  7.  6.]
 [ 9. 10. 11. 12. 11. 10.]
 [ 5.  6.  7.  8.  7.  6.]]
```

```
[7]: # Check that it's even, if you don't believe me
n = np.random.randint(np.shape(f)[0])
j = np.random.randint(np.shape(f)[1])
print((n,j))
print(fe[n,j])
print(fe[-n,-j])
```

```
(1, 3)
8.0
8.0
```

```
[8]: # Inverse even extension
g = IEvenExtension(fe)
print(g)
```

```
[[ 1.  2.  3.  4.]
 [ 5.  6.  7.  8.]
 [ 9. 10. 11. 12.]]
```

1.1.2 myDCT

```
[52]: def myDCT(f):
    """
    F = myDCT(f)

    Computes the 2-D Discrete Cosine Transform of input image f.
    It uses an even extension of f, along with the 2D-DFT.
    This function is the inverse of myIDCT.

    Input:
    f is a 2-D array of real values

    Output:
    F is a real-valued array the same size as f
    """
    F = np.zeros_like(f)
    # ===== YOUR CODE HERE =====
    N = len(f)
    M = len(f[0])
```

```

g = EvenExtension(f)
#print("extension:")
#print(g)
G = fft2(g)
#Ng = len(g)
#Mg = len(g[0])
#G = np.zeros_like(g)
#print("N = "+str(N)+"", M = "+str(M)+"", Ng = "+str(Ng)+"", Mg = "+str(Mg)")
#WNg = np.exp([2*np.pi*np.sqrt(-1+0j)/Ng])[0]
#WMg = np.exp([2*np.pi*np.sqrt(-1+0j)/Mg])[0]
#for k in range(Ng):
#    for l in range(Mg):
#        for n in range(Ng):
#            for m in range(Mg):
#                G[k][l] += g[n][m]*pow(WNg, -n*k)*pow(WMg, -m*l)
#            G[k][l] = G[k][l]*1/(Ng*Mg)

for k in range(N):
    for l in range(M):
        F[k][l] = G[k][l]

return np.real(F)

```

1.1.3 myIDCT

```

[53]: def myIDCT(F):
    '''
        f = myIDCT(F)

        Computes the 2-D Inverse Discrete Cosine Transform (IDCT) of input
        array Fdct. It uses an even extension of Fdct, along with the 2D-IDFT.
        This function is the inverse of myDCT.

        Input:
            F is a 2-D array of real values

        Output:
            f is a real-valued array the same size as Fdct
    '''
    f = np.zeros_like(F)
    g = np.zeros_like(F)
    # ===== YOUR CODE HERE =====
    #N = len(F)
    #M = len(F[0])
    #WN = np.exp([2*np.pi*np.sqrt(-1+0j)/N])[0]
    #WM = np.exp([2*np.pi*np.sqrt(-1+0j)/M])[0]
    #for k in range(N):

```

```

#     for l in range(M):
#         for n in range(N):
#             for m in range(M):
#                 g[k][l] += F[n][m]*pow(WN,n*k)*pow(WM,m*l)
#
F2 = EvenExtension(F)
g = ifft2(F2)
f = IEvenExtension(g)

return np.real(f)

```

```

[54]: from scipy.fft import dct, idct
f = np.array([[1,2,3,4],[5,6,7,8],[9,10,11,12]], dtype=float)
print(f)
F = myDCT(f)
Freal = dct(dct(f.T, type=1).T, type=1)
print("found F:")
print(F)
print("actual F:")
print(Freal)
g = myIDCT(F)
print(g)
greal = np.real(idct(idct(Freal.T, type=1).T, type=1))
print(greal)

```

```

[[ 1.  2.  3.  4.]
 [ 5.  6.  7.  8.]
 [ 9. 10. 11. 12.]]
found F:
[[ 1.56000000e+02 -1.60000000e+01 -8.8817842e-16 -4.00000000e+00]
 [-4.80000000e+01  0.00000000e+00  0.00000000e+00  0.00000000e+00]
 [ 0.00000000e+00  0.00000000e+00  0.00000000e+00  0.00000000e+00]]
actual F:
[[ 1.56000000e+02 -1.60000000e+01 -8.8817842e-16 -4.00000000e+00]
 [-4.80000000e+01  0.00000000e+00  0.00000000e+00  0.00000000e+00]
 [ 0.00000000e+00  0.00000000e+00  0.00000000e+00  0.00000000e+00]]
[[ 1.  2.  3.  4.]
 [ 5.  6.  7.  8.]
 [ 9. 10. 11. 12.]]
[[ 1.  2.  3.  4.]
 [ 5.  6.  7.  8.]
 [ 9. 10. 11. 12.]]

```

/srv/jupyter_python3-extras/lib/python3.7/site-packages/ipykernel_launcher.py:38: ComplexWarning: Casting complex values to real discards the imaginary part

1.2 Here are some built-in implementations...

... in case you're having trouble with myDCT and myIDCT.

