

Lecture 2: Lagrangian discretization of evolution equations using optimal transport

Quentin Mérigot

Joint work with Jean-Marie Mirebeau, Thomas Gallouët,
Hugo Leclerc, Filippo Santambrogio, Federico Stra

CEA/EDF/Inria School on Computational Optimal transport, Paris, 2019

1. Optimal quantization

Optimal transport and optimal quantization

What is the best way to approximate a given probability density ρ on \mathbb{R}^d with a uniform measure $\frac{1}{N} \sum_i \delta_{y_i}$ over N points?

Optimal transport and optimal quantization

What is the best way to approximate a given probability density ρ on \mathbb{R}^d with a uniform measure $\frac{1}{N} \sum_i \delta_{y_i}$ over N points?

Wasserstein distance between two probability measures ρ, ν on \mathbb{R}^d ,

$$W_2^2(\rho, \nu) = \min \left\{ \int \|x - y\|^2 d\gamma(x, y) \mid \gamma \in \Gamma(\rho, \nu) \right\},$$

where $\Gamma(\rho, \nu)$ = probability measures on $\mathbb{R}^d \times \mathbb{R}^d$ with marginals ρ and ν .

Optimal transport and optimal quantization

What is the best way to approximate a given probability density ρ on \mathbb{R}^d with a uniform measure $\frac{1}{N} \sum_i \delta_{y_i}$ over N points?

Wasserstein distance between two probability measures ρ, ν on \mathbb{R}^d ,

$$W_2^2(\rho, \nu) = \min \left\{ \int \|x - y\|^2 d\gamma(x, y) \mid \gamma \in \Gamma(\rho, \nu) \right\},$$

where $\Gamma(\rho, \nu)$ = probability measures on $\mathbb{R}^d \times \mathbb{R}^d$ with marginals ρ and ν .

Optimal quantization: minimize $\mathcal{D} : (y_1, \dots, y_N) \in \mathbb{R}^{dN} \mapsto \frac{N}{2} W_2^2(\rho, \frac{1}{N} \sum_i \delta_{y_i})$

Optimal transport and optimal quantization

What is the best way to approximate a given probability density ρ on \mathbb{R}^d with a uniform measure $\frac{1}{N} \sum_i \delta_{y_i}$ over N points?

Wasserstein distance between two probability measures ρ, ν on \mathbb{R}^d ,

$$W_2^2(\rho, \nu) = \min \left\{ \int \|x - y\|^2 d\gamma(x, y) \mid \gamma \in \Gamma(\rho, \nu) \right\},$$

where $\Gamma(\rho, \nu)$ = probability measures on $\mathbb{R}^d \times \mathbb{R}^d$ with marginals ρ and ν .

Optimal quantization: minimize $\mathcal{D} : (y_1, \dots, y_N) \in \mathbb{R}^{dN} \mapsto \frac{N}{2} W_2^2(\rho, \frac{1}{N} \sum_i \delta_{y_i})$

- ▶ **Applications:** numerical integration, meshing, statistics, clustering, etc.

Optimal transport and optimal quantization

What is the best way to approximate a given probability density ρ on \mathbb{R}^d with a uniform measure $\frac{1}{N} \sum_i \delta_{y_i}$ over N points?

Wasserstein distance between two probability measures ρ, ν on \mathbb{R}^d ,

$$W_2^2(\rho, \nu) = \min \left\{ \int \|x - y\|^2 d\gamma(x, y) \mid \gamma \in \Gamma(\rho, \nu) \right\},$$

where $\Gamma(\rho, \nu)$ = probability measures on $\mathbb{R}^d \times \mathbb{R}^d$ with marginals ρ and ν .

Optimal quantization: minimize $\mathcal{D} : (y_1, \dots, y_N) \in \mathbb{R}^{dN} \mapsto \frac{N}{2} W_2^2(\rho, \frac{1}{N} \sum_i \delta_{y_i})$

- ▶ **Applications:** numerical integration, meshing, statistics, clustering, etc.
- ▶ Non-convex optimization problem, usually solved via gradient descent.

Optimal transport and optimal quantization

What is the best way to approximate a given probability density ρ on \mathbb{R}^d with a uniform measure $\frac{1}{N} \sum_i \delta_{y_i}$ over N points?

Wasserstein distance between two probability measures ρ, ν on \mathbb{R}^d ,

$$W_2^2(\rho, \nu) = \min \left\{ \int \|x - y\|^2 d\gamma(x, y) \mid \gamma \in \Gamma(\rho, \nu) \right\},$$

where $\Gamma(\rho, \nu)$ = probability measures on $\mathbb{R}^d \times \mathbb{R}^d$ with marginals ρ and ν .

Optimal quantization: minimize $\mathcal{D} : (y_1, \dots, y_N) \in \mathbb{R}^{dN} \mapsto \frac{N}{2} W_2^2(\rho, \frac{1}{N} \sum_i \delta_{y_i})$

- ▶ **Applications:** numerical integration, meshing, statistics, clustering, etc.
- ▶ Non-convex optimization problem, usually solved via gradient descent.
- ▶ Need to compute the squared Wasserstein distance \mathcal{D} (and $\nabla \mathcal{D}$) efficiently...

Optimal transport and optimal quantization

What is the best way to approximate a given probability density ρ on \mathbb{R}^d with a uniform measure $\frac{1}{N} \sum_i \delta_{y_i}$ over N points?

Wasserstein distance between two probability measures ρ, ν on \mathbb{R}^d ,

$$W_2^2(\rho, \nu) = \min \left\{ \int \|x - y\|^2 d\gamma(x, y) \mid \gamma \in \Gamma(\rho, \nu) \right\},$$

where $\Gamma(\rho, \nu)$ = probability measures on $\mathbb{R}^d \times \mathbb{R}^d$ with marginals ρ and ν .

Optimal quantization: minimize $\mathcal{D} : (y_1, \dots, y_N) \in \mathbb{R}^{dN} \mapsto \frac{N}{2} W_2^2(\rho, \frac{1}{N} \sum_i \delta_{y_i})$

Recall: Computing $\mathcal{D}(y_1, \dots, y_N) \iff$ Finding $\psi \in \mathbb{R}^N$ s.t. $\forall i, \rho(\text{Lag}_i(\psi)) = \frac{1}{N}$.

where $\text{Lag}_i(\psi) = \{x \in \mathbb{R}^d \mid \forall j, \|x - y_i\|^2 + \psi_i \leq \|x - y_j\|^2 + \psi_j\}$.

Optimal transport and optimal quantization

What is the best way to approximate a given probability density ρ on \mathbb{R}^d with a uniform measure $\frac{1}{N} \sum_i \delta_{y_i}$ over N points?

Wasserstein distance between two probability measures ρ, ν on \mathbb{R}^d ,

$$W_2^2(\rho, \nu) = \min \left\{ \int \|x - y\|^2 d\gamma(x, y) \mid \gamma \in \Gamma(\rho, \nu) \right\},$$

where $\Gamma(\rho, \nu)$ = probability measures on $\mathbb{R}^d \times \mathbb{R}^d$ with marginals ρ and ν .

Optimal quantization: minimize $\mathcal{D} : (y_1, \dots, y_N) \in \mathbb{R}^{dN} \mapsto \frac{N}{2} W_2^2(\rho, \frac{1}{N} \sum_i \delta_{y_i})$

Recall: Computing $\mathcal{D}(y_1, \dots, y_N) \iff$ Finding $\psi \in \mathbb{R}^N$ s.t. $\forall i, \rho(\text{Lag}_i(\psi)) = \frac{1}{N}$.

where $\text{Lag}_i(\psi) = \{x \in \mathbb{R}^d \mid \forall j, \|x - y_i\|^2 + \psi_i \leq \|x - y_j\|^2 + \psi_j\}$.

For such a ψ , the quantization energy and its gradient are given by

$$\mathcal{D}(y_1, \dots, y_N) = \frac{N}{2} \sum_i \int_{\text{Lag}_i(\psi)} \|x - y_i\|^2 d\rho(x)$$

Optimal transport and optimal quantization

What is the best way to approximate a given probability density ρ on \mathbb{R}^d with a uniform measure $\frac{1}{N} \sum_i \delta_{y_i}$ over N points?

Wasserstein distance between two probability measures ρ, ν on \mathbb{R}^d ,

$$W_2^2(\rho, \nu) = \min \left\{ \int \|x - y\|^2 d\gamma(x, y) \mid \gamma \in \Gamma(\rho, \nu) \right\},$$

where $\Gamma(\rho, \nu)$ = probability measures on $\mathbb{R}^d \times \mathbb{R}^d$ with marginals ρ and ν .

Optimal quantization: minimize $\mathcal{D} : (y_1, \dots, y_N) \in \mathbb{R}^{dN} \mapsto \frac{N}{2} W_2^2(\rho, \frac{1}{N} \sum_i \delta_{y_i})$

Recall: Computing $\mathcal{D}(y_1, \dots, y_N) \iff$ Finding $\psi \in \mathbb{R}^N$ s.t. $\forall i, \rho(\text{Lag}_i(\psi)) = \frac{1}{N}$.

where $\text{Lag}_i(\psi) = \{x \in \mathbb{R}^d \mid \forall j, \|x - y_i\|^2 + \psi_i \leq \|x - y_j\|^2 + \psi_j\}$.

For such a ψ , the quantization energy and its gradient are given by

$$\mathcal{D}(y_1, \dots, y_N) = \frac{N}{2} \sum_i \int_{\text{Lag}_i(\psi)} \|x - y_i\|^2 d\rho(x)$$

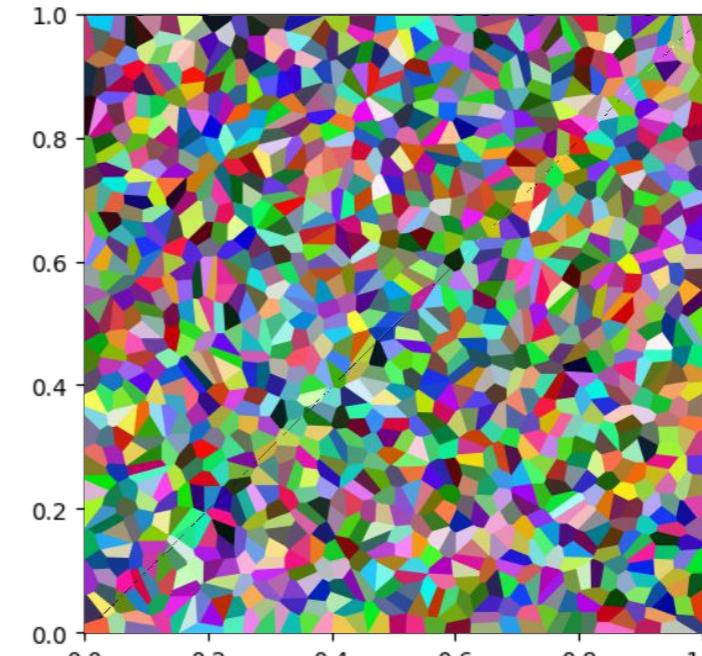
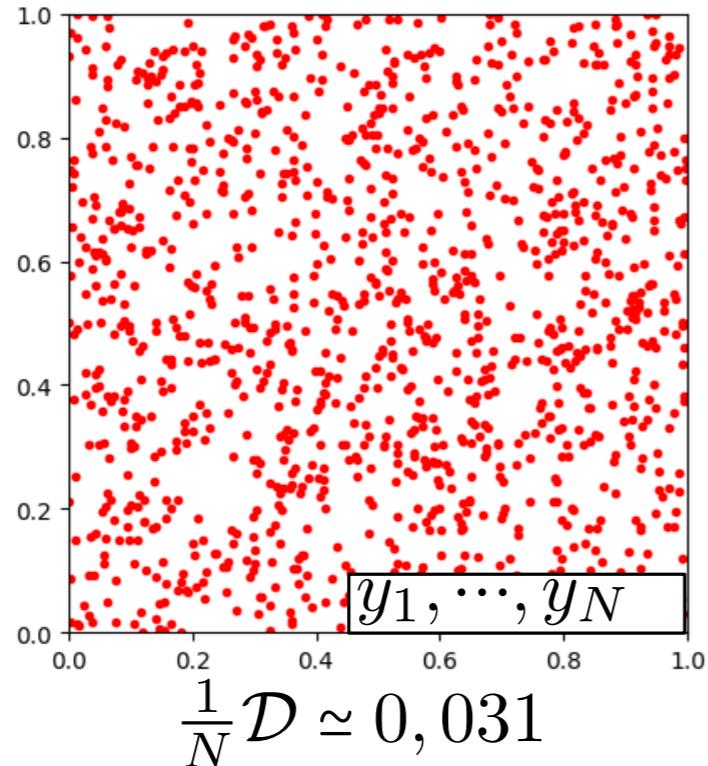
$$\nabla_{y_i} \mathcal{D}(y_1, \dots, y_N) = y_i - \boxed{\text{bary}(\text{Lag}_i(\psi))}$$

$$= B_i(y_1, \dots, y_N)$$

Computing \mathcal{D} (incompressibility) — example

- ▶ **Example 1:** $N = 900$, $\rho_0 = \text{Leb}_{[0,1]^2}$.

$$\mathcal{D}(y_1, \dots, y_N) = \frac{N}{2} W_2^2(\rho_0, \frac{1}{N} \sum_i \delta_{y_i})$$

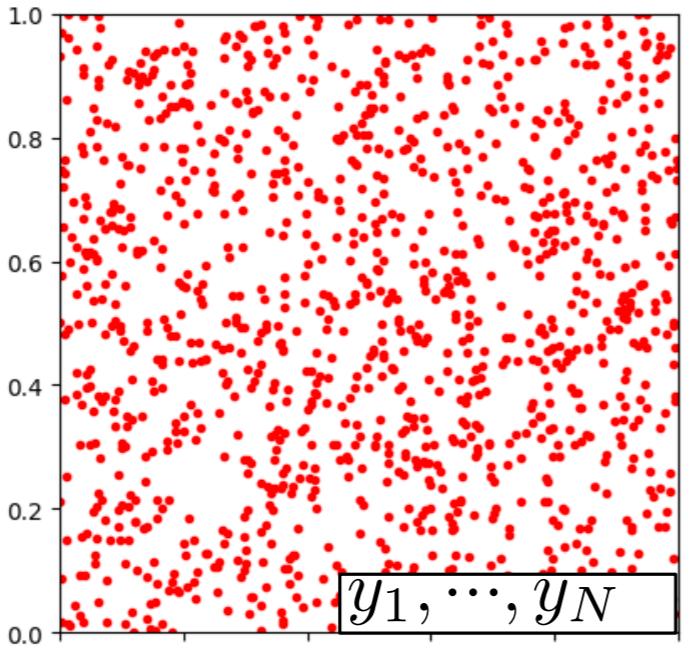


$V_i = T^{-1}(y_i)$ (Laguerre diagram)

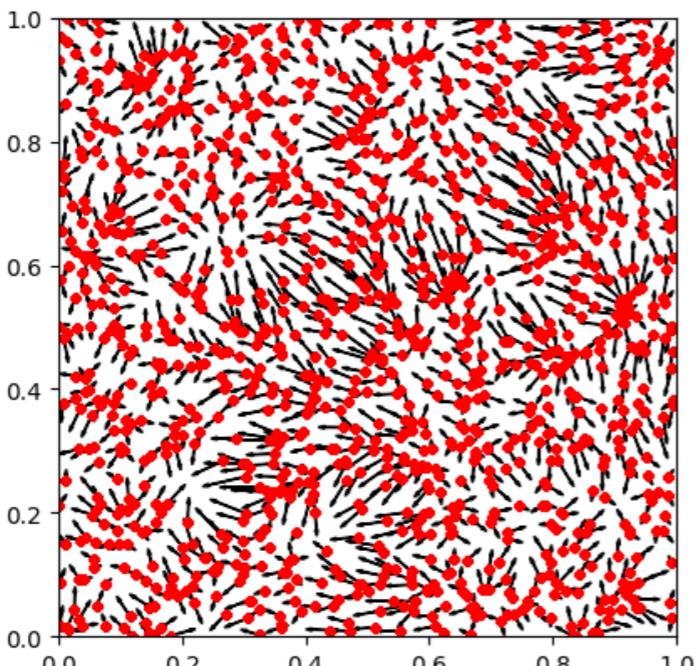
Computing \mathcal{D} (incompressibility) — example

- ▶ **Example 1:** $N = 900$, $\rho_0 = \text{Leb}_{[0,1]^2}$.

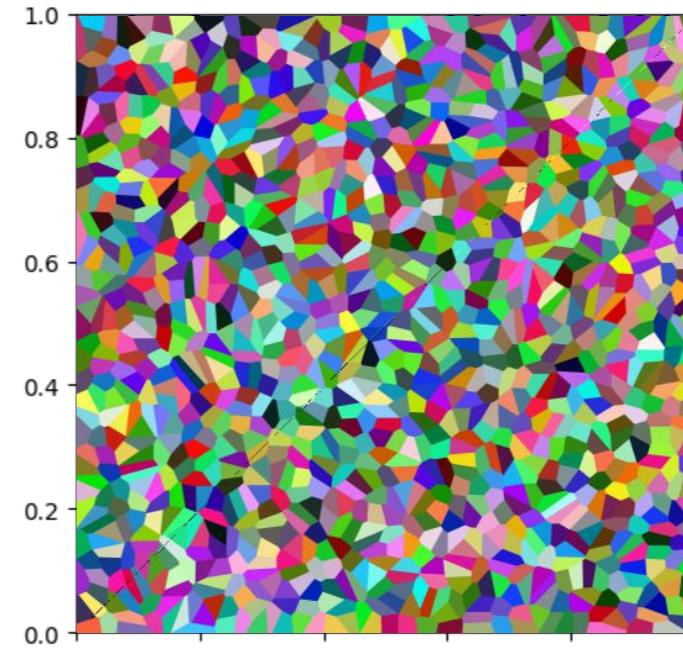
$$\mathcal{D}(y_1, \dots, y_N) = \frac{N}{2} W_2^2(\rho_0, \frac{1}{N} \sum_i \delta_{y_i})$$



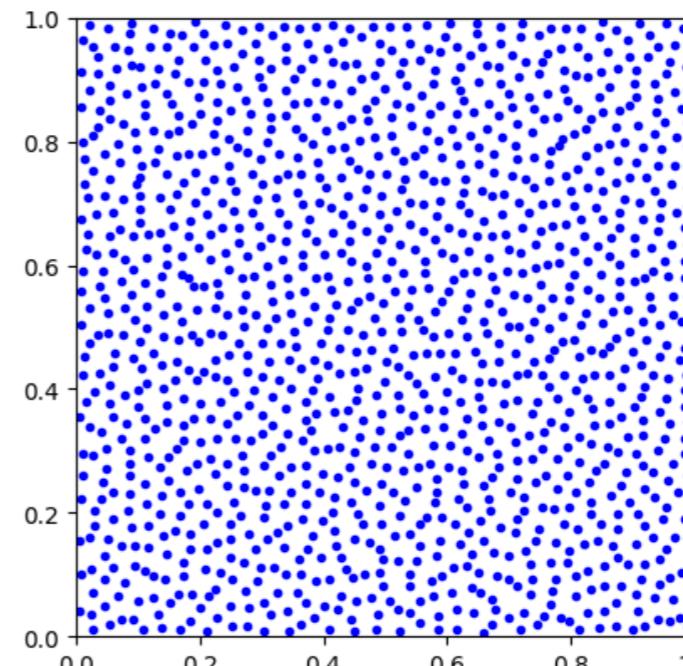
$$\frac{1}{N} \mathcal{D} \simeq 0,031$$



$$(-\nabla_{y_i} \mathcal{D})_{1 \leq i \leq N}$$



$$V_i = T^{-1}(y_i) \text{ (Laguerre diagram)}$$



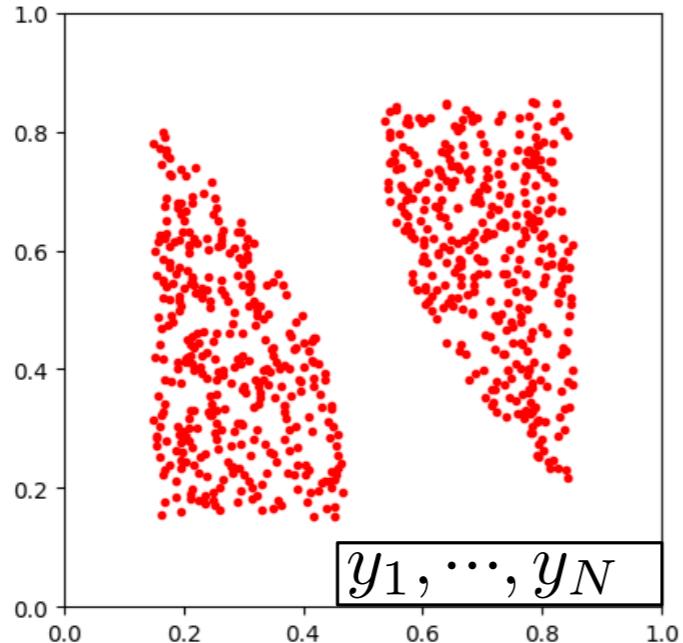
$$(y_i - \nabla_{y_i} \mathcal{D})_{1 \leq i \leq N}$$

Computing \mathcal{D} (incompressibility) — example

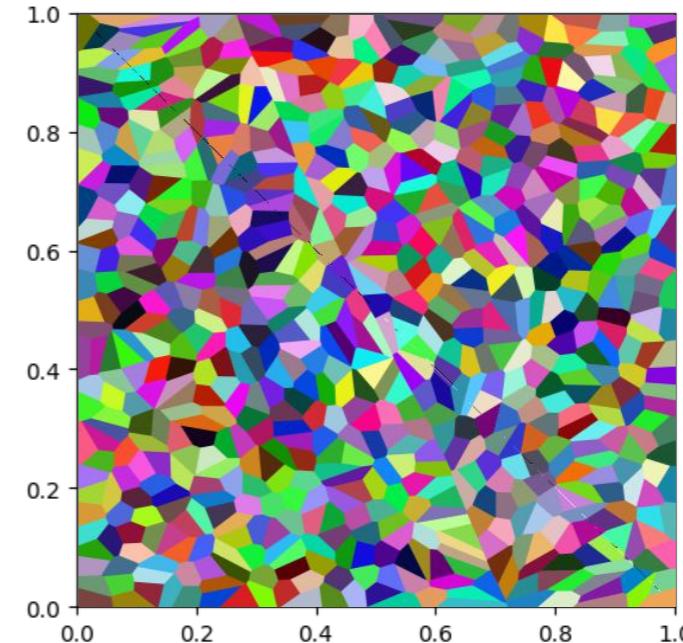


Example 2: $N = 740$, $\rho_0 = \text{Leb}_{[0,1]^2}$.

$$\mathcal{D}(y_1, \dots, y_N) = \frac{N}{2} W_2^2(\rho_0, \frac{1}{N} \sum_i \delta_{y_i})$$



$$\frac{1}{N} \mathcal{D} \simeq 0,15$$

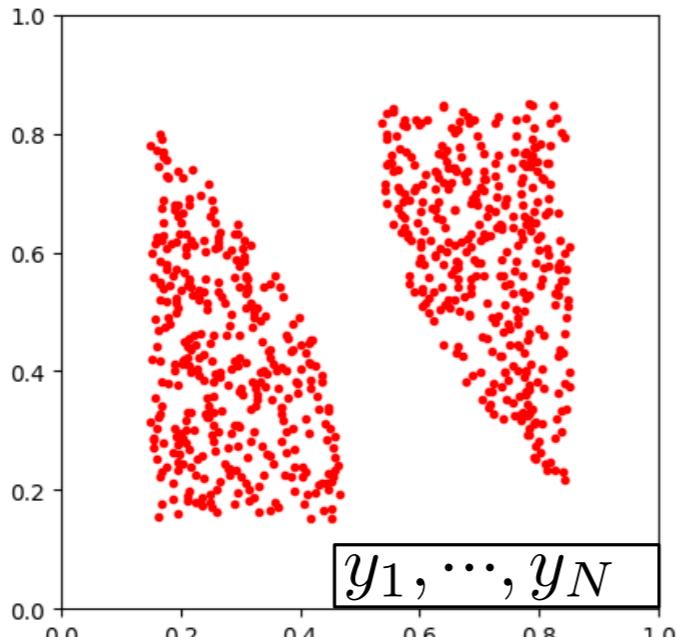


$$V_i = T^{-1}(y_i) \text{ (Laguerre diagram)}$$

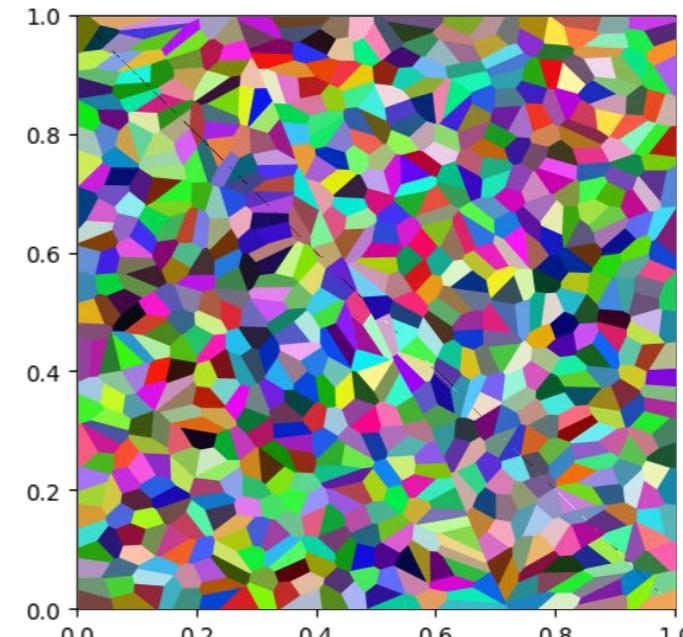
Computing \mathcal{D} (incompressibility) — example

- **Example 2:** $N = 740$, $\rho_0 = \text{Leb}_{[0,1]^2}$.

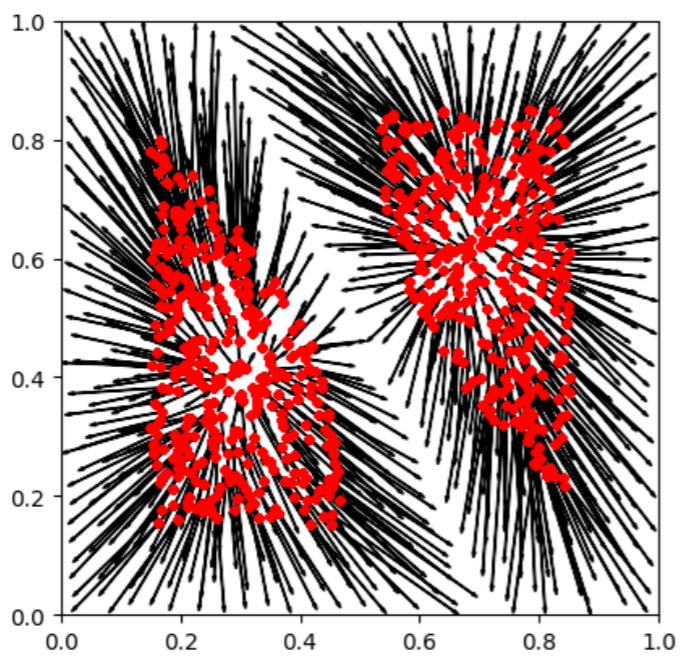
$$\mathcal{D}(y_1, \dots, y_N) = \frac{N}{2} W_2^2(\rho_0, \frac{1}{N} \sum_i \delta_{y_i})$$



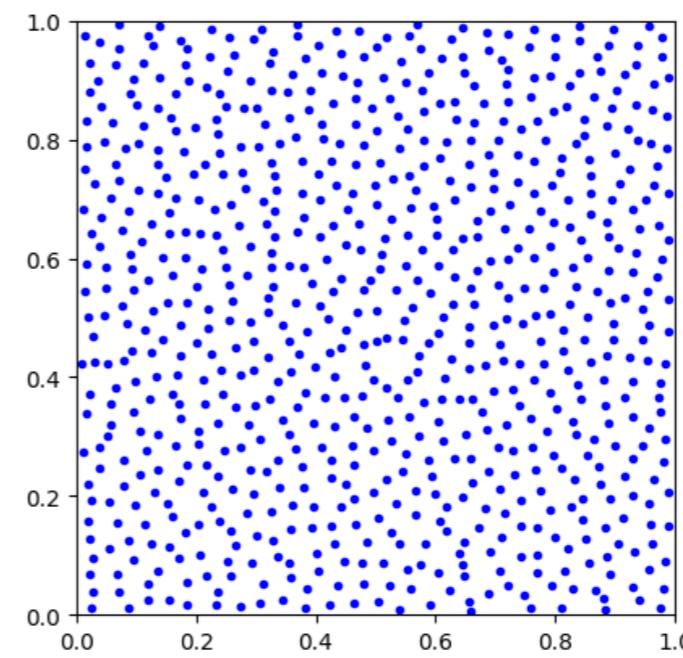
$$\frac{1}{N} \mathcal{D} \simeq 0,15$$



$$V_i = T^{-1}(y_i) \text{ (Laguerre diagram)}$$



$$(-\nabla_{y_i} \mathcal{D})_{1 \leq i \leq N}$$



$$(y_i - \nabla_{y_i} \mathcal{D})_{1 \leq i \leq N}$$

Optimal quantization as a gradient flow

$$\mathcal{D} : y = (y_1, \dots, y_N) \in \mathbb{R}^{Nd} \mapsto \frac{N}{2} W_2^2(\rho, \frac{1}{N} \sum_i \delta_{y_i})$$

$$\begin{cases} \dot{y}(t) = -\nabla \mathcal{D}(y(t)) \\ y(0) = y_0 \in \mathbb{R}^{Nd} \end{cases}$$

Optimal quantization as a gradient flow

$$\mathcal{D} : y = (y_1, \dots, y_N) \in \mathbb{R}^{Nd} \mapsto \frac{N}{2} W_2^2(\rho, \frac{1}{N} \sum_i \delta_{y_i})$$

$$\begin{cases} \dot{y}(t) = -\nabla \mathcal{D}(y(t)) \\ y(0) = y_0 \in \mathbb{R}^{Nd} \end{cases}$$

$$\iff \begin{cases} \dot{y}_i(t) = -(B_i(y_1(t), \dots, y_N(t)) - y_i(t)) \\ y(0) = y_0 \in \mathbb{R}^{Nd} \end{cases}$$

Optimal quantization as a gradient flow

$$\mathcal{D} : y = (y_1, \dots, y_N) \in \mathbb{R}^{Nd} \mapsto \frac{N}{2} W_2^2(\rho, \frac{1}{N} \sum_i \delta_{y_i})$$

$$\begin{cases} \dot{y}(t) = -\nabla \mathcal{D}(y(t)) \\ y(0) = y_0 \in \mathbb{R}^{Nd} \end{cases}$$

$$\iff \begin{cases} \dot{y}_i(t) = -(B_i(y_1(t), \dots, y_N(t)) - y_i(t)) \\ y(0) = y_0 \in \mathbb{R}^{Nd} \end{cases}$$

(\iff $\mu(t) = \frac{1}{N} \sum_i \delta_{y_i(t)}$ is the gradient flow of $\mathcal{F} = \frac{1}{2} W_2^2(\rho, \cdot)$ in $(\mathcal{P}_N(\mathbb{R}^d), W_2)$)

Optimal quantization as a gradient flow

$$\mathcal{D} : y = (y_1, \dots, y_N) \in \mathbb{R}^{Nd} \mapsto \frac{N}{2} W_2^2(\rho, \frac{1}{N} \sum_i \delta_{y_i})$$

$$\begin{cases} \dot{y}(t) = -\nabla \mathcal{D}(y(t)) \\ y(0) = y_0 \in \mathbb{R}^{Nd} \end{cases}$$

$$\iff \begin{cases} \dot{y}_i(t) = -(B_i(y_1(t), \dots, y_N(t)) - y_i(t)) \\ y(0) = y_0 \in \mathbb{R}^{Nd} \end{cases}$$

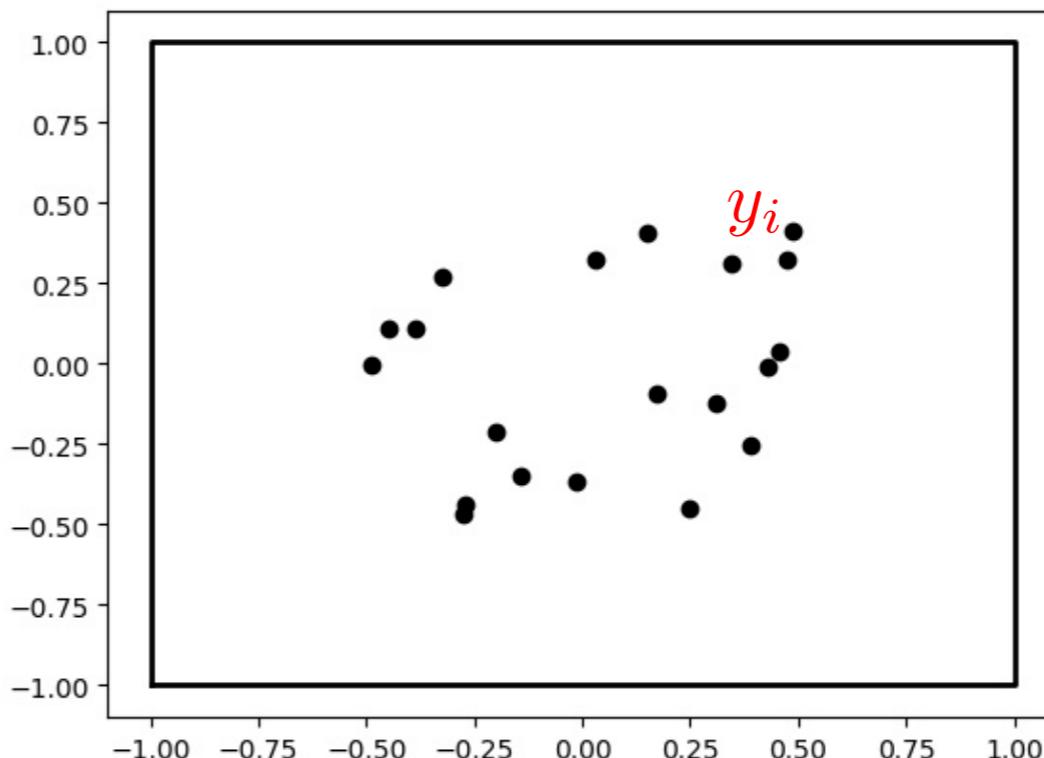
(\iff $\mu(t) = \frac{1}{N} \sum_i \delta_{y_i(t)}$ is the gradient flow of $\mathcal{F} = \frac{1}{2} W_2^2(\rho, \cdot)$ in $(\mathcal{P}_N(\mathbb{R}^d), W_2)$)

Example:

$$\rho = \frac{1}{4} \text{Leb}_{[-1,1]^2}$$

$y_1(0), \dots, y_N(0)$ iid

$$N = 20$$



Optimal quantization as a gradient flow

$$\mathcal{D} : y = (y_1, \dots, y_N) \in \mathbb{R}^{Nd} \mapsto \frac{N}{2} W_2^2(\rho, \frac{1}{N} \sum_i \delta_{y_i})$$

$$\begin{cases} \dot{y}(t) = -\nabla \mathcal{D}(y(t)) \\ y(0) = y_0 \in \mathbb{R}^{Nd} \end{cases}$$

$$\iff \begin{cases} \dot{y}_i(t) = -(B_i(y_1(t), \dots, y_N(t)) - y_i(t)) \\ y(0) = y_0 \in \mathbb{R}^{Nd} \end{cases}$$

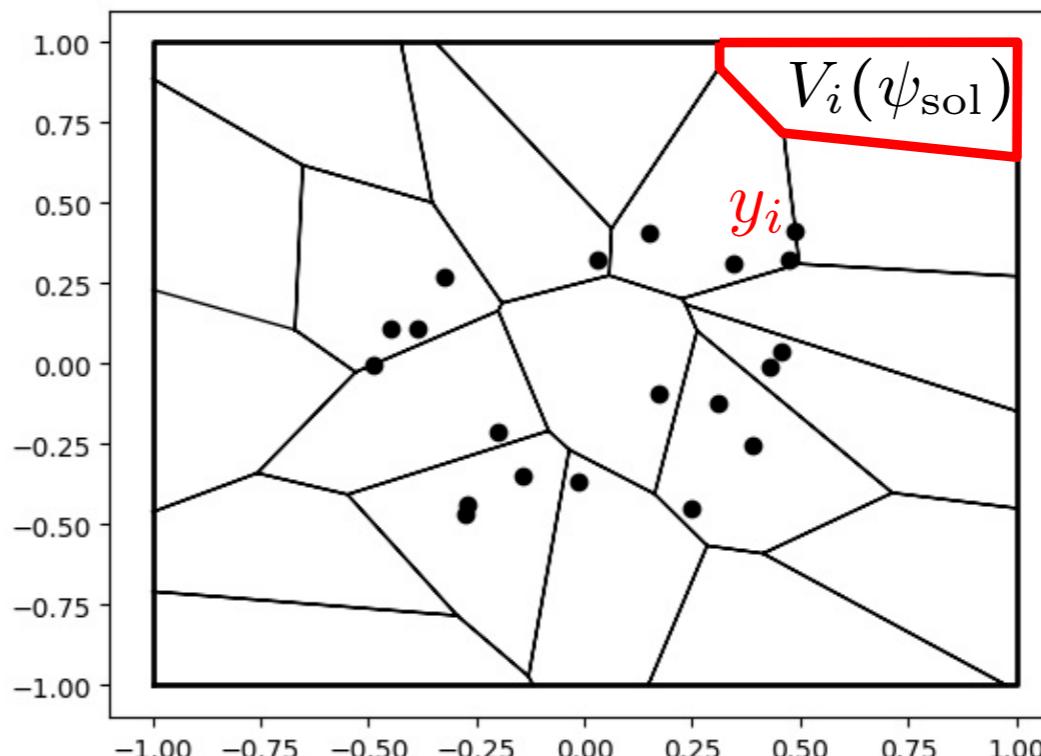
(\iff $\mu(t) = \frac{1}{N} \sum_i \delta_{y_i(t)}$ is the gradient flow of $\mathcal{F} = \frac{1}{2} W_2^2(\rho, \cdot)$ in $(\mathcal{P}_N(\mathbb{R}^d), W_2)$)

Example:

$$\rho = \frac{1}{4} \text{Leb}_{[-1,1]^2}$$

$y_1(0), \dots, y_N(0)$ iid

$$N = 20$$



Optimal quantization as a gradient flow

$$\mathcal{D} : y = (y_1, \dots, y_N) \in \mathbb{R}^{Nd} \mapsto \frac{N}{2} W_2^2(\rho, \frac{1}{N} \sum_i \delta_{y_i})$$

$$\begin{aligned} & \begin{cases} \dot{y}(t) = -\nabla \mathcal{D}(y(t)) \\ y(0) = y_0 \in \mathbb{R}^{Nd} \end{cases} \\ \iff & \begin{cases} \dot{y}_i(t) = -(B_i(y_1(t), \dots, y_N(t)) - y_i(t)) \\ y(0) = y_0 \in \mathbb{R}^{Nd} \end{cases} \end{aligned}$$

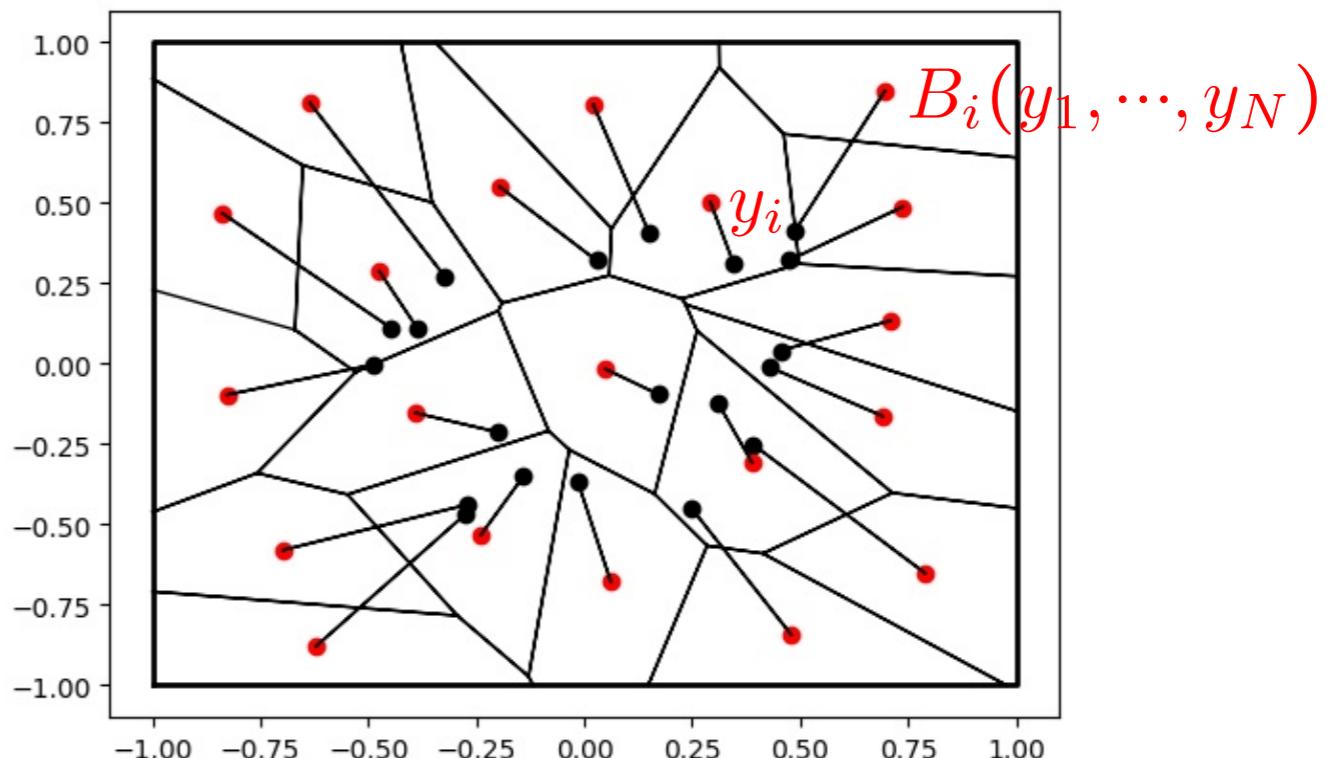
(\iff $\mu(t) = \frac{1}{N} \sum_i \delta_{y_i(t)}$ is the gradient flow of $\mathcal{F} = \frac{1}{2} W_2^2(\rho, \cdot)$ in $(\mathcal{P}_N(\mathbb{R}^d), W_2)$)

Example:

$$\rho = \frac{1}{4} \text{Leb}_{[-1,1]^2}$$

$$y_1(0), \dots, y_N(0) \text{ iid}$$

$$N = 20$$



Optimal quantization as a gradient flow

$$\mathcal{D} : y = (y_1, \dots, y_N) \in \mathbb{R}^{Nd} \mapsto \frac{N}{2} W_2^2(\rho, \frac{1}{N} \sum_i \delta_{y_i})$$

$$\begin{aligned} & \begin{cases} \dot{y}(t) = -\nabla \mathcal{D}(y(t)) \\ y(0) = y_0 \in \mathbb{R}^{Nd} \end{cases} \\ \iff & \begin{cases} \dot{y}_i(t) = -(B_i(y_1(t), \dots, y_N(t)) - y_i(t)) \\ y(0) = y_0 \in \mathbb{R}^{Nd} \end{cases} \end{aligned}$$

(\iff $\mu(t) = \frac{1}{N} \sum_i \delta_{y_i(t)}$ is the gradient flow of $\mathcal{F} = \frac{1}{2} W_2^2(\rho, \cdot)$ in $(\mathcal{P}_N(\mathbb{R}^d), W_2)$)

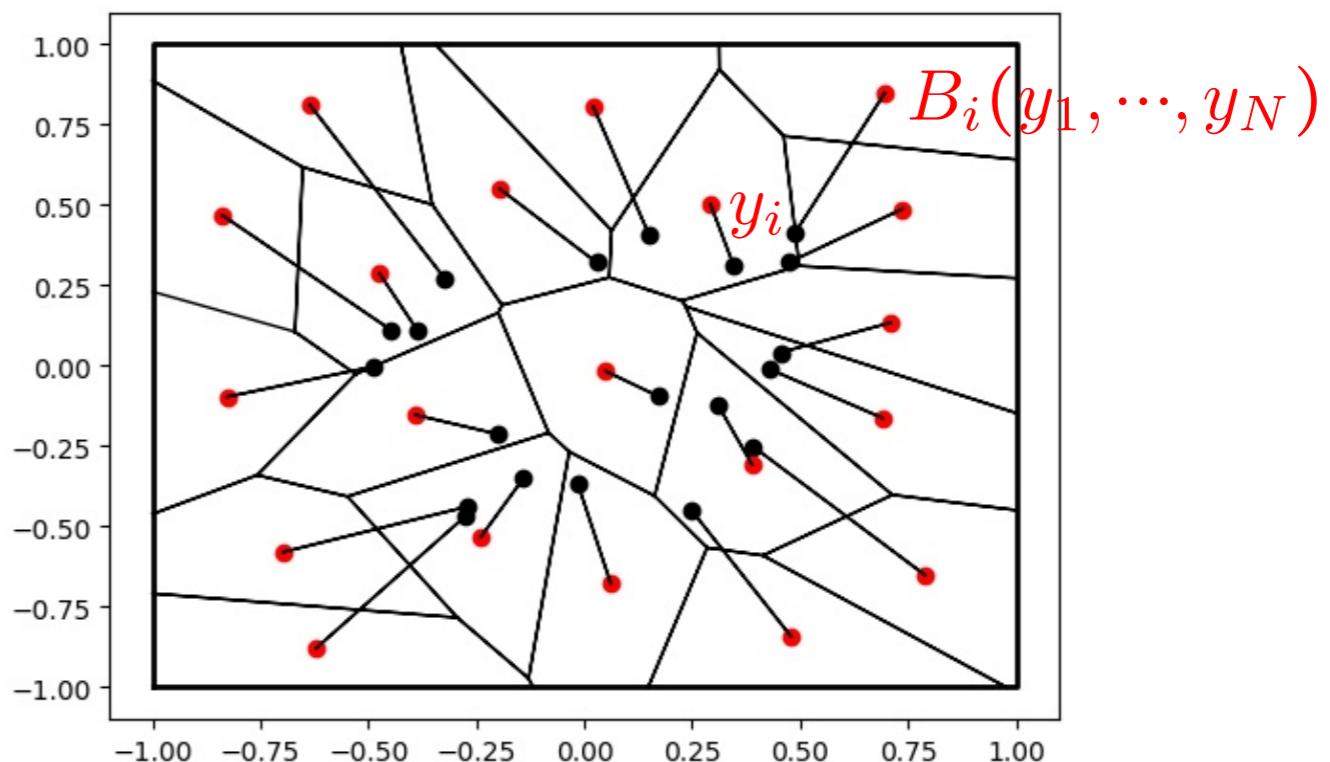
Example:

$$\rho = \frac{1}{4} \text{Leb}_{[-1,1]^2}$$

$y_1(0), \dots, y_N(0)$ iid

$$N = 20$$

Demo



2. Incompressible Euler equations

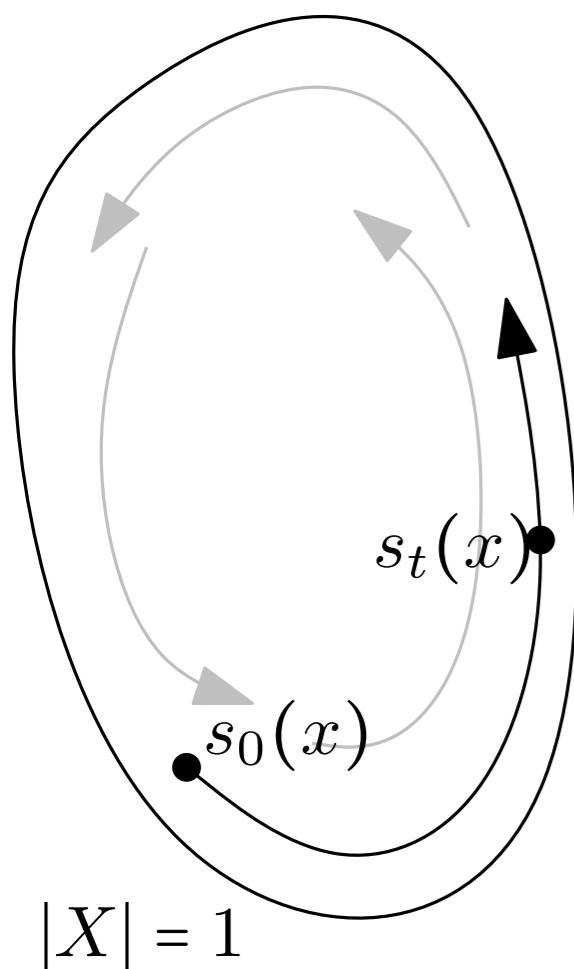
Joint works with JM Mirebeau and Thomas Gallouët

Solutions to Euler's equations as geodesics in \mathbb{SDiff}

$$\mathbb{SDiff} = \{s : X \rightarrow X \text{ diffeomorphism} \mid \det(Ds) = 1\} \subseteq L^2(X, \mathbb{R}^d)$$

[Arnold 1966]

$X \subseteq \mathbb{R}^d$ bounded



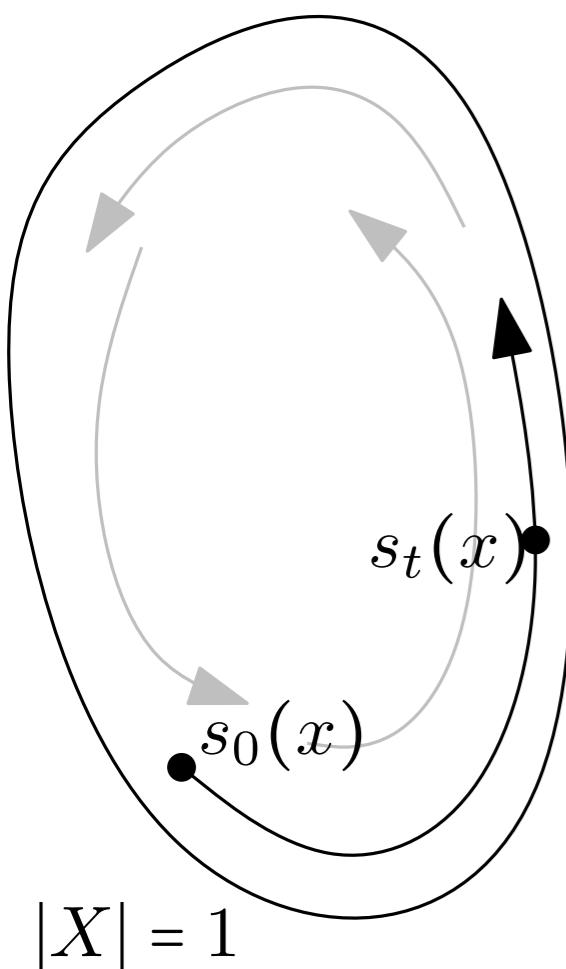
→ Formally, a path $s : [0, 1] \rightarrow \mathbb{SDiff}$ is a **geodesic** iff
 $\ddot{s}_t \perp T_{s_t} \mathbb{SDiff}$

Solutions to Euler's equations as geodesics in \mathbb{SDiff}

$$\mathbb{SDiff} = \{s : X \rightarrow X \text{ diffeomorphism} \mid \det(Ds) = 1\} \subseteq L^2(X, \mathbb{R}^d)$$

[Arnold 1966]

$X \subseteq \mathbb{R}^d$ bounded



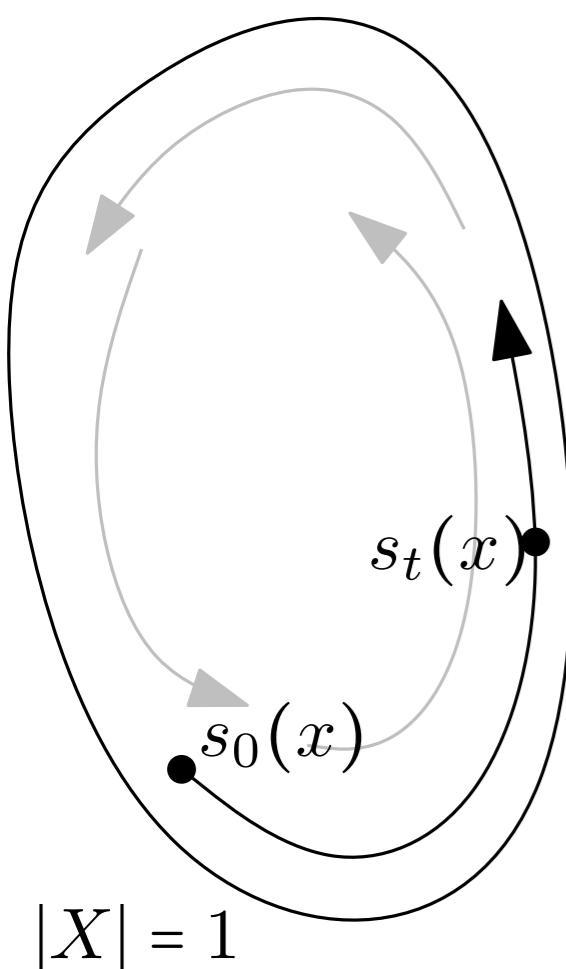
→ Formally, a path $s : [0, 1] \rightarrow \mathbb{SDiff}$ is a **geodesic** iff
 $\ddot{s}_t \perp T_{s_t} \mathbb{SDiff} \iff \ddot{s}_t \circ s_t^{-1} \perp T_{id} \mathbb{SDiff}$

Solutions to Euler's equations as geodesics in \mathbb{SDiff}

$$\mathbb{SDiff} = \{s : X \rightarrow X \text{ diffeomorphism} \mid \det(Ds) = 1\} \subseteq L^2(X, \mathbb{R}^d)$$

[Arnold 1966]

$X \subseteq \mathbb{R}^d$ bounded



→ Formally, a path $s : [0, 1] \rightarrow \mathbb{SDiff}$ is a **geodesic** iff

$$\ddot{s}_t \perp T_{s_t} \mathbb{SDiff} \iff \ddot{s}_t \circ s_t^{-1} \perp T_{id} \mathbb{SDiff}$$

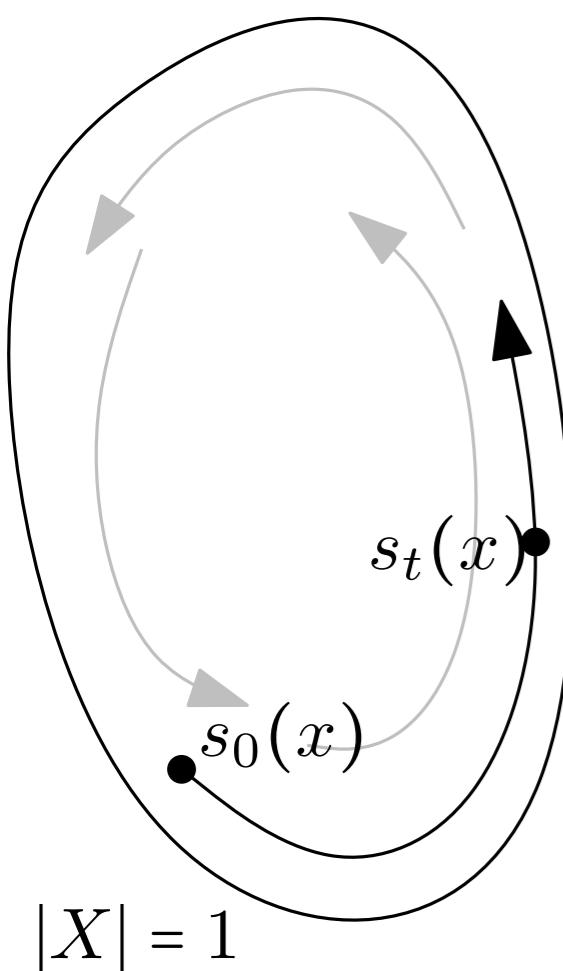
$$(T_{id} \mathbb{SDiff} = \text{divergence-free vector fields} = \{\nabla p \mid p : X \rightarrow \mathbb{R}\}^\perp)$$

Solutions to Euler's equations as geodesics in \mathbb{SDiff}

$$\mathbb{SDiff} = \{s : X \rightarrow X \text{ diffeomorphism} \mid \det(Ds) = 1\} \subseteq L^2(X, \mathbb{R}^d)$$

[Arnold 1966]

$X \subseteq \mathbb{R}^d$ bounded



→ Formally, a path $s : [0, 1] \rightarrow \mathbb{SDiff}$ is a **geodesic** iff

$$\ddot{s}_t \perp T_{s_t} \mathbb{SDiff} \iff \ddot{s}_t \circ s_t^{-1} \perp T_{id} \mathbb{SDiff}$$

$$\iff \exists p : [0, 1] \times X \rightarrow \mathbb{R}, \ddot{s}_t = -\nabla p_t \circ s_t$$

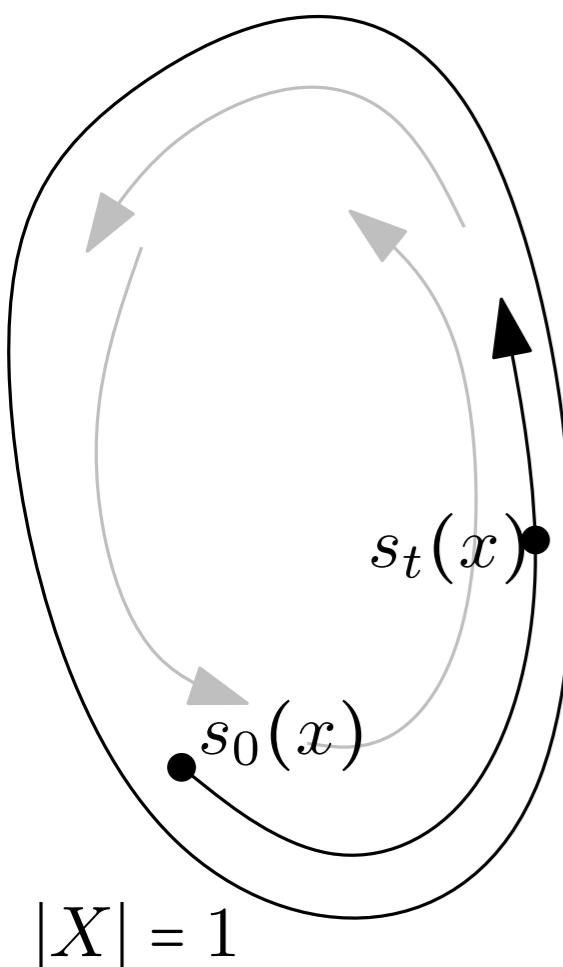
($T_{id} \mathbb{SDiff}$ = divergence-free vector fields = $\{\nabla p \mid p : X \rightarrow \mathbb{R}\}^\perp$)

Solutions to Euler's equations as geodesics in \mathbb{SDiff}

$$\mathbb{SDiff} = \{s : X \rightarrow X \text{ diffeomorphism} \mid \det(Ds) = 1\} \subseteq L^2(X, \mathbb{R}^d)$$

[Arnold 1966]

$X \subseteq \mathbb{R}^d$ bounded



→ Formally, a path $s : [0, 1] \rightarrow \mathbb{SDiff}$ is a **geodesic** iff

$$\ddot{s}_t \perp T_{s_t} \mathbb{SDiff} \iff \ddot{s}_t \circ s_t^{-1} \perp T_{id} \mathbb{SDiff}$$

$$\iff \exists p : [0, 1] \times X \rightarrow \mathbb{R}, \ddot{s}_t = -\nabla p_t \circ s_t$$

$$(T_{id} \mathbb{SDiff} = \text{divergence-free vector fields} = \{\nabla p \mid p : X \rightarrow \mathbb{R}\}^\perp)$$

→ With $u_t := \dot{s}_t \circ s_t^{-1}$ (= velocity in Eulerian coordinates), one recovers **Euler's equations** for incompressible fluids:

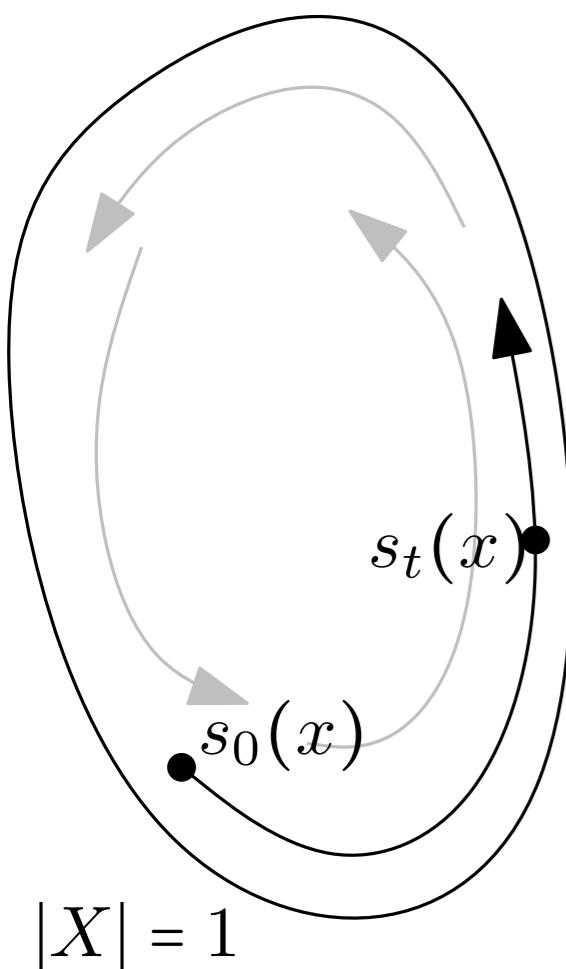
$$\begin{cases} \partial_t u + u \cdot \nabla u = -\nabla p & \text{in } X \\ \operatorname{div} u = 0 & \text{in } X \\ u \cdot n = 0 & \text{on } \partial X \end{cases}$$

Solutions to Euler's equations as geodesics in \mathbb{SDiff}

$$\mathbb{SDiff} = \{s : X \rightarrow X \text{ diffeomorphism} \mid \det(Ds) = 1\} \subseteq L^2(X, \mathbb{R}^d)$$

[Arnold 1966]

$X \subseteq \mathbb{R}^d$ bounded



$$|X| = 1$$

→ Formally, a path $s : [0, 1] \rightarrow \mathbb{SDiff}$ is a **geodesic** iff

$$\ddot{s}_t \perp T_{s_t} \mathbb{SDiff} \iff \ddot{s}_t \circ s_t^{-1} \perp T_{id} \mathbb{SDiff}$$

$$\iff \exists p : [0, 1] \times X \rightarrow \mathbb{R}, \ddot{s}_t = -\nabla p_t \circ s_t$$

$$(T_{id} \mathbb{SDiff} = \text{divergence-free vector fields} = \{\nabla p \mid p : X \rightarrow \mathbb{R}\}^\perp)$$

→ With $u_t := \dot{s}_t \circ s_t^{-1}$ (= velocity in Eulerian coordinates), one recovers **Euler's equations** for incompressible fluids:

$$\begin{cases} \partial_t u + u \cdot \nabla u = -\nabla p & \text{in } X \\ \operatorname{div} u = 0 & \text{in } X \\ u \cdot n = 0 & \text{on } \partial X \end{cases}$$

Can this formulation be used for numerical computations (Brenier) ?

- Minimizing geodesics (with Jean-Marie Mirebeau, 2015)
- Cauchy problem (with Thomas Gallouet, 2016).

Approximation of geodesics $S \subseteq \mathbb{R}^d$

$$\begin{cases} \ddot{s}(t) \perp T_{s(t)}S \\ s(t) \in S \\ (s(0), \dot{s}(0)) = (s_0, v_0) \end{cases}$$

where $S \subseteq \mathbb{R}^d$ submanifold

Approximation of geodesics $S \subseteq \mathbb{R}^d$

$$\begin{cases} \ddot{s}(t) \perp T_{s(t)}S \\ s(t) \in S \\ (s(0), \dot{s}(0)) = (s_0, v_0) \end{cases}$$

where $S \subseteq \mathbb{R}^d$ submanifold



$$\begin{cases} \ddot{m}(t) + \frac{1}{2\varepsilon^2} \nabla d_S^2(m(t)) = 0 \\ m(t) \in \mathbb{R}^d \\ (m(0), \dot{m}(0)) = (\tilde{s}_0, \tilde{v}_0) \end{cases}$$

where $d_S^2(m) = \min_{s \in S} \|m - s\|^2$.

Approximation of geodesics $S \subseteq \mathbb{R}^d$

$$\begin{cases} \ddot{s}(t) \perp T_{s(t)}S \\ s(t) \in S \\ (s(0), \dot{s}(0)) = (s_0, v_0) \end{cases}$$

where $S \subseteq \mathbb{R}^d$ submanifold



$$\begin{cases} \ddot{m}(t) + \frac{1}{2\varepsilon^2} \nabla d_S^2(m(t)) = 0 \\ m(t) \in \mathbb{R}^d \\ (m(0), \dot{m}(0)) = (\tilde{s}_0, \tilde{v}_0) \end{cases}$$

where $d_S^2(m) = \min_{s \in S} \|m - s\|^2$.

→ Recall: $\frac{1}{2} \nabla d_S^2(m) = m - \Pi_S(m)$ a.e. where $\Pi_S(\cdot)$ = closest point map

Approximation of geodesics $S \subseteq \mathbb{R}^d$

$$\begin{cases} \ddot{s}(t) \perp T_{s(t)}S \\ s(t) \in S \\ (s(0), \dot{s}(0)) = (s_0, v_0) \end{cases} \xrightarrow{\hspace{10em}} \begin{cases} \ddot{m}(t) + \frac{1}{2\varepsilon^2} \nabla d_S^2(m(t)) = 0 \\ m(t) \in \mathbb{R}^d \\ (m(0), \dot{m}(0)) = (\tilde{s}_0, \tilde{v}_0) \end{cases}$$

where $S \subseteq \mathbb{R}^d$ submanifold where $d_S^2(m) = \min_{s \in S} \|m - s\|^2$.

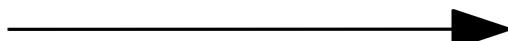
→ Recall: $\frac{1}{2} \nabla d_S^2(m) = m - \Pi_S(m)$ a.e. where $\Pi_S(\cdot)$ = closest point map

→ **Hamiltonian system** for $H(m, v) = \frac{1}{2} \|v\|^2 + \frac{1}{2\varepsilon^2} d_S^2(m)$.

Approximation of geodesics $S \subseteq \mathbb{R}^d$

$$\begin{cases} \ddot{s}(t) \perp T_{s(t)}S \\ s(t) \in S \\ (s(0), \dot{s}(0)) = (s_0, v_0) \end{cases}$$

where $S \subseteq \mathbb{R}^d$ submanifold



$$\begin{cases} \ddot{m}(t) + \frac{1}{2\varepsilon^2} \nabla d_S^2(m(t)) = 0 \\ m(t) \in \mathbb{R}^d \\ (m(0), \dot{m}(0)) = (\tilde{s}_0, \tilde{v}_0) \end{cases}$$

where $d_S^2(m) = \min_{s \in S} \|m - s\|^2$.

→ Recall: $\frac{1}{2} \nabla d_S^2(m) = m - \Pi_S(m)$ a.e. where $\Pi_S(\cdot)$ = closest point map

→ **Hamiltonian system** for $H(m, v) = \frac{1}{2} \|v\|^2 + \frac{1}{2\varepsilon^2} d_S^2(m)$.

Simple example: Take $S = \mathbb{R} \times \{0\} \subseteq \mathbb{R}^2$, $s_0 = (0, 0)$, $v_0 = (1, 0)$

$$\tilde{s}_0 = (0, h), \tilde{v}_0 = (1, \nu)$$



with $m = (x, y)$ we have $\begin{cases} \ddot{x} = 0 \\ \ddot{y} + \frac{1}{\varepsilon^2} y = 0 \end{cases}$

Approximation of geodesics $S \subseteq \mathbb{R}^d$

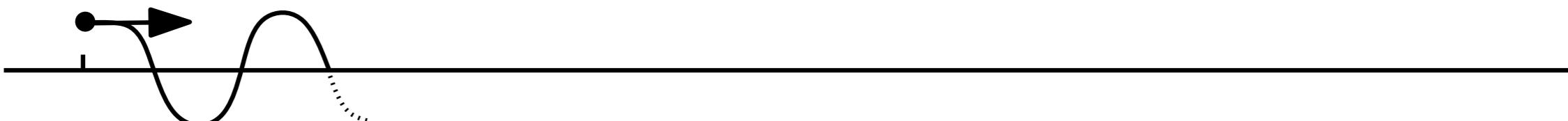
$$\begin{array}{c} \left\{ \begin{array}{l} \ddot{s}(t) \perp T_{s(t)}S \\ s(t) \in S \\ (s(0), \dot{s}(0)) = (s_0, v_0) \end{array} \right. \xrightarrow{\hspace{10em}} \left\{ \begin{array}{l} \ddot{m}(t) + \frac{1}{2\varepsilon^2} \nabla d_S^2(m(t)) = 0 \\ m(t) \in \mathbb{R}^d \\ (m(0), \dot{m}(0)) = (\tilde{s}_0, \tilde{v}_0) \end{array} \right. \\ \text{where } S \subseteq \mathbb{R}^d \text{ submanifold} \qquad \qquad \text{where } d_S^2(m) = \min_{s \in S} \|m - s\|^2. \end{array}$$

→ Recall: $\frac{1}{2} \nabla d_S^2(m) = m - \Pi_S(m)$ a.e. where $\Pi_S(\cdot)$ = closest point map

→ **Hamiltonian system** for $H(m, v) = \frac{1}{2} \|v\|^2 + \frac{1}{2\varepsilon^2} d_S^2(m)$.

Simple example: Take $S = \mathbb{R} \times \{0\} \subseteq \mathbb{R}^2$, $s_0 = (0, 0)$, $v_0 = (1, 0)$

$$\tilde{s}_0 = (0, h), \tilde{v}_0 = (1, \nu)$$



with $m = (x, y)$ we have $\begin{cases} \ddot{x} = 0 \\ \ddot{y} + \frac{1}{\varepsilon^2}y = 0 \end{cases}$

$$\text{i.e. } \begin{cases} x(t) = t \\ y(t) = h \cos(t/\varepsilon) + \nu \varepsilon \sin(t/\varepsilon) \end{cases}$$

Approximation of geodesics $S \subseteq \mathbb{R}^d$

$$\begin{cases} \ddot{s}(t) \perp T_{s(t)}S \\ s(t) \in S \\ (s(0), \dot{s}(0)) = (s_0, v_0) \end{cases} \xrightarrow{\hspace{10em}} \begin{cases} \ddot{m}(t) + \frac{1}{2\varepsilon^2} \nabla d_S^2(m(t)) = 0 \\ m(t) \in \mathbb{R}^d \\ (m(0), \dot{m}(0)) = (\tilde{s}_0, \tilde{v}_0) \end{cases}$$

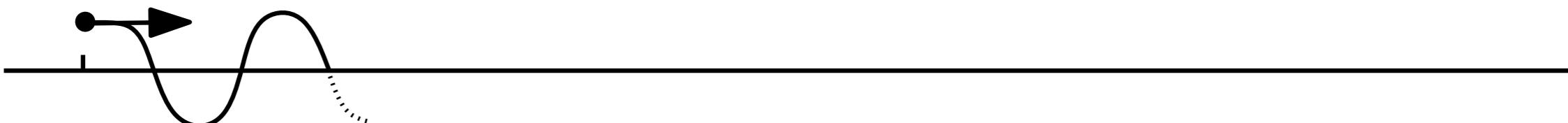
where $S \subseteq \mathbb{R}^d$ submanifold where $d_S^2(m) = \min_{s \in S} \|m - s\|^2$.

→ Recall: $\frac{1}{2} \nabla d_S^2(m) = m - \Pi_S(m)$ a.e. where $\Pi_S(\cdot)$ = closest point map

→ **Hamiltonian system** for $H(m, v) = \frac{1}{2} \|v\|^2 + \frac{1}{2\varepsilon^2} d_S^2(m)$.

Simple example: Take $S = \mathbb{R} \times \{0\} \subseteq \mathbb{R}^2$, $s_0 = (0, 0)$, $v_0 = (1, 0)$

$$\tilde{s}_0 = (0, h), \tilde{v}_0 = (1, \nu)$$



with $m = (x, y)$ we have $\begin{cases} \ddot{x} = 0 \\ \ddot{y} + \frac{1}{\varepsilon^2}y = 0 \end{cases}$ i.e. $\begin{cases} x(t) = t \\ y(t) = h \cos(t/\varepsilon) + \nu \varepsilon \sin(t/\varepsilon) \end{cases}$

$\rightarrow C^1$ convergence towards the geodesic requires $\frac{h}{\varepsilon} \rightarrow 0$.

Approximation of geodesics in \mathbb{S}

$\text{Leb} = \text{restriction of Lebesgue measure to a compact domain } X$

$\mathbb{S} = \{s : X \rightarrow X \mid s_{\#}\text{Leb} = \text{Leb}\} \longrightarrow \text{"measure-preserving maps"}$

$\mathbb{M} = L^2(X, \mathbb{R}^d)$

$$\begin{cases} \ddot{m}(t) + \frac{1}{2\varepsilon^2} \nabla d_{\mathbb{S}}^2(m(t)) = 0 \\ m(t) \in \mathbb{M} \\ (m(0), \dot{m}(0)) = (\tilde{s}_0, \tilde{v}_0) \end{cases}$$

Approximation of geodesics in \mathbb{S}

$\text{Leb} = \text{restriction of Lebesgue measure to a compact domain } X$

$\mathbb{S} = \{s : X \rightarrow X \mid s_{\#}\text{Leb} = \text{Leb}\} \longrightarrow \text{"measure-preserving maps"}$

$\mathbb{M} = L^2(X, \mathbb{R}^d)$

$$\begin{cases} \ddot{m}(t) + \frac{1}{2\varepsilon^2} \nabla d_{\mathbb{S}}^2(m(t)) = 0 \\ m(t) \in \mathbb{M} \\ (m(0), \dot{m}(0)) = (\tilde{s}_0, \tilde{v}_0) \end{cases}$$

- ▶ discretizing this formulation for numerical resolution of Euler's equations ?
 - difficulty: computation of the square distance $d_{\mathbb{S}}^2$ and its gradient
 - NB: \mathbb{S} is non-convex, existence and uniqueness is non-trivial

Approximation of geodesics in \mathbb{S}

$\text{Leb} = \text{restriction of Lebesgue measure to a compact domain } X$

$\mathbb{S} = \{s : X \rightarrow X \mid s_{\#}\text{Leb} = \text{Leb}\} \longrightarrow \text{"measure-preserving maps"}$

$\mathbb{M} = L^2(X, \mathbb{R}^d)$

$$\begin{cases} \ddot{m}(t) + \frac{1}{2\varepsilon^2} \nabla d_{\mathbb{S}}^2(m(t)) = 0 \\ m(t) \in \mathbb{M} \\ (m(0), \dot{m}(0)) = (\tilde{s}_0, \tilde{v}_0) \end{cases}$$

- ▶ discretizing this formulation for numerical resolution of Euler's equations ?
 - difficulty: computation of the square distance $d_{\mathbb{S}}^2$ and its gradient
NB: \mathbb{S} is non-convex, existence and uniqueness is non-trivial
 - early numerical work by Brenier (80's), where \mathbb{S} is approximated by the set of permutations \mathbb{S}_N of a fixed partition $X = \bigsqcup_{1 \leq i \leq N} \omega_i$.

Approximation of geodesics in \mathbb{S}

$\text{Leb} = \text{restriction of Lebesgue measure to a compact domain } X$

$\mathbb{S} = \{s : X \rightarrow X \mid s_{\#}\text{Leb} = \text{Leb}\} \longrightarrow \text{"measure-preserving maps"}$

$\mathbb{M} = L^2(X, \mathbb{R}^d)$

$$\begin{cases} \ddot{m}(t) + \frac{1}{2\varepsilon^2} \nabla d_{\mathbb{S}}^2(m(t)) = 0 \\ m(t) \in \mathbb{M} \\ (m(0), \dot{m}(0)) = (\tilde{s}_0, \tilde{v}_0) \end{cases}$$

- ▶ discretizing this formulation for numerical resolution of Euler's equations ?
 - difficulty: computation of the square distance $d_{\mathbb{S}}^2$ and its gradient
NB: \mathbb{S} is non-convex, existence and uniqueness is non-trivial
 - early numerical work by Brenier (80's), where \mathbb{S} is approximated by the set of permutations \mathbb{S}_N of a fixed partition $X = \bigsqcup_{1 \leq i \leq N} \omega_i$.
(combinatorial optimization problem with cost N^3)

Distance to \mathbb{S} and polar factorization of maps

Leb = restriction of Lebesgue measure to a compact domain X

$\mathbb{S} = \{s : X \rightarrow X \mid s_{\#}\text{Leb} = \text{Leb}\} \longrightarrow \text{"measure-preserving maps"}$

Distance to \mathbb{S} and polar factorization of maps

Leb = restriction of Lebesgue measure to a compact domain X

$\mathbb{S} = \{s : X \rightarrow X \mid s_{\#}\text{Leb} = \text{Leb}\} \rightarrow \text{"measure-preserving maps"}$

Notation: Let $d_{\mathbb{S}}^2(\cdot) = \min_{s \in \mathbb{S}} \|\cdot - s\|_2^2$ and $\Pi_{\mathbb{S}}(\cdot)$ the set of projections.

Distance to \mathbb{S} and polar factorization of maps

Leb = restriction of Lebesgue measure to a compact domain X

$\mathbb{S} = \{s : X \rightarrow X \mid s_{\#}\text{Leb} = \text{Leb}\} \rightarrow \text{"measure-preserving maps"}$

Notation: Let $d_{\mathbb{S}}^2(\cdot) = \min_{s \in \mathbb{S}} \|\cdot - s\|_2^2$ and $\Pi_{\mathbb{S}}(\cdot)$ the set of projections.

Polar Factorization Theorem (Brenier): For every map m in $\mathbb{M} = L^2(X, \mathbb{R}^d)$,

$$d_{\mathbb{S}}^2(m) = W_2^2(\text{Leb}, m_{\#}\text{Leb})$$

[Brenier '92]

Distance to \mathbb{S} and polar factorization of maps

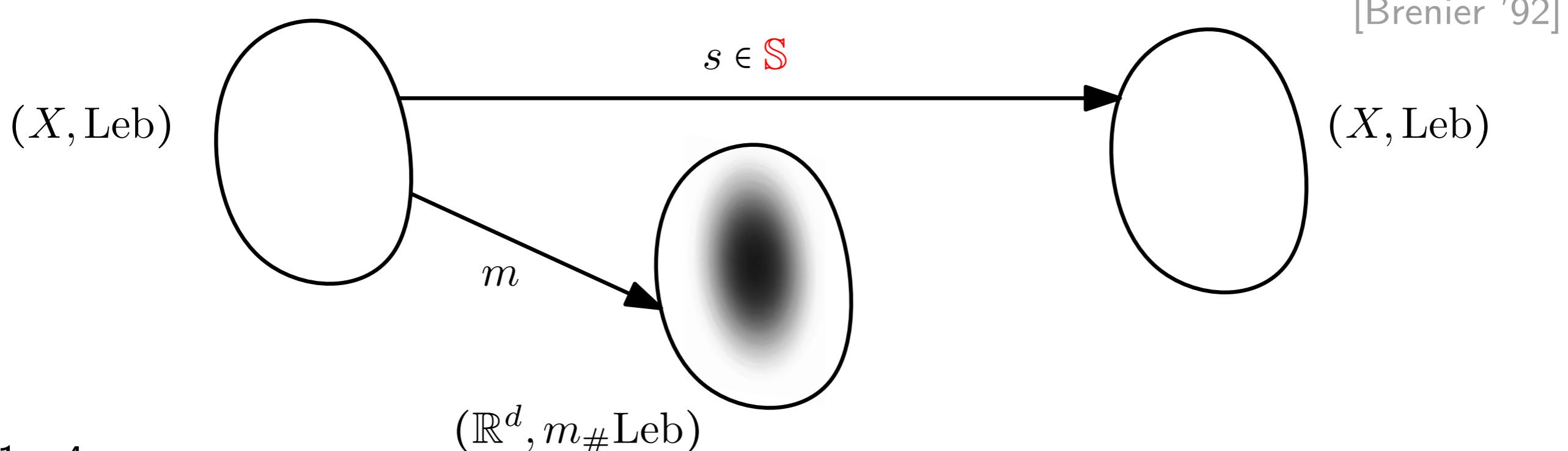
Leb = restriction of Lebesgue measure to a compact domain X

$\mathbb{S} = \{s : X \rightarrow X \mid s_{\#}\text{Leb} = \text{Leb}\} \rightarrow \text{"measure-preserving maps"}$

Notation: Let $d_{\mathbb{S}}^2(\cdot) = \min_{s \in \mathbb{S}} \|\cdot - s\|_2^2$ and $\Pi_{\mathbb{S}}(\cdot)$ the set of projections.

Polar Factorization Theorem (Brenier): For every map m in $\mathbb{M} = L^2(X, \mathbb{R}^d)$,

$$d_{\mathbb{S}}^2(m) = W_2^2(\text{Leb}, m_{\#}\text{Leb})$$



Distance to \mathbb{S} and polar factorization of maps

Leb = restriction of Lebesgue measure to a compact domain X

$\mathbb{S} = \{s : X \rightarrow X \mid s_{\#}\text{Leb} = \text{Leb}\} \rightarrow \text{"measure-preserving maps"}$

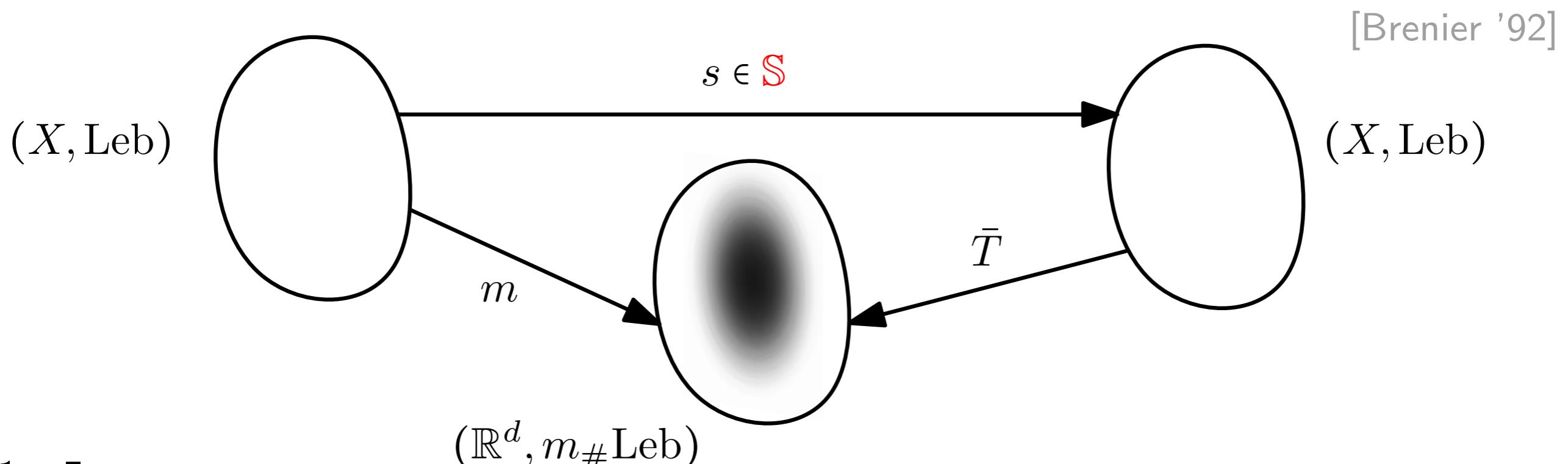
Notation: Let $d_{\mathbb{S}}^2(\cdot) = \min_{s \in \mathbb{S}} \|\cdot - s\|_2^2$ and $\Pi_{\mathbb{S}}(\cdot)$ the set of projections.

Polar Factorization Theorem (Brenier): For every map m in $\mathbb{M} = L^2(X, \mathbb{R}^d)$,

$$d_{\mathbb{S}}^2(m) = W_2^2(\text{Leb}, m_{\#}\text{Leb})$$

Let \bar{T} be the quadratic optimal transport map between Leb and $m_{\#}\text{Leb}$. Then,

$$\Pi_{\mathbb{S}}(m) = \{\bar{s} \in \mathbb{S} \mid \bar{T} \circ \bar{s} = m\}$$



Space-discretization of Euler's equations

→ X is partitioned into $(V_k)_{1 \leq k \leq N}$ with $\text{Leb}(V_k) = \frac{1}{N}$ and $\text{diam}(V_k) \simeq N^{-\frac{1}{d}}$

Space-discretization of Euler's equations

- X is partitioned into $(V_k)_{1 \leq k \leq N}$ with $\text{Leb}(V_k) = \frac{1}{N}$ and $\text{diam}(V_k) \simeq N^{-\frac{1}{d}}$
- $\mathbb{M}_N := \{ \text{piecewise constant functions on } (V_k) \} \subseteq \mathbb{M}$

Space-discretization of Euler's equations

- X is partitioned into $(V_k)_{1 \leq k \leq N}$ with $\text{Leb}(V_k) = \frac{1}{N}$ and $\text{diam}(V_k) \simeq N^{-\frac{1}{d}}$
- $\mathbb{M}_N := \{ \text{piecewise constant functions on } (V_k) \} \subseteq \mathbb{M}$
- Given $m = \sum_i y_i \mathbf{1}_{V_i} \in \mathbb{M}_N$ one has $m \# \text{Leb} = \frac{1}{N} \sum_i \delta_{y_i}$

Space-discretization of Euler's equations

- X is partitioned into $(V_k)_{1 \leq k \leq N}$ with $\text{Leb}(V_k) = \frac{1}{N}$ and $\text{diam}(V_k) \simeq N^{-\frac{1}{d}}$
- $\mathbb{M}_N := \{ \text{piecewise constant functions on } (V_k) \} \subseteq \mathbb{M}$
- Given $m = \sum_i y_i \mathbf{1}_{V_i} \in \mathbb{M}_N$ one has $m_{\#} \text{Leb} = \frac{1}{N} \sum_i \delta_{y_i}$

$$(1) \quad \begin{cases} \ddot{m}(t) + \frac{1}{2\varepsilon^2} \Pi_{\mathbb{M}_N} \nabla d_{\mathbb{S}}^2(m) = 0 \\ (m(0), \dot{m}(0)) = (\Pi_{\mathbb{M}_N}(\text{id}), \Pi_{\mathbb{M}_N}(u_0)) \end{cases}$$

Space-discretization of Euler's equations

- X is partitioned into $(V_k)_{1 \leq k \leq N}$ with $\text{Leb}(V_k) = \frac{1}{N}$ and $\text{diam}(V_k) \simeq N^{-\frac{1}{d}}$
- $\mathbb{M}_N := \{ \text{piecewise constant functions on } (V_k) \} \subseteq \mathbb{M}$
- Given $m = \sum_i y_i \mathbf{1}_{V_i} \in \mathbb{M}_N$ one has $m_\# \text{Leb} = \frac{1}{N} \sum_i \delta_{y_i}$

$$(1) \quad \begin{cases} \ddot{m}(t) + \frac{1}{2\varepsilon^2} \Pi_{\mathbb{M}_N} \nabla d_{\mathbb{S}}^2(m) = 0 \\ (m(0), \dot{m}(0)) = (\Pi_{\mathbb{M}_N}(\text{id}), \Pi_{\mathbb{M}_N}(u_0)) \end{cases}$$

writing $m(t) = \sum_i y_i(t) \mathbf{1}_{V_i}$:
and using polar factorization

$$(2) \quad \ddot{y}_i(t) + \frac{1}{\varepsilon^2} \nabla_{y_i} \mathcal{D}(y_1(t), \dots, y_N(t)) = 0$$

$[d_{\mathbb{S}}^2(m) = W_2^2(\text{Leb}, m_\# \text{Leb}) = W_2^2(\text{Leb}, \frac{1}{N} \sum_i \delta_{y_i})]$

Space-discretization of Euler's equations

- X is partitioned into $(V_k)_{1 \leq k \leq N}$ with $\text{Leb}(V_k) = \frac{1}{N}$ and $\text{diam}(V_k) \simeq N^{-\frac{1}{d}}$
- $\mathbb{M}_N := \{ \text{piecewise constant functions on } (V_k) \} \subseteq \mathbb{M}$
- Given $m = \sum_i y_i \mathbf{1}_{V_i} \in \mathbb{M}_N$ one has $m_{\#} \text{Leb} = \frac{1}{N} \sum_i \delta_{y_i}$

$$(1) \quad \begin{cases} \ddot{m}(t) + \frac{1}{2\varepsilon^2} \Pi_{\mathbb{M}_N} \nabla d_{\mathbb{S}}^2(m) = 0 \\ (m(0), \dot{m}(0)) = (\Pi_{\mathbb{M}_N}(\text{id}), \Pi_{\mathbb{M}_N}(u_0)) \end{cases}$$

writing $m(t) = \sum_i y_i(t) \mathbf{1}_{V_i}$:
and using polar factorization

$$(2) \quad \ddot{y}_i(t) + \frac{1}{\varepsilon^2} \nabla_{y_i} \mathcal{D}(y_1(t), \dots, y_N(t)) = 0$$

$$[d_{\mathbb{S}}^2(m) = W_2^2(\text{Leb}, m_{\#} \text{Leb}) = W_2^2(\text{Leb}, \frac{1}{N} \sum_i \delta_{y_i})]$$

opt. quant.: $\nabla_{y_i} \mathcal{D} = B_i - y_i$

$$(3) \quad \ddot{y}_i(t) + \frac{1}{2\varepsilon^2} (B_i(y_1(t), \dots, y_N(t)) - y_i(t)) = 0$$

Space-discretization of Euler's equations

- X is partitioned into $(V_k)_{1 \leq k \leq N}$ with $\text{Leb}(V_k) = \frac{1}{N}$ and $\text{diam}(V_k) \simeq N^{-\frac{1}{d}}$
- $\mathbb{M}_N := \{ \text{piecewise constant functions on } (V_k) \} \subseteq \mathbb{M}$
- Given $m = \sum_i y_i \mathbf{1}_{V_i} \in \mathbb{M}_N$ one has $m_{\#} \text{Leb} = \frac{1}{N} \sum_i \delta_{y_i}$

$$(1) \quad \begin{cases} \ddot{m}(t) + \frac{1}{2\varepsilon^2} \Pi_{\mathbb{M}_N} \nabla d_{\mathbb{S}}^2(m) = 0 \\ (m(0), \dot{m}(0)) = (\Pi_{\mathbb{M}_N}(\text{id}), \Pi_{\mathbb{M}_N}(u_0)) \end{cases}$$

writing $m(t) = \sum_i y_i(t) \mathbf{1}_{V_i}$:
and using polar factorization

$$(2) \quad \ddot{y}_i(t) + \frac{1}{\varepsilon^2} \nabla_{y_i} \mathcal{D}(y_1(t), \dots, y_N(t)) = 0$$

$$[d_{\mathbb{S}}^2(m) = W_2^2(\text{Leb}, m_{\#} \text{Leb}) = W_2^2(\text{Leb}, \frac{1}{N} \sum_i \delta_{y_i})]$$

opt. quant.: $\nabla_{y_i} \mathcal{D} = B_i - y_i$

$$(3) \quad \ddot{y}_i(t) + \frac{1}{2\varepsilon^2} (B_i(y_1(t), \dots, y_N(t)) - y_i(t)) = 0$$

$\simeq y_i(t)$ is attached by a spring to the time-dependent barycenter $B_i(y_1(t), \dots, y_N(t))$.

Convergence of the space-discretization

space-discretization: (1)
$$\begin{cases} \ddot{m}(t) + \frac{1}{2\varepsilon^2} (m - \Pi_{\mathbb{M}_N} \circ \Pi_{\mathbb{S}}(m(t))) = 0 \\ m(t) \in \mathbb{M}_N \\ (m(0), \dot{m}(0)) = (\Pi_{\mathbb{M}_N}(\text{id}), \Pi_{\mathbb{M}_N}(u_0)) \end{cases}$$

Convergence of the space-discretization

space-discretization: (1)
$$\begin{cases} \ddot{m}(t) + \frac{1}{2\varepsilon^2} (m - \Pi_{\mathbb{M}_N} \circ \Pi_{\mathbb{S}}(m(t))) = 0 \\ m(t) \in \mathbb{M}_N \\ (m(0), \dot{m}(0)) = (\Pi_{\mathbb{M}_N}(\text{id}), \Pi_{\mathbb{M}_N}(u_0)) \end{cases}$$

writing $m(t) = \sum_i y_i(t) \mathbf{1}_{V_i}$: (2) $\ddot{y}_i(t) + \frac{1}{2\varepsilon^2} (B_i(y_1(t), \dots, y_N(t) - y_i(t))) = 0$

Convergence of the space-discretization

space-discretization: (1)
$$\begin{cases} \ddot{m}(t) + \frac{1}{2\varepsilon^2} (m - \Pi_{\mathbb{M}_N} \circ \Pi_{\mathbb{S}}(m(t))) = 0 \\ m(t) \in \mathbb{M}_N \\ (m(0), \dot{m}(0)) = (\Pi_{\mathbb{M}_N}(\text{id}), \Pi_{\mathbb{M}_N}(u_0)) \end{cases}$$

writing $m(t) = \sum_i y_i(t) \mathbf{1}_{V_i}$: (2) $\ddot{y}_i(t) + \frac{1}{2\varepsilon^2} (B_i(y_1(t), \dots, y_N(t) - y_i(t))) = 0$

[$\simeq y_i$ is attached by a spring to the barycenter of its (time-dependent) Laguerre cell.]

Convergence of the space-discretization

space-discretization: (1)
$$\begin{cases} \ddot{m}(t) + \frac{1}{2\varepsilon^2} (m - \Pi_{\mathbb{M}_N} \circ \Pi_{\mathbb{S}}(m(t))) = 0 \\ m(t) \in \mathbb{M}_N \\ (m(0), \dot{m}(0)) = (\Pi_{\mathbb{M}_N}(\text{id}), \Pi_{\mathbb{M}_N}(u_0)) \end{cases}$$

writing $m(t) = \sum_i y_i(t) \mathbf{1}_{V_i}$: (2) $\ddot{y}_i(t) + \frac{1}{2\varepsilon^2} (B_i(y_1(t), \dots, y_N(t) - y_i(t))) = 0$

[$\simeq y_i$ is attached by a spring to the barycenter of its (time-dependent) Laguerre cell.]

Theorem: Let (u, p) be a regular (e.g. $C^{1,1}$) solution to Euler's equations. Then,

$$\forall t \in [0, T], \quad \|\dot{m}_t - u_t \circ m_t\|_{L^2(X, \mathbb{R}^d)}^2 \leq C \left(\frac{h_N^2}{\varepsilon^2} + \varepsilon^2 + h_N \right) \quad \text{w. } h_N = N^{-1/d}$$

[Gallouët–M., 2016]

Convergence of the space-discretization

space-discretization: (1)
$$\begin{cases} \ddot{m}(t) + \frac{1}{2\varepsilon^2} (m - \Pi_{\mathbb{M}_N} \circ \Pi_{\mathbb{S}}(m(t))) = 0 \\ m(t) \in \mathbb{M}_N \\ (m(0), \dot{m}(0)) = (\Pi_{\mathbb{M}_N}(\text{id}), \Pi_{\mathbb{M}_N}(u_0)) \end{cases}$$

writing $m(t) = \sum_i y_i(t) \mathbf{1}_{V_i}$: (2) $\ddot{y}_i(t) + \frac{1}{2\varepsilon^2} (B_i(y_1(t), \dots, y_N(t) - y_i(t))) = 0$

[$\simeq y_i$ is attached by a spring to the barycenter of its (time-dependent) Laguerre cell.]

Theorem: Let (u, p) be a regular (e.g. $C^{1,1}$) solution to Euler's equations. Then,

$$\forall t \in [0, T], \quad \|\dot{m}_t - u_t \circ m_t\|_{L^2(X, \mathbb{R}^d)}^2 \leq C \left(\frac{h_N^2}{\varepsilon^2} + \varepsilon^2 + h_N \right) \quad \text{w. } h_N = N^{-1/d}$$

[Gallouët–M., 2016]

→ Proof: Gronwall on modulated energy $E_u(t) = \frac{1}{2} \|\dot{m}_t - u_t \circ m_t\|^2 + \frac{1}{2\varepsilon^2} d_{\mathbb{S}}^2(m_t)$
(Very similar to [Brenier, CMP 2000])

Convergence of the space-discretization

space-discretization: (1)
$$\begin{cases} \ddot{m}(t) + \frac{1}{2\varepsilon^2} (m - \Pi_{\mathbb{M}_N} \circ \Pi_{\mathbb{S}}(m(t))) = 0 \\ m(t) \in \mathbb{M}_N \\ (m(0), \dot{m}(0)) = (\Pi_{\mathbb{M}_N}(\text{id}), \Pi_{\mathbb{M}_N}(u_0)) \end{cases}$$

writing $m(t) = \sum_i y_i(t) \mathbf{1}_{V_i}$: (2) $\ddot{y}_i(t) + \frac{1}{2\varepsilon^2} (B_i(y_1(t), \dots, y_N(t) - y_i(t))) = 0$

[$\simeq y_i$ is attached by a spring to the barycenter of its (time-dependent) Laguerre cell.]

Theorem: Let (u, p) be a regular (e.g. $C^{1,1}$) solution to Euler's equations. Then,

$$\forall t \in [0, T], \quad \|\dot{m}_t - u_t \circ m_t\|_{L^2(X, \mathbb{R}^d)}^2 \leq C \left(\frac{h_N^2}{\varepsilon^2} + \varepsilon^2 + h_N \right) \quad \text{w. } h_N = N^{-1/d}$$

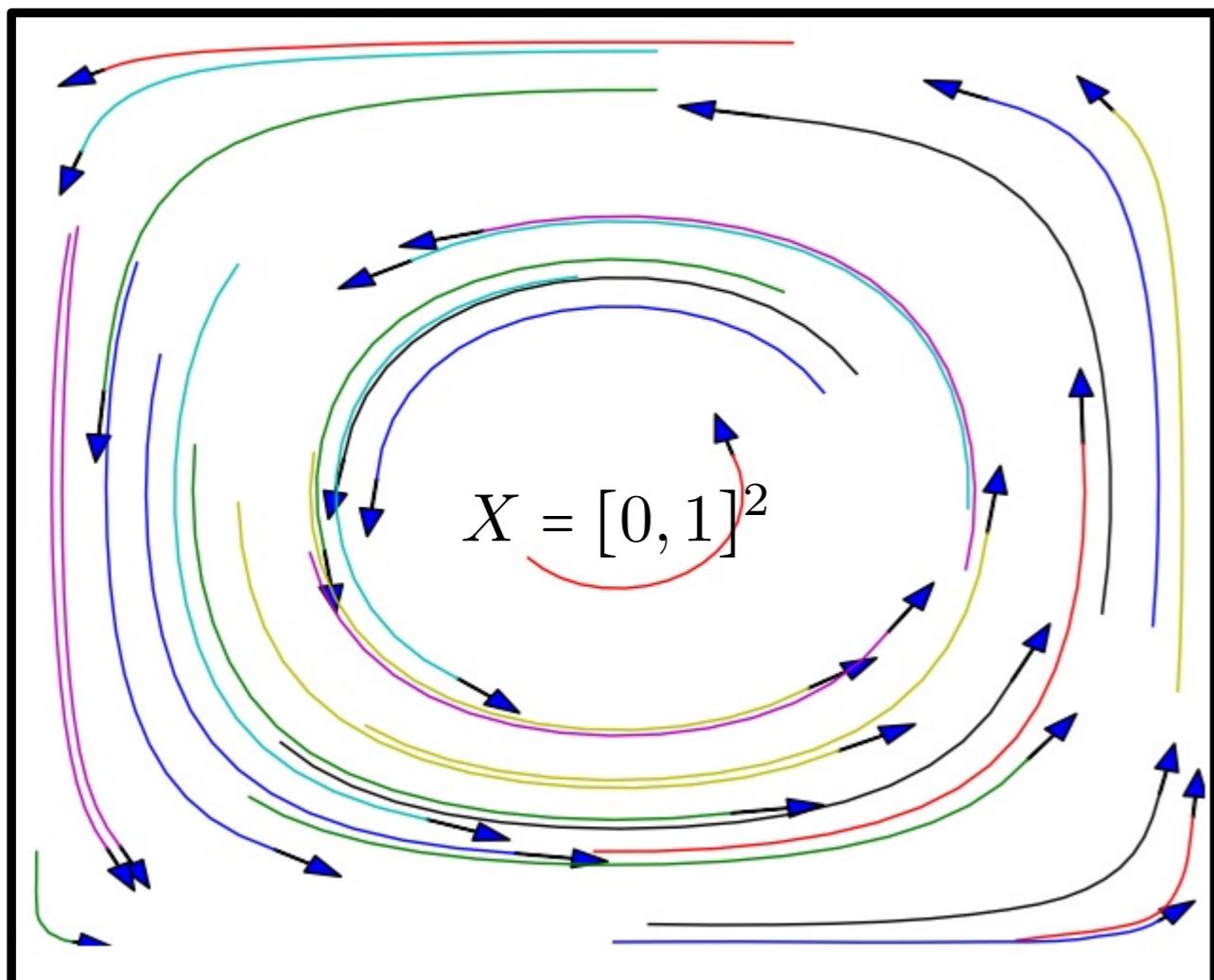
[Gallouët–M., 2016]

→ Proof: Gronwall on modulated energy $E_u(t) = \frac{1}{2} \|\dot{m}_t - u_t \circ m_t\|^2 + \frac{1}{2\varepsilon^2} d_{\mathbb{S}}^2(m_t)$
(Very similar to [Brenier, CMP 2000])

→ Convergence of a time-discretization using the symplectic Euler scheme.

Numerical result: Stationary flow on $[0, 1]^2$

Stationary flow on $[0, 1]^2$: speed: $u(\mathbf{x}) = (\cos(\pi x_1) \sin(\pi x_2), \sin(\pi x_1) \cos(\pi x_2))$
pressure: $p(\mathbf{x}) = \frac{1}{4}(\sin^2(\pi x_1) + \sin^2(\pi x_2))$



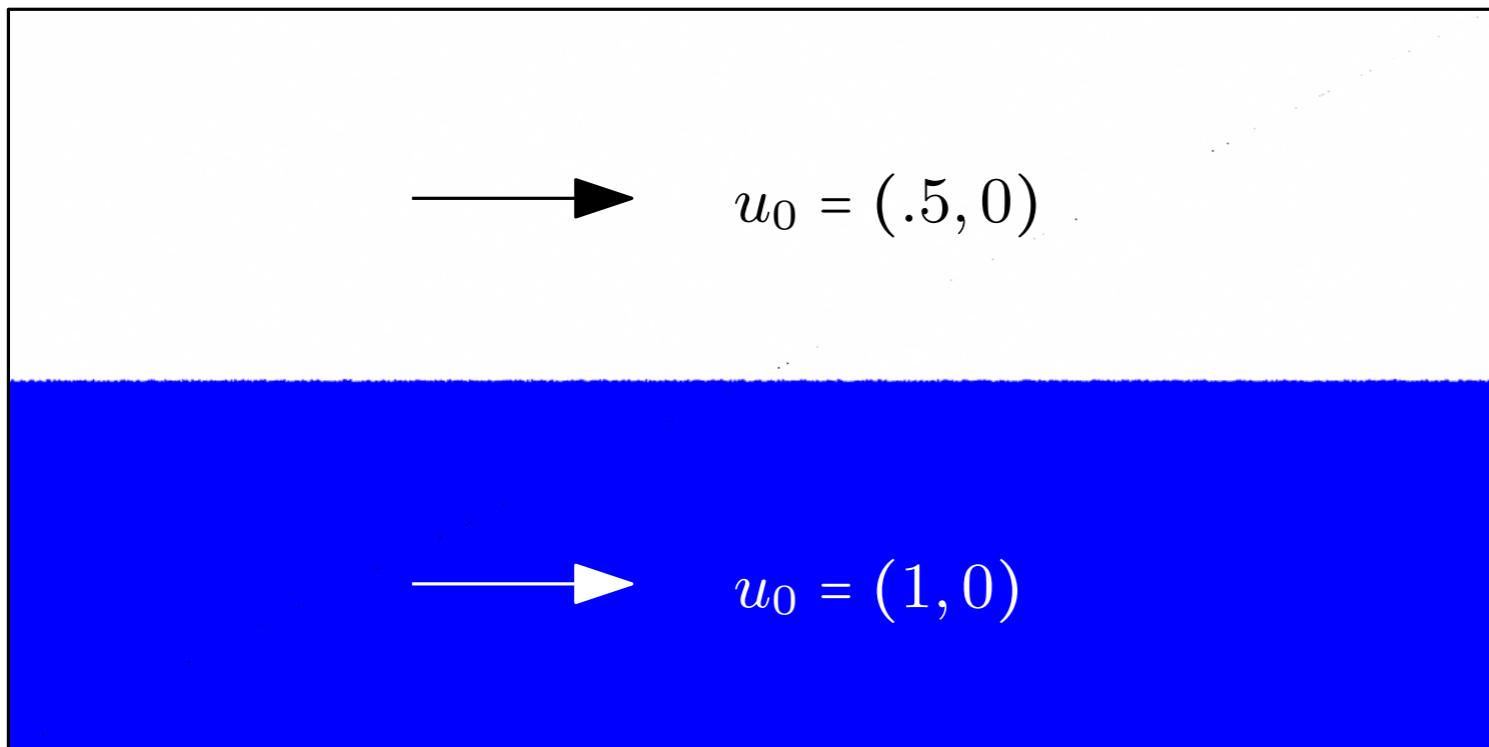
Numerical result: Instabilities

Objectives: → Larger computations, with more complex behaviour.
→ Preservation of the Hamiltonian by the discrete scheme.

Numerical result: Instabilities

Objectives: → Larger computations, with more complex behaviour.
→ Preservation of the Hamiltonian by the discrete scheme.

A. Discontinuous initial velocity



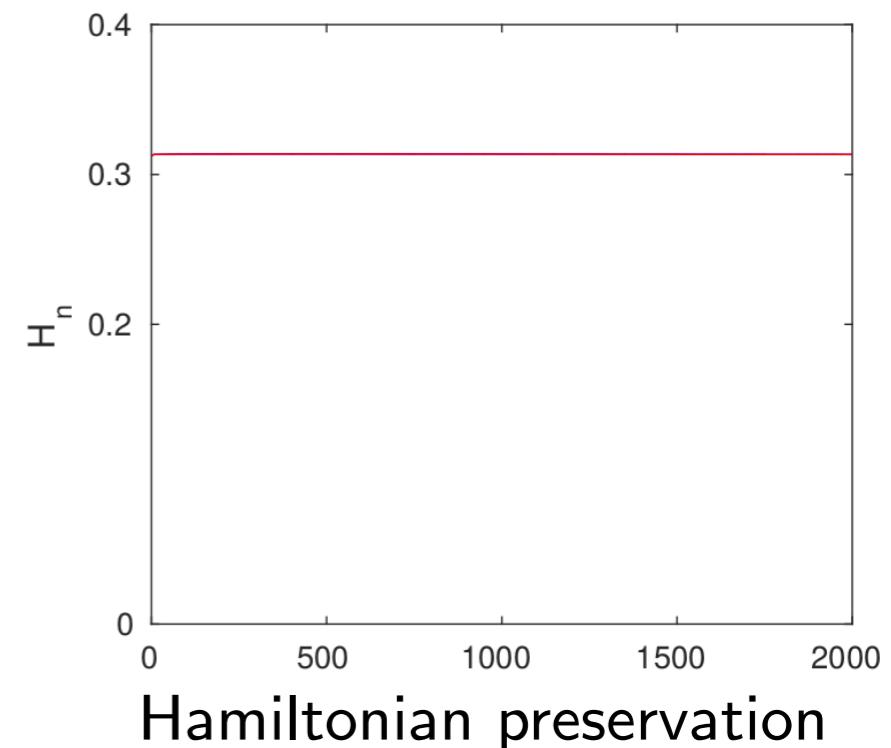
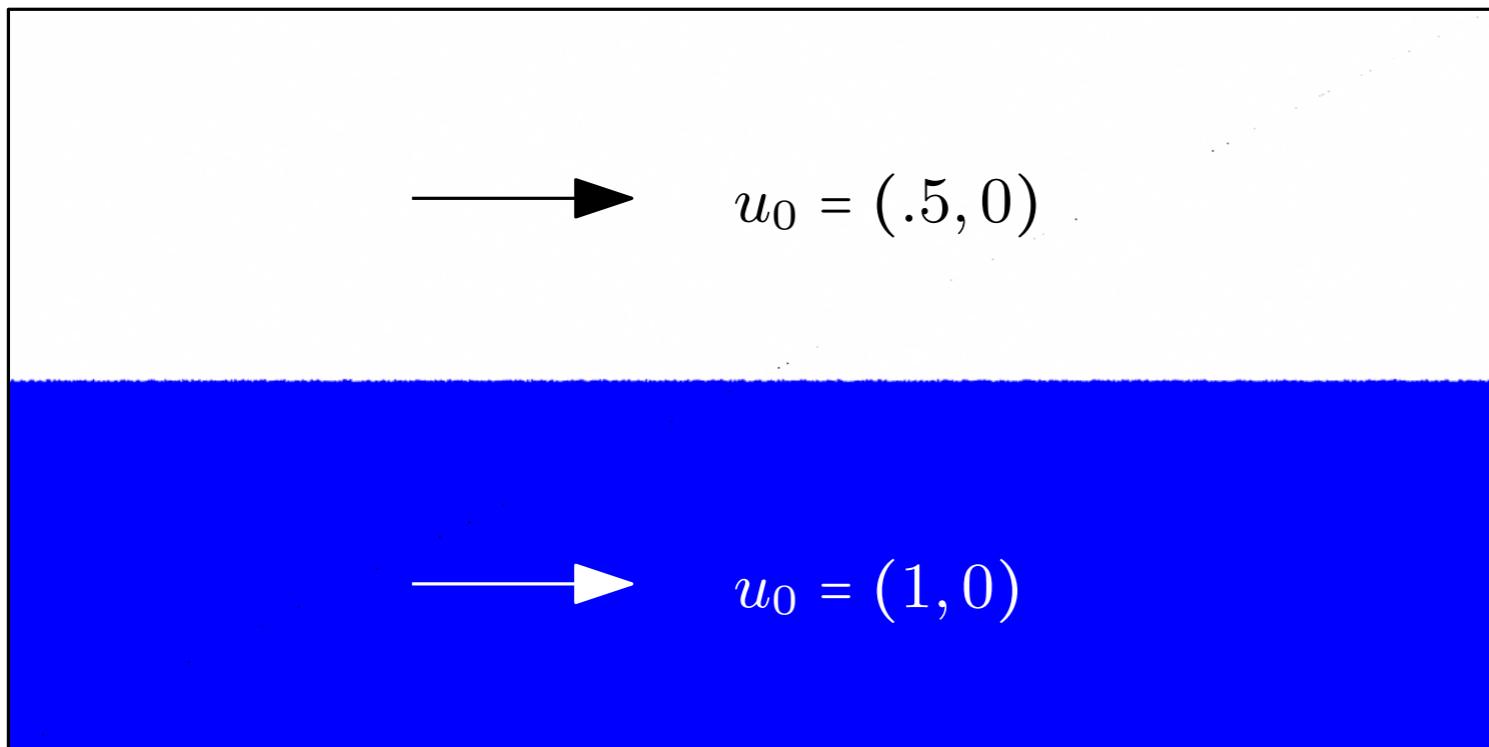
$$X = [0, 2] \times [-.5, .5] / (x = 0 \sim x = 2)$$

200k particles, 2000 timesteps, $t_{\max} = 8$

Numerical result: Instabilities

Objectives: → Larger computations, with more complex behaviour.
→ Preservation of the Hamiltonian by the discrete scheme.

A. Discontinuous initial velocity



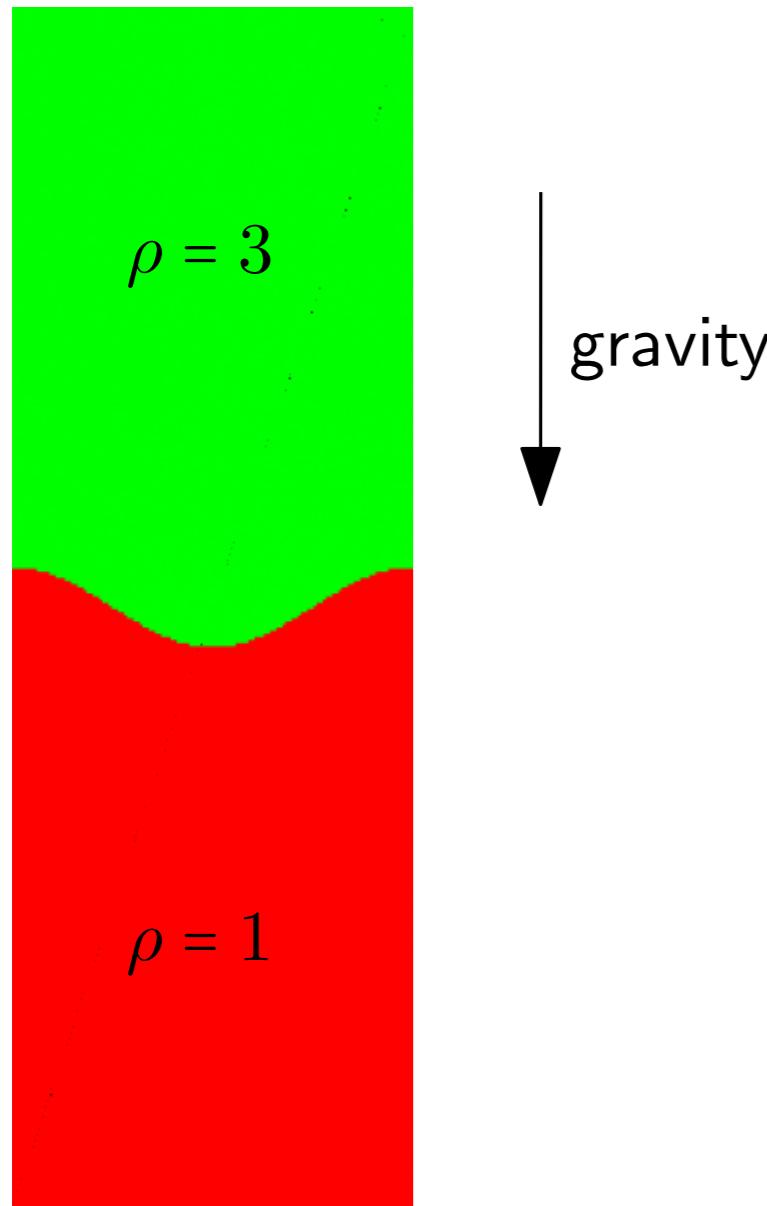
$$X = [0, 2] \times [-.5, .5] / (x = 0 \sim x = 2)$$

200k particles, 2000 timesteps, $t_{\max} = 8$

Numerical result: Instabilities

Objectives: → Larger computations, with more complex behaviour.
→ Preservation of the Hamiltonian by the discrete scheme.

B. Rayleigh-Taylor instability (Inhomogeneous fluid)



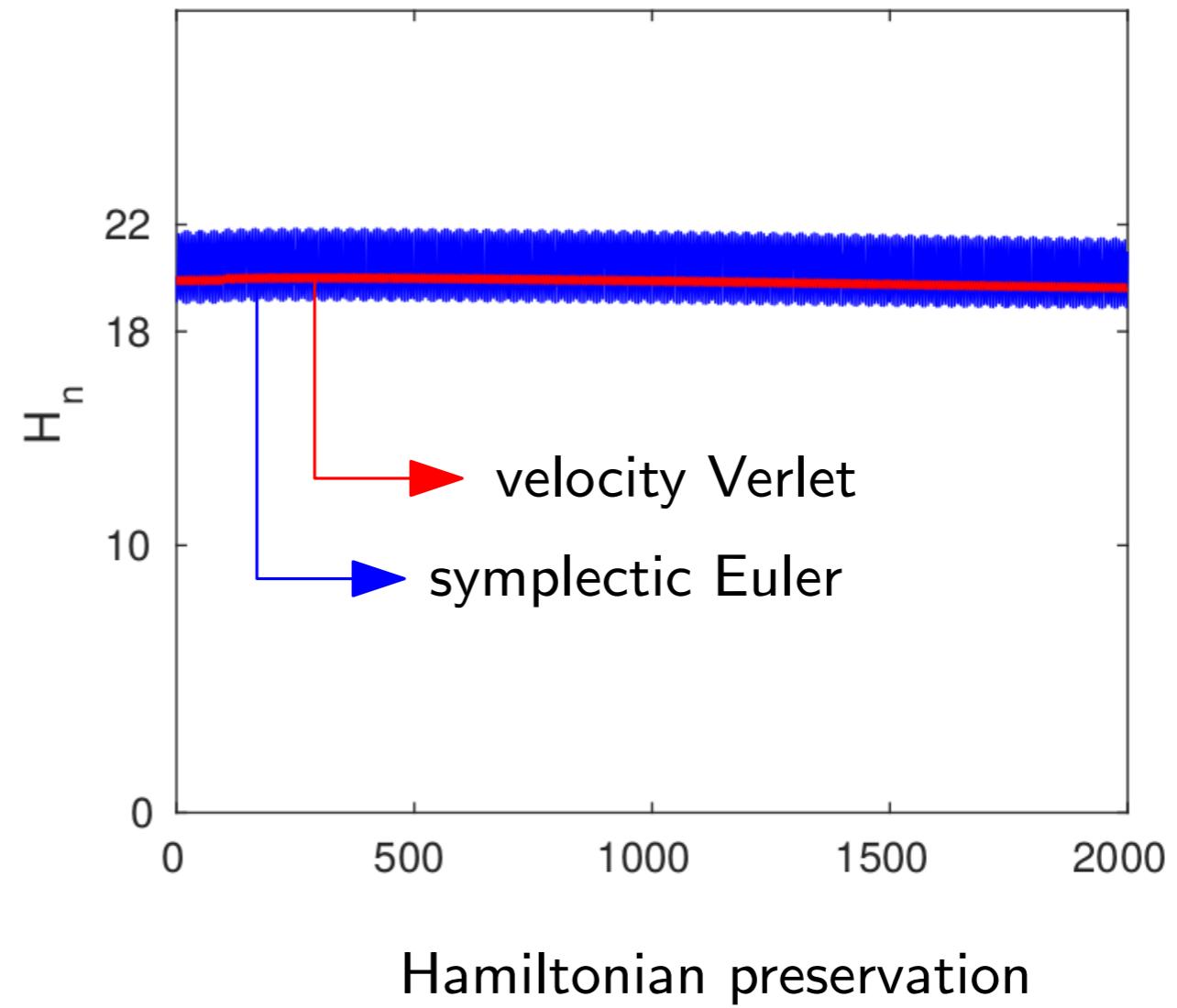
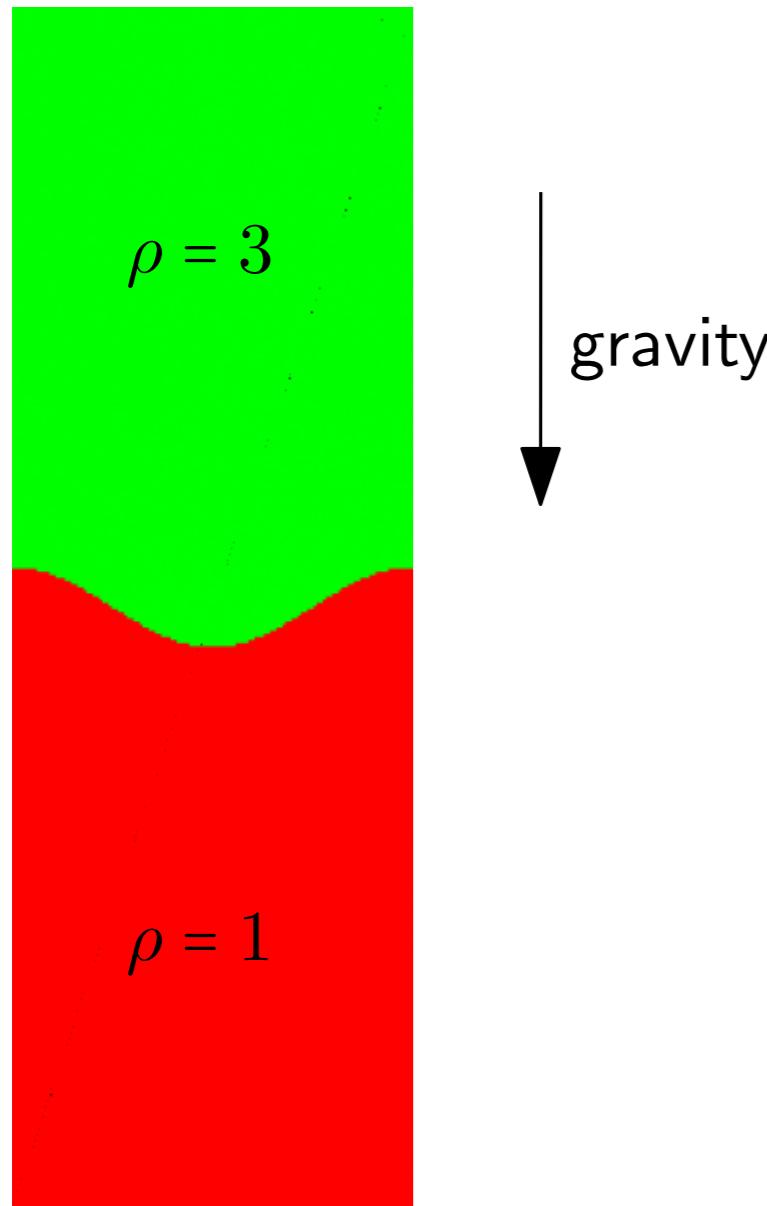
$$X = [-1, 1] \times [-3, 3]$$

15 50k particles, 2000 timesteps, $t_{\max} = 2$

Numerical result: Instabilities

Objectives: → Larger computations, with more complex behaviour.
→ Preservation of the Hamiltonian by the discrete scheme.

B. Rayleigh-Taylor instability (Inhomogeneous fluid)



$$X = [-1, 1] \times [-3, 3]$$

15 50k particles, 2000 timesteps, $t_{\max} = 2$

3. General picture

Lagrangian formulation of (some) PDEs

- We track the evolution of a **population of particles** (= probability distribution) $\rho_0 \in \mathcal{P}_2(\mathbb{R}^d)$, whose **displacement field** $s : [0, T] \rightarrow L^2(\rho_0, \mathbb{R}^d)$ satisfies

$$\dot{s} \in -\partial E(s) \quad (\textit{gradient flow})$$

$$\text{or } \ddot{s} \in -\partial E(s) \quad (\textit{hamiltonian flow})$$

Lagrangian formulation of (some) PDEs

- ▶ We track the evolution of a **population of particles** (= probability distribution) $\rho_0 \in \mathcal{P}_2(\mathbb{R}^d)$, whose **displacement field** $s : [0, T] \rightarrow L^2(\rho_0, \mathbb{R}^d)$ satisfies
 - $\dot{s} \in -\partial E(s)$ (*gradient flow*)
 - or $\ddot{s} \in -\partial E(s)$ (*hamiltonian flow*)
- ▶ The distribution of particles at time t is then $\rho(t) = s(t)_\# \rho_0$.

Lagrangian formulation of (some) PDEs

- ▶ We track the evolution of a **population of particles** (= probability distribution) $\rho_0 \in \mathcal{P}_2(\mathbb{R}^d)$, whose **displacement field** $s : [0, T] \rightarrow L^2(\rho_0, \mathbb{R}^d)$ satisfies

$$\dot{s} \in -\partial E(s) \quad (\textit{gradient flow})$$

$$\text{or } \ddot{s} \in -\partial E(s) \quad (\textit{hamiltonian flow})$$

- ▶ The distribution of particles at time t is then $\rho(t) = s(t)_\# \rho_0$.
- ▶ **Main assumption:** The energy/entropy E only depends on the distribution of particles, i.e. $E(s) = \mathcal{E}(s_\# \rho_0)$, with $\mathcal{E} : \mathcal{P}_2(\mathbb{R}^d) \rightarrow \mathbb{R} \cup \{+\infty\}$.

Lagrangian formulation of (some) PDEs

- ▶ We track the evolution of a **population of particles** (= probability distribution) $\rho_0 \in \mathcal{P}_2(\mathbb{R}^d)$, whose **displacement field** $s : [0, T] \rightarrow L^2(\rho_0, \mathbb{R}^d)$ satisfies

$$\dot{s} \in -\partial E(s) \quad (\text{gradient flow})$$

$$\text{or } \ddot{s} \in -\partial E(s) \quad (\text{hamiltonian flow})$$

- ▶ The distribution of particles at time t is then $\rho(t) = s(t)_\# \rho_0$.

- ▶ **Main assumption:** The energy/entropy E only depends on the distribution of particles, i.e. $E(s) = \mathcal{E}(s_\# \rho_0)$, with $\mathcal{E} : \mathcal{P}_2(\mathbb{R}^d) \rightarrow \mathbb{R} \cup \{+\infty\}$.

$$\mathcal{E}_{\text{ent}}(\rho) = \begin{cases} \int \rho \log \rho & \text{if } \rho \in \mathcal{P}_2^{\text{ac}}(\Omega) \\ +\infty & \text{if not} \end{cases}$$

$$\mathcal{E}_{\text{inc}}(\rho) = \begin{cases} 0 & \text{if } \rho = \text{Leb}_\Omega \\ +\infty & \text{if not} \end{cases}$$

$$\mathcal{E}_{\text{cong}}(\rho) = \begin{cases} 0 & \text{if } \rho \leq \text{Leb}_\Omega \\ +\infty & \text{if not} \end{cases}$$

$$\mathcal{E}_{\text{pot}}(\rho) = \int V d\rho$$

Lagrangian formulation of (some) PDEs

- We track the evolution of a **population of particles** (= probability distribution) $\rho_0 \in \mathcal{P}_2(\mathbb{R}^d)$, whose **displacement field** $s : [0, T] \rightarrow L^2(\rho_0, \mathbb{R}^d)$ satisfies

$$\dot{s} \in -\partial E(s) \quad (\text{gradient flow})$$

$$\text{or } \ddot{s} \in -\partial E(s) \quad (\text{hamiltonian flow})$$

- The distribution of particles at time t is then $\rho(t) = s(t)_\# \rho_0$.

- **Main assumption:** The energy/entropy E only depends on the distribution of particles, i.e. $E(s) = \mathcal{E}(s_\# \rho_0)$, with $\mathcal{E} : \mathcal{P}_2(\mathbb{R}^d) \rightarrow \mathbb{R} \cup \{+\infty\}$.

$$\mathcal{E}_{\text{ent}}(\rho) = \begin{cases} \int \rho \log \rho & \text{if } \rho \in \mathcal{P}_2^{\text{ac}}(\Omega) \\ +\infty & \text{if not} \end{cases}$$

$$\mathcal{E}_{\text{inc}}(\rho) = \begin{cases} 0 & \text{if } \rho = \text{Leb}_\Omega \\ +\infty & \text{if not} \end{cases}$$

$$\mathcal{E}_{\text{cong}}(\rho) = \begin{cases} 0 & \text{if } \rho \leq \text{Leb}_\Omega \\ +\infty & \text{if not} \end{cases}$$

$$\mathcal{E}_{\text{pot}}(\rho) = \int V d\rho$$

- **NB:** E is typically non-convex, with values in $\mathbb{R} \cup \{+\infty\}$.

Lagrangian-Eulerian dictionary

	$\dot{s} \in -\partial E(s)$
\mathcal{E}_{inc}	
$\mathcal{E}_{\text{cong}} + \mathcal{E}_{\text{pot}}$	crowd motion
$\mathcal{E}_{\text{ent}} + \mathcal{E}_{\text{pot}}$	linear Fokker-Planck equation

Wasserstein gradient-flows:

[Otto '99],

[Jordan-Kinderlehrer-Otto '98],

[Ambrosio-Gigli-Savaré '08], etc.

[Evans-Gangbo-Savin '08]

Lagrangian-Eulerian dictionary

	$\dot{s} \in -\partial E(s)$	$\ddot{s} \in -\partial E(s)$
\mathcal{E}_{inc}		incompressible Euler equation
$\mathcal{E}_{\text{cong}} + \mathcal{E}_{\text{pot}}$	crowd motion	pressureless Euler equation
$\mathcal{E}_{\text{ent}} + \mathcal{E}_{\text{pot}}$	linear Fokker-Planck equation	isentropic Euler equation

Wasserstein gradient-flows:

[Otto '99],
 [Jordan-Kinderlehrer-Otto '98],
 [Ambrosio-Gigli-Savaré '08], etc.
 [Evans-Gangbo-Savin '08]

incompressible Euler as geodesics:

[Arnold '66],
 [Ebin–Marsden '70],
 [Brenier],

Lagrangian-Eulerian dictionary

	$\dot{s} \in -\partial E(s)$	$\ddot{s} \in -\partial E(s)$
\mathcal{E}_{inc}		incompressible Euler equation
$\mathcal{E}_{\text{cong}} + \mathcal{E}_{\text{pot}}$	crowd motion	pressureless Euler equation
$\mathcal{E}_{\text{ent}} + \mathcal{E}_{\text{pot}}$	linear Fokker-Planck equation	isentropic Euler equation

Wasserstein gradient-flows:

[Otto '99],
 [Jordan-Kinderlehrer-Otto '98],
 [Ambrosio-Gigli-Savaré '08], etc.
 [Evans-Gangbo-Savin '08]

incompressible Euler as geodesics:

[Arnold '66],
 [Ebin–Marsden '70],
 [Brenier],

- ▶ Numerical advantages of using a Lagrangian formulation:
 - 1) handling many phases
 - 2) tracking of individual particles / interfaces
 - 3) allowing singular solutions (e.g. Dirac masses)

Lagrangian-Eulerian dictionary

	$\dot{s} \in -\partial E(s)$	$\ddot{s} \in -\partial E(s)$
\mathcal{E}_{inc}		incompressible Euler equation
$\mathcal{E}_{\text{cong}} + \mathcal{E}_{\text{pot}}$	crowd motion	pressureless Euler equation
$\mathcal{E}_{\text{ent}} + \mathcal{E}_{\text{pot}}$	linear Fokker-Planck equation	isentropic Euler equation

Wasserstein gradient-flows:

[Otto '99],
 [Jordan-Kinderlehrer-Otto '98],
 [Ambrosio-Gigli-Savaré '08], etc.
 [Evans-Gangbo-Savin '08]

incompressible Euler as geodesics:

[Arnold '66],
 [Ebin–Marsden '70],
 [Brenier],

- ▶ Numerical advantages of using a Lagrangian formulation:
 - 1) handling many phases
 - 2) tracking of individual particles / interfaces
 - 3) allowing singular solutions (e.g. Dirac masses)

▶ **Moreau-Yosida regularization:** $E_\varepsilon(s) := \inf_{s'} \frac{1}{2\varepsilon} \|s - s'\|^2 + E(s')$

$\dot{s}_\varepsilon = -\nabla E_\varepsilon(s_\varepsilon)$



or $\ddot{s}_\varepsilon = -\nabla E_\varepsilon(s_\varepsilon)$

4. Gradient flows and Moreau-Yosida regularization

Gradient flow case

We consider $\mathcal{E}(\rho) = \int f(\rho) + \rho V$ and $E(s) = \mathcal{E}(s\#\rho_0)$ with $s \in L^2(\rho_0, \mathbb{R}^d)$

- If $\dot{s}_t = v_t \circ s_t$ and $\rho_t := s_t \# \rho_0$, then: 1) $\dot{\rho}_t + \operatorname{div}(\rho_t v_t) = 0$,

Gradient flow case

We consider $\mathcal{E}(\rho) = \int f(\rho) + \rho V$ and $E(s) = \mathcal{E}(s\#\rho_0)$ with $s \in L^2(\rho_0, \mathbb{R}^d)$

- If $\dot{s}_t = v_t \circ s_t$ and $\rho_t := s_t \# \rho_0$, then:
 - 1) $\dot{\rho}_t + \operatorname{div}(\rho_t v_t) = 0,$
 - 2) $\frac{d}{dt} \mathcal{E}(\rho_t) = \langle \nabla(f'(\rho_t) + \nabla V) \circ s_t | \dot{s}_t \rangle_{L^2(\rho_0)}$

Gradient flow case

We consider $\mathcal{E}(\rho) = \int f(\rho) + \rho V$ and $E(s) = \mathcal{E}(s\#\rho_0)$ with $s \in L^2(\rho_0, \mathbb{R}^d)$

- ▶ If $\dot{s}_t = v_t \circ s_t$ and $\rho_t := s_t \# \rho_0$, then:
 - 1) $\dot{\rho}_t + \operatorname{div}(\rho_t v_t) = 0,$
 - 2) $\frac{d}{dt} \mathcal{E}(\rho_t) = \langle \nabla(f'(\rho_t) + \nabla V) \circ s_t | \dot{s}_t \rangle_{L^2(\rho_0)}$

$$\begin{aligned}\text{Proof of 2): } \frac{d}{dt} \mathcal{E}(\rho_t) &= \frac{d}{dt} \int f(\rho_t) + \rho_t V = \int (f'(\rho_t) + V) \dot{\rho}_t \\&= - \int (f'(\rho_t) + V) \operatorname{div}(\rho_t v_t) && [\text{by 1)}] \\&= \int \langle \nabla f'(\rho_t) + \nabla V | v_t \rangle d\rho_t && [\text{by Stokes}] \\&= \int \langle (\nabla f'(\rho_t) + \nabla V) \circ s_t | \dot{s}_t \rangle d\rho_0 && [y = s_t(x)]\end{aligned}$$

Gradient flow case

We consider $\mathcal{E}(\rho) = \int f(\rho) + \rho V$ and $E(s) = \mathcal{E}(s\#\rho_0)$ with $s \in L^2(\rho_0, \mathbb{R}^d)$

- If $\dot{s}_t = v_t \circ s_t$ and $\rho_t := s_t \# \rho_0$, then:
 - 1) $\dot{\rho}_t + \operatorname{div}(\rho_t v_t) = 0$,
 - 2) $\frac{d}{dt} \mathcal{E}(\rho_t) = \langle \nabla(f'(\rho_t) + \nabla V) \circ s_t | \dot{s}_t \rangle_{L^2(\rho_0)}$

$$\nabla E(s) = (\nabla f'(\rho) + \nabla V) \circ s, \text{ with } \rho = s \# \rho_0$$

Gradient flow case

We consider $\mathcal{E}(\rho) = \int f(\rho) + \rho V$ and $E(s) = \mathcal{E}(s\#\rho_0)$ with $s \in L^2(\rho_0, \mathbb{R}^d)$

- If $\dot{s}_t = v_t \circ s_t$ and $\rho_t := s_t \# \rho_0$, then:
 - 1) $\dot{\rho}_t + \operatorname{div}(\rho_t v_t) = 0$,
 - 2) $\frac{d}{dt} \mathcal{E}(\rho_t) = \langle \nabla(f'(\rho_t) + \nabla V) \circ s_t | \dot{s}_t \rangle_{L^2(\rho_0)}$
- $\nabla E(s) = (\nabla f'(\rho) + \nabla V) \circ s$, with $\rho = s \# \rho_0$
- Formally $\dot{s}_t = -\nabla E(s_t)$ leads to the equations

$$\begin{cases} \dot{s}_t = v_t \circ s_t \\ \rho_t = s_t \# \rho_0 \\ v_t = -(\nabla f'(\rho_t) + \nabla V) \end{cases}$$

(Lagrangian)
[Evans-Gangbo-Savin '08]

Gradient flow case

We consider $\mathcal{E}(\rho) = \int f(\rho) + \rho V$ and $E(s) = \mathcal{E}(s\#\rho_0)$ with $s \in L^2(\rho_0, \mathbb{R}^d)$

- If $\dot{s}_t = v_t \circ s_t$ and $\rho_t := s_t \# \rho_0$, then: 1) $\dot{\rho}_t + \operatorname{div}(\rho_t v_t) = 0$,
2) $\frac{d}{dt} \mathcal{E}(\rho_t) = \langle \nabla(f'(\rho_t) + \nabla V) \circ s_t | \dot{s}_t \rangle_{L^2(\rho_0)}$

$$\nabla E(s) = (\nabla f'(\rho) + \nabla V) \circ s, \text{ with } \rho = s \# \rho_0$$

- Formally $\dot{s}_t = -\nabla E(s_t)$ leads to the equations

$$\begin{cases} \dot{s}_t = v_t \circ s_t \\ \rho_t = s_t \# \rho_0 \\ v_t = -(\nabla f'(\rho_t) + \nabla V) \end{cases}$$

(Lagrangian)

[Evans-Gangbo-Savin '08]

$$\dot{\rho}_t + \operatorname{div}[\rho_t(\nabla f'(\rho_t) + \nabla V)] = 0$$

(Eulerian)

[Otto '99]

Gradient flow case

We consider $\mathcal{E}(\rho) = \int f(\rho) + \rho V$ and $E(s) = \mathcal{E}(s\#\rho_0)$ with $s \in L^2(\rho_0, \mathbb{R}^d)$

- If $\dot{s}_t = v_t \circ s_t$ and $\rho_t := s_t \# \rho_0$, then: 1) $\dot{\rho}_t + \operatorname{div}(\rho_t v_t) = 0$,
2) $\frac{d}{dt} \mathcal{E}(\rho_t) = \langle \nabla(f'(\rho_t) + \nabla V) \circ s_t | \dot{s}_t \rangle_{L^2(\rho_0)}$

$$\nabla E(s) = (\nabla f'(\rho) + \nabla V) \circ s, \text{ with } \rho = s \# \rho_0$$

- Formally $\dot{s}_t = -\nabla E(s_t)$ leads to the equations

$$\begin{cases} \dot{s}_t = v_t \circ s_t \\ \rho_t = s_t \# \rho_0 \\ v_t = -(\nabla f'(\rho_t) + \nabla V) \end{cases}$$

(Lagrangian)

[Evans-Gangbo-Savin '08]

$$\dot{\rho}_t + \operatorname{div}[\rho_t(\nabla f'(\rho_t) + \nabla V)] = 0$$

(Eulerian)

[Otto '99]

Examples: $f(r) = r \log r \rightarrow \dot{\rho}_t = \Delta \rho_t + \operatorname{div}(\rho_t \nabla V)$

$f(r) = \frac{1}{m} r^m \rightarrow \dot{\rho}_t = \Delta \rho_t^m + \operatorname{div}(\rho_t \nabla V)$

Gradient flow case

We consider $\mathcal{E}(\rho) = \int f(\rho) + \rho V$ and $E(s) = \mathcal{E}(s\#\rho_0)$ with $s \in L^2(\rho_0, \mathbb{R}^d)$

- If $\dot{s}_t = v_t \circ s_t$ and $\rho_t := s_t \# \rho_0$, then: 1) $\dot{\rho}_t + \operatorname{div}(\rho_t v_t) = 0$,
2) $\frac{d}{dt} \mathcal{E}(\rho_t) = \langle \nabla(f'(\rho_t) + \nabla V) \circ s_t | \dot{s}_t \rangle_{L^2(\rho_0)}$

$$\nabla E(s) = (\nabla f'(\rho) + \nabla V) \circ s, \text{ with } \rho = s \# \rho_0$$

- Formally $\dot{s}_t = -\nabla E(s_t)$ leads to the equations

$$\begin{cases} \dot{s}_t = v_t \circ s_t \\ \rho_t = s_t \# \rho_0 \\ v_t = -(\nabla f'(\rho_t) + \nabla V) \end{cases}$$

(Lagrangian)
[Evans-Gangbo-Savin '08]

$$\dot{\rho}_t + \operatorname{div}[\rho_t(\nabla f'(\rho_t) + \nabla V)] = 0$$

(Eulerian)
[Otto '99]

Examples: $f(r) = r \log r \rightarrow \dot{\rho}_t = \Delta \rho_t + \operatorname{div}(\rho_t \nabla V)$

$$f(r) = \frac{1}{m} r^m \rightarrow \dot{\rho}_t = \Delta \rho_t^m + \operatorname{div}(\rho_t \nabla V)$$

- **Regular** lagrangian trajectory associated to heat flow (\neq Brownian motion!)

(Numerical) approximation of gradient flows

- ▶ **Minimizing-movement (JKO) scheme:** for $\tau > 0$ define a time-discretization by

$$s_\tau^{n+1} \in \arg \min_s \frac{1}{2\tau} \|s_\tau^n - s\|^2 + E(s)$$

[Jordan-Kinderlehrer-Otto '98]

(Numerical) approximation of gradient flows

- ▶ **Minimizing-movement (JKO) scheme:** for $\tau > 0$ define a time-discretization by

$$s_\tau^{n+1} \in \arg \min_s \frac{1}{2\tau} \|s_\tau^n - s\|^2 + E(s)$$

[Jordan-Kinderlehrer-Otto '98]

$$\iff \text{Implicit Euler scheme } \frac{s_\tau^{n+1} - s_\tau^n}{\tau} = -\nabla E(s_\tau^{n+1}).$$

(Numerical) approximation of gradient flows

- ▶ **Minimizing-movement (JKO) scheme:** for $\tau > 0$ define a time-discretization by

$$s_\tau^{n+1} \in \arg \min_s \frac{1}{2\tau} \|s_\tau^n - s\|^2 + E(s)$$

[Jordan-Kinderlehrer-Otto '98]

$$\iff \text{Implicit Euler scheme } \frac{s_\tau^{n+1} - s_\tau^n}{\tau} = -\nabla E(s_\tau^{n+1}).$$

- ▶ **Particle discretization:** i.e. s piecewise constant / $\rho = s_\# \rho_0$ finitely supported

Main difficulty: $\mathcal{E}\left(\frac{1}{N} \sum_i \delta_{y_i}\right) = +\infty$. Possible solutions:

- spreading the mass $\frac{1}{N} \delta_{y_i}$ uniformly over a Voronoi/Laguerre cell or a ball:

[Blanchet-Calvez-Carrillo '08] [Benamou-Carlier-M.-Oudet '14]

[Carrillo-Huang-Patacchini-Wollansky '17]

(Numerical) approximation of gradient flows

- ▶ **Minimizing-movement (JKO) scheme:** for $\tau > 0$ define a time-discretization by

$$s_\tau^{n+1} \in \arg \min_s \frac{1}{2\tau} \|s_\tau^n - s\|^2 + E(s)$$

[Jordan-Kinderlehrer-Otto '98]

$$\iff \text{Implicit Euler scheme } \frac{s_\tau^{n+1} - s_\tau^n}{\tau} = -\nabla E(s_\tau^{n+1}).$$

- ▶ **Particle discretization:** i.e. s piecewise constant / $\rho = s_\# \rho_0$ finitely supported

Main difficulty: $\mathcal{E}\left(\frac{1}{N} \sum_i \delta_{y_i}\right) = +\infty$. Possible solutions:

- spreading the mass $\frac{1}{N} \delta_{y_i}$ uniformly over a Voronoi/Laguerre cell or a ball:

[Blanchet-Calvez-Carrillo '08] [Benamou-Carlier-M.-Oudet '14]

[Carrillo-Huang-Patacchini-Wollansky '17]

- replacing $\mathcal{E}(\mu)$ by $\mathcal{E}(\mu * \eta_\varepsilon)$: [Carrillo-Craig-Patacchini '18]

(Numerical) approximation of gradient flows

- ▶ **Minimizing-movement (JKO) scheme:** for $\tau > 0$ define a time-discretization by

$$s_\tau^{n+1} \in \arg \min_s \frac{1}{2\tau} \|s_\tau^n - s\|^2 + E(s)$$

[Jordan-Kinderlehrer-Otto '98]

$$\iff \text{Implicit Euler scheme } \frac{s_\tau^{n+1} - s_\tau^n}{\tau} = -\nabla E(s_\tau^{n+1}).$$

- ▶ **Particle discretization:** i.e. s piecewise constant / $\rho = s_\# \rho_0$ finitely supported

Main difficulty: $\mathcal{E}\left(\frac{1}{N} \sum_i \delta_{y_i}\right) = +\infty$. Possible solutions:

- spreading the mass $\frac{1}{N} \delta_{y_i}$ uniformly over a Voronoi/Laguerre cell or a ball:

[Blanchet-Calvez-Carrillo '08] [Benamou-Carlier-M.-Oudet '14]

[Carrillo-Huang-Patacchini-Wollansky '17]

- replacing $\mathcal{E}(\mu)$ by $\mathcal{E}(\mu * \eta_\varepsilon)$: [Carrillo-Craig-Patacchini '18]

- ▶ **Moreau-Yosida regularization:** $E_\varepsilon(s) := \inf_{s'} \frac{1}{2\varepsilon} \|s - s'\|^2 + E(s')$

$$\dot{s} \in -\partial E(s) \longrightarrow \dot{s}_\varepsilon = -\nabla E_\varepsilon(s_\varepsilon)$$

Moreau-Yosida regularization in Wasserstein space

- ▶ **Wasserstein distance** between two probability measures $\rho, \mu \in \mathcal{P}_2(\mathbb{R}^d)$,

$$\begin{aligned} W_2^2(\rho, \mu) &= \min_T \int \|x - T(x)\|^2 d\rho(x) \text{ under the constraint } T_{\#}\rho = \mu \\ &= \text{measures how "costly" it is to move mass from } \rho \text{ to } \mu \end{aligned}$$

Moreau-Yosida regularization in Wasserstein space

- ▶ **Wasserstein distance** between two probability measures $\rho, \mu \in \mathcal{P}_2(\mathbb{R}^d)$,

$W_2^2(\rho, \mu) = \min_T \int \|x - T(x)\|^2 d\rho(x)$ under the constraint $T_\# \rho = \mu$
= measures how "costly" it is to move mass from ρ to μ

- ▶ **Moreau-Yosida in $(\mathcal{P}(\mathbb{R}^d), W_2)$ vs $(L^2(\rho_0, \mathbb{R}^d), \|.\|)$:**

$$E_\varepsilon(s) := \inf_{s'} \frac{1}{2\varepsilon} \|s - s'\|^2 + E(s')$$

$$\mathcal{E}_\varepsilon(\mu) := \inf_\sigma \frac{1}{2\varepsilon} W_2^2(\sigma, \mu) + \mathcal{E}(\sigma)$$

Prop. If $E(s) := \mathcal{E}(s_\# \rho)$, then $E_\varepsilon(s) = \mathcal{E}_\varepsilon(s_\# \rho_0)$.

Moreau-Yosida regularization in Wasserstein space

- ▶ **Wasserstein distance** between two probability measures $\rho, \mu \in \mathcal{P}_2(\mathbb{R}^d)$,

$W_2^2(\rho, \mu) = \min_T \int \|x - T(x)\|^2 d\rho(x)$ under the constraint $T_{\#}\rho = \mu$
= measures how "costly" it is to move mass from ρ to μ

- ▶ **Moreau-Yosida in $(\mathcal{P}(\mathbb{R}^d), W_2)$ vs $(L^2(\rho_0, \mathbb{R}^d), \|.\|)$:**

$$E_\varepsilon(s) := \inf_{s'} \frac{1}{2\varepsilon} \|s - s'\|^2 + E(s')$$

$$\mathcal{E}_\varepsilon(\mu) := \inf_{\sigma} \frac{1}{2\varepsilon} W_2^2(\sigma, \mu) + \mathcal{E}(\sigma)$$

$$\text{"\geq": } \|s - s'\|_{L^2(\rho_0)}^2 \geq W_2^2(s_{\#}\rho_0, s'_{\#}\rho_0)$$

Prop. If $E(s) := \mathcal{E}(s_{\#}\rho)$, then $E_\varepsilon(s) = \mathcal{E}_\varepsilon(s_{\#}\rho_0)$.

Moreau-Yosida regularization in Wasserstein space

- ▶ **Wasserstein distance** between two probability measures $\rho, \mu \in \mathcal{P}_2(\mathbb{R}^d)$,

$W_2^2(\rho, \mu) = \min_T \int \|x - T(x)\|^2 d\rho(x)$ under the constraint $T_\# \rho = \mu$
= measures how "costly" it is to move mass from ρ to μ

- ▶ **Moreau-Yosida in $(\mathcal{P}(\mathbb{R}^d), W_2)$ vs $(L^2(\rho_0, \mathbb{R}^d), \|.\|)$:**

$$E_\varepsilon(s) := \inf_{s'} \frac{1}{2\varepsilon} \|s - s'\|^2 + E(s')$$

$$\text{"\geq": } \|s - s'\|_{L^2(\rho_0)}^2 \geq W_2^2(s_\# \rho_0, s'_\# \rho_0)$$

$$\mathcal{E}_\varepsilon(\mu) := \inf_\sigma \frac{1}{2\varepsilon} W_2^2(\sigma, \mu) + \mathcal{E}(\sigma)$$

Prop. If $E(s) := \mathcal{E}(s_\# \rho)$, then $E_\varepsilon(s) = \mathcal{E}_\varepsilon(s_\# \rho_0)$.

$$\mathcal{E}_{\text{inc}}(\rho) = \begin{cases} 0 & \text{if } \rho = \text{Leb}_\Omega \\ +\infty & \text{if not} \end{cases} \longrightarrow \mathcal{E}_{\text{inc}, \varepsilon}(\mu) = \frac{1}{2\varepsilon} W_2^2(\text{Leb}_\Omega, \mu)$$

Moreau-Yosida regularization in Wasserstein space

- ▶ **Wasserstein distance** between two probability measures $\rho, \mu \in \mathcal{P}_2(\mathbb{R}^d)$,

$W_2^2(\rho, \mu) = \min_T \int \|x - T(x)\|^2 d\rho(x)$ under the constraint $T_{\#}\rho = \mu$
 = measures how "costly" it is to move mass from ρ to μ

- ▶ **Moreau-Yosida in $(\mathcal{P}(\mathbb{R}^d), W_2)$ vs $(L^2(\rho_0, \mathbb{R}^d), \|\cdot\|)$:**

$$E_\varepsilon(s) := \inf_{s'} \frac{1}{2\varepsilon} \|s - s'\|^2 + E(s')$$

$$\mathcal{E}_\varepsilon(\mu) := \inf_\sigma \frac{1}{2\varepsilon} W_2^2(\sigma, \mu) + \mathcal{E}(\sigma)$$

" \geq ": $\|s - s'\|_{L^2(\rho_0)}^2 \geq W_2^2(s_{\#}\rho_0, s'_{\#}\rho_0)$

Prop. If $E(s) := \mathcal{E}(s_{\#}\rho)$, then $E_\varepsilon(s) = \mathcal{E}_\varepsilon(s_{\#}\rho_0)$.

$$\mathcal{E}_{\text{inc}}(\rho) = \begin{cases} 0 & \text{if } \rho = \text{Leb}_\Omega \\ +\infty & \text{if not} \end{cases} \longrightarrow \mathcal{E}_{\text{inc}, \varepsilon}(\mu) = \frac{1}{2\varepsilon} W_2^2(\text{Leb}_\Omega, \mu)$$

$$\mathcal{E}_{\text{cong}}(\rho) = \begin{cases} 0 & \text{if } \rho \leq \text{Leb}_\Omega \\ +\infty & \text{if not} \end{cases} \longrightarrow \mathcal{E}_{\text{cong}, \varepsilon}(\mu) = \frac{1}{2\varepsilon} \min_{\sigma \leq \text{Leb}_\Omega} W_2^2(\sigma, \mu)$$

Moreau-Yosida regularization in Wasserstein space

- ▶ **Wasserstein distance** between two probability measures $\rho, \mu \in \mathcal{P}_2(\mathbb{R}^d)$,

$W_2^2(\rho, \mu) = \min_T \int \|x - T(x)\|^2 d\rho(x)$ under the constraint $T_{\#}\rho = \mu$
 = measures how "costly" it is to move mass from ρ to μ

- ▶ **Moreau-Yosida in $(\mathcal{P}(\mathbb{R}^d), W_2)$ vs $(L^2(\rho_0, \mathbb{R}^d), \|\cdot\|)$:**

$$E_\varepsilon(s) := \inf_{s'} \frac{1}{2\varepsilon} \|s - s'\|^2 + E(s')$$

$$\mathcal{E}_\varepsilon(\mu) := \inf_\sigma \frac{1}{2\varepsilon} W_2^2(\sigma, \mu) + \mathcal{E}(\sigma)$$

" \geq ": $\|s - s'\|_{L^2(\rho_0)}^2 \geq W_2^2(s_{\#}\rho_0, s'_{\#}\rho_0)$

Prop. If $E(s) := \mathcal{E}(s_{\#}\rho)$, then $E_\varepsilon(s) = \mathcal{E}_\varepsilon(s_{\#}\rho_0)$.

$$\mathcal{E}_{\text{inc}}(\rho) = \begin{cases} 0 & \text{if } \rho = \text{Leb}_\Omega \\ +\infty & \text{if not} \end{cases} \longrightarrow \mathcal{E}_{\text{inc}, \varepsilon}(\mu) = \frac{1}{2\varepsilon} W_2^2(\text{Leb}_\Omega, \mu)$$

$$\mathcal{E}_{\text{cong}}(\rho) = \begin{cases} 0 & \text{if } \rho \leq \text{Leb}_\Omega \\ +\infty & \text{if not} \end{cases} \longrightarrow \mathcal{E}_{\text{cong}, \varepsilon}(\mu) = \frac{1}{2\varepsilon} \min_{\sigma \leq \text{Leb}_\Omega} W_2^2(\sigma, \mu)$$

Space-discretization: assume that $\mu = \text{uniform over a finite set} = \frac{1}{N} \sum_{1 \leq i \leq N} \delta_{y_i}$

5. Lagrangian discretization of crowd motion

Crowd motion model

$$\Omega \subset \mathbb{R}^d, |\Omega| > 1, \rho_0 \in \mathcal{P}^{\text{ac}}(\Omega)$$

[Maury, Roudneff-Chupin, Santambrogio '09]

- ▶ The crowd is subject to two forces:

$$E_{\text{pot}}(s) = \int V(s(x)) d\rho_0(x)$$

$$E_{\text{cong}}(s) = \begin{cases} 0 & \text{if } s_{\#}\rho_0 \leq \text{Leb}_{\Omega} \\ +\infty & \text{if not} \end{cases}$$

- ▶ Lagrangian formulation of the model:

$$\dot{s} \in -\partial(E_{\text{pot}} + E_{\text{cong}})(s)$$

Crowd motion model

$$\Omega \subset \mathbb{R}^d, |\Omega| > 1, \rho_0 \in \mathcal{P}^{\text{ac}}(\Omega)$$

[Maury, Roudneff-Chupin, Santambrogio '09]

- The crowd is subject to two forces:

$$E_{\text{pot}}(s) = \int V(s(x)) d\rho_0(x)$$

$$E_{\text{cong}}(s) = \begin{cases} 0 & \text{if } s_{\#}\rho_0 \leq \text{Leb}_{\Omega} \\ +\infty & \text{if not} \end{cases}$$

- Lagrangian formulation of the model:

$$\dot{s} \in -\partial(E_{\text{pot}} + E_{\text{cong}})(s)$$

Prop: If $s \in K$ and $\rho = s_{\#}\rho_0$, then

$$\partial E_{\text{cong}}(s) = \{\nabla p \circ s \mid p \geq 0, p(1 - \rho) = 0\}.$$

Crowd motion model

$$\Omega \subset \mathbb{R}^d, |\Omega| > 1, \rho_0 \in \mathcal{P}^{\text{ac}}(\Omega)$$

[Maury, Roudneff-Chupin, Santambrogio '09]

- The crowd is subject to two forces:

$$E_{\text{pot}}(s) = \int V(s(x)) d\rho_0(x)$$

$$E_{\text{cong}}(s) = \begin{cases} 0 & \text{if } s_{\#}\rho_0 \leq \text{Leb}_{\Omega} \\ +\infty & \text{if not} \end{cases}$$

- Lagrangian formulation of the model:

$$\dot{s} \in -\partial(E_{\text{pot}} + E_{\text{cong}})(s)$$

Prop: If $s \in K$ and $\rho = s_{\#}\rho_0$, then

$$\partial E_{\text{cong}}(s) = \{\nabla p \circ s \mid p \geq 0, p(1 - \rho) = 0\}.$$

$$\iff \begin{cases} \dot{s} = -\nabla V \circ s - \nabla p \circ s \\ \rho = s_{\#}\rho_0 \\ \rho \leq \text{Leb}_{\Omega} \\ p \geq 0, p(1 - \rho) = 0 \end{cases}$$

Crowd motion model

$$\Omega \subset \mathbb{R}^d, |\Omega| > 1, \rho_0 \in \mathcal{P}^{\text{ac}}(\Omega)$$

[Maury, Roudneff-Chupin, Santambrogio '09]

- The crowd is subject to two forces:

$$E_{\text{pot}}(s) = \int V(s(x)) d\rho_0(x)$$

$$E_{\text{cong}}(s) = \begin{cases} 0 & \text{if } s_{\#}\rho_0 \leq \text{Leb}_{\Omega} \\ +\infty & \text{if not} \end{cases}$$

- Lagrangian formulation of the model:

$$\dot{s} \in -\partial(E_{\text{pot}} + E_{\text{cong}})(s)$$

Prop: If $s \in K$ and $\rho = s_{\#}\rho_0$, then

$$\partial E_{\text{cong}}(s) = \{\nabla p \circ s \mid p \geq 0, p(1 - \rho) = 0\}.$$

$$\iff \begin{cases} \dot{s} = -\nabla V \circ s - \nabla p \circ s \\ \rho = s_{\#}\rho_0 \\ \rho \leq \text{Leb}_{\Omega} \\ p \geq 0, p(1 - \rho) = 0 \end{cases}$$

- Eulerian formulation of the model:

$$\begin{cases} \partial_t \rho - \text{div}(\rho \nabla V + \rho \nabla p) = 0 \\ \rho(0) = \rho_0 \\ \rho \leq \text{Leb}_{\Omega} \\ p \geq 0, p(1 - \rho) = 0 \end{cases}$$

Computing $\mathcal{E}_{\text{cong}, \varepsilon}$ (congestion)

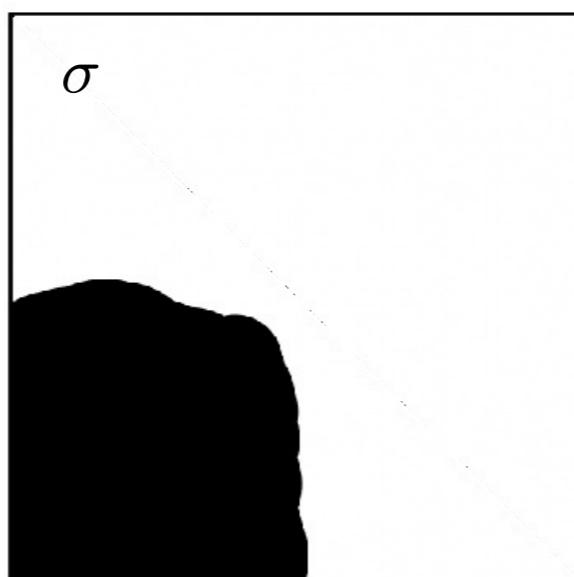
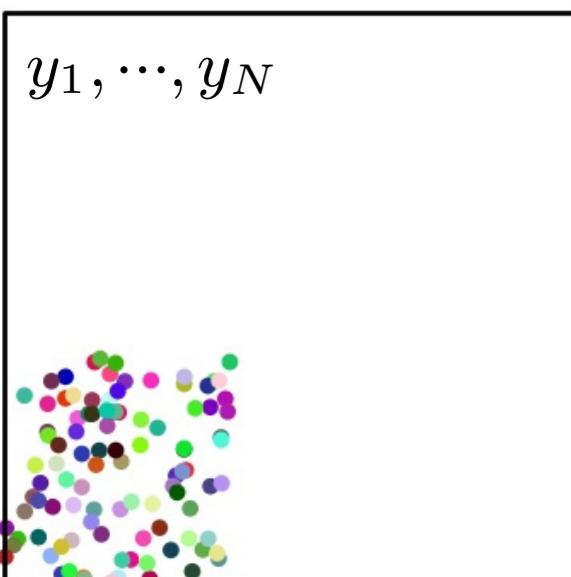
- ▶ Let $\Omega \subseteq \mathbb{R}^d$, with $|\Omega| > 1$ and let $K = \{\sigma \in \mathcal{P}(\Omega) \mid \sigma \leq \text{Leb}_\Omega\}$.
- ▶ To measure whether $\mu = \frac{1}{N} \sum_i \delta_{y_i}$ is close to being "non-congested", we use

$$\mathcal{D}^{\text{cong}}(y_1, \dots, y_N) := \frac{N}{2} \min_{\sigma \in K} W_2^2(\sigma, \frac{1}{N} \sum_i \delta_{y_i}) \quad (*)$$

Computing $\mathcal{E}_{\text{cong}, \varepsilon}$ (congestion)

- ▶ Let $\Omega \subseteq \mathbb{R}^d$, with $|\Omega| > 1$ and let $K = \{\sigma \in \mathcal{P}(\Omega) \mid \sigma \leq \text{Leb}_\Omega\}$.
- ▶ To measure whether $\mu = \frac{1}{N} \sum_i \delta_{y_i}$ is close to being "non-congested", we use

$$\mathcal{D}^{\text{cong}}(y_1, \dots, y_N) := \frac{N}{2} \min_{\sigma \in K} W_2^2(\sigma, \frac{1}{N} \sum_i \delta_{y_i}) \quad (*)$$



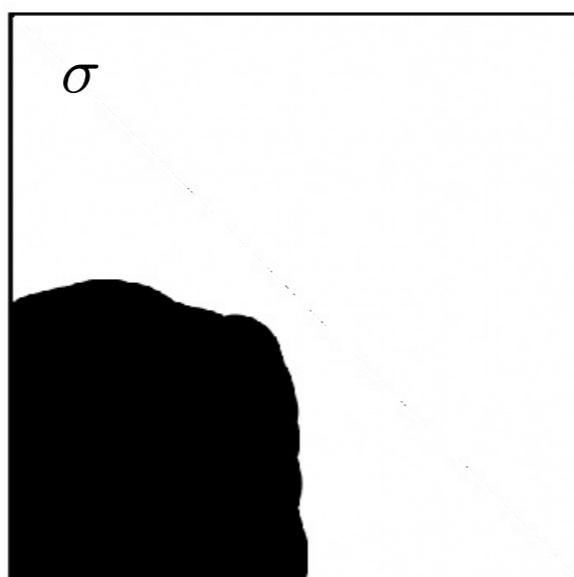
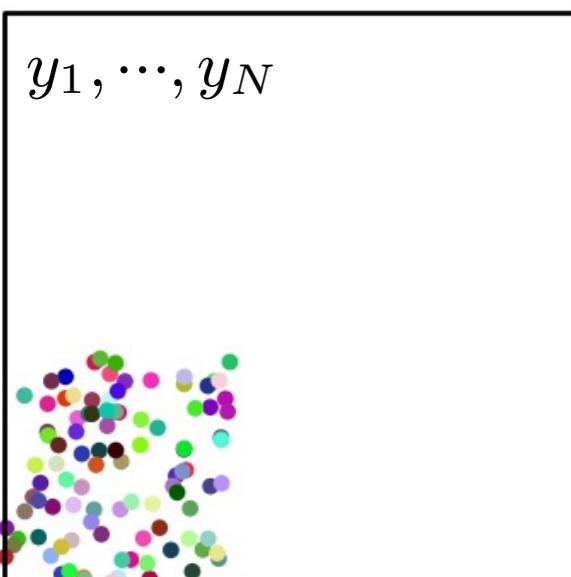
Prop: 1) $\exists! \sigma$ minimizer of $(*)$

[Maury, Roudneff-Chupin, Santambrogio]

Computing $\mathcal{E}_{\text{cong}, \varepsilon}$ (congestion)

- ▶ Let $\Omega \subseteq \mathbb{R}^d$, with $|\Omega| > 1$ and let $K = \{\sigma \in \mathcal{P}(\Omega) \mid \sigma \leq \text{Leb}_\Omega\}$.
- ▶ To measure whether $\mu = \frac{1}{N} \sum_i \delta_{y_i}$ is close to being "non-congested", we use

$$\mathcal{D}^{\text{cong}}(y_1, \dots, y_N) := \frac{N}{2} \min_{\sigma \in K} W_2^2(\sigma, \frac{1}{N} \sum_i \delta_{y_i}) \quad (*)$$



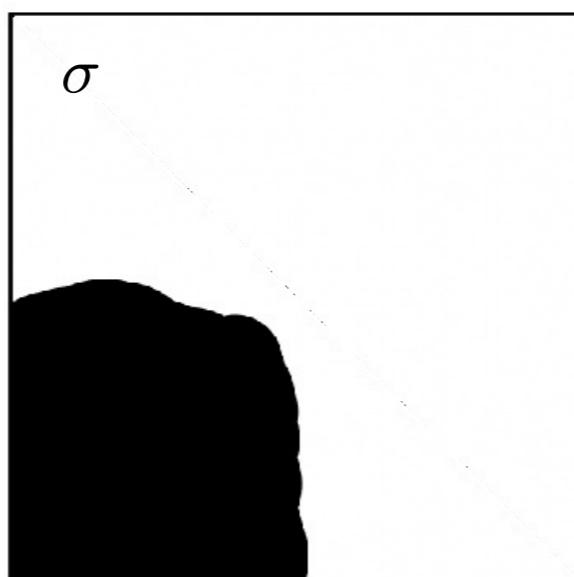
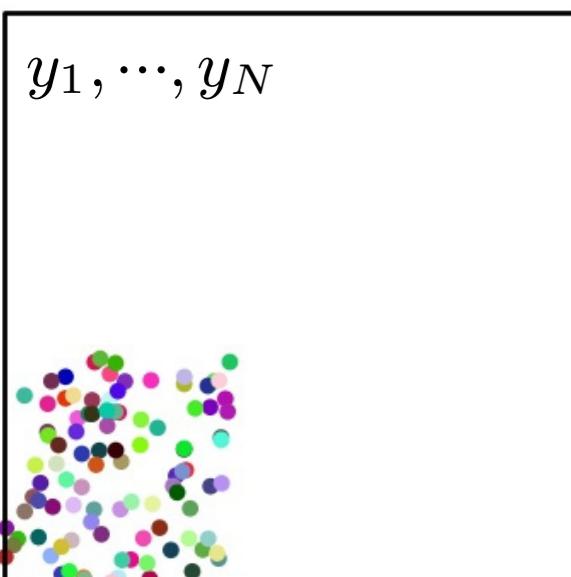
Prop: 1) $\exists! \sigma$ minimizer of $(*)$
2) $\exists! T$ OT map between σ and $\frac{1}{N} \sum_i \delta_{y_i}$

[Maury, Roudneff-Chupin, Santambrogio]

Computing $\mathcal{E}_{\text{cong}, \varepsilon}$ (congestion)

- ▶ Let $\Omega \subseteq \mathbb{R}^d$, with $|\Omega| > 1$ and let $K = \{\sigma \in \mathcal{P}(\Omega) \mid \sigma \leq \text{Leb}_\Omega\}$.
- ▶ To measure whether $\mu = \frac{1}{N} \sum_i \delta_{y_i}$ is close to being "non-congested", we use

$$\mathcal{D}^{\text{cong}}(y_1, \dots, y_N) := \frac{N}{2} \min_{\sigma \in K} W_2^2(\sigma, \frac{1}{N} \sum_i \delta_{y_i}) \quad (*)$$



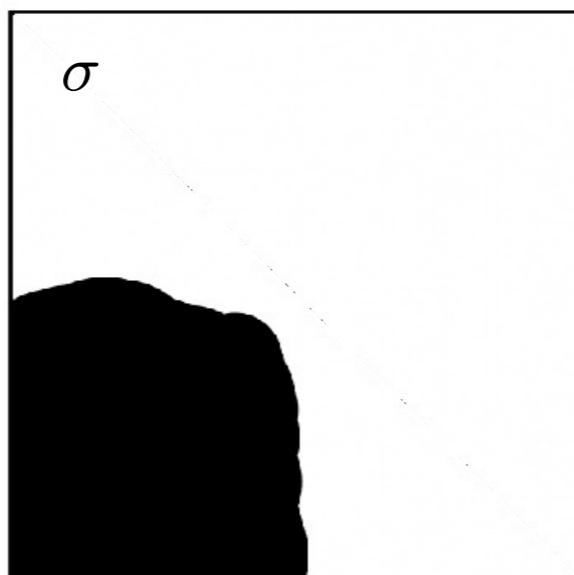
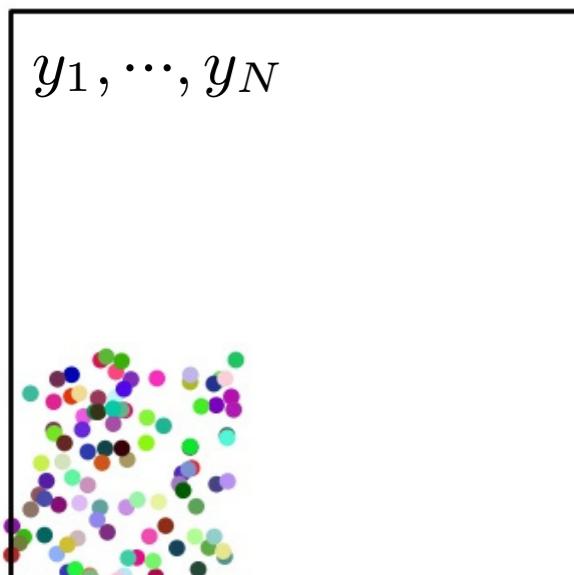
Prop: 1) $\exists! \sigma$ minimizer of $(*)$
2) $\exists! T$ OT map between σ and $\frac{1}{N} \sum_i \delta_{y_i}$
2) $T = \text{id} - \frac{1}{2} \nabla \phi$, where the Kantorovich potential ϕ is 1-semiconcave and
 $\phi \leq 0$, and $\phi(1 - \sigma) = 0$

[Maury, Roudneff-Chupin, Santambrogio]

Computing $\mathcal{E}_{\text{cong}, \varepsilon}$ (congestion)

- ▶ Let $\Omega \subseteq \mathbb{R}^d$, with $|\Omega| > 1$ and let $K = \{\sigma \in \mathcal{P}(\Omega) \mid \sigma \leq \text{Leb}_\Omega\}$.
- ▶ To measure whether $\mu = \frac{1}{N} \sum_i \delta_{y_i}$ is close to being "non-congested", we use

$$\mathcal{D}^{\text{cong}}(y_1, \dots, y_N) := \frac{N}{2} \min_{\sigma \in K} W_2^2(\sigma, \frac{1}{N} \sum_i \delta_{y_i}) \quad (*)$$



Prop: 1) $\exists! \sigma$ minimizer of $(*)$
2) $\exists! T$ OT map between σ and $\frac{1}{N} \sum_i \delta_{y_i}$
2) $T = \text{id} - \frac{1}{2} \nabla \phi$, where the Kantorovich potential ϕ is 1-semiconcave and
 $\phi \leq 0$, and $\phi(1 - \sigma) = 0$

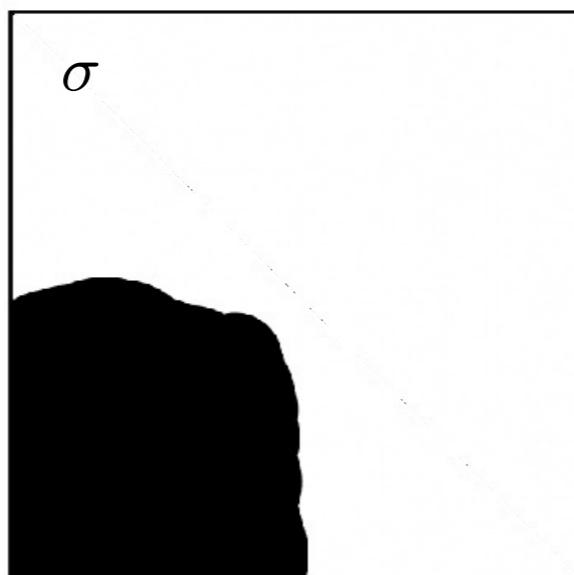
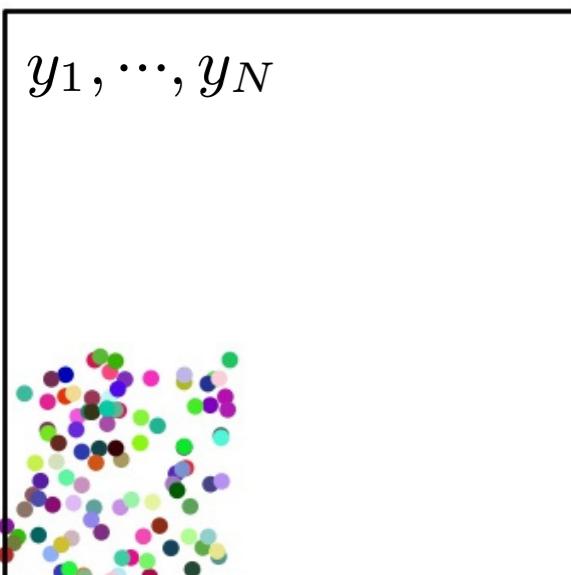
[Maury, Roudneff-Chupin, Santambrogio]

- ▶ Kantorovich potential $\simeq -$ pressure

Computing $\mathcal{E}_{\text{cong}, \varepsilon}$ (congestion)

- Let $\Omega \subseteq \mathbb{R}^d$, with $|\Omega| > 1$ and let $K = \{\sigma \in \mathcal{P}(\Omega) \mid \sigma \leq \text{Leb}_\Omega\}$.
- To measure whether $\mu = \frac{1}{N} \sum_i \delta_{y_i}$ is close to being "non-congested", we use

$$\mathcal{D}^{\text{cong}}(y_1, \dots, y_N) := \frac{N}{2} \min_{\sigma \in K} W_2^2(\sigma, \frac{1}{N} \sum_i \delta_{y_i}) \quad (*)$$

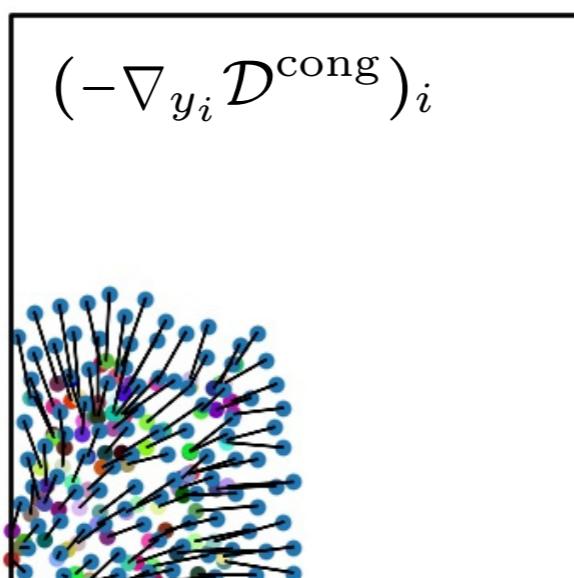
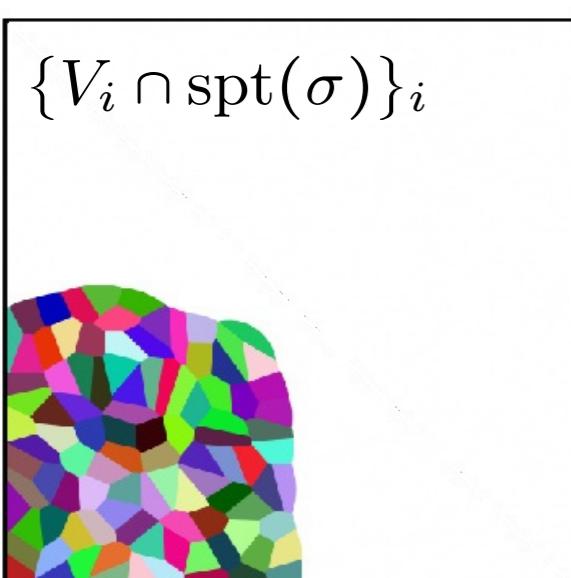


Prop: 1) $\exists! \sigma$ minimizer of $(*)$

2) $\exists! T$ OT map between σ and $\frac{1}{N} \sum_i \delta_{y_i}$

2) $T = \text{id} - \frac{1}{2} \nabla \phi$, where the Kantorovich potential ϕ is 1-semiconcave and

$\phi \leq 0$, and $\phi(1 - \sigma) = 0$



[Maury, Roudneff-Chupin, Santambrogio]

- Kantorovich potential $\simeq -$ pressure
- $\mathcal{D}^{\text{cong}}, \nabla \mathcal{D}^{\text{cong}}$ and σ are also computed in *near-linear* time in 2D/3D.

Discretization of the crowd motion model

- ▶ **Eulerian schemes:** [Maury, Roudneff-Chupin, Santambrogio '10] → "catching up"
[Benamou, Carlier, Laborde '15] → "ALG2-JKO"

Discretization of the crowd motion model

- ▶ **Eulerian schemes:** [Maury, Roudneff-Chupin, Santambrogio '10] → "catching up"
[Benamou, Carlier, Laborde '15] → "ALG2-JKO"

- ▶ **Lagrangian setting:** Let $M_N := \{s = \sum_i y_i \mathbf{1}_{\omega_i} \mid y_1, \dots, y_N \in \mathbb{R}^d\} \subseteq L^2(\rho_0, \mathbb{R}^d)$
where $\rho_0(\omega_i) = \frac{1}{N}$ and $\rho_0(\omega_i \cap \omega_j) = 0$,

$$\begin{cases} \dot{s}_N = -\Pi_{M_N} [\nabla E_{\text{pot}}(s_N) + \nabla E_{\text{cong}, \varepsilon_N}(s_N)] \\ s(0) = \Pi_{M_N}(\text{id}) \end{cases}$$

Discretization of the crowd motion model

- ▶ **Eulerian schemes:** [Maury, Roudneff-Chupin, Santambrogio '10] → "catching up"
[Benamou, Carlier, Laborde '15] → "ALG2-JKO"

- ▶ **Lagrangian setting:** Let $M_N := \{s = \sum_i y_i \mathbf{1}_{\omega_i} \mid y_1, \dots, y_N \in \mathbb{R}^d\} \subseteq L^2(\rho_0, \mathbb{R}^d)$

where $\rho_0(\omega_i) = \frac{1}{N}$ and $\rho_0(\omega_i \cap \omega_j) = 0$,

$$\begin{cases} \dot{s}_N = -\Pi_{M_N} [\nabla E_{\text{pot}}(s_N) + \nabla E_{\text{cong}, \varepsilon_N}(s_N)] \\ s(0) = \Pi_{M_N}(\text{id}) \end{cases}$$

$$[\text{with } s|_{\omega_i} = y_i] \iff \begin{cases} \dot{y}_i = -\nabla V(y_i) - \frac{1}{\varepsilon_N} \nabla_{y_i} \mathcal{D}^{\text{cong}}(y_1, \dots, y_N) \\ y_i(0) = f_{\omega_i} x \, d\rho_0 \end{cases}$$

where $\mathcal{D}^{\text{cong}}(y_1, \dots, y_N) := \frac{N}{2} \min_{\sigma \leq \text{Leb}_\Omega} W_2^2(\sigma, \frac{1}{N} \sum_i \delta_{y_i})$

Discretization of the crowd motion model

- **Eulerian schemes:** [Maury, Roudneff-Chupin, Santambrogio '10] → "catching up"
[Benamou, Carlier, Laborde '15] → "ALG2-JKO"

- **Lagrangian setting:** Let $M_N := \{s = \sum_i y_i \mathbf{1}_{\omega_i} \mid y_1, \dots, y_N \in \mathbb{R}^d\} \subseteq L^2(\rho_0, \mathbb{R}^d)$

where $\rho_0(\omega_i) = \frac{1}{N}$ and $\rho_0(\omega_i \cap \omega_j) = 0$,

$$\begin{cases} \dot{s}_N = -\Pi_{M_N} [\nabla E_{\text{pot}}(s_N) + \nabla E_{\text{cong}, \varepsilon_N}(s_N)] \\ s(0) = \Pi_{M_N}(\text{id}) \end{cases}$$

$$[\text{with } s|_{\omega_i} = y_i] \iff \begin{cases} \dot{y}_i = -\nabla V(y_i) - \frac{1}{\varepsilon_N} \nabla_{y_i} \mathcal{D}^{\text{cong}}(y_1, \dots, y_N) \\ y_i(0) = f_{\omega_i} x \, d\rho_0 \end{cases}$$

where $\mathcal{D}^{\text{cong}}(y_1, \dots, y_N) := \frac{N}{2} \min_{\sigma \leq \text{Leb}_\Omega} W_2^2(\sigma, \frac{1}{N} \sum_i \delta_{y_i})$

We let $\mu_N(t) = \frac{1}{N} \sum_i \delta_{y_i(t)} \in \mathcal{P}(\Omega)$ the corresponding distribution of particles.

Convergence theorem

Consider

$$\begin{cases} \dot{y}_i = -\nabla V(y_i) - \frac{1}{\varepsilon_N} \nabla_{y_i} \mathcal{D}^{\text{cong}}(y_1(t), \dots, y_N(t)) \\ y_i(0) = f_{\omega_i} x \, d\rho_0 \end{cases}$$

Denote $\mu_N = \frac{1}{N} \sum_i \delta_{y_i} \in \mathcal{P}(\Omega)$ and $\sigma_N = \arg \min \frac{1}{2\varepsilon} W_2^2(\mu_N, \cdot) + \mathcal{E}_{\text{cong}}(\cdot)$.

Convergence theorem

Consider

$$\begin{cases} \dot{y}_i = -\nabla V(y_i) - \frac{1}{\varepsilon_N} \nabla_{y_i} \mathcal{D}^{\text{cong}}(y_1(t), \dots, y_N(t)) \\ y_i(0) = f_{\omega_i} x \, d\rho_0 \end{cases}$$

Denote $\mu_N = \frac{1}{N} \sum_i \delta_{y_i} \in \mathcal{P}(\Omega)$ and $\sigma_N = \arg \min \frac{1}{2\varepsilon} W_2^2(\mu_N, \cdot) + \mathcal{E}_{\text{cong}}(\cdot)$.

Theorem: For every N , choose $\varepsilon_N \rightarrow 0$ and assume that $V \in \mathcal{C}^1, V \geq 0$ and

$$\frac{1}{\varepsilon_N} W_2^2(\rho_0, \mu_N(0)) \leq C \quad \text{and} \quad \frac{1}{\varepsilon_N^2} \int_0^T W_2^2(\mu_N, \sigma_N) \, dt \leq C$$

Then $\mu_N \rightharpoonup \rho \in \mathcal{C}^0([0, T], \mathcal{P}(\Omega))$, where ρ satisfies in the sense of distribution,

$$\begin{cases} \partial_t \rho + \operatorname{div}(\rho v) = 0 \\ v = -\nabla V - \nabla p, \\ \rho \leq 1 \\ p \geq 0, \quad p(1 - \rho) = 0, \end{cases} \quad \text{for some } p \in L^2([0, T], H^1(\Omega))$$

[M., Stra, Santambrogio '18]

Convergence theorem

Consider

$$\begin{cases} \dot{y}_i = -\nabla V(y_i) - \frac{1}{\varepsilon_N} \nabla_{y_i} \mathcal{D}^{\text{cong}}(y_1(t), \dots, y_N(t)) \\ y_i(0) = f_{\omega_i} x \, d\rho_0 \end{cases}$$

Denote $\mu_N = \frac{1}{N} \sum_i \delta_{y_i} \in \mathcal{P}(\Omega)$ and $\sigma_N = \arg \min \frac{1}{2\varepsilon} W_2^2(\mu_N, \cdot) + \mathcal{E}_{\text{cong}}(\cdot)$.

Theorem: For every N , choose $\varepsilon_N \rightarrow 0$ and assume that $V \in \mathcal{C}^1, V \geq 0$ and

$$\frac{1}{\varepsilon_N} W_2^2(\rho_0, \mu_N(0)) \leq C \quad \text{and} \quad \frac{1}{\varepsilon_N^2} \int_0^T W_2^2(\mu_N, \sigma_N) \, dt \leq C \quad (*)$$

Then $\mu_N \rightharpoonup \rho \in \mathcal{C}^0([0, T], \mathcal{P}(\Omega))$, where ρ satisfies in the sense of distribution,

$$\begin{cases} \partial_t \rho + \operatorname{div}(\rho v) = 0 \\ v = -\nabla V - \nabla p, \\ \rho \leq 1 \\ p \geq 0, \quad p(1 - \rho) = 0, \end{cases} \quad \text{for some } p \in L^2([0, T], H^1(\Omega))$$

[M., Stra, Santambrogio '18]

- ▶ The assumption $(*)$ is always true in 1D, and can be checked numerically in 2D.

Proof techniques

- ▶ **Existence of a limit.** Let $\sigma_N = \Pi_K(\mu_N)$ and $\mathcal{E}_N(t) = \int V d\mu_N + \frac{1}{2\varepsilon_N} W_2^2(\mu_N, \sigma_N)$.

Proof techniques

- ▶ **Existence of a limit.** Let $\sigma_N = \Pi_K(\mu_N)$ and $\mathcal{E}_N(t) = \int V d\mu_N + \frac{1}{2\varepsilon_N} W_2^2(\mu_N, \sigma_N)$.
A) $\int_0^T \|\dot{\mu}_N\|_{W_2}^2 \leq \mathcal{E}_N(0) - \mathcal{E}_N(T) \leq \mathcal{E}_N(0) \leq C$.

Proof techniques

- ▶ **Existence of a limit.** Let $\sigma_N = \Pi_K(\mu_N)$ and $\mathcal{E}_N(t) = \int V d\mu_N + \frac{1}{2\varepsilon_N} W_2^2(\mu_N, \sigma_N)$.

A) $\int_0^T \|\dot{\mu}_N\|_{W_2}^2 \leq \mathcal{E}_N(0) - \mathcal{E}_N(T) \leq \mathcal{E}_N(0) \leq C$.

Thus, $\mu_N \in \mathcal{C}^{1/2}([0, T], W_2)$, and by Ascoli $\mu_N \xrightarrow{\mathcal{C}^0([0, T], W_2)} \rho$.

Proof techniques

- ▶ **Existence of a limit.** Let $\sigma_N = \Pi_K(\mu_N)$ and $\mathcal{E}_N(t) = \int V d\mu_N + \frac{1}{2\varepsilon_N} W_2^2(\mu_N, \sigma_N)$.

A) $\int_0^T \|\dot{\mu}_N\|_{W_2}^2 \leq \mathcal{E}_N(0) - \mathcal{E}_N(T) \leq \mathcal{E}_N(0) \leq C$.

Thus, $\mu_N \in \mathcal{C}^{1/2}([0, T], W_2)$, and by Ascoli $\mu_N \xrightarrow{\mathcal{C}^0([0, T], W_2)} \rho$.

B) $\frac{1}{2\varepsilon_N} W_2^2(\mu_N, \sigma_N) \leq \mathcal{E}_N(0)$. Thus, $\sigma_N \xrightarrow{\mathcal{C}^0([0, T], W_2)} \rho$, and $\rho \in K$.

Proof techniques

- **Existence of a limit.** Let $\sigma_N = \Pi_K(\mu_N)$ and $\mathcal{E}_N(t) = \int V d\mu_N + \frac{1}{2\varepsilon_N} W_2^2(\mu_N, \sigma_N)$.

A) $\int_0^T \|\dot{\mu}_N\|_{W_2}^2 \leq \mathcal{E}_N(0) - \mathcal{E}_N(T) \leq \mathcal{E}_N(0) \leq C$.

Thus, $\mu_N \in \mathcal{C}^{1/2}([0, T], W_2)$, and by Ascoli $\mu_N \xrightarrow{\mathcal{C}^0([0, T], W_2)} \rho$.

B) $\frac{1}{2\varepsilon_N} W_2^2(\mu_N, \sigma_N) \leq \mathcal{E}_N(0)$. Thus, $\sigma_N \xrightarrow{\mathcal{C}^0([0, T], W_2)} \rho$, and $\rho \in K$.

- **Continuity equation.** μ_N satisfies $\partial_t \mu_N + \operatorname{div} M_N = 0$ with

$$M_N = \frac{1}{N} \sum_{1 \leq i \leq N} \dot{y}_i \delta_{y_i} = \frac{1}{N} \sum_i \left(-\nabla V(y_i) - \frac{1}{\varepsilon_N} \nabla_{y_i} \mathcal{D}^{\text{cong}}(y_1, \dots, y_N) \right) \delta_{y_i}$$

Proof techniques

- **Existence of a limit.** Let $\sigma_N = \Pi_K(\mu_N)$ and $\mathcal{E}_N(t) = \int V d\mu_N + \frac{1}{2\varepsilon_N} W_2^2(\mu_N, \sigma_N)$.

A) $\int_0^T \|\dot{\mu}_N\|_{W_2}^2 \leq \mathcal{E}_N(0) - \mathcal{E}_N(T) \leq \mathcal{E}_N(0) \leq C$.

Thus, $\mu_N \in \mathcal{C}^{1/2}([0, T], W_2)$, and by Ascoli $\mu_N \xrightarrow{\mathcal{C}^0([0, T], W_2)} \rho$.

B) $\frac{1}{2\varepsilon_N} W_2^2(\mu_N, \sigma_N) \leq \mathcal{E}_N(0)$. Thus, $\sigma_N \xrightarrow{\mathcal{C}^0([0, T], W_2)} \rho$, and $\rho \in K$.

- **Continuity equation.** μ_N satisfies $\partial_t \mu_N + \operatorname{div} M_N = 0$ with

$$M_N = \frac{1}{N} \sum_{1 \leq i \leq N} \dot{y}_i \delta_{y_i} = \frac{1}{N} \sum_i \left(-\nabla V(y_i) - \frac{1}{\varepsilon_N} \nabla_{y_i} \mathcal{D}^{\text{cong}}(y_1, \dots, y_N) \right) \delta_{y_i}$$

With T_N = OT map between σ_N and μ_N , ϕ_N = OT potential, and $p_N = -\frac{\phi_N}{\varepsilon_N}$,

$$\int_{\Omega} \xi \cdot M_N = - \int_{\Omega} \nabla V d\mu_N - \int_{\Omega} \frac{T_N - \text{id}}{\varepsilon_N} \xi(T_N) d\sigma_N$$

Proof techniques

- ▶ **Existence of a limit.** Let $\sigma_N = \Pi_K(\mu_N)$ and $\mathcal{E}_N(t) = \int V d\mu_N + \frac{1}{2\varepsilon_N} W_2^2(\mu_N, \sigma_N)$.

A) $\int_0^T \|\dot{\mu}_N\|_{W_2}^2 \leq \mathcal{E}_N(0) - \mathcal{E}_N(T) \leq \mathcal{E}_N(0) \leq C$.

Thus, $\mu_N \in \mathcal{C}^{1/2}([0, T], W_2)$, and by Ascoli $\mu_N \xrightarrow{\mathcal{C}^0([0, T], W_2)} \rho$.

B) $\frac{1}{2\varepsilon_N} W_2^2(\mu_N, \sigma_N) \leq \mathcal{E}_N(0)$. Thus, $\sigma_N \xrightarrow{\mathcal{C}^0([0, T], W_2)} \rho$, and $\rho \in K$.

- ▶ **Continuity equation.** μ_N satisfies $\partial_t \mu_N + \operatorname{div} M_N = 0$ with

$$M_N = \frac{1}{N} \sum_{1 \leq i \leq N} \dot{y}_i \delta_{y_i} = \frac{1}{N} \sum_i \left(-\nabla V(y_i) - \frac{1}{\varepsilon_N} \nabla_{y_i} \mathcal{D}^{\text{cong}}(y_1, \dots, y_N) \right) \delta_{y_i}$$

With T_N = OT map between σ_N and μ_N , ϕ_N = OT potential, and $p_N = -\frac{\phi_N}{\varepsilon_N}$,

$$\begin{aligned} \int_{\Omega} \xi \cdot M_N &= - \int_{\Omega} \nabla V d\mu_N - \int_{\Omega} \frac{T_N - \text{id}}{\varepsilon_N} \xi(T_N) d\sigma_N \\ &= - \frac{1}{\varepsilon_N} \nabla \phi_N = \nabla p_N \end{aligned}$$

Proof techniques

- ▶ **Existence of a limit.** Let $\sigma_N = \Pi_K(\mu_N)$ and $\mathcal{E}_N(t) = \int V d\mu_N + \frac{1}{2\varepsilon_N} W_2^2(\mu_N, \sigma_N)$.

A) $\int_0^T \|\dot{\mu}_N\|_{W_2}^2 \leq \mathcal{E}_N(0) - \mathcal{E}_N(T) \leq \mathcal{E}_N(0) \leq C$.

Thus, $\mu_N \in \mathcal{C}^{1/2}([0, T], W_2)$, and by Ascoli $\mu_N \xrightarrow{\mathcal{C}^0([0, T], W_2)} \rho$.

B) $\frac{1}{2\varepsilon_N} W_2^2(\mu_N, \sigma_N) \leq \mathcal{E}_N(0)$. Thus, $\sigma_N \xrightarrow{\mathcal{C}^0([0, T], W_2)} \rho$, and $\rho \in K$.

- ▶ **Continuity equation.** μ_N satisfies $\partial_t \mu_N + \operatorname{div} M_N = 0$ with

$$M_N = \frac{1}{N} \sum_{1 \leq i \leq N} \dot{y}_i \delta_{y_i} = \frac{1}{N} \sum_i \left(-\nabla V(y_i) - \frac{1}{\varepsilon_N} \nabla_{y_i} \mathcal{D}^{\text{cong}}(y_1, \dots, y_N) \right) \delta_{y_i}$$

With T_N = OT map between σ_N and μ_N , ϕ_N = OT potential, and $p_N = -\frac{\phi_N}{\varepsilon_N}$,

$$\begin{aligned} \int_{\Omega} \xi \cdot M_N &= - \int_{\Omega} \nabla V d\mu_N - \int_{\Omega} \frac{T_N - \text{id}}{\varepsilon_N} \xi(T_N) d\sigma_N \\ &= -\frac{1}{\varepsilon_N} \nabla \phi_N = \nabla p_N \end{aligned}$$

- ▶ **Convergence:**
- $$\begin{cases} \partial_t \mu_N + \operatorname{div} M_N = 0 \\ M_N \simeq -\nabla V \mu_N - \nabla p_N \sigma_N \\ p_N \geq 0, \quad p_N(1 - \sigma_N) = 0 \end{cases}$$

Proof techniques

- ▶ **Existence of a limit.** Let $\sigma_N = \Pi_K(\mu_N)$ and $\mathcal{E}_N(t) = \int V d\mu_N + \frac{1}{2\varepsilon_N} W_2^2(\mu_N, \sigma_N)$.

A) $\int_0^T \|\dot{\mu}_N\|_{W_2}^2 \leq \mathcal{E}_N(0) - \mathcal{E}_N(T) \leq \mathcal{E}_N(0) \leq C$.

Thus, $\mu_N \in \mathcal{C}^{1/2}([0, T], W_2)$, and by Ascoli $\mu_N \xrightarrow{\mathcal{C}^0([0, T], W_2)} \rho$.

B) $\frac{1}{2\varepsilon_N} W_2^2(\mu_N, \sigma_N) \leq \mathcal{E}_N(0)$. Thus, $\sigma_N \xrightarrow{\mathcal{C}^0([0, T], W_2)} \rho$, and $\rho \in K$.

- ▶ **Continuity equation.** μ_N satisfies $\partial_t \mu_N + \operatorname{div} M_N = 0$ with

$$M_N = \frac{1}{N} \sum_{1 \leq i \leq N} \dot{y}_i \delta_{y_i} = \frac{1}{N} \sum_i \left(-\nabla V(y_i) - \frac{1}{\varepsilon_N} \nabla_{y_i} \mathcal{D}^{\text{cong}}(y_1, \dots, y_N) \right) \delta_{y_i}$$

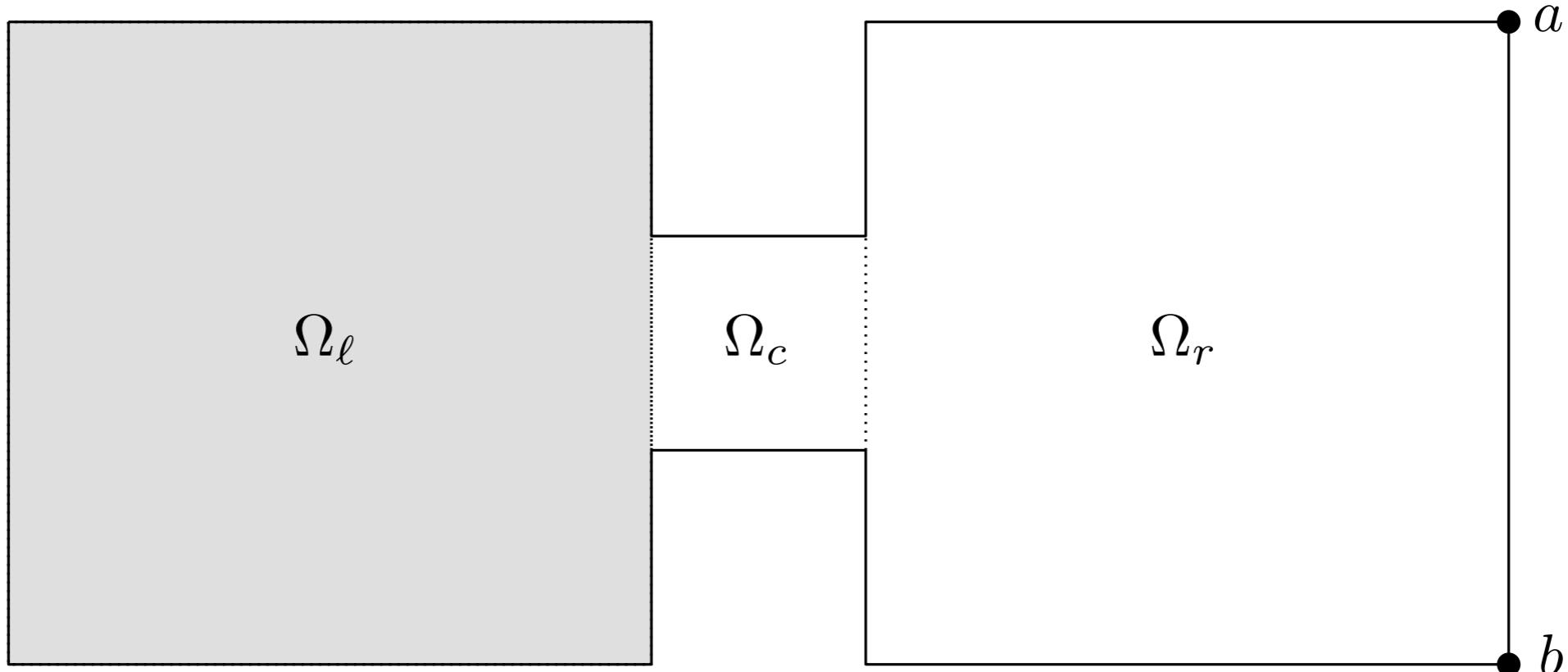
With T_N = OT map between σ_N and μ_N , ϕ_N = OT potential, and $p_N = -\frac{\phi_N}{\varepsilon_N}$,

$$\begin{aligned} \int_{\Omega} \xi \cdot M_N &= - \int_{\Omega} \nabla V d\mu_N - \int_{\Omega} \frac{T_N - \text{id}}{\varepsilon_N} \xi(T_N) d\sigma_N \\ &= -\frac{1}{\varepsilon_N} \nabla \phi_N = \nabla p_N \end{aligned}$$

- ▶ **Convergence:**

$$\begin{cases} \partial_t \mu_N + \operatorname{div} M_N = 0 \\ M_N \simeq -\nabla V \mu_N - \nabla p_N \sigma_N \\ p_N \geq 0, \quad p_N(1 - \sigma_N) = 0 \end{cases} \longrightarrow \begin{cases} \partial_t \rho + \operatorname{div}(M) = 0 \\ M = -(\nabla V + \nabla p)\rho, \\ p \geq 0, \quad p(1 - \rho) = 0, \end{cases}$$

Numerical example



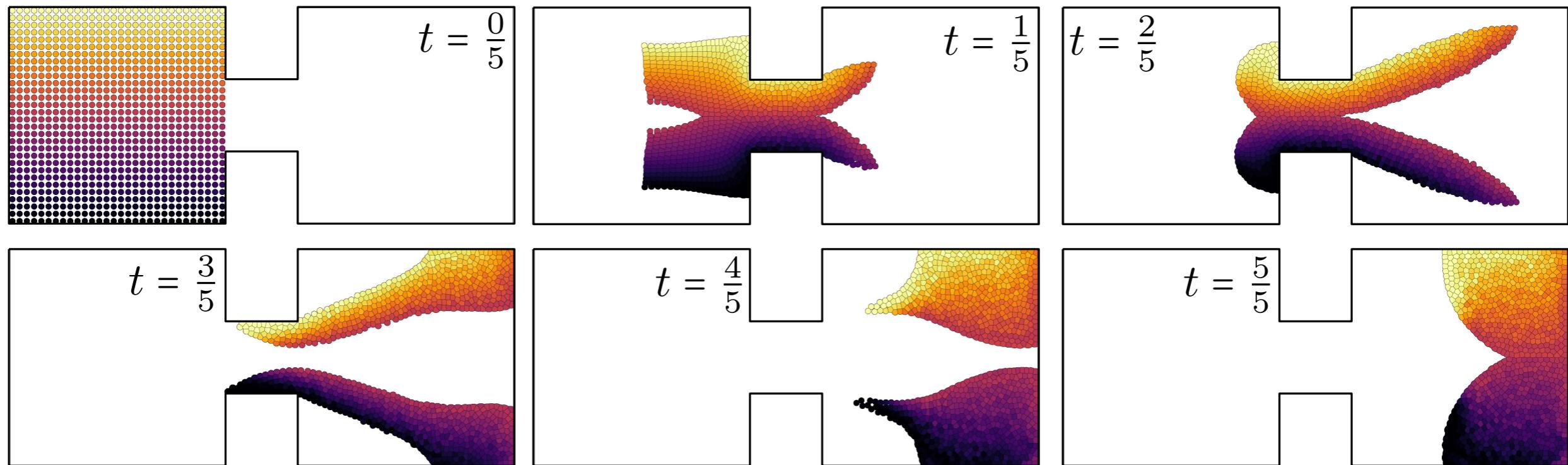
initial density: $\rho_0 \simeq 0.78 \cdot \text{Leb}_{\Omega_\ell}$

potential: $V = \text{geodesic distance to } \{a, b\}$, i.e. V satisfies the Eikonal equation

$$\begin{cases} \|\nabla V\| = 1 & \text{in } \Omega_\ell \cup \Omega_c \cup \Omega_r \\ V(a) = V(b) = 0 \end{cases}$$

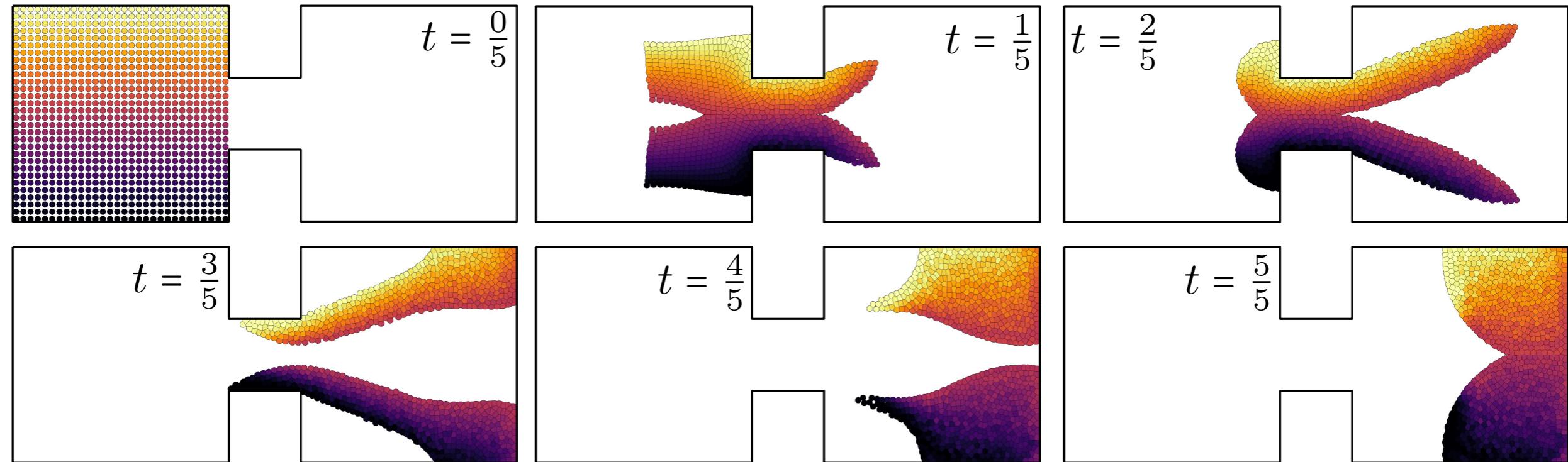
Numerical example

$N = 30^2$

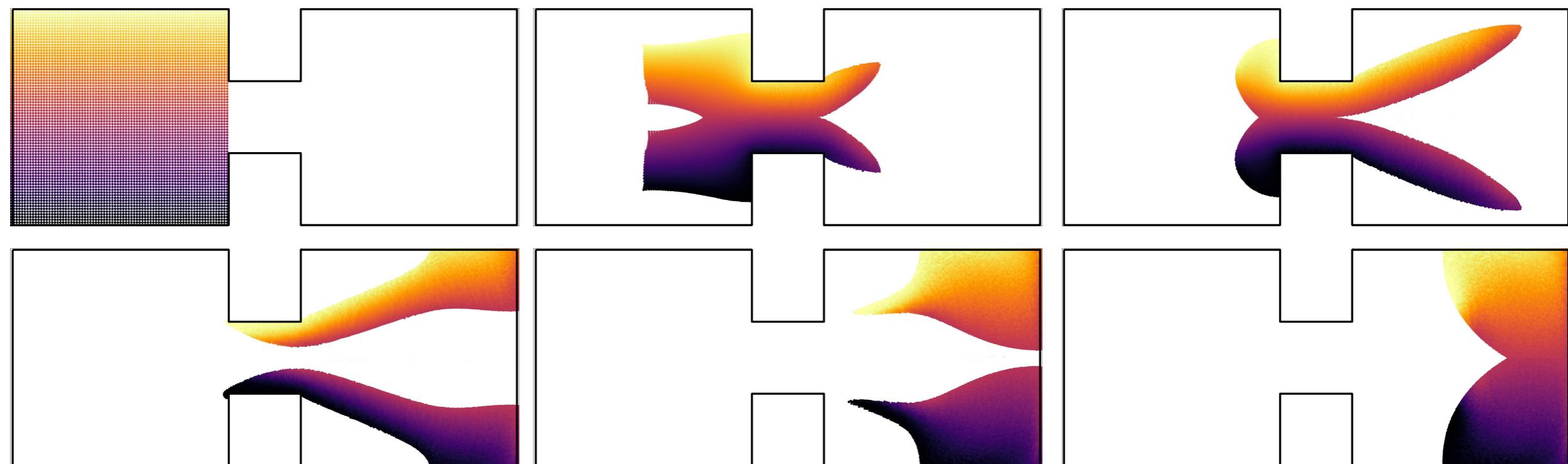


Numerical example

$N = 30^2$



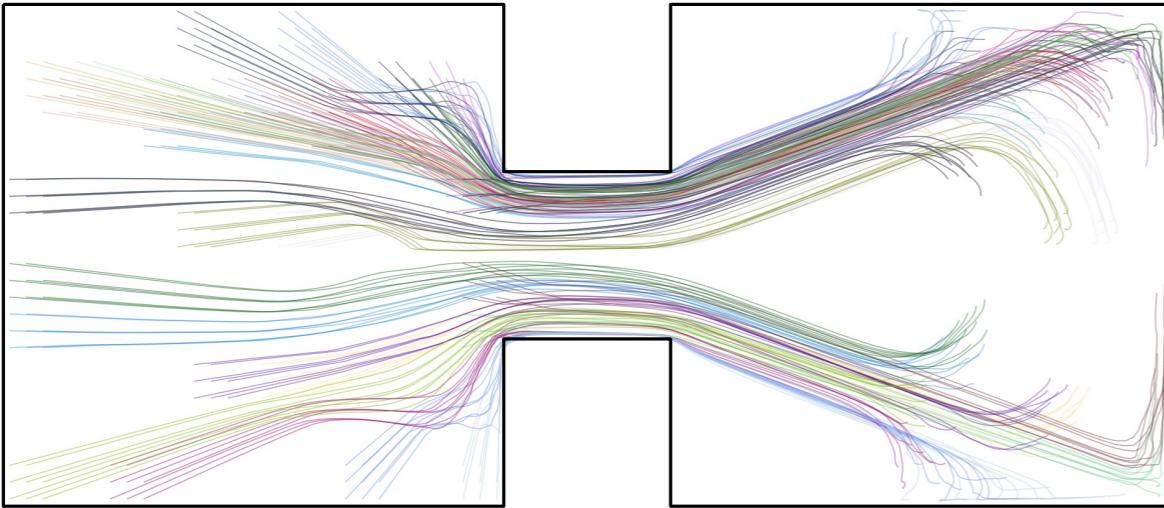
$N = 80^2$



Numerical example

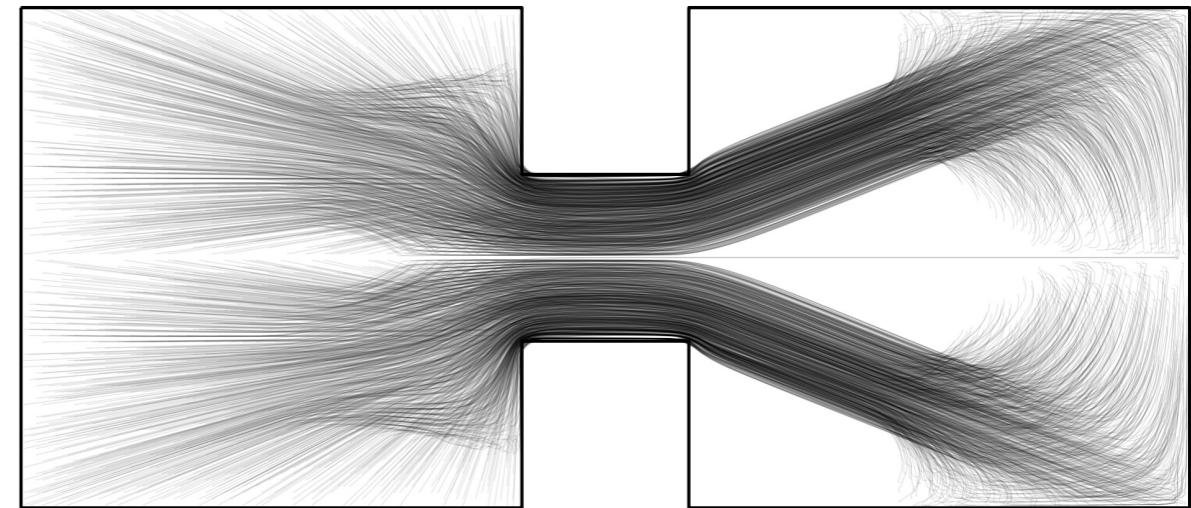
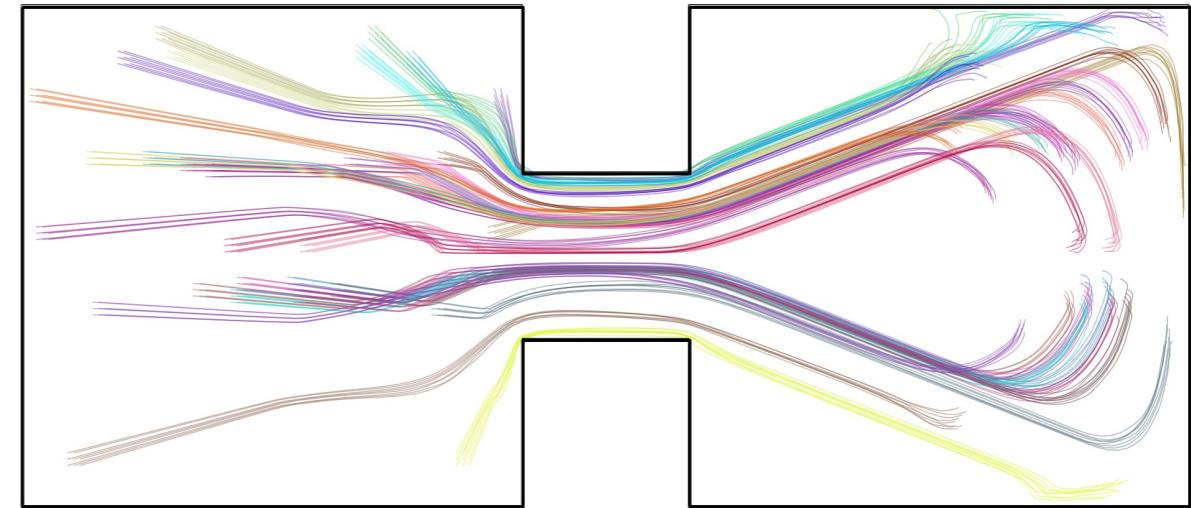
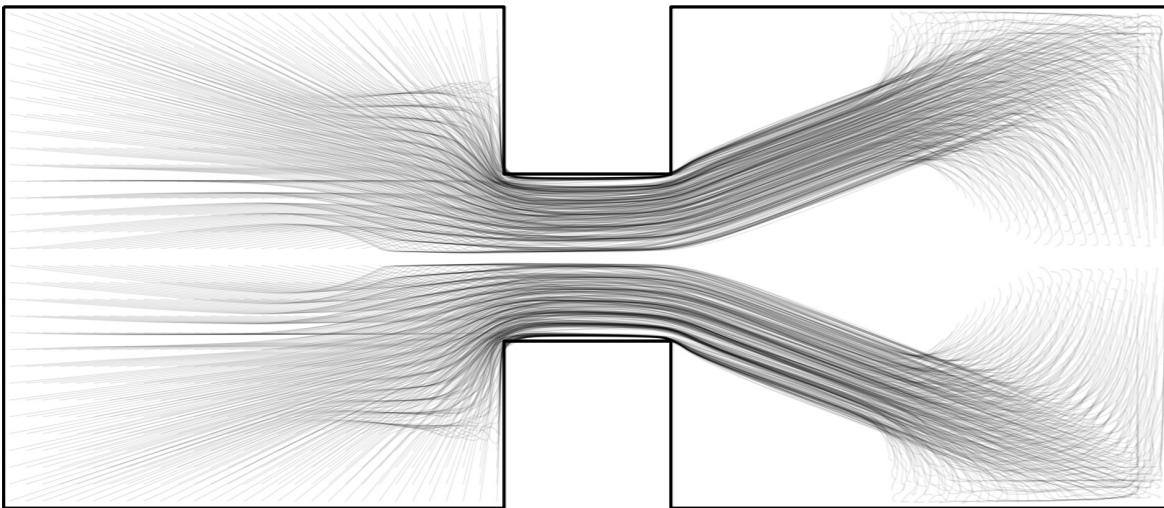
$$N = 30^2$$

some trajectories



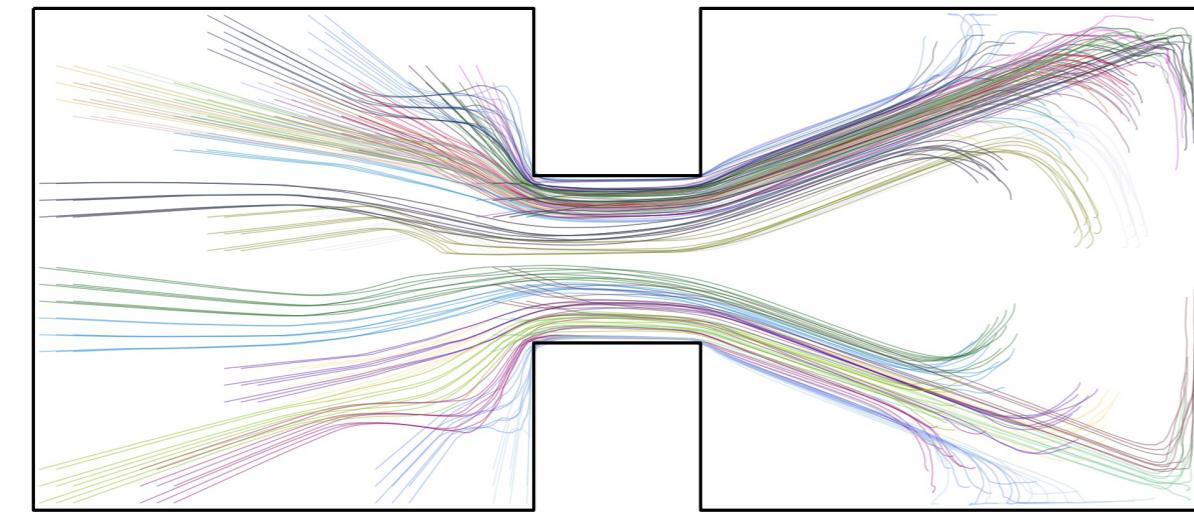
$$N = 80^2$$

all trajectories

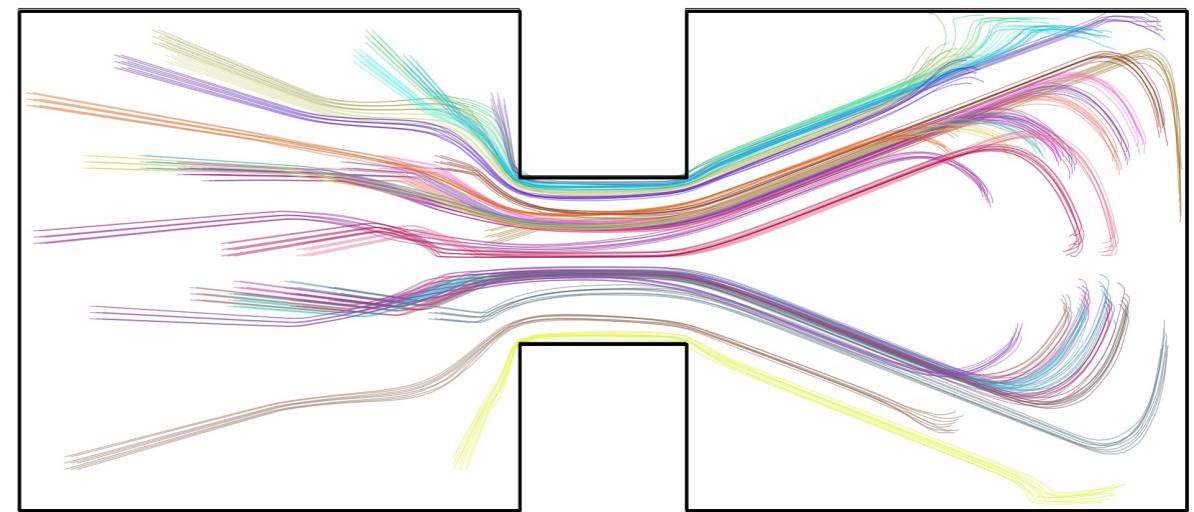


Numerical example

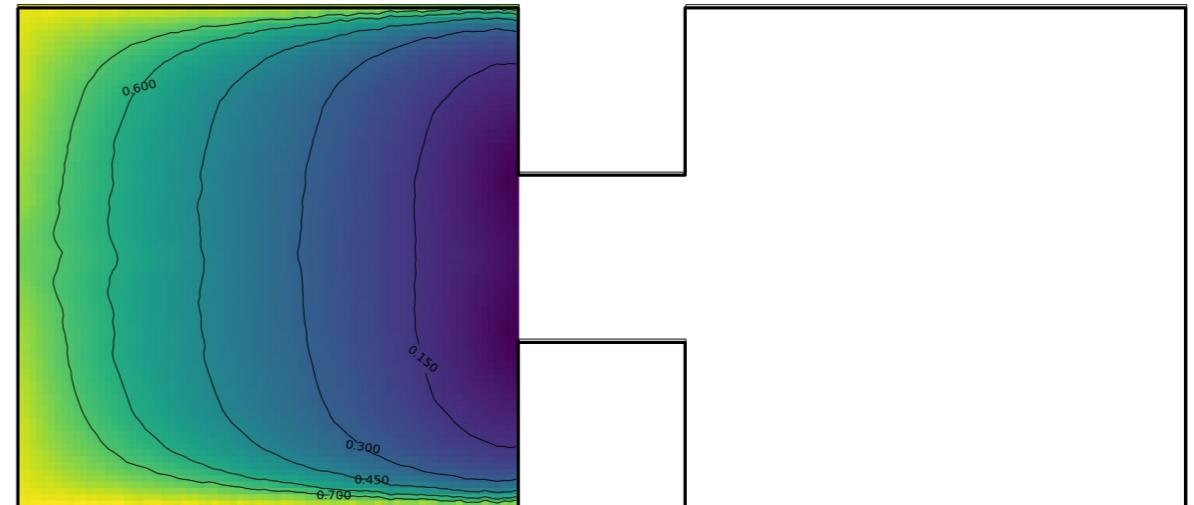
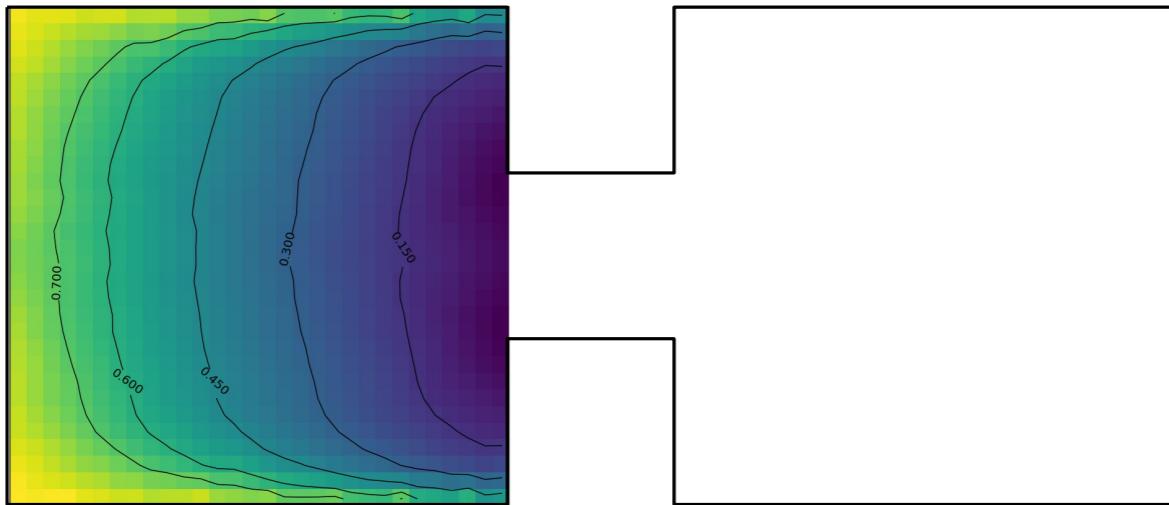
$N = 30^2$



$N = 80^2$



time to enter Ω_r



6. Linear diffusion

Computing $\mathcal{E}_{\text{ent},\varepsilon}$ (entropy)

Entropy of a probability density: $\mathcal{E}_{\text{ent}}(\rho) = \int \rho \log \rho$ (or more generally $\int f(\rho)$)

Computing $\mathcal{E}_{\text{ent},\varepsilon}$ (entropy)

Entropy of a probability density: $\mathcal{E}_{\text{ent}}(\rho) = \int \rho \log \rho$ (or more generally $\int f(\rho)$)

- Moreau-Yosida regularization allows to associate a notion of ε -entropy to any point cloud $\{y_i\}_i$.

$$\mathcal{D}_\varepsilon^{\text{ent}}(y_1, \dots, y_N) = N \min_{\sigma} \frac{1}{2\varepsilon} W_2^2(\sigma, \frac{1}{N} \sum_i \delta_{y_i}) + \mathcal{E}_{\text{ent}}(\sigma), \quad (*)$$

Computing $\mathcal{E}_{\text{ent}, \varepsilon}$ (entropy)

Entropy of a probability density: $\mathcal{E}_{\text{ent}}(\rho) = \int \rho \log \rho$ (or more generally $\int f(\rho)$)

- **Moreau-Yosida regularization** allows to associate a notion of ε -entropy to any point cloud $\{y_i\}_i$.

$$\mathcal{D}_\varepsilon^{\text{ent}}(y_1, \dots, y_N) = N \min_{\sigma} \frac{1}{2\varepsilon} W_2^2(\sigma, \frac{1}{N} \sum_i \delta_{y_i}) + \mathcal{E}_{\text{ent}}(\sigma), \quad (*)$$

Proposition: 1) $\exists! \sigma$ minimizer of $(*)$
2) The Kantorovich potential satisfies $\frac{\phi}{2\varepsilon} + \log \sigma = 0$.

