

# RepnDecomp

**Decompose representations of finite  
groups into irreducibles**

0.1

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# Chapter 1

## Block diagonalizing representations

### 1.1 Finding the correct basis

Given a representation  $\rho : G \rightarrow GL(V)$ , it is often desirable to find a basis for  $V$  that block diagonalizes each  $\rho(g)$  with the block sizes being as small as possible.

#### 1.1.1 BlockDiagonalBasis (for IsGroupHomomorphism)

▷ `BlockDiagonalBasis(rho)` (attribute)

**Returns:** Basis for  $V$  that block diagonalizes  $\rho$ .

Let  $G$  have irreducible representations  $\rho_i$ , with dimension  $d_i$  and multiplicity  $m_i$ . The basis returned by this operation gives each  $\rho(g)$  as a block diagonal matrix which has  $m_i$  blocks of size  $d_i \times d_i$  for each  $i$ .

#### 1.1.2 BlockDiagonalRepresentation (for IsGroupHomomorphism)

▷ `BlockDiagonalRepresentation(rho)` (attribute)

**Returns:** Representation of  $G$  isomorphic to  $\rho$  where the images  $\rho(g)$  are block diagonalized.

This is just a convenience operation that uses `BlockDiagonalBasis` (??) to calculate the basis change matrix and put  $\rho$  into a nice form.

## Chapter 2

# Calculating centralizer rings

### 2.1 Centralizer (commutant) of a representation

#### 2.1.1 RepresentationCentralizerBlocks

▷ RepresentationCentralizerBlocks( $\rho$ ) (function)

**Returns:** List of standard generators (as a vector space) for the centralizer ring of  $\rho(G)$ , written in the basis given by BlockDiagonalBasis (??). The matrices are given as a list of blocks.

Let  $G$  have irreducible representations  $\rho_i$  with multiplicities  $m_i$ . The centralizer has dimension  $\sum_i m_i^2$  as a  $\mathbb{C}$ -vector space. This function gives the minimal number of generators required.

### 2.2 Useful convenience functions

#### 2.2.1 RepresentationCentralizer

▷ RepresentationCentralizer( $\rho$ ) (function)

**Returns:** List of standard generators (as a vector space) for the centralizer ring of  $\rho(G)$ .

This gives the same result as RepresentationCentralizerBlocks (2.1.1), but with the matrices given in their entirety: not as lists of blocks, but as full matrices.

#### 2.2.2 RepresentationCentralizerDecomposed

▷ RepresentationCentralizerDecomposed( $\rho$ ) (function)

**Returns:** List of generators (as a vector space) for the centralizer ring of  $\rho(G)$ , under the map taking each identity matrix block to a 1 by 1 block.

This function is here to demonstrate the reduction in dimension of the centralizer  $C$  by writing it in the basis given by BlockDiagonalBasis (??). The matrices given are as reduced as possible.

## Chapter 3

# Useful predicates

### 3.1 Types of group representations

#### 3.1.1 `IsFiniteGroupLinearRepresentation` (for `IsGroupHomomorphism`)

▷ `IsFiniteGroupLinearRepresentation( $\rho$ )` (attribute)

**Returns:** true or false

Tells you if  $\rho$  is a linear representation of a finite group. This is important since Serre's algorithms only work on these.

#### 3.1.2 `IsFiniteGroupPermutationRepresentation` (for `IsGroupHomomorphism`)

▷ `IsFiniteGroupPermutationRepresentation( $\rho$ )` (attribute)

**Returns:** true or false

Tells you if  $\rho$  is a homomorphism from finite group to a permutation group. Such homomorphisms occur often in applications.

## Chapter 4

# Computing decompositions of representations

### 4.1 Algorithms due to Serre

These operations compute various decompositions of a representation  $\rho : G \rightarrow GL(V)$  where  $G$  is finite and  $V$  is a finite-dimensional  $\mathbb{C}$ -vector space. The terms used here are taken from Serre's Linear Representations of Finite Groups.

#### 4.1.1 CanonicalDecomposition (for IsGroupHomomorphism)

▷ CanonicalDecomposition( $\rho$ ) (attribute)

**Returns:** List of vector spaces  $V_i$ , each  $G$ -invariant and a direct sum of isomorphic irreducibles. That is, for each  $i$ ,  $V_i \cong \oplus_j W_j$  (as representations) where  $W_j$  is an irreducible  $G$ -invariant vector space.

Computes the canonical decomposition of  $V$  into  $\oplus_i V_i$  using the formulas for projections  $V \rightarrow V_i$  due to Serre.

#### 4.1.2 IrreducibleDecomposition (for IsGroupHomomorphism)

▷ IrreducibleDecomposition( $\rho$ ) (attribute)

**Returns:** List of vector spaces  $W_j$  such that  $V = \oplus_j W_j$  and each  $W_j$  is an irreducible  $G$ -invariant vector space.

Computes the decomposition of  $V$  into irreducible subrepresentations.

#### 4.1.3 IrreducibleDecompositionCollected (for IsGroupHomomorphism)

▷ IrreducibleDecompositionCollected( $\rho$ ) (attribute)

**Returns:** List of lists  $V_i$  of vector spaces  $V_{ij}$  such that  $V = \oplus_i \oplus_j V_{ij}$  and  $V_{ik} \cong V_{il}$  for all  $i, k$  and  $l$  (as representations).

Computes the decomposition of  $V$  into irreducible subrepresentations, grouping together the isomorphic subrepresentations.

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