

TheoryPrep Readings

May 2020

Selected from Mathematics for Computer Science (Lehman, Leighton, Meyer 2017), Building Blocks for Computer Science (Fleck 2013), and Introduction to Theoretical Computer Science (Barak, 2020)

The first part of this reading (until 3.2) is exposition and motivation.

These are certainly important parts of theoretical CS so read them, but the purpose is to build intuition, so even if you don't understand all the details, feel free to forge ahead

3

Defining computation

"there is no reason why mental as well as bodily labor should not be economized by the aid of machinery",
Charles Babbage, 1852

"If, unwarned by my example, any man shall undertake and shall succeed in constructing an engine embodying in itself the whole of the executive department of mathematical analysis upon different principles or by simpler mechanical means, I have no fear of leaving my reputation in his charge, for he alone will be fully able to appreciate the nature of my efforts and the value of their results.", Charles Babbage, 1864

"To understand a program you must become both the machine and the program.", Alan Perlis, 1982

People have been computing for thousands of years, with aids that include not just pen and paper, but also abacus, slide rules, various mechanical devices, and modern electronic computers. A priori, the notion of computation seems to be tied to the particular mechanism that you use. You might think that the “best” algorithm for multiplying numbers will differ if you implement it in *Python* on a modern laptop than if you use pen and paper. However, as we saw in the introduction (Chapter 0), an algorithm that is asymptotically better would eventually beat a worse one regardless of the underlying technology. This gives us hope for a *technology independent* way of defining computation. This is what we do in this chapter. We will define the notion of computing an output from an input by applying a sequence of basic operations (see Fig. 3.3). Using this, we will be able to precisely define statements such as “function f can be computed by model X ” or “function f can be computed by model X using s operations”.

Learning Objectives:

- See that computation can be precisely modeled.
- Learn the computational model of *Boolean circuits / straight-line programs*.
- Equivalence of circuits and straight-line programs.
- Equivalence of AND/OR/NOT and NAND.
- Examples of computing in the physical world.

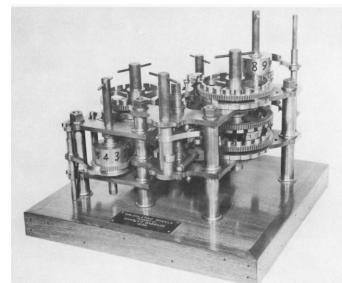


Figure 3.1: Calculating wheels by Charles Babbage.
Image taken from the Mark I ‘operating manual’



Figure 3.2: A 1944 *Popular Mechanics* article on the Harvard Mark I computer.

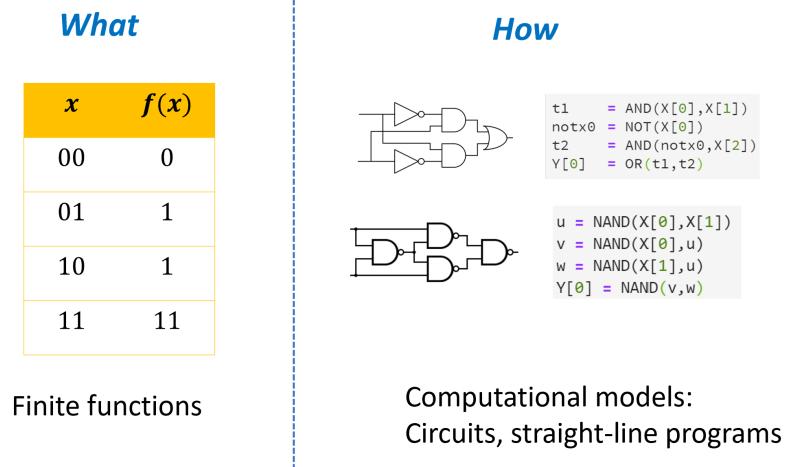


Figure 3.3: A function mapping strings to strings specifies a computational task, i.e., describes *what* the desired relation between the input and the output is. In this chapter we define models for *implementing* computational processes that achieve the desired relation, i.e., describe *how* to compute the output from the input. We will see several examples of such models using both Boolean circuits and straight-line programming languages.

This chapter: A non-mathy overview

The main takeaways from this chapter are:

- We can use *logical operations* such as *AND*, *OR*, and *NOT* to compute an output from an input (see [Section 3.2](#)).
- A *Boolean circuit* is a way to compose the basic logical operations to compute a more complex function (see [Section 3.3](#)). We can think of Boolean circuits as both a mathematical model (which is based on directed acyclic graphs) as well as physical devices we can construct in the real world in a variety of ways, including not just silicon-based semi-conductors but also mechanical and even biological mechanisms (see [Section 3.4](#)).
- We can describe Boolean circuits also as *straight-line programs*, which are programs that do not have any looping constructs (i.e., no `while` / `for` / `do .. until` etc.), see [Section 3.3.2](#).
- It is possible to implement the *AND*, *OR*, and *NOT* operations using the *NAND* operation (as well as vice versa). This means that circuits with *AND/OR/NOT* gates can compute the same functions (i.e., are *equivalent in power*) to circuits with *NAND* gates, and we can use either model to describe computation based on our convenience, see [Section 3.5](#). To give out a “spoiler”, we will see in [Chapter 4](#) that such circuits can compute *all* finite functions.

One “big idea” of this chapter is the notion of *equivalence* between models (Big Idea 3). Two computational models are *equivalent* if they can compute the same set of functions. Boolean circuits with AND/OR/NOT gates are equivalent to circuits with NAND gates, but this is just one example of the more general phenomenon that we will see many times in this book.

3.1 DEFINING COMPUTATION

The name “algorithm” is derived from the Latin transliteration of Muhammad ibn Musa al-Khwarizmi’s name. Al-Khwarizmi was a Persian scholar during the 9th century whose books introduced the western world to the decimal positional numeral system, as well as to the solutions of linear and quadratic equations (see Fig. 3.4). However Al-Khwarizmi’s descriptions of algorithms were rather informal by today’s standards. Rather than use “variables” such as x, y , he used concrete numbers such as 10 and 39, and trusted the reader to be able to extrapolate from these examples, much as algorithms are still taught to children today.

Here is how Al-Khwarizmi described the algorithm for solving an equation of the form $x^2 + bx = c$:

[How to solve an equation of the form] “roots and squares are equal to numbers”: For instance “one square , and ten roots of the same, amount to thirty-nine dirhems” that is to say, what must be the square which, when increased by ten of its own root, amounts to thirty-nine? The solution is this: you halve the number of the roots, which in the present instance yields five. This you multiply by itself; the product is twenty-five. Add this to thirty-nine’ the sum is sixty-four. Now take the root of this, which is eight, and subtract from it half the number of roots, which is five; the remainder is three. This is the root of the square which you sought for; the square itself is nine.

For the purposes of this book, we will need a much more precise way to describe algorithms. Fortunately (or is it unfortunately?), at least at the moment, computers lag far behind school-age children in learning from examples. Hence in the 20th century, people came up with exact formalisms for describing algorithms, namely *programming languages*. Here is al-Khwarizmi’s quadratic equation solving algorithm described in the *Python* programming language:



Figure 3.4: Text pages from Algebra manuscript with geometrical solutions to two quadratic equations. Shelfmark: MS. Huntington 214 fol. 004v-005

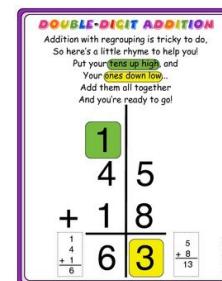


Figure 3.5: An explanation for children of the two digit addition algorithm

```

from math import sqrt
#Pythonspeak to enable use of the sqrt function to compute
↪ square roots.

def solve_eq(b,c):
    # return solution of  $x^2 + bx = c$  following Al
    ↪ Khwarizmi's instructions
    # Al Kwarizmi demonstrates this for the case b=10 and
    ↪ c= 39

    val1 = b / 2.0 # "halve the number of the roots"
    val2 = val1 * val1 # "this you multiply by itself"
    val3 = val2 + c # "Add this to thirty-nine"
    val4 = sqrt(val3) # "take the root of this"
    val5 = val4 - val1 # "subtract from it half the number
    ↪ of roots"
    return val5 # "This is the root of the square which
    ↪ you sought for"

# Test: solve  $x^2 + 10x = 39$ 
print(solve_eq(10,39))
# 3.0

```

We can define algorithms informally as follows:

Informal definition of an algorithm: An *algorithm* is a set of instructions for how to compute an output from an input by following a sequence of “elementary steps”.