```
[55]: # '''
# These work for 2D arrays only.
# '''
# from scipy.fft import dct, idct
# def myDCT(f):
#     t = 1
#     return dct(dct(f.T, type=t).T, type=t)
# def myIDCT(F):
#     return np.real(idct(idct(F.T, type=1).T, type=1))
```

1.3 Q4: JPEG Compression

```
[56]: # A couple functions to help you
def NumPixels(f):
    '''
    n = NumPixels(f) returns the total number of elements in the array f.

    For example,
    NumPixels( np.ones((5,4)) )
    returns the value 20.
    '''
    return np.prod(np.shape(f))

def Show(g, title=''):
    '''
    Show(g, title='')

    Displays the image g as a graylevel image with intensities
    clipped to the range [0,255].
    '''
    plt.imshow(np.clip(g, a_min=0, a_max=255), cmap='gray');
    plt.axis('off');
    plt.title(title);
```

1.3.1 myJPEGCompress

```
[65]: def myJPEGCompress(f, T, D):
    '''
    G = myJPEGCompress(f, T, D)

    Input
    f is the input image, a 2D array of real numbers
    T is the tile size to break the input image into
```

*D is the size of the block of Fourier coefficients to keep
(Bigger values of D result in less loss, but less compression)*

Output

G is the compressed encoding of the image

Example: If f is 120x120, then

G = myJPEGCompress(f, 10, 4)

would return an array (G) of size 48x48.

'''

h,w = np.shape(f) # returns the width and height of f

*G = np.zeros((int(np.floor(h/T)*D), int(np.floor(w/T)*D))) # this is not*

↪ guaranteed to be the right size

===== YOUR CODE HERE =====

for i in range(int(np.floor(h/T))):

for j in range(int(np.floor(w/T))):

tile = np.zeros((T,T))

for k in range(T):

for l in range(T):

*tile[k][l] = f[i*T+k][j*T+l]*

tileDCT = myDCT(tile)

for k in range(D):

for l in range(D):

*G[i*D+k][j*D+l] = tileDCT[k][l]*

return G

1.3.2 myJPEGDecompress

[66]: `def myJPEGDecompress(G, T, D):`

'''

f = myJPEGDecompress(G, T, D)

Input

G is the compressed encoding, a 2D array of real numbers

T is the tile size for reassembling the decompressed image

*D is the size of the blocks of Fourier coefficients that were
kept when the image was compressed*

(Bigger values of D result in less loss, but less compression)

Output

f is the decompressed, reconstructed image

Example: If G is 48x48, then

```

    f = myJPEGDecompress(G, 10, 4);

    would return an array (f) of size 120x120.
    '''
n_hblocks = int( np.shape(G)[0]/D )
n_wblocks = int( np.shape(G)[1]/D )

f = np.zeros( (T*n_hblocks, T*n_wblocks) )

wblocks = np.arange(0, np.shape(f)[1], T)
hblocks = np.arange(0, np.shape(f)[0], T)

# ==== YOUR CODE HERE ====
for i in range(n_hblocks):
    for j in range(n_wblocks):
        tile = np.zeros((T,T))
        for k in range(D):
            for l in range(D):
                tile[k][l] = G[i*D+k][j*D+l]
        Ttile = myIDCT(tile)
        for k in range(T):
            for l in range(T):
                f[i*T+k][j*T+l] = Ttile[k][l]

return f

```

1.3.3 Demonstrate Compression

```

[67]: f = plt.imread('Jinan.jpg')[:, :, 0]
      Show(f)

```




```
[72]: # Set the tile size
T = 10
```

```
[73]: # Compression ratio 2:1
D = 7
compressed1 = myJPEGCompress(f, T, D)
decompressed1 = myJPEGDecompress(compressed1, T, D)
```

/srv/jupyter_python3-extras/lib/python3.7/site-packages/ipykernel_launcher.py:38: ComplexWarning: Casting complex values to real discards the imaginary part

```
[74]: # Compression ratio 4:1
D = 5
compressed2 = myJPEGCompress(f, T, D)
decompressed2 = myJPEGDecompress(compressed2, T, D)
```

/srv/jupyter_python3-extras/lib/python3.7/site-packages/ipykernel_launcher.py:38: ComplexWarning: Casting complex values to real discards the imaginary part

```
[75]: # Compression ratio 25:1
D = 2
compressed3 = myJPEGCompress(f, T, D)
decompressed3 = myJPEGDecompress(compressed3, T, D)
```

/srv/jupyter_python3-extras/lib/python3.7/site-packages/ipykernel_launcher.py:38: ComplexWarning: Casting complex values to real discards the imaginary part

```
[77]: # Plot your reconstructions.
plt.figure(figsize=(15,12))
plt.subplot(2,2,1); Show(f, title='Original');
# === YOUR CODE HERE ===
plt.figure(figsize=(15,12))
plt.subplot(2,2,1);
Show(decompressed1, '2:1')
plt.figure(figsize=(15,12))
plt.subplot(2,2,1);
Show(decompressed2, '4:1')
plt.figure(figsize=(15,12))
plt.subplot(2,2,1);
Show(decompressed3, '25:1')
```

Original



2:1



4:1



25:1



[]:

[]: