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Nusa Zidaric Mark Aagaard Guang Gong

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Nusa Zidaric Email: nzidaric@uwaterloo.ca
Homepage: http://

Mark Aagaard Email: maagaard@uwaterloo.ca
Homepage: http://

Guang Gong Email: ggong@uwaterloo.ca
Homepage: http://
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Abstract

The GAP package FSR ...

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If you obtained FSR, we would be grateful for a short notification sent to one of the authors.

If you publish a result which was partially obtained with the usage of FSR, please cite it in the following form:

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Chapter 1

Preface

The GAP package FSR implements Feedback Shift Registers

Chapter 2

FSR (Feedback Shift Register)

2.1 Common functionality

We define an object FSR (Feedback Shift Register), which can come in two flavours: with linear feedback LFSR (2.2.1) and nonlinear feedback NLFSR (2.3.2). Because of many similarities between the two, the basic common functionality can be found here, while specialized functions (such as LFSR and NLFSR object creation) in corresponding sections.

2.1.1 IsFSR

▷ IsFSR (filter)

This is the category of FSR objects. Objects in this category are created using functions LFSR (2.2.1) or NLFSR (2.3.2).

2.1.2 FieldPoly

FieldPoly of the *fsr* stores the irreducible polynomial used to construct the extension field or 1 in case of a prime field.

UnderlyingField of the fsr is the finite field over which the fsr is defined (all indeterminates and constants are from this field).

NOTE: it may seem redundant to sore both FieldPoly and UnderlyingField, however, they are used by other functions in the package.

FeedbackVec of the *fsr* stores the coefficients of the CharPoly without its leading term in case of LFSR, and coefficients of the nonzero monomials present in the multivariate function defining the feedback in case of NLFSR.

 ${\tt OutputTap}$ holds the output tap position(s): the sequence elements are taken from the stage(s) listed in ${\tt OutputTap}$.

2.1.3 Length

ightharpoonup Length(fsr) (attribute) ightharpoonup InternalStateSize(fsr) (attribute) ightharpoonup Threshold(fsr) (attribute)

Length of the fsr is the number of its stages.

InternalStateSize of the fsr is size in bits needed to store the state $length \cdot width$, where width = DegreeOverPrimeField(UnderlyingField(fsr)).

Threshold of the fsr is currently set to $Characteristic(fsr)^t + \ell$, where t = InternalStateSize(fsr) and $\ell = Length(fsr)$.

2.1.4 ChangeBasis

```
▷ ChangeBasis(fsr, B) (method)
▷ WhichBasis(fsr) (method)
```

ChangeBasis allows changing the basis of the fsr to basis B. Basis B must be given for UnderlyingField(fsr) over its prime subfield.

WhichBasis returns the basis currently set for the fsr. Elements in the fsr state are still represented in GAP native representation, but the functions with basis switch turned on will print the elements w.r.t to currently set basis.

2.1.5 LoadFSR

$$\triangleright$$
 LoadFSR(fsr , ist) (method)

Loading the *fsr* with the initial state *ist*, which is a *FFE* vector of same length as *fsr* and with elements from its underlying finite field. If either of those two requirements is violated, loading fails and error message appears. At the time of loading the initial sequence elements (ie zeroth elements) are obtained and numsteps is set to 0.

2.1.6 StepFSR

Perform one step the fsr, ie. compute the new state and update the numsteps, then output the elements denoted by OutputTap. If the optional parameter elm is used then the new element is computed as a sum of computed feedback and elm. Elemen elm must be an element of the underlying finite field.

As this is a way to destroy the linearity of an LFSR, we refer to StepFSR with the optiomal nonzero elm as nonlinear step. Similarly, the NLFSR can also have an extra element added to the (already nonlinear) feedback.

Returns an error if the fsr is not loaded!

2.1.7 RunFSR

Returns: A sequence of elements generated by FSR.

The fsr will be run for min(num, Threshold(fsr)) number of steps: value Threshold(fsr) is used by all versions without explicit num and enforced when num exceeds Threshold(fsr). There is an optional printing switch pr, with default set to false; if true then the state and the output sequence element(s) are printed in GAP shell on every step of the fsr (we call this output for RunFSR), and the currently set basis B is used for representation of elements.

- RunFSR(fsr[, num, pr]) run fsr for num/threshold steps with/without output
- RunFSR(fsr, ist[, num, pr]) load fsr with ist, then run fsr for num/threshold steps with/without output (ie. linear version)
- RunFSR(fsr, elm[, num, pr]) run fsr for num/threshold steps, whereby the SAME element elm is added to the feedback at each step, with/without output (ie. non-linear version)
- RunFSR(fsr, ist, elmvec[, pr]) load fsr with ist, then run fsr for Length(elmvec) steps, whereby one element of elmvec is added to the feedback at each step (starting with elmvec[1]), with/without output (ie. non-linear version). NOTE: the sequence returned has length Length(elmvec)+1, because the zeroth sequence element is returned at the time of loading the FSR.
- RunFSR(fsr, z, elmvec[, pr]) input z must be set to 0 to indicate we want to continue a run with new elmvec: run fsr for Length(elmvec) steps, whereby one element of elmvec is added to the feedback at each step (starting with elmvec[1]), with/without output (ie. non-linear version). NOTE: the sequence returned has length Length(elmvec).

For the load and run versions, element seq₀ is a part of the output sequence, hence the output sequence has the length num+1/threshold+1/Length(elmvec)+1.

For versions without the loading of ist, calling RunFSR returns an error if the fsr is not loaded! The ouput of RunFSR is:

- sequence of FFEs: seq₀, seq₁, seq₂, ..., for Length(OutputTap)=1
- sequence of vectors, each of them with t FFEs: seq_0 , seq_1 , seq_2 , ..., where $seq_i = (seq_{i1}, ..., seq_{it})$ for Length(OutputTap) = t

Example of RunFSR called for an lfsr *test* over F_{24} , with initial state *ist*, print switch *true* for basis B, with run length 5:

```
gap> K := GF(2);; x := X(K, "x");;
gap> f := x^4 + x^3 + 1;; F := FieldExtension(K, f);; B := Basis(F);;
gap> y := X(F, "y");; 1 := y^4+ y+ Z(2^4);;
gap> test := LFSR(K, f, 1);;
< empty LFSR given by CharPoly = y^4+y+Z(2^4)>
```

```
gap> ist :=[0*Z(2), Z(2^4), Z(2^4)^5, Z(2)^0];;
gap> RunFSR(test, ist, 5, true);
using basis B := [Z(2)^0, Z(2^4)^7, Z(2^4)^14, Z(2^4)^6]
                      [3,
                                         ...,0 ] with taps [0]
 [[0,0,0,0],[0,1,1,0],[1,1,0,1],[1,0,0,0]]
                                              [1, 0, 0, 0]
      [[1,0,1,1],[0,0,0],[0,1,1,0],[1,1,0,1]]
                                              [ 1, 1, 0, 1 ]
      [[0, 1, 1, 1], [1, 0, 1, 1], [0, 0, 0, 0], [0, 1, 1, 0]]
                                              [0,1,1,0]
      [[1,0,1,1],[0,1,1],[1,0,1,1],[0,0,0,0]]
                                              [ 0, 0, 0, 0 ]
      [[1,0,1,1],[1,0,1,1],[0,1,1,1],[1,0,1,1]]
                                              [ 1, 0, 1, 1 ]
      [[1, 1, 0, 1], [1, 0, 1, 1], [1, 0, 1, 1], [0, 1, 1, 1]]
                                              [ 0, 1, 1, 1 ]
[ Z(2)^0, Z(2^2), Z(2^4), 0*Z(2), Z(2^4)^2, Z(2^4)^1]
```