An algorithm A computes a function F if for every input x , if we follow the instructions of A on the input x , we obtain the output $F(x)$.

In this chapter we will make this informal definition precise using the model of **Boolean Circuits**. We will show that Boolean Circuits are equivalent in power to **straight line programs** that are written in “ultra simple” programming languages that do not even have loops. We will also see that the particular choice of **elementary operations** is immaterial and many different choices yield models with equivalent power (see Fig. 3.6). However, it will take us some time to get there. We will start by discussing what are “elementary operations” and how we map a description of an algorithm into an actual physical process that produces an output from an input in the real world.

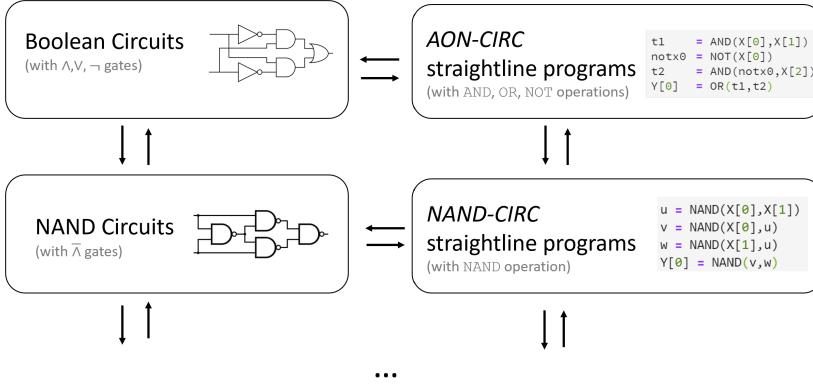


Figure 3.6: An overview of the computational models defined in this chapter. We will show several equivalent ways to represent a recipe for performing a finite computation. Specifically we will show that we can model such a computation using either a *Boolean circuit* or a *straight line program*, and these two representations are equivalent to one another. We will also show that we can choose as our basic operations either the set {AND, OR, NOT} or the set {NAND} and these two choices are equivalent in power. By making the choice of whether to use circuits or programs, and whether to use {AND, OR, NOT} or {NAND} we obtain four equivalent ways of modeling finite computation. Moreover, there are many other choices of sets of basic operations that are equivalent in power.

Start reading rigorously

3.2 COMPUTING USING AND, OR, AND NOT.

An algorithm breaks down a *complex* calculation into a series of *simpler* steps. These steps can be executed in a variety of different ways, including:

- Writing down symbols on a piece of paper.
- Modifying the current flowing on electrical wires.
- Binding a protein to a strand of DNA.
- Responding to a stimulus by a member of a collection (e.g., a bee in a colony, a trader in a market).

To formally define algorithms, let us try to “err on the side of simplicity” and model our “basic steps” as truly minimal. For example, here are some very simple functions:

- $OR : \{0, 1\}^2 \rightarrow \{0, 1\}$ defined as

$$OR(a, b) = \begin{cases} 0 & a = b = 0 \\ 1 & \text{otherwise} \end{cases} \quad (3.1)$$

- $AND : \{0, 1\}^2 \rightarrow \{0, 1\}$ defined as

$$AND(a, b) = \begin{cases} 1 & a = b = 1 \\ 0 & \text{otherwise} \end{cases} \quad (3.2)$$

- $NOT : \{0, 1\} \rightarrow \{0, 1\}$ defined as

$$NOT(a) = \begin{cases} 0 & a = 1 \\ 1 & a = 0 \end{cases} \quad (3.3)$$

The functions *AND*, *OR* and *NOT*, are the basic logical operators used in logic and many computer systems. In the context of logic, it is common to use the notation $a \wedge b$ for $\text{AND}(a, b)$, $a \vee b$ for $\text{OR}(a, b)$ and \bar{a} and $\neg a$ for $\text{NOT}(a)$, and we will use this notation as well.

Each one of the functions *AND*, *OR*, *NOT* takes either one or two single bits as input, and produces a single bit as output. Clearly, it cannot get much more basic than that. However, the power of computation comes from *composing* such simple building blocks together.

■ **Example 3.1 — Majority from AND, OR and NOT.** Consider the function $\text{MAJ} : \{0, 1\}^3 \rightarrow \{0, 1\}$ that is defined as follows:

$$\text{MAJ}(x) = \begin{cases} 1 & x_0 + x_1 + x_2 \geq 2 \\ 0 & \text{otherwise} \end{cases}. \quad (3.4)$$

That is, for every $x \in \{0, 1\}^3$, $\text{MAJ}(x) = 1$ if and only if the majority (i.e., at least two out of the three) of x 's elements are equal to 1. Can you come up with a formula involving *AND*, *OR* and *NOT* to compute MAJ ? (It would be useful for you to pause at this point and work out the formula for yourself. As a hint, although the *NOT* operator is needed to compute some functions, you will not need to use it to compute MAJ .)

Let us first try to rephrase $\text{MAJ}(x)$ in words: “ $\text{MAJ}(x) = 1$ if and only if there exists some pair of distinct elements i, j such that both x_i and x_j are equal to 1.” In other words it means that $\text{MAJ}(x) = 1$ iff *either* both $x_0 = 1$ and $x_1 = 1$, *or* both $x_1 = 1$ and $x_2 = 1$, *or* both $x_0 = 1$ and $x_2 = 1$. Since the *OR* of three conditions c_0, c_1, c_2 can be written as $\text{OR}(c_0, \text{OR}(c_1, c_2))$, we can now translate this into a formula as follows:

$$\text{MAJ}(x_0, x_1, x_2) = \text{OR}(\text{AND}(x_0, x_1), \text{OR}(\text{AND}(x_1, x_2), \text{AND}(x_0, x_2))). \quad (3.5)$$

Recall that we can also write $a \vee b$ for $\text{OR}(a, b)$ and $a \wedge b$ for $\text{AND}(a, b)$. With this notation, (3.5) can also be written as

$$\text{MAJ}(x_0, x_1, x_2) = ((x_0 \wedge x_1) \vee (x_1 \wedge x_2)) \vee (x_0 \wedge x_2). \quad (3.6)$$

We can also write (3.5) in a “programming language” form, expressing it as a set of instructions for computing MAJ given the basic operations *AND*, *OR*, *NOT*:

```
def MAJ(X[0],X[1],X[2]):  
    firstpair = AND(X[0],X[1])  
    secondpair = AND(X[1],X[2])  
    thirdpair = AND(X[0],X[2])  
    temp       = OR(secondpair,thirdpair)  
    return OR(firstpair,temp)
```

3.2.3 Informally defining “basic operations” and “algorithms”

We have seen that we can obtain at least some examples of interesting functions by composing together applications of *AND*, *OR*, and *NOT*. This suggests that we can use *AND*, *OR*, and *NOT* as our “basic operations”, hence obtaining the following definition of an “algorithm”:

Semi-formal definition of an algorithm: An *algorithm* consists of a sequence of steps of the form “compute a new value by applying *AND*, *OR*, or *NOT* to previously computed values”.

An algorithm A *computes* a function F if for every input x to F , if we feed x as input to the algorithm, the value computed in its last step is $F(x)$.

There are several concerns that are raised by this definition:

1. First and foremost, this definition is indeed too informal. We do not specify exactly what each step does, nor what it means to “feed x as input”.
2. Second, the choice of *AND*, *OR* or *NOT* seems rather arbitrary. Why not *XOR* and *MAJ*? Why not allow operations like addition and multiplication? What about any other logical constructions such *if/then* or *while*?
3. Third, do we even know that this definition has anything to do with actual computing? If someone gave us a description of such an algorithm, could we use it to actually compute the function in the real world?



These concerns will to a large extent guide us in the upcoming chapters. Thus you would be well advised to re-read the above informal definition and see what you think about these issues.

A large part of this book will be devoted to addressing the above issues. We will see that:

1. We can make the definition of an algorithm fully formal, and so give a precise mathematical meaning to statements such as “Algorithm A computes function f ”.
2. While the choice of *AND/OR/NOT* is arbitrary, and we could just as well have chosen other functions, we will also see this choice does not matter much. We will see that we would obtain the same

computational power if we instead used addition and multiplication, and essentially every other operation that could be reasonably thought of as a basic step.

3. It turns out that we can and do compute such “AND/OR/NOT based algorithms” in the real world. First of all, such an algorithm is clearly well specified, and so can be executed by a human with a pen and paper. Second, there are a variety of ways to *mechanize* this computation. We’ve already seen that we can write Python code that corresponds to following such a list of instructions. But in fact we can directly implement operations such as *AND*, *OR*, and *NOT* via electronic signals using components known as *transistors*. This is how modern electronic computers operate.

In the remainder of this chapter, and the rest of this book, we will begin to answer some of these questions. We will see more examples of the power of simple operations to compute more complex operations including addition, multiplication, sorting and more.

3.3 BOOLEAN CIRCUITS

Boolean circuits provide a precise notion of “composing basic operations together”. A Boolean circuit (see Fig. 3.9) is composed of *gates* and *inputs* that are connected by *wires*. The *wires* carry a signal that represents either the value 0 or 1. Each gate corresponds to either the *OR*, *AND*, or *NOT* operation. An *OR gate* has two incoming wires, and one or more outgoing wires. If these two incoming wires carry the signals a and b (for $a, b \in \{0, 1\}$), then the signal on the outgoing wires will be $OR(a, b)$. *AND* and *NOT* gates are defined similarly. The *inputs* have only outgoing wires. If we set a certain input to a value $a \in \{0, 1\}$, then this value is propagated on all the wires outgoing from it. We also designate some gates as *output gates*, and their value corresponds to the result of evaluating the circuit.

We evaluate an n -input Boolean circuit C on an input $x \in \{0, 1\}^n$ by placing the bits of x on the inputs, and then propagating the values on the wires until we reach an output, see Fig. 3.9.



Remark 3.4 — Physical realization of Boolean circuits.

Boolean circuits are a *mathematical model* that does not necessarily correspond to a physical object, but they can be implemented physically. In physical implementation of circuits, the signal is often implemented

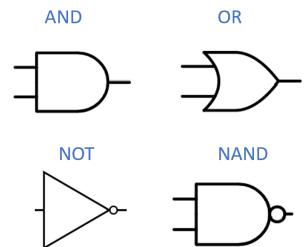


Figure 3.7: Standard symbols for the logical operations or “gates” of *AND*, *OR*, *NOT*, as well as the operation *NAND* discussed in Section 3.5.

by electric potential, or *voltage*, on a wire, where for example voltage above a certain level is interpreted as a logical value of 1, and below a certain level is interpreted as a logical value of 0. Section 3.4 discusses physical implementation of Boolean circuits (with examples including using electrical signals such as in silicon-based circuits, but also biological and mechanical implementations as well).

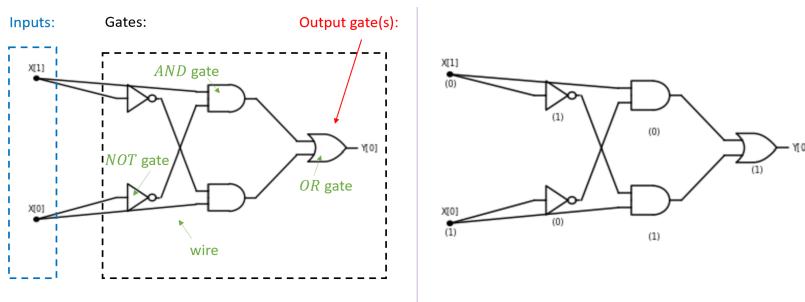


Figure 3.9: A Boolean Circuit consists of *gates* that are connected by *wires* to one another and the *inputs*. The left side depicts a circuit with 2 inputs and 5 gates, one of which is designated the output gate. The right side depicts the evaluation of this circuit on the input $x \in \{0, 1\}^2$ with $x_0 = 1$ and $x_1 = 0$. The value of every gate is obtained by applying the corresponding function (*AND*, *OR*, or *NOT*) to values on the wire(s) that enter it. The output of the circuit on a given input is the value of the output gate(s). In this case, the circuit computes the *XOR* function and hence it outputs 1 on the input 10.

Solved Exercise 3.3 — All equal function. Define $\text{ALLEQ} : \{0, 1\}^4 \rightarrow \{0, 1\}$ to be the function that on input $x \in \{0, 1\}^4$ outputs 1 if and only if $x_0 = x_1 = x_2 = x_3$. Give a Boolean circuit for computing ALLEQ .

If you feel like you already have a good understanding of what a boolean circuit is, you can skip this solved example. TheoryPrep uses boolean circuits as a way to build definition-understanding skills, so it's not so important you are super proficient at constructing boolean circuits to calculate arbitrary functions

Solution:

Another way to describe the function ALLEQ is that it outputs 1 on an input $x \in \{0, 1\}^4$ if and only if $x = 0^4$ or $x = 1^4$. We can phrase the condition $x = 1^4$ as $x_0 \wedge x_1 \wedge x_2 \wedge x_3$ which can be computed using three AND gates. Similarly we can phrase the condition $x = 0^4$ as $\bar{x}_0 \wedge \bar{x}_1 \wedge \bar{x}_2 \wedge \bar{x}_3$ which can be computed using four NOT gates and three AND gates. The output of ALLEQ is the OR of these two conditions, which results in the circuit of 4 NOT gates, 6 AND gates, and one OR gate presented in Fig. 3.10.

Resume reading rigorously

3.3.1 Boolean circuits: a formal definition

We defined Boolean circuits informally as obtained by connecting *AND*, *OR*, and *NOT* gates via wires so as to produce an output from an input. However, to be able to prove theorems about the existence or non-existence of Boolean circuits for computing various functions we need to:

1. Formally define a Boolean circuit as a mathematical object.

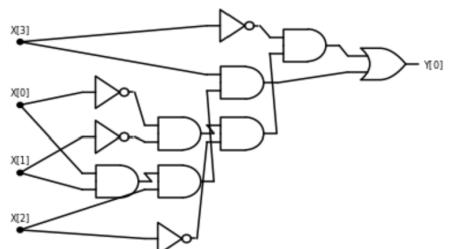


Figure 3.10: A Boolean circuit for computing the *all equal* function $\text{ALLEQ} : \{0, 1\}^4 \rightarrow \{0, 1\}$ that outputs 1 on $x \in \{0, 1\}^4$ if and only if $x_0 = x_1 = x_2 = x_3$.

2. Formally define what it means for a circuit C to compute a function f .

We now proceed to do so. We will define a Boolean circuit as a labeled *Directed Acyclic Graph (DAG)*. The *vertices* of the graph correspond to the gates and inputs of the circuit, and the *edges* of the graph correspond to the wires. A wire from an input or gate u to a gate v in the circuit corresponds to a directed edge between the corresponding vertices. The inputs are vertices with no incoming edges, while each gate has the appropriate number of incoming edges based on the function it computes. (That is, *AND* and *OR* gates have two in-neighbors, while *NOT* gates have one in-neighbor.) The formal definition is as follows (see also Fig. 3.11):

If you want a refresher on DAGs and topological sorting, see last week's reading (pg 12-16)

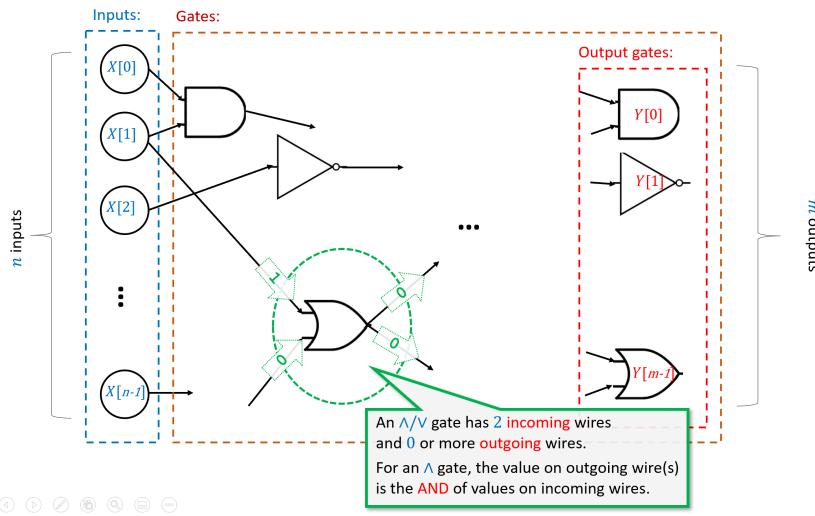


Figure 3.11: A Boolean Circuit is a labeled directed acyclic graph (DAG). It has n input vertices, which are marked with $X[0], \dots, X[n - 1]$ and have no incoming edges, and the rest of the vertices are *gates*. AND, OR, and NOT gates have two, two, and one incoming edges, respectively. If the circuit has m outputs, then m of the gates are known as *outputs* and are marked with $Y[0], \dots, Y[m - 1]$. When we evaluate a circuit C on an input $x \in \{0, 1\}^n$, we start by setting the value of the input vertices to x_0, \dots, x_{n-1} and then propagate the values, assigning to each gate g the result of applying the operation of g to the values of g 's in-neighbors. The output of the circuit is the value assigned to the output gates.

Definition 3.5 — Boolean Circuits. Let n, m, s be positive integers with $s \geq m$. A Boolean circuit with n inputs, m outputs, and s gates, is a labeled directed acyclic graph (DAG) $G = (V, E)$ with $s+n$ vertices satisfying the following properties:

- Exactly n of the vertices have no in-neighbors. These vertices are known as *inputs* and are labeled with the n labels $X[0], \dots, X[n - 1]$. Each input has at least one out-neighbor.
 - The other s vertices are known as *gates*. Each gate is labeled with \wedge , \vee or \neg . Gates labeled with \wedge (AND) or \vee (OR) have two in-neighbors. Gates labeled with \neg (NOT) have one in-neighbor.
- We will allow parallel edges.¹

- Exactly m of the gates are also labeled with the m labels $Y[0], \dots, Y[m - 1]$ (in addition to their label $\wedge/\vee/\neg$). These are known as *outputs*.

The *size* of a Boolean circuit is the number of gates it contains.

P

This is a non-trivial mathematical definition, so it is worth taking the time to read it slowly and carefully. As in all mathematical definitions, we are using a known mathematical object — a directed acyclic graph (DAG) — to define a new object, a Boolean circuit. This might be a good time to review some of the basic properties of DAGs and in particular the fact that they can be *topologically sorted*, see Section 1.6.

If C is a circuit with n inputs and m outputs, and $x \in \{0, 1\}^n$, then we can compute the output of C on the input x in the natural way: assign the input vertices $X[0], \dots, X[n - 1]$ the values x_0, \dots, x_{n-1} , apply each gate on the values of its in-neighbors, and then output the values that correspond to the output vertices. Formally, this is defined as follows:

Definition 3.6 — Computing a function via a Boolean circuit. Let C be a Boolean circuit with n inputs and m outputs. For every $x \in \{0, 1\}^n$, the *output* of C on the input x , denoted by $C(x)$, is defined as the result of the following process:

We let $h : V \rightarrow \mathbb{N}$ be the *minimal layering* of C (aka *topological sorting*, see Theorem 1.26). We let L be the maximum layer of h , and for $\ell = 0, 1, \dots, L$ we do the following:

- For every v in the ℓ -th layer (i.e., v such that $h(v) = \ell$) do:
 - If v is an input vertex labeled with $X[i]$ for some $i \in [n]$, then we assign to v the value x_i .
 - If v is a gate vertex labeled with \wedge and with two in-neighbors u, w then we assign to v the AND of the values assigned to u and w . (Since u and w are in-neighbors of v , they are in a lower layer than v , and hence their values have already been assigned.)
 - If v is a gate vertex labeled with \vee and with two in-neighbors u, w then we assign to v the OR of the values assigned to u and w .

¹ Having parallel edges means an AND or OR gate u can have both its in-neighbors be the same gate v . Since $AND(a, a) = OR(a, a) = a$ for every $a \in \{0, 1\}$, such parallel edges don't help in computing new values in circuits with AND/OR/NOT gates. However, we will see circuits with more general sets of gates later on.

Instead of a minimal layering, let h be a function that maps each vertex to its place in the order of a topological sort (to be consistent with definition 10.5.2 on page 14 of last week's reading of a topological sort). This implies that there will be as many "layers" (L) as vertices, so you can just think of doing the for loop for every vertex in the topological sort list

- If v is a gate vertex labeled with \neg and with one in-neighbor u then we assign to v the negation of the value assigned to u .
- The result of this process is the value $y \in \{0, 1\}^m$ such that for every $j \in [m]$, y_j is the value assigned to the vertex with label $\gamma[j]$.

Let $f : \{0, 1\}^n \rightarrow \{0, 1\}^m$. We say that the circuit C computes f if for every $x \in \{0, 1\}^n$, $C(x) = f(x)$.

R

Remark 3.7 — Boolean circuits nitpicks (optional). In phrasing Definition 3.5, we've made some technical choices that are not very important, but will be convenient for us later on. Having parallel edges means an AND or OR gate u can have both its in-neighbors be the same gate v . Since $AND(a, a) = OR(a, a) = a$ for every $a \in \{0, 1\}$, such parallel edges don't help in computing new values in circuits with AND/OR/NOT gates. However, we will see circuits with more general sets of gates later on. The condition that every input vertex has at least one out-neighbor is also not very important because we can always add "dummy gates" that touch these inputs. However, it is convenient since it guarantees that (since every gate has at most two in-neighbors) that the number of inputs in a circuit is never larger than twice its size.

3.3.2 Equivalence of circuits and straight-line programs

We have seen two ways to describe how to compute a function f using AND, OR and NOT:

- A Boolean circuit, defined in Definition 3.5, computes f by connecting via wires AND, OR, and NOT gates to the inputs.
- We can also describe such a computation using a *straight-line program* that has lines of the form $foo = AND(bar, blah)$, $foo = OR(bar, blah)$ and $foo = NOT(bar)$ where foo , bar and $blah$ are variable names. (We call this a *straight-line program* since it contains no loops or branching (e.g., if/then) statements.)

We now formally define the AON-CIRC programming language ("AON" stands for AND/OR/NOT; "CIRC" stands for *circuit*) which has the above operations, and show that it is equivalent to Boolean circuits.

Definition 3.8 — AON-CIRC Programming language. An *AON-CIRC program* is a string of lines of the form $\text{foo} = \text{AND}(\text{bar}, \text{blah})$, $\text{foo} = \text{OR}(\text{bar}, \text{blah})$ and $\text{foo} = \text{NOT}(\text{bar})$ where foo , bar and blah are variable names.² Variables of the form $X[i]$ are known as *input variables*, and variables of the form $Y[j]$ are known as *output variables*. In every line, the variables on the righthand side of the assignment operators must either be input variables or variables that have already been assigned a value.

A valid AON-CIRC program P includes input variables of the form $X[0], \dots, X[n - 1]$ and output variables of the form $Y[0], \dots, Y[m - 1]$ for some $n, m \geq 1$. If P is valid AON-CIRC program and $x \in \{0, 1\}^n$, then we define the *output of P on input x* , denoted by $P(x)$, to be the string $y \in \{0, 1\}^m$ corresponding to the values of the output variables $Y[0], \dots, Y[m - 1]$ in the execution of P where we initialize the input variables $X[0], \dots, X[n - 1]$ to the values x_0, \dots, x_{n-1} .

We say that such an AON-CIRC program P *computes* a function $f : \{0, 1\}^n \rightarrow \{0, 1\}^m$ if $P(x) = f(x)$ for every $x \in \{0, 1\}^n$.

AON-CIRC is not a practical programming language: it was designed for pedagogical purposes only, as a way to model computation as composition of *AND*, *OR*, and *NOT*. However, AON-CIRC can still be easily implemented on a computer. The following solved exercise gives an example of an AON-CIRC program.

Solved Exercise 3.4 Consider the following function $CMP : \{0, 1\}^4 \rightarrow \{0, 1\}$ that on four input bits $a, b, c, d \in \{0, 1\}$, outputs 1 iff the number represented by (a, b) is larger than the number represented by (c, d) . That is $CMP(a, b, c, d) = 1$ iff $2a + b > 2c + d$.

Write an AON-CIRC program to compute CMP .

² We follow the common [programming languages convention](#) of using names such as `foo`, `bar`, `baz`, `blah` as stand-ins for generic identifiers. A variable identifier in our programming language can be any combination of letters, numbers, underscores, and brackets. The [appendix](#) contains a full formal specification of our programming language.

Solution:

Writing such a program is tedious but not truly hard. To compare two numbers we first compare their most significant digit, and then go down to the next digit and so on and so forth. In this case where the numbers have just two binary digits, these comparisons are particularly simple. The number represented by (a, b) is larger than the number represented by (c, d) if and only if one of the following conditions happens:

1. The most significant bit a of (a, b) is larger than the most significant bit c of (c, d) .

or

2. The two most significant bits a and c are equal, but $b > d$.

Another way to express the same condition is the following: the number (a, b) is larger than (c, d) iff $a > c$ **OR** $(a \geq c$ **AND** $b > d)$.

For binary digits α, β , the condition $\alpha > \beta$ is simply that $\alpha = 1$ and $\beta = 0$ or $AND(\alpha, NOT(\beta)) = 1$, and the condition $\alpha \geq \beta$ is simply $OR(\alpha, NOT(\beta)) = 1$. Together these observations can be used to give the following AON-CIRC program to compute *CMP*:

```
temp_1 = NOT(X[2])
temp_2 = AND(X[0], temp_1)
temp_3 = OR(X[0], temp_1)
temp_4 = NOT(X[3])
temp_5 = AND(X[1], temp_4)
temp_6 = AND(temp_5, temp_3)
Y[0] = OR(temp_2, temp_6)
```

We can also present this 8-line program as a circuit with 8 gates, see Fig. 3.12.

It turns out that AON-CIRC programs and Boolean circuits have exactly the same power:

Theorem 3.9 — Equivalence of circuits and straight-line programs. Let $f : \{0, 1\}^n \rightarrow \{0, 1\}^m$ and $s \geq m$ be some number. Then f is computable by a Boolean circuit of s gates if and only if f is computable by an AON-CIRC program of s lines.

Proof Idea:

The idea is simple - AON-CIRC programs and Boolean circuits are just different ways of describing the exact same computational process. For example, an *AND* gate in a Boolean circuit corresponding to computing the *AND* of two previously-computed values. In a AON-CIRC program this will correspond to the line that stores in a variable the *AND* of two previously-computed variables.

*



This proof of Theorem 3.9 is simple at heart, but all the details it contains can make it a little cumbersome to read. You might be better off trying to work it out yourself before reading it. Our [GitHub repository](#) contains a “proof by Python” of Theorem 3.9: implementation of functions `circuit2prog` and `prog2circuits`

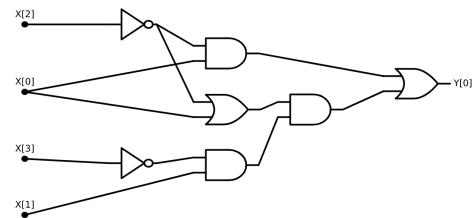


Figure 3.12: A circuit for computing the *CMP* function. The evaluation of this circuit on $(1, 1, 1, 0)$ yields the output 1, since the number 3 (represented in binary as 11) is larger than the number 2 (represented in binary as 10).

mapping Boolean circuits to AON-CIRC programs and vice versa.

Proof of Theorem 3.9. Let $f : \{0, 1\}^n \rightarrow \{0, 1\}^m$. Since the theorem is an “if and only if” statement, to prove it we need to show both directions: translating an AON-CIRC program that computes f into a circuit that computes f , and translating a circuit that computes f into an AON-CIRC program that does so.

We start with the first direction. Let P be an s line AON-CIRC that computes f . We define a circuit C as follows: the circuit will have n inputs and s gates. For every $i \in [s]$, if the i -th line has the form $\text{foo} = \text{AND}(\text{bar}, \text{blah})$ then the i -th gate in the circuit will be an AND gate that is connected to gates j and k where j and k correspond to the last lines before i where the variables bar and blah (respectively) were written to. (For example, if $i = 57$ and the last line bar was written to is 35 and the last line blah was written to is 17 then the two in-neighbors of gate 57 will be gates 35 and 17.) If either bar or blah is an input variable then we connect the gate to the corresponding input vertex instead. If foo is an output variable of the form $\text{Y}[j]$ then we add the same label to the corresponding gate to mark it as an output gate. We do the analogous operations if the i -th line involves an OR or a NOT operation (except that we use the corresponding *OR* or *NOT* gate, and in the latter case have only one in-neighbor instead of two). For every input $x \in \{0, 1\}^n$, if we run the program P on x , then the value written that is computed in the i -th line is exactly the value that will be assigned to the i -th gate if we evaluate the circuit C on x . Hence $C(x) = P(x)$ for every $x \in \{0, 1\}^n$.

For the other direction, let C be a circuit of s gates and n inputs that computes the function f . We sort the gates according to a topological order and write them as v_0, \dots, v_{s-1} . We now can create a program P of s lines as follows. For every $i \in [s]$, if v_i is an AND gate with in-neighbors v_j, v_k then we will add a line to P of the form $\text{temp}_i = \text{AND}(\text{temp}_j, \text{temp}_k)$, unless one of the vertices is an input vertex or an output gate, in which case we change this to the form $\text{X}[.]$ or $\text{Y}[.]$ appropriately. Because we work in topological ordering, we are guaranteed that the in-neighbors v_j and v_k correspond to variables that have already been assigned a value. We do the same for OR and NOT gates. Once again, one can verify that for every input x , the value $P(x)$ will equal $C(x)$ and hence the program computes the same function as the circuit. (Note that since C is a valid circuit, per Definition 3.5, every input vertex of C has at least one out-neighbor and there are exactly m output gates labeled $0, \dots, m-1$; hence all the

variables $X[0], \dots, X[n - 1]$ and $Y[0], \dots, Y[m - 1]$ will appear in the program P .)

Section 3.4 is high-level content. You can skim, and skip if you're getting bogged down. This is mainly important for understanding how our mathematical definition corresponds to real computers in real life.

3.4 PHYSICAL IMPLEMENTATIONS OF COMPUTING DEVICES (DI- GRESSION)

Computation is an abstract notion that is distinct from its physical *implementations*. While most modern computing devices are obtained by mapping logical gates to semiconductor based transistors, over history people have computed using a huge variety of mechanisms, including mechanical systems, gas and liquid (known as *fluidics*), biological and chemical processes, and even living creatures (e.g., see Fig. 3.14 or [this video](#) for how crabs or slime mold can be used to do computations).

In this section we will review some of these implementations, both so you can get an appreciation of how it is possible to directly translate Boolean circuits to the physical world, without going through the entire stack of architecture, operating systems, and compilers, as well as to emphasize that silicon-based processors are by no means the only way to perform computation. Indeed, as we will see in Chapter 22, a very exciting recent line of work involves using different media for computation that would allow us to take advantage of *quantum mechanical effects* to enable different types of algorithms.

Such a cool way to explain logic gates. pic.twitter.com/6Wgu2ZKFCx
— Lionel Page ([page_eco]) October 28, 2019

3.4.1 Transistors

A *transistor* can be thought of as an electric circuit with two inputs, known as the *source* and the *gate* and an output, known as the *sink*. The gate controls whether current flows from the source to the sink. In a *standard transistor*, if the gate is “ON” then current can flow from the source to the sink and if it is “OFF” then it can’t. In a *complementary transistor* this is reversed: if the gate is “OFF” then current can flow from the source to the sink and if it is “ON” then it can’t.

There are several ways to implement the logic of a transistor. For example, we can use faucets to implement it using water pressure (e.g. Fig. 3.15). This might seem as merely a curiosity, but there is a field known as *fluidics* concerned with implementing logical operations using liquids or gasses. Some of the motivations include operating in extreme environmental conditions such as in space or a battlefield, where standard electronic equipment would not survive.

The standard implementations of transistors use electrical current. One of the original implementations used *vacuum tubes*. As its name

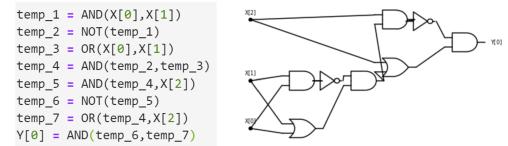


Figure 3.13: Two equivalent descriptions of the same AND/OR/NOT computation as both an AON program and a Boolean circuit.

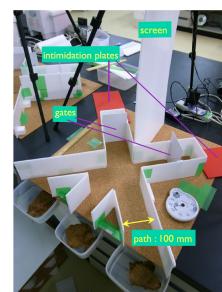


Figure 3.14: Crab-based logic gates from the paper “Robust soldier-crab ball gate” by Gunji, Nishiyama and Adamatzky. This is an example of an AND gate that relies on the tendency of two swarms of crabs arriving from different directions to combine to a single swarm that continues in the average of the directions.

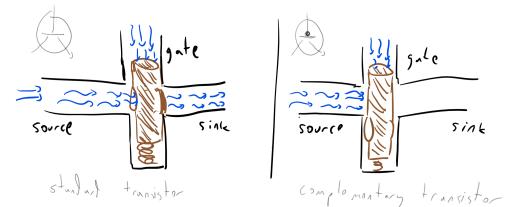


Figure 3.15: We can implement the logic of transistors using water. The water pressure from the gate closes or opens a faucet between the source and the sink.

implies, a vacuum tube is a tube containing nothing (i.e., a vacuum) and where a priori electrons could freely flow from the source (a wire) to the sink (a plate). However, there is a gate (a grid) between the two, where modulating its voltage can block the flow of electrons.

Early vacuum tubes were roughly the size of lightbulbs (and looked very much like them too). In the 1950's they were supplanted by *transistors*, which implement the same logic using *semiconductors* which are materials that normally do not conduct electricity but whose conductivity can be modified and controlled by inserting impurities ("doping") and applying an external electric field (this is known as the *field effect*). In the 1960's computers started to be implemented using *integrated circuits* which enabled much greater density. In 1965, Gordon Moore predicted that the number of transistors per integrated circuit would double every year (see Fig. 3.16), and that this would lead to "such wonders as home computers—or at least terminals connected to a central computer—automatic controls for automobiles, and personal portable communications equipment". Since then, (adjusted versions of) this so-called "Moore's law" have been running strong, though exponential growth cannot be sustained forever, and some physical limitations are already becoming apparent.

3.4.2 Logical gates from transistors

We can use transistors to implement various Boolean functions such as *AND*, *OR*, and *NOT*. For each a two-input gate $G : \{0, 1\}^2 \rightarrow \{0, 1\}$, such an implementation would be a system with two input wires x, y and one output wire z , such that if we identify high voltage with "1" and low voltage with "0", then the wire z will equal to "1" if and only if applying G to the values of the wires x and y is 1 (see Fig. 3.19 and Fig. 3.20). This means that if there exists a AND/OR/NOT circuit to compute a function $g : \{0, 1\}^n \rightarrow \{0, 1\}^m$, then we can compute g in the physical world using transistors as well.

3.4.3 Biological computing

Computation can be based on **biological or chemical systems**. For example the *lac operon* produces the enzymes needed to digest lactose only if the conditions $x \wedge (\neg y)$ hold where x is "lactose is present" and y is "glucose is present". Researchers have managed to **create transistors**, and from them logic gates, based on DNA molecules (see also Fig. 3.21). One motivation for DNA computing is to achieve increased parallelism or storage density; another is to create "smart biological agents" that could perhaps be injected into bodies, replicate themselves, and fix or kill cells that were damaged by a disease such as cancer. Computing in biological systems is not restricted, of course, to

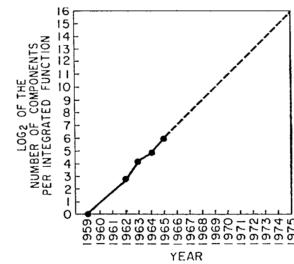


Figure 3.16: The number of transistors per integrated circuits from 1959 till 1965 and a prediction that exponential growth will continue for at least another decade. Figure taken from "Cramming More Components onto Integrated Circuits", Gordon Moore, 1965

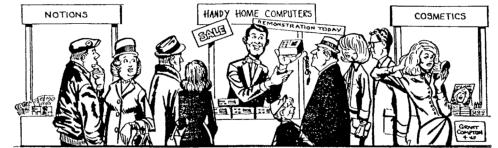


Figure 3.17: Cartoon from Gordon Moore's article "predicting" the implications of radically improving transistor density.



Figure 3.18: The exponential growth in computing power over the last 120 years. Graph by Steve Jurvetson, extending a prior graph of Ray Kurzweil.

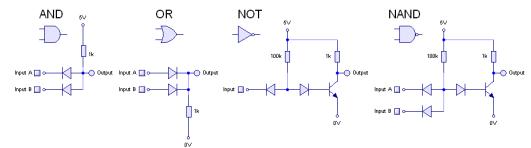


Figure 3.19: Implementing logical gates using transistors. Figure taken from [Rory Mangels' website](#).

DNA: even larger systems such as **flocks of birds** can be considered as computational processes.

3.4.4 Cellular automata and the game of life

Cellular automata is a model of a system composed of a sequence of *cells*, each of which can have a finite state. At each step, a cell updates its state based on the states of its *neighboring cells* and some simple rules. As we will discuss later in this book (see Section 7.4), cellular automata such as Conway's "Game of Life" can be used to simulate computation gates.

3.4.5 Neural networks

One computation device that we all carry with us is our own *brain*. Brains have served humanity throughout history, doing computations that range from distinguishing prey from predators, through making scientific discoveries and artistic masterpieces, to composing witty 280 character messages. The exact working of the brain is still not fully understood, but one common mathematical model for it is a (very large) *neural network*.

A neural network can be thought of as a Boolean circuit that instead of AND/OR/NOT uses some other gates as the basic basis. For example, one particular basis we can use are *threshold gates*. For every vector $w = (w_0, \dots, w_{k-1})$ of integers and integer t (some or all of which could be negative), the *threshold function corresponding to w, t* is the function $T_{w,t} : \{0,1\}^k \rightarrow \{0,1\}$ that maps $x \in \{0,1\}^k$ to 1 if and only if $\sum_{i=0}^{k-1} w_i x_i \geq t$. For example, the threshold function $T_{w,t}$ corresponding to $w = (1, 1, 1, 1, 1)$ and $t = 3$ is simply the majority function MAJ_5 on $\{0,1\}^5$. Threshold gates can be thought of as an approximation for *neuron cells* that make up the core of human and animal brains. To a first approximation, a neuron has k inputs and a single output, and the neurons "fires" or "turns on" its output when those signals pass some threshold.

Many machine learning algorithms use *artificial neural networks* whose purpose is not to imitate biology but rather to perform some computational tasks, and hence are not restricted to threshold or other biologically-inspired gates. Generally, a neural network is often described as operating on signals that are real numbers, rather than 0/1 values, and where the output of a gate on inputs x_0, \dots, x_{k-1} is obtained by applying $f(\sum_i w_i x_i)$ where $f : \mathbb{R} \rightarrow \mathbb{R}$ is an **activation function** such as rectified linear unit (ReLU), Sigmoid, or many others (see Fig. 3.23). However, for the purposes of our discussion, all of the above are equivalent (see also Exercise 3.13). In particular we can reduce the setting of real inputs to binary inputs by representing a

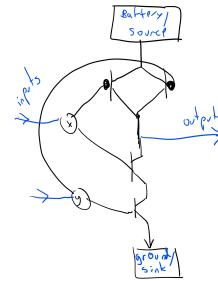


Figure 3.20: Implementing a NAND gate (see Section 3.5) using transistors.

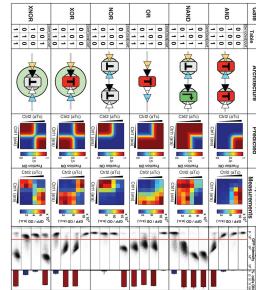


Figure 3.21: Performance of DNA-based logic gates. Figure taken from paper of Bonnet et al, Science, 2013.

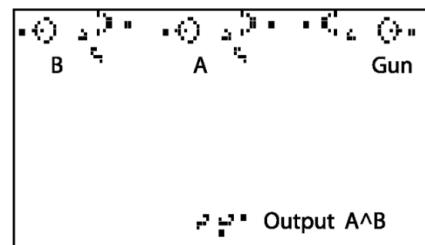


Figure 3.22: An AND gate using a "Game of Life" configuration. Figure taken from Jean-Philippe Rennard's paper.

real number in the binary basis, and multiplying the weight of the bit corresponding to the i^{th} digit by 2^i .

3.4.6 A computer made from marbles and pipes

We can implement computation using many other physical media, without any electronic, biological, or chemical components. Many suggestions for *mechanical* computers have been put forward, going back at least to Gottfried Leibniz' computing machines from the 1670s and Charles Babbage's 1837 plan for a mechanical “[Analytical Engine](#)”. As one example, Fig. 3.24 shows a simple implementation of a NAND (negation of AND, see Section 3.5) gate using marbles going through pipes. We represent a logical value in $\{0, 1\}$ by a pair of pipes, such that there is a marble flowing through exactly one of the pipes. We call one of the pipes the “0 pipe” and the other the “1 pipe”, and so the identity of the pipe containing the marble determines the logical value. A NAND gate corresponds to a mechanical object with two pairs of incoming pipes and one pair of outgoing pipes, such that for every $a, b \in \{0, 1\}$, if two marbles are rolling toward the object in the a pipe of the first pair and the b pipe of the second pair, then a marble will roll out of the object in the $\text{NAND}(a, b)$ -pipe of the outgoing pair. In fact, there is even a commercially-available educational game that uses marbles as a basis of computing, see Fig. 3.26.

Start reading rigorously again

3.5 THE NAND FUNCTION

The NAND function is another simple function that is extremely useful for defining computation. It is the function mapping $\{0, 1\}^2$ to $\{0, 1\}$ defined by:

$$\text{NAND}(a, b) = \begin{cases} 0 & a = b = 1 \\ 1 & \text{otherwise} \end{cases}. \quad (3.9)$$

As its name implies, NAND is the NOT of AND (i.e., $\text{NAND}(a, b) = \text{NOT}(\text{AND}(a, b))$), and so we can clearly compute NAND using AND and NOT. Interestingly, the opposite direction holds as well:

Theorem 3.10 — NAND computes AND,OR,NOT. We can compute AND, OR, and NOT by composing only the NAND function.

Proof. We start with the following observation. For every $a \in \{0, 1\}$, $\text{AND}(a, a) = a$. Hence, $\text{NAND}(a, a) = \text{NOT}(\text{AND}(a, a)) = \text{NOT}(a)$. This means that NAND can compute NOT. By the principle of “double negation”, $\text{AND}(a, b) = \text{NOT}(\text{NOT}(\text{AND}(a, b)))$, and hence we can use NAND to compute AND as well. Once we can compute AND and NOT, we can compute OR using “[De Morgan’s Law](#)”:

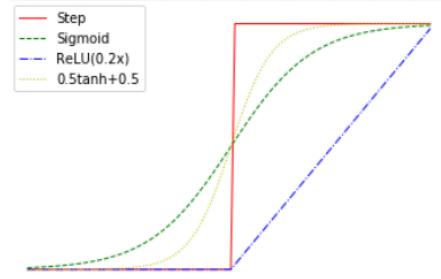


Figure 3.23: Common activation functions used in Neural Networks, including rectified linear units (ReLU), sigmoids, and hyperbolic tangent. All of those can be thought of as continuous approximations to simple the step function. All of these can be used to compute the NAND gate (see Exercise 3.13). This property enables neural networks to (approximately) compute any function that can be computed by a Boolean circuit.

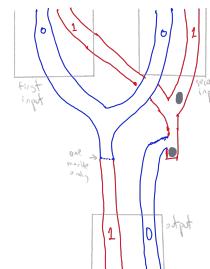


Figure 3.24: A physical implementation of a NAND gate using marbles. Each wire in a Boolean circuit is modeled by a pair of pipes representing the values 0 and 1 respectively, and hence a gate has four input pipes (two for each logical input) and two output pipes. If one of the input pipes representing the value 0 has a marble in it then that marble will flow to the output pipe representing the value 1. (The dashed line represents a gadget that will ensure that at most one marble is allowed to flow onward in the pipe.) If both the input pipes representing the value 1 have marbles in them, then the first marble will be stuck but the second one will flow onwards to the output pipe representing the value 0.