Computing $\mathcal{E}_{\text{ent}, \varepsilon}$ (entropy)

Entropy of a probability density: $\mathcal{E}_{\text{ent}}(\rho) = \int \rho \log \rho$ (or more generally $\int f(\rho)$)

- Moreau-Yosida regularization allows to associate a notion of ε -entropy to any point cloud $\{y_i\}_i$.

$$\mathcal{D}_\varepsilon^{\text{ent}}(y_1, \dots, y_N) = N \min_\sigma \frac{1}{2\varepsilon} W_2^2(\sigma, \frac{1}{N} \sum_i \delta_{y_i}) + \mathcal{E}_{\text{ent}}(\sigma), \quad (*)$$

Proposition: 1) $\exists! \sigma$ minimizer of $(*)$
2) The Kantorovich potential satisfies $\frac{\phi}{2\varepsilon} + \log \sigma = 0$.

σ is piecewise Gaussian
on Laguerre diagram

Computing $\mathcal{E}_{\text{ent}, \varepsilon}$ (entropy)

Entropy of a probability density: $\mathcal{E}_{\text{ent}}(\rho) = \int \rho \log \rho$ (or more generally $\int f(\rho)$)

- Moreau-Yosida regularization allows to associate a notion of ε -entropy to any point cloud $\{y_i\}_i$.

$$\mathcal{D}_\varepsilon^{\text{ent}}(y_1, \dots, y_N) = N \min_\sigma \frac{1}{2\varepsilon} W_2^2(\sigma, \frac{1}{N} \sum_i \delta_{y_i}) + \mathcal{E}_{\text{ent}}(\sigma), \quad (*)$$

Proposition: 1) $\exists! \sigma$ minimizer of $(*)$
2) The Kantorovich potential satisfies $\frac{\phi}{2\varepsilon} + \log \sigma = 0$.

σ is piecewise Gaussian
on Laguerre diagram

- If $\mu_N \rightarrow \text{Leb}_{\Omega'}$, then the sequence of Kantorovich potentials (ϕ_N) converges to a solution ϕ of the Monge-Ampère equation:

$$\det(\text{id} - \frac{1}{2} D^2 \phi) = \exp(-\frac{\phi}{2\varepsilon}) + \text{suitable b.c.} \quad [\text{Klartag, M., Santambrogio '17}]$$

Computing $\mathcal{E}_{\text{ent}, \varepsilon}$ (entropy)

Entropy of a probability density: $\mathcal{E}_{\text{ent}}(\rho) = \int \rho \log \rho$ (or more generally $\int f(\rho)$)

- Moreau-Yosida regularization allows to associate a notion of ε -entropy to any point cloud $\{y_i\}_i$.

$$\mathcal{D}_\varepsilon^{\text{ent}}(y_1, \dots, y_N) = N \min_{\sigma} \frac{1}{2\varepsilon} W_2^2(\sigma, \frac{1}{N} \sum_i \delta_{y_i}) + \mathcal{E}_{\text{ent}}(\sigma), \quad (*)$$

Proposition: 1) $\exists! \sigma$ minimizer of $(*)$
2) The Kantorovich potential satisfies $\frac{\phi}{2\varepsilon} + \log \sigma = 0$.

σ is piecewise Gaussian
on Laguerre diagram

- If $\mu_N \rightarrow \text{Leb}_{\Omega'}$, then the sequence of Kantorovich potentials (ϕ_N) converges to a solution ϕ of the Monge-Ampère equation:

$$\det(\text{id} - \frac{1}{2} D^2 \phi) = \exp(-\frac{\phi}{2\varepsilon}) + \text{suitable b.c.} \quad [\text{Klartag, M., Santambrogio '17}]$$

- Applications to density estimation in statistics?

Convergence theorem

Consider

$$\begin{cases} \dot{y}_i = -\nabla V(y_i) - \frac{1}{\varepsilon_N} \nabla_{y_i} \mathcal{D}_\varepsilon^{\text{ent}}(y_1(t), \dots, y_N(t)) \\ y_i(0) = f_{\omega_i} x \, d\rho_0 \end{cases}$$

Denote $\mu_N = \frac{1}{N} \sum_i \delta_{y_i} \in \mathcal{P}(\Omega)$ and $\sigma_N = \arg \min \frac{1}{2\varepsilon} W_2^2(\mu_N, \cdot) + \mathcal{E}_{\text{ent}}(\cdot)$.

Convergence theorem

Consider

$$\begin{cases} \dot{y}_i = -\nabla V(y_i) - \frac{1}{\varepsilon_N} \nabla_{y_i} \mathcal{D}_\varepsilon^{\text{ent}}(y_1(t), \dots, y_N(t)) \\ y_i(0) = f_{\omega_i} x \, d\rho_0 \end{cases}$$

Denote $\mu_N = \frac{1}{N} \sum_i \delta_{y_i} \in \mathcal{P}(\Omega)$ and $\sigma_N = \arg \min \frac{1}{2\varepsilon} W_2^2(\mu_N, \cdot) + \mathcal{E}_{\text{ent}}(\cdot)$.

Theorem: For every N , choose $\varepsilon_N \rightarrow 0$ and assume that $V \in \mathcal{C}^1, V \geq 0$ and

$$\frac{1}{\varepsilon_N} W_2^2(\rho_0, \mu_N(0)) \leq C \quad \text{and} \quad \lim_{N \rightarrow +\infty} \frac{1}{\varepsilon_N} \int_0^T W_2^2(\mu_N, \sigma_N) \, dt = 0$$

Then $\mu_N \rightharpoonup \rho \in \mathcal{C}^0([0, T], \mathcal{P}(\Omega))$, where ρ satisfies in the sense of distribution,

$$\begin{cases} \partial_t \rho + \operatorname{div}(\rho v) = 0 \\ v = -\nabla V - \nabla p, \\ p = \log \rho \end{cases}$$

[M., Stra, Santambrogio '18]

Convergence theorem

Consider

$$\begin{cases} \dot{y}_i = -\nabla V(y_i) - \frac{1}{\varepsilon_N} \nabla_{y_i} \mathcal{D}_\varepsilon^{\text{ent}}(y_1(t), \dots, y_N(t)) \\ y_i(0) = f_{\omega_i} x \, d\rho_0 \end{cases}$$

Denote $\mu_N = \frac{1}{N} \sum_i \delta_{y_i} \in \mathcal{P}(\Omega)$ and $\sigma_N = \arg \min \frac{1}{2\varepsilon} W_2^2(\mu_N, \cdot) + \mathcal{E}_{\text{ent}}(\cdot)$.

Theorem: For every N , choose $\varepsilon_N \rightarrow 0$ and assume that $V \in \mathcal{C}^1, V \geq 0$ and

$$\frac{1}{\varepsilon_N} W_2^2(\rho_0, \mu_N(0)) \leq C \quad \text{and} \quad \lim_{N \rightarrow +\infty} \frac{1}{\varepsilon_N} \int_0^T W_2^2(\mu_N, \sigma_N) \, dt = 0 \quad (*)$$

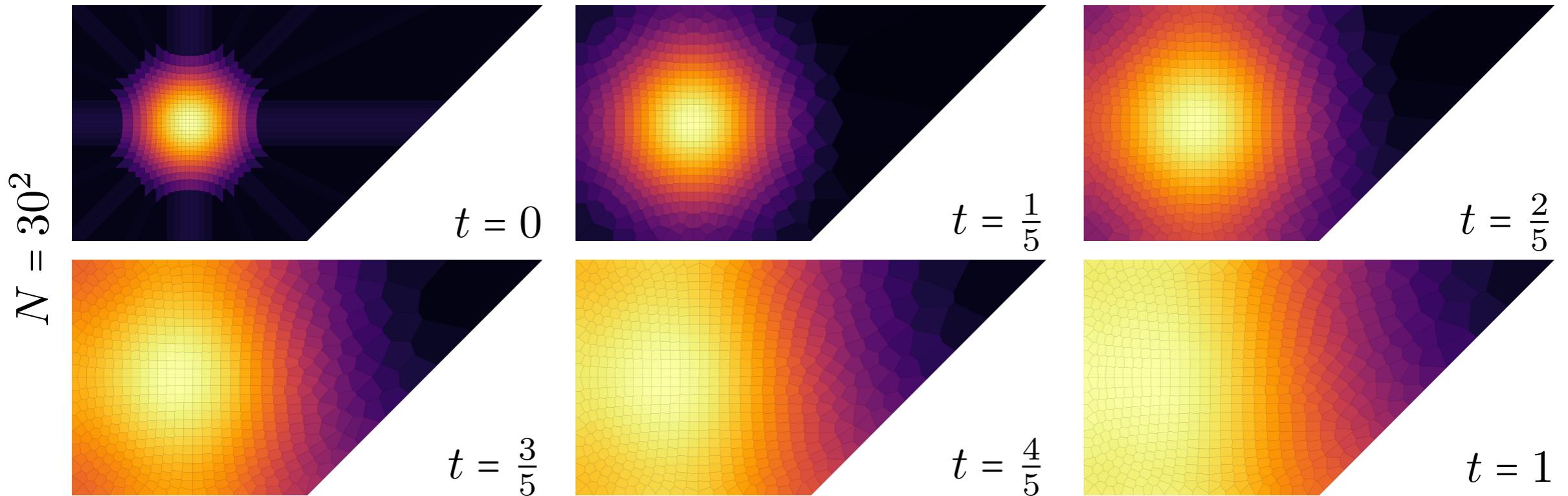
Then $\mu_N \rightharpoonup \rho \in \mathcal{C}^0([0, T], \mathcal{P}(\Omega))$, where ρ satisfies in the sense of distribution,

$$\begin{cases} \partial_t \rho + \text{div}(\rho v) = 0 \\ v = -\nabla V - \nabla p, \\ p = \log \rho \end{cases}$$

[M., Stra, Santambrogio '18]

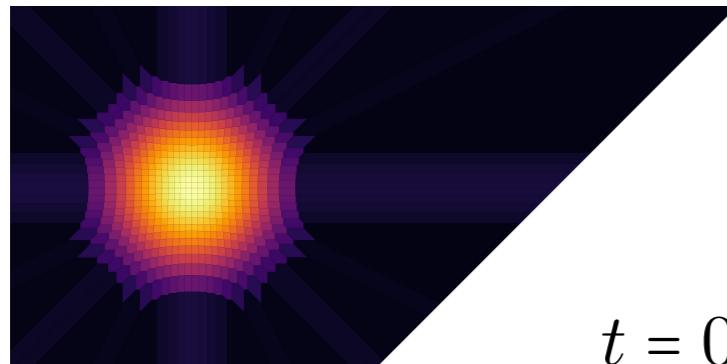
- ▶ The assumption $(*)$ is always true in 1D, and can be checked numerically in 2D.
(it is less strong than in the crowd motion case)

Numerical example

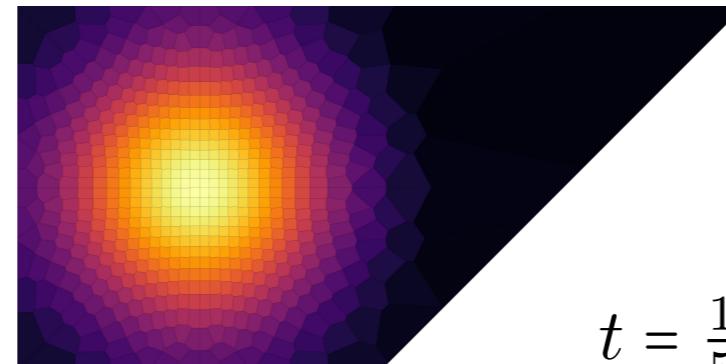


Numerical example

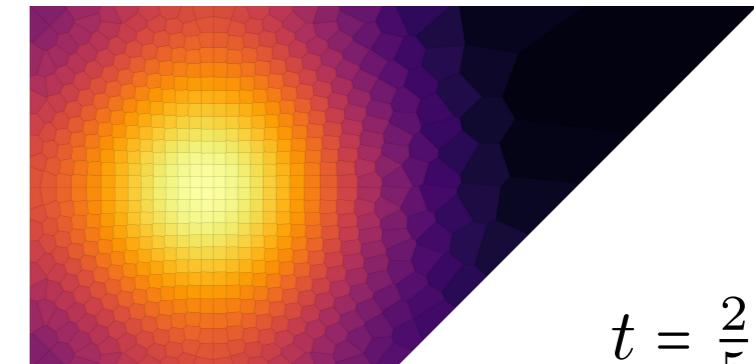
$N = 30^2$



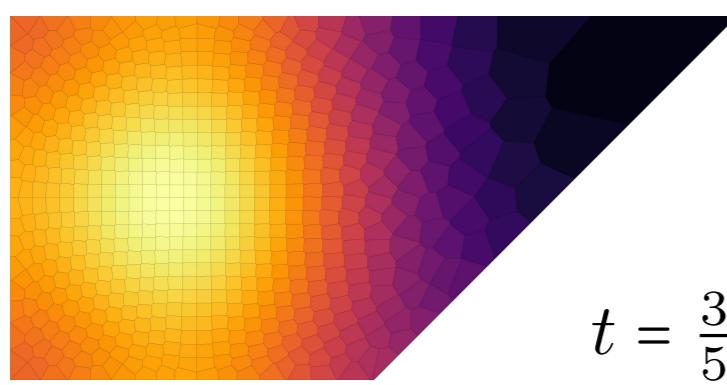
$t = 0$



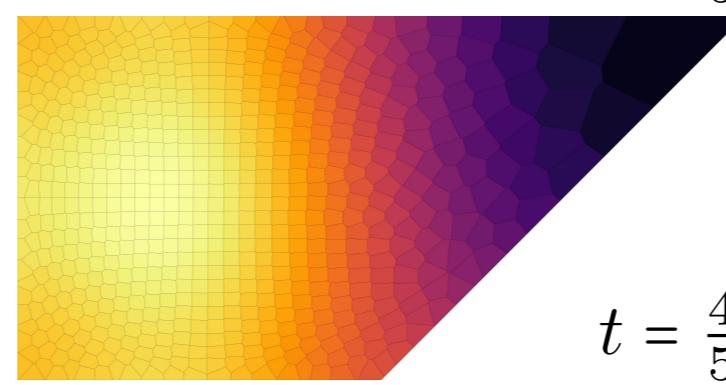
$t = \frac{1}{5\pi}$



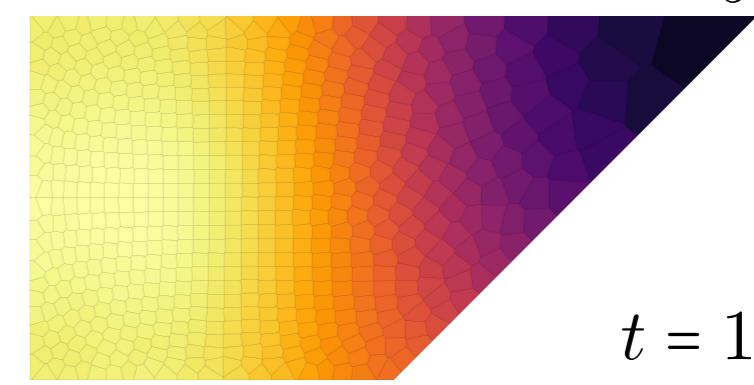
$t = \frac{1}{5\pi^2}$



$t = \frac{3}{5\pi}$

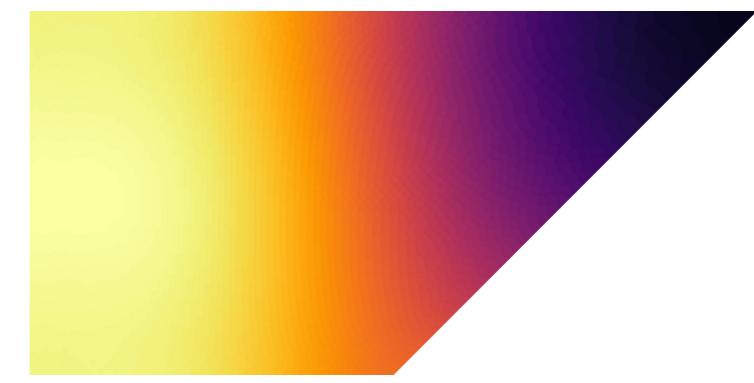
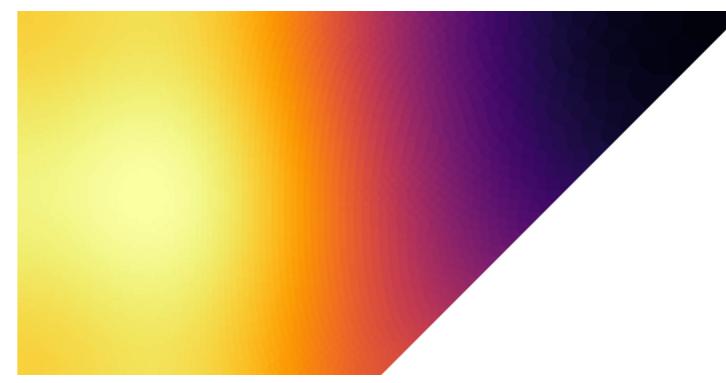
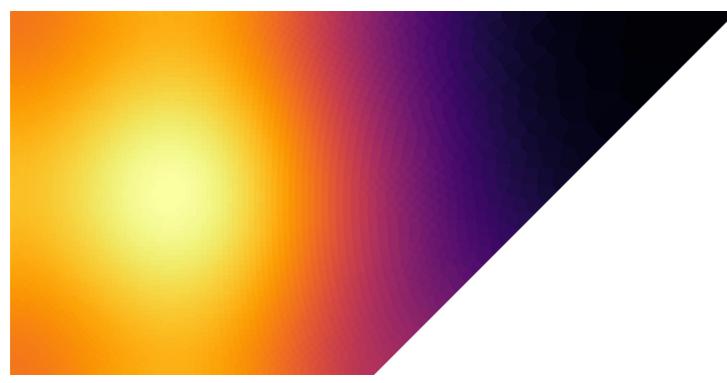
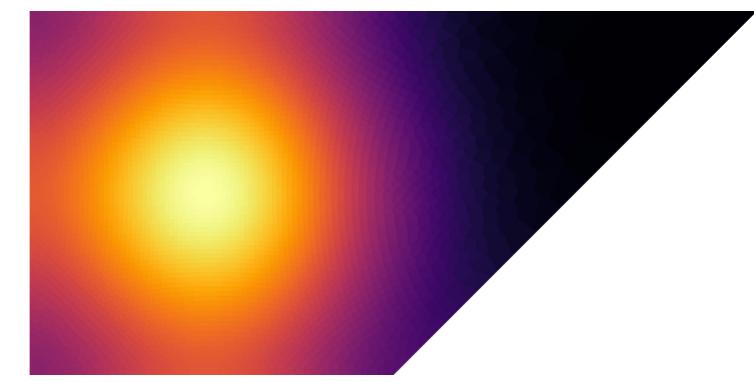
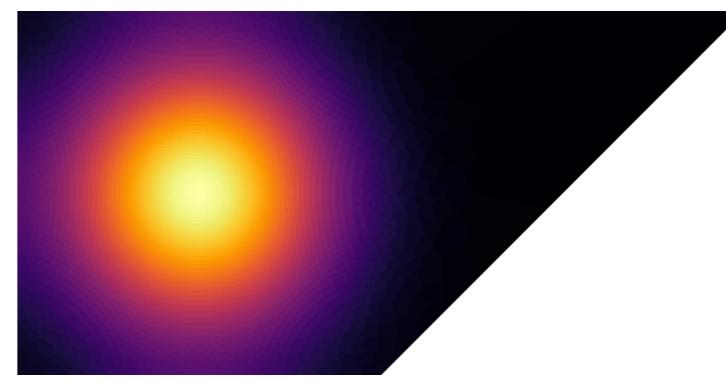
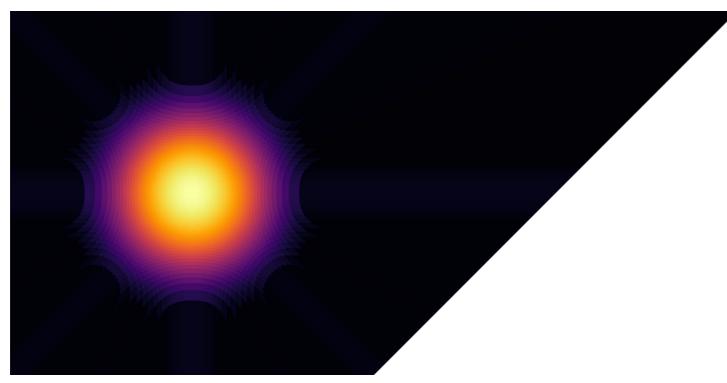


$t = \frac{4}{5\pi}$



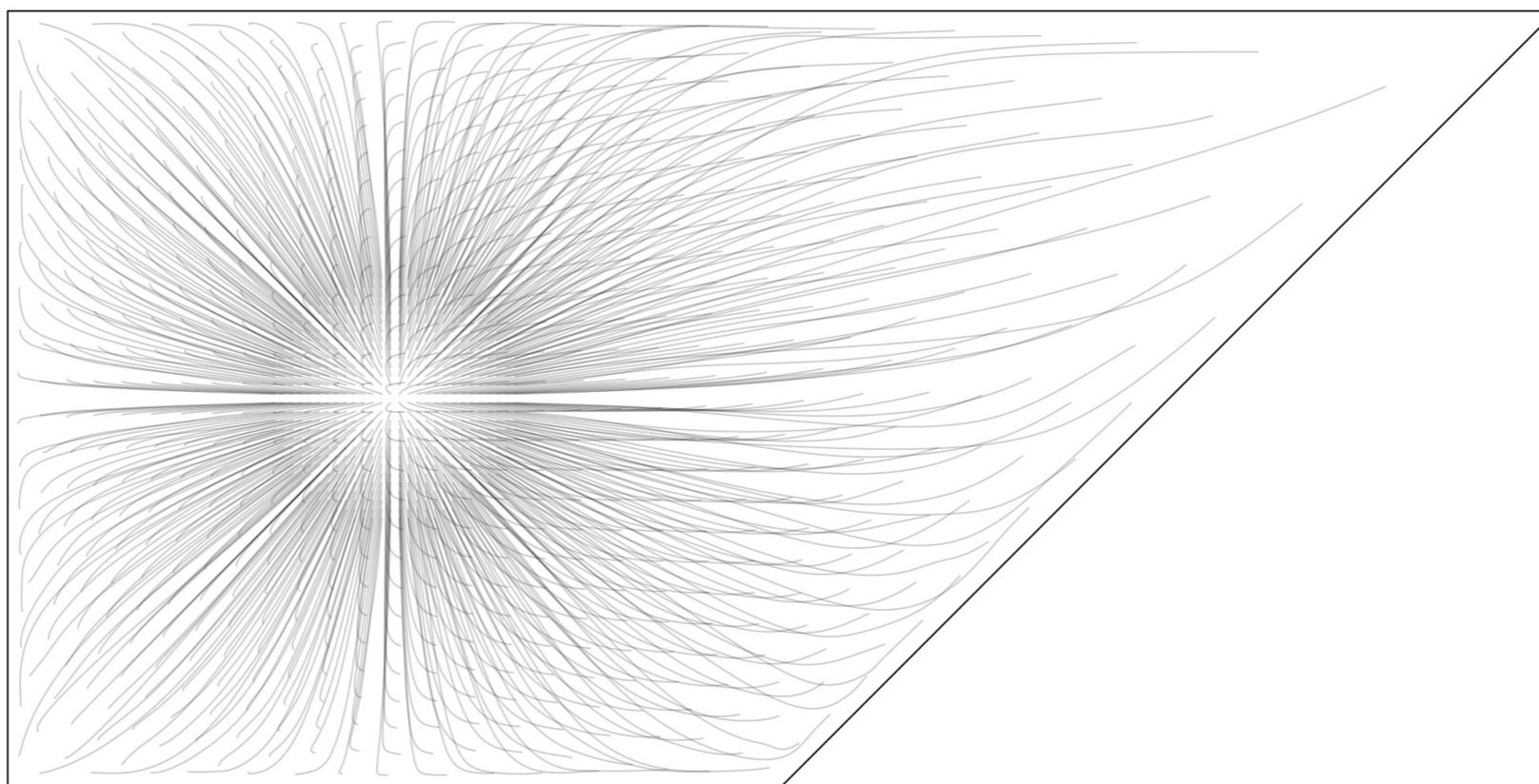
$t = 1$

$N = 80^2$

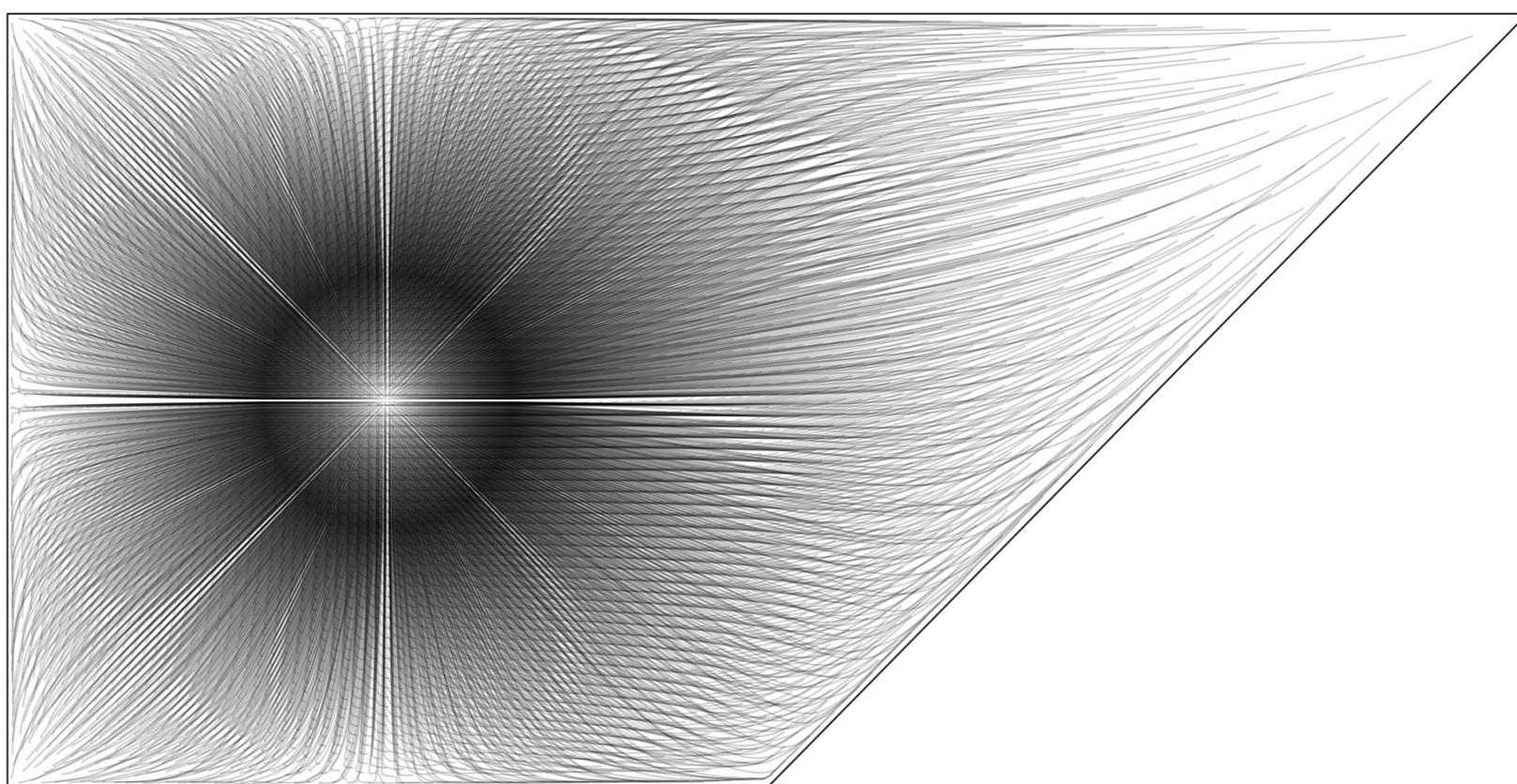


Numerical example

$$N = 30^2$$



$$N = 80^2$$



Summary

Optimal transport can be used to construct particle discretization of (some) evolution PDEs with congestion/incompressibility constraints or diffusion terms

<https://github.com/sd-ot>

Summary

Optimal transport can be used to construct particle discretization of (some) evolution PDEs with congestion/incompressibility constraints or diffusion terms

<https://github.com/sd-ot>

Some perspectives:

- ▶ more general models: non-linear diffusion, reaction terms (e.g. tumor growth),
multiple population, surface tension, interaction forces (e.g. Keller-Segel) ?
- ▶ convergence towards Lagrangian solutions (à la [Evans-Gangbo-Savin '05]) ?
- ▶ using the ε -entropy (resp. ε -relative entropy) as regularization/data fidelity terms in statistics or inverse problems ?

Summary

Optimal transport can be used to construct particle discretization of (some) evolution PDEs with congestion/incompressibility constraints or diffusion terms

<https://github.com/sd-ot>

Some perspectives:

- ▶ more general models: non-linear diffusion, reaction terms (e.g. tumor growth),
multiple population, surface tension, interaction forces (e.g. Keller-Segel) ?
- ▶ convergence towards Lagrangian solutions (à la [Evans-Gangbo-Savin '05]) ?
- ▶ using the ε -entropy (resp. ε -relative entropy) as regularization/data fidelity terms in statistics or inverse problems ?

Thank you for your attention!