Example of RunFSR called for an lfsr *test* over F_{2^4} , with initial state *ist*, print switch *true* for basis B, with 5 nonlinear inputs :

```
_{\scriptscriptstyle -} Example
gap> elmvec := [Z(2^4)^2, Z(2^4)^2, Z(2^2), Z(2^4)^7, Z(2^4)^6];
gap> RunFSR(test, ist, elmvec, true);
using basis B := [Z(2)^0, Z(2^4)^7, Z(2^4)^14, Z(2^4)^6]
                                       ...,0 ] with taps [0]
elm
                  [ 3,
[0,0,0,0]
                            [[0, 0, 0, 0], [0, 1, 1, 0], [1, 1, 0, 1],
 [1,0,0,0]]
                               [1,0,0,0]
                            [[0, 0, 0, 0], [0, 0, 0, 0], [0, 1, 1, 0],
[ 1, 0, 1, 1 ]
 [ 1, 1, 0, 1 ] ]
                               [ 1, 1, 0, 1 ]
[ 1, 0, 1, 1 ]
                            [[1, 1, 0, 0], [0, 0, 0, 0], [0, 0, 0, 0],
 [0, 1, 1, 0]]
                               [0, 1, 1, 0]
                            [[0, 1, 1, 0], [1, 1, 0, 0], [0, 0, 0, 0],
[ 1, 1, 0, 1 ]
 [ 0, 0, 0, 0 ] ]
                               [ 0, 0, 0, 0 ]
                            [[0, 1, 0, 0], [0, 1, 1, 0], [1, 1, 0, 0],
[ 0, 1, 0, 0 ]
 [0,0,0,0]]
                               [0,0,0,0]
                            [[1, 1, 0, 1], [0, 1, 0, 0], [0, 1, 1, 0],
[0,0,0,1]
 [1, 1, 0, 0]]
                               [1, 1, 0, 0]
[ Z(2^4)^9, Z(2^2), Z(2^4), 0*Z(2), 0*Z(2), Z(2^4)^9 ]
```

In both examples above the there is a column elm, which is in first case empty, because we are not adding nonlinear inputs to the feedback, while in the second example, this column shows the element being added at each step (empty in first row - the loading step). Also note that the two examples above use the call LoadFSR, which adds the elm seq₀ to the sequence, so both sequences above are of length num+1/Length(elmvec)+1, ie 6. The last row in both examples is the actual sequence obtained from this run, and is kept in Zechs logarithm representation.

```
gap> RunFSR(test, ist); Length(last);
[ Z(2)^0, Z(2^2), Z(2^4), 0*Z(2), Z(2^4)^2, Z(2^4)^1, Z(2^4)^2, Z(2^4)^2,
```

```
Z(2^2), Z(2^4)^7, Z(2^4)^6, Z(2^4)^11, Z(2^2)^2, Z(2^4)^14, Z(2^4)^8, Z(2^4)^3, Z(2^2)^2, Z(2^4)^2, Z(2^4), Z(2^4)^2, Z(2^4)^9]
21
```

Last example above shows a sequence of length 21, ie *threshold+1*, getting first sequence element from LoadFSR followed by *threshold* iterations of StepFSR.

2.2 LFSR specific funcionality

2.2.1 LFSR

```
\triangleright \  \, \mathsf{LFSR}(F, \, \mathsf{charpol}[, \, B, \, \mathsf{tap}]) \qquad \qquad (\mathsf{function}) \\ \triangleright \  \, \mathsf{LFSR}(K, \, \mathsf{fieldpol}, \, \mathsf{charpol}[, \, B, \, \mathsf{tap}]) \qquad \qquad (\mathsf{function}) \\ \triangleright \  \, \mathsf{LFSR}(F, \, \mathsf{charpol}[, \, B, \, \mathsf{tap}]) \qquad \qquad (\mathsf{function}) \\ \triangleright \  \, \mathsf{LFSR}(p, \, m, \, n[, \, \mathsf{tap}]) \qquad \qquad (\mathsf{function})
```

 $\pmb{Returns:}$ An empty LFSR with components init, state , numsteps and basis

Different ways to create an LFSR oblject, main difference is in creation of the underlying finite field.