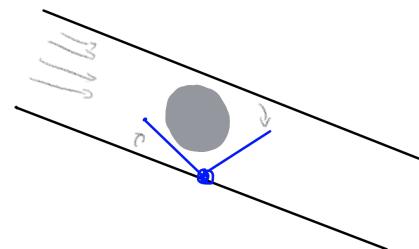


Figure 3.25: A “gadget” in a pipe that ensures that at most one marble can pass through it. The first marble that passes causes the barrier to lift and block new ones.

$OR(a, b) = NOT(AND(NOT(a), NOT(b)))$ (which can also be written as $a \vee b = \bar{a} \wedge \bar{b}$) for every $a, b \in \{0, 1\}$.

P

Theorem 3.10's proof is very simple, but you should make sure that (i) you understand the statement of the theorem, and (ii) you follow its proof. In particular, you should make sure you understand why De Morgan's law is true.

We can use *NAND* to compute many other functions, as demonstrated in the following exercise.

Solved Exercise 3.5 — Compute majority with NAND. Let $MAJ : \{0, 1\}^3 \rightarrow \{0, 1\}$ be the function that on input a, b, c outputs 1 iff $a + b + c \geq 2$. Show how to compute MAJ using a composition of *NAND*'s.

Solution:

Recall that (3.5) states that

$$MAJ(x_0, x_1, x_2) = OR(AND(x_0, x_1), OR(AND(x_1, x_2), AND(x_0, x_2))). \quad (3.10)$$

We can use Theorem 3.10 to replace all the occurrences of *AND* and *OR* with *NAND*'s. Specifically, we can use the equivalence $AND(a, b) = NOT(NAND(a, b))$, $OR(a, b) = NAND(NOT(a), NOT(b))$, and $NOT(a) = NAND(a, a)$ to replace the righthand side of (3.10) with an expression involving only *NAND*, yielding that $MAJ(a, b, c)$ is equivalent to the (somewhat unwieldy) expression

$$\begin{aligned} &NAND\left(NAND\left(NAND(NAND(a, b), NAND(a, c)),\right.\right. \\ &\quad \left.\left.NAND(NAND(a, b), NAND(a, c))\right),\right. \\ &\quad \left.\left.NAND(b, c)\right)\right) \end{aligned} \quad (3.11)$$

The same formula can also be expressed as a circuit with *NAND* gates, see Fig. 3.27.

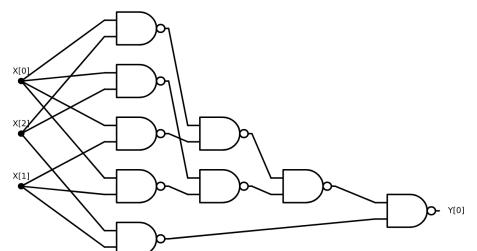
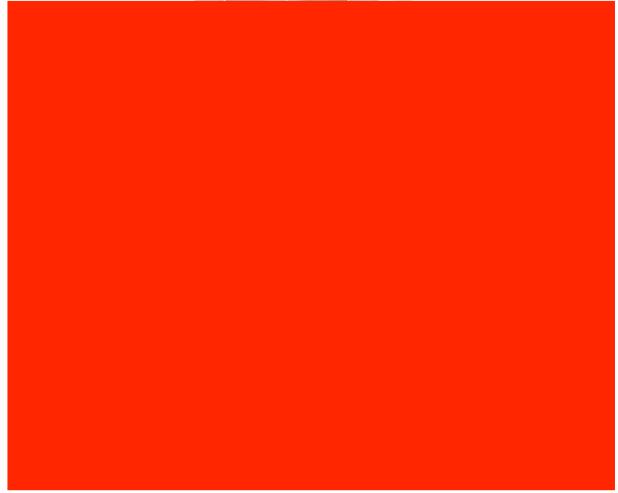


Figure 3.27: A circuit with *NAND* gates to compute the Majority function on three bits

3.5.1 NAND Circuits

We define *NAND Circuits* as circuits in which all the gates are *NAND* operations. Such a circuit again corresponds to a directed acyclic

graph (DAG) since all the gates correspond to the same function (i.e., NAND), we do not even need to label them, and all gates have in-degree exactly two. Despite their simplicity, NAND circuits can be quite powerful.

■ **Example 3.11 — NAND circuit for XOR.** Recall the XOR function which maps $x_0, x_1 \in \{0, 1\}$ to $x_0 + x_1 \bmod 2$. We have seen in Section 3.2.2 that we can compute XOR using AND, OR, and NOT, and so by Theorem 3.10 we can compute it using only NAND's. However, the following is a direct construction of computing XOR by a sequence of NAND operations:

1. Let $u = \text{NAND}(x_0, x_1)$.
2. Let $v = \text{NAND}(x_0, u)$
3. Let $w = \text{NAND}(x_1, u)$.
4. The XOR of x_0 and x_1 is $y_0 = \text{NAND}(v, w)$.

One can verify that this algorithm does indeed compute XOR by enumerating all the four choices for $x_0, x_1 \in \{0, 1\}$. We can also represent this algorithm graphically as a circuit, see Fig. 3.28.

In fact, we can show the following theorem:

Theorem 3.12 — NAND is a universal operation. For every Boolean circuit C of s gates, there exists a NAND circuit C' of at most $3s$ gates that computes the same function as C .

This theorem was proven in the video so no need to reread the proof

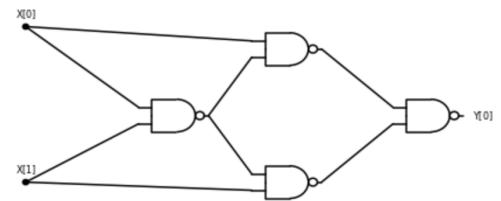


Figure 3.28: A circuit with NAND gates to compute the XOR of two bits.

Q **Big Idea 3** Two models are *equivalent in power* if they can be used to compute the same set of functions.

3.5.3 The NAND-CIRC Programming language

Just like we did for Boolean circuits, we can define a programming-language analog of NAND circuits. It is even simpler than the AON-CIRC language since we only have a single operation. We define the

NAND-CIRC Programming Language to be a programming language where every line has the following form:

```
foo = NAND(bar,blah)
```

where foo, bar and blah are variable identifiers.

■ **Example 3.15 — Our first NAND-CIRC program.** Here is an example of a NAND-CIRC program:

```
u = NAND(X[0],X[1])
v = NAND(X[0],u)
w = NAND(X[1],u)
Y[0] = NAND(v,w)
```



Do you know what function this program computes?

Hint: you have seen it before.

Formally, just like we did in [Definition 3.8](#) for AON-CIRC, we can define the notion of computation by a NAND-CIRC program in the natural way:

Definition 3.16 — Computing by a NAND-CIRC program. Let $f : \{0, 1\}^n \rightarrow \{0, 1\}^m$ be some function, and let P be a NAND-CIRC program. We say that P *computes* the function f if:

1. P has n input variables $X[0], \dots, X[n-1]$ and m output variables $Y[0], \dots, Y[m-1]$.
2. For every $x \in \{0, 1\}^n$, if we execute P when we assign to $X[0], \dots, X[n-1]$ the values x_0, \dots, x_{n-1} , then at the end of the execution, the output variables $Y[0], \dots, Y[m-1]$ have the values y_0, \dots, y_{m-1} where $y = f(x)$.

LEAVE THIS BOX HERE--DO NOT DELETE THIS BOX (IT IS COVERING THE ANSWER TO A PSET PROBLEM SO IF YOU DO YOU'RE DENYING YOURSELF A LEARNING EXPERIENCE)