# The Mathematics of Deep Learning

UT Tyler Math Club

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# Al Balderdash

Five of the following are real mathematical terms (from encyclopediaofmath.org), and five were generated using a neural network. Guess which are which!

- (real) V 1 Nephroid
- (fake) X @ Axtric group
  - X @ Polthedo-prime varceset assusting and quasi-logarithmic residue

  - Cohn-Vossen transformation
  - B-Phi-structure
  - Antimatroid
  - X @ Rebuture condition
  - Generatrix

Here's a further sampling from the Al-generated category:

Sylthetial measure

Harbynskay square

Merten algebra

D0L-sequence

Brayamingor projector

Bikeanov theorem

Sortenkeveâdynami newarger problem

Commutants, method of

Banosi reparnections

Loxic group

Bloschteghans theorem

Finite-Hopgeostal category

Errsen errorplination transform

Abne-lays formula

Snav hoooten Ontle

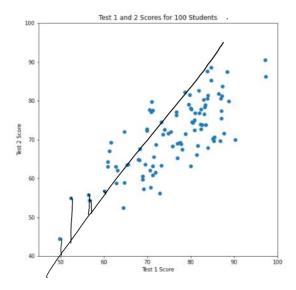
Lie belivid-Floqued substatistic

Sumpay of a curve

The main goal of this talk is to explain some of the mathematics behind neural networks like the one that generated these phrases. Some of the mathematical concepts we'll encounter along the way are:

- Using derivatives for optimization;
- ② Probabilities;
- 3 The function  $\sigma(x) = \frac{1}{1 + e^{-x}}$  and its basic properties;
- Using logs to convert a product into a sum;
- The Chain Rule;
- Nightmarish proliferation of notation.

Suppose that the following graph shows Test 1 and Test 2 scores for 90 students in a course, and we wish to find the line that best captures the relationship between these points.



The most common measure of how well a line fits a collection of points is called the "mean squared error"—this is the average of the squares of the vertical distances from each point to the line. If the points given are

$$(x_1, y_1), (x_2, y_2), \ldots, (x_n, y_n),$$

then mean squared error to a line y = mx is

$$MSE = \frac{1}{n} \left( (y_1 - mx_1)^2 + (y_2 - mx_2)^2 + \dots + (y_n - mx_n)^2 \right).$$

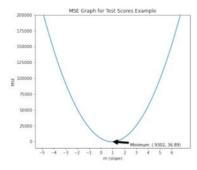
The goal then is to find the value of m that makes MSE as small as possible. This sounds like a job for...

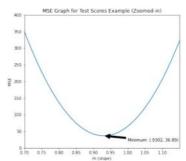
### Bloschteghans theorem!!!

I mean, calculus. Setting the derivative of MSE (with respect to the variable m) equal to 0 and solving gives that the optimal m is:

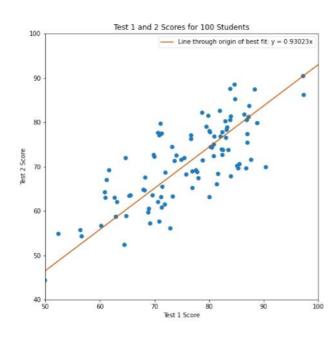
$$m_{bestest} = \frac{x_1 y_1 + x_2 y_2 + \cdots + x_n y_n}{x_1^2 + x_2^2 + \cdots + x_n^2}.$$

Here's a graph of MSE against m for the student test scores example:



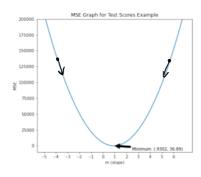


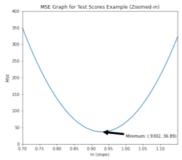
And here's the resulting line through the origin of best fit:



Having a closed form solution for  $m_{bestest}$  is nice, but could become very costly to compute in more complicated situations. An alternate approach is start somewhere on the curve, compute the derivative, and let that tell you where to go.

More specifically, we could guess an initial  $m_0$ , compute  $MSE'(m_0)$ , update our slope to  $m_1=m_0-0.1MSE'(m_0)$ , and so on.



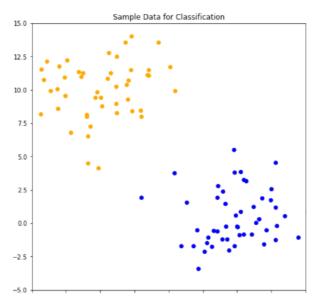


(See visualization.)

To recap what we did in terms we can generalize, we:

- ① Started with labeled data: (x, y).
- ② Chose a model: y = mx. (one parameter, m)
- 3 Chose a "cost function": MSE.
- $oldsymbol{\Theta}$  Optimized to find the m that minimized the cost.

Moving on to a new problem, suppose we have a bunch of points labeled either blue or orange as in the following, and we wish to get a computer to "learn" what the difference is and be able to decide the color of any future dots we provide to it.



Going through the same process as above, we have:

1 Labeled data: (x,y,c)

$$C = \begin{cases} 1 & \text{if } (m, x + m, y + b) = \frac{1}{2} \\ 0 & \text{if } (m, x + m, y + b) < \frac{1}{2} \end{cases}$$

Model:

$$C = \begin{cases} 1 & \text{if } (m, x + m, y + b) = \frac{1}{2} \\ 0 & \text{if } (m, x + m, y + b) < \frac{1}{2} \end{cases} \text{ (three parameters)}$$

3 Cost function:

$$- \int (m_1, m_2, b) = \begin{cases} p_1 & \text{if } c_1 = 1 \\ (-p_1) & \text{if } c_2 = 0 \end{cases} \begin{pmatrix} p_2 & \text{if } c_2 = 1 \\ (-p_1) & \text{if } c_3 = 0 \end{pmatrix} \begin{pmatrix} p_2 & \text{if } c_4 = 1 \\ (-p_1) & \text{if } c_4 = 0 \end{pmatrix}$$

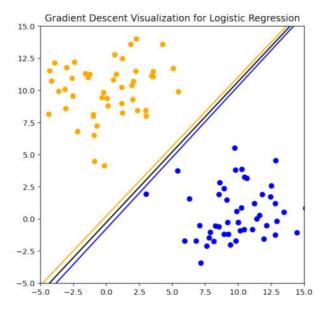
4 Optimize:

$$= \frac{1}{N} \left( c_1 \ln p_1 + \left( (-c) \ln \left( (-p_1) \right) + \cdots + \left( (-c) \ln \left( (-p_1) \right) + \cdots + \left( (-c) \ln \left( (-p_1) \right) + \cdots + (-c) \ln \left( (-p_1) \right) + \cdots + (-c) \ln \left( (-p_1) \right) + \cdots + (-c) \ln \left( (-p_1) \right) \end{pmatrix}$$

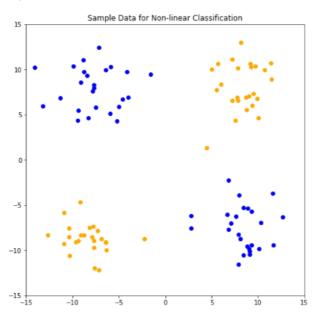
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### Here's the result on the data above:



In the previous demonstration, the decision boundary was always a line. What if our data looks like this though? A logistic regression would be hopeless...

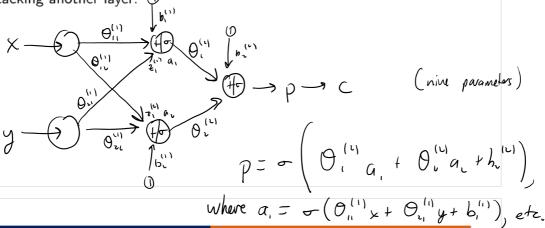


## Neural networks!

The logistic regression model we used above can be graphed like this:  $\mathbb{Q}$ 

 $y \xrightarrow{m_1} p \xrightarrow{p} c$ 

Taking inspiration from neurons in the brain (or perhaps just driven by pure masochism), we can ramp up the complexity by stacking another layer:  $\bigcirc$ 



Neural networks are generally unwieldy, but nowadays people have tamed them pretty well. In general, they could have any number of layers and neurons per layer. There are also several important specialty architectures that are used for computer vision, natural language processing, etc.

As for training a neural network, the simplest effective algorithm is gradient descent, where the derivatives are computed via a process called backpropogation, which relies on the Chain Rule from calculus.

If f, g, and h are all differentiable functions, then the derivative of  $f \circ g \circ h$  is given by

$$\int_{0}^{1} \left( g \left( h(x) \right) \right) g \left( h(x) \right) h'(x) = \frac{df}{dg} \cdot \frac{dg}{dh} \cdot \frac{dh}{dx}$$
Wouldn't it be fun to work out the derivatives  $\frac{\partial J}{\partial \theta_{1}^{(2)}}$  and  $\frac{\partial J}{\partial \theta_{1}^{(1)}}$ ?!

(For one impet.)

$$\frac{\partial \mathcal{J}}{\partial \theta_{i}^{(2)}} = \frac{\partial \mathcal{J}}{\partial \rho} \cdot \frac{\partial \rho}{\partial z^{(2)}} \cdot \frac{\partial z^{(2)}}{\partial \theta_{i}^{(2)}} = \frac{\partial \mathcal{J}}{\partial \rho} \cdot \frac{\partial \rho}{\partial z^{(2)}} \cdot \frac{\partial z^{(2)}}{\partial \rho_{i}^{(2)}} \cdot \frac{\partial z^{(2)}}{\partial \rho_{i}^{$$

(using 
$$J = c \ln p + (1-c) \ln (1-p)$$
,  $p = \sigma(z^{(2)})$ ,  $z^{(1)} = \Theta_{i}^{(1)}a_{i}$ ,  $a_{i} = \sigma(z_{i}^{(1)})$ ,  $z_{i}^{(1)} = \Theta_{i}^{(1)}x + \Theta_{i}^{(1)}y + b_{i}^{(1)}$ )

Thank you!