Inputs:

- F the underlying finite field (either an extension field or a prime field)
- B basis of F over its prime subfield
- charpol LFSR dfining polynomial
- fieldpol defifning polynomial of the extension field (must be irreducible)
- p characteeristic
- m degree of extension (degree of fieldpol)
- n length of LFSR (degree of charpoly)
- tap optional parameter: the output tap (must be a positive integer or a list of positive integers) and will be changed to the default S_0 if the specified integer is out of LFSR range.

Compoents:

- init FFE vector of length n=deg(charpol), storing the initial state of the LFSR, with indeces from n-1, ..., 0
- state FFE vector of length n=deg(charpol), storing the current state of the LFSR, with indeces from n-1, ..., 0
- numsteps the number of steps performed thus far (initialized to -1 when created, set to 0 when loaded using LoadFSR (2.1.5) and incremented by 1 with each step (using StepFSR (2.1.6)))
- basis basis of F over its prime subfield (if no basis is given this field is set to canonical basis of F over its prime subfield)

Attributes FieldPoly (2.1.2), UnderlyingFied (??), CharPoly, FeedbackVec (2.1.2), Length (2.1.3) and OutputTap (2.1.2) and the property IsLinearFeedback are set during the construction of anLFSR.

If there is something wrong with the arguments (e.g. attempting to create an extension field using a reducible poynomial), an error message appears and the function returns fail.

Example below shows how to create an empty LFSR over F_{24} created as extension of F_2 , called *test*, firstly without a specified basis, and then with basis B:

```
gap> K := GF(2);; x := X(K, "x");;
gap> f := x^4 + x^3 + 1;; F := FieldExtension(K, f);;
gap> y := X(F, "y");; 1 := y^4+ y+ Z(2^4);;
gap> test := LFSR(K, f, 1);
< empty LFSR given by CharPoly = y^4+y+Z(2^4)>
gap> WhichBasis(test);
CanonicalBasis( GF(2^4) )
gap> B := Basis(F, Conjugates(Z(2^4)^3));;
gap> test := LFSR(K, f, 1, B);
< empty LFSR given by CharPoly = y^4+y+Z(2^4)>
gap> WhichBasis(test);
Basis( GF(2^4), [ Z(2^4)^3, Z(2^4)^6, Z(2^4)^12, Z(2^4)^9 ] )
```

2.2.2 IsLinearFeedback

If we were to represent the *lsfr* with a multivariate polynomial, DegreeOfPolynomial would return 1 - the feedback polynomial is linear and *lsLinearFeedback* is set to *true*. (ie. only linear terms are present: monomials with only one variable)

Filter IsLFSR is defined as and-filter of IsFSR and IsLinearFeedback.

2.2.3 CharPoly

```
▷ CharPoly(1fsr) (attribute)
```

Attribute holding the characteristic polynomial (the feedback polynomial).

2.2.4 IsPeriodic

Properties, attributes and methods concerning the periodicity of the output sequence(s), generated by the *lsfr*.

Properties:

- IsPeriodic: true if constant term of CharPoly != 0 (8.11 lidl, niederreiter)
- IsUltPeriodic: true if IsLFSR is true (8.7 lidl, niederreiter)
- IsMaxSeqLFSR: true if CharPoly is primitive (ref???)

Attributes:

• Period: holds the period of the UNKNOWNEntity(LFSR)

Methods to compute the period:

- PeriodIrreducible:
- PeriodReducible:

2.3 NLFSR specific funcionality

2.3.1 ChooseField

 \triangleright ChooseField(F) (function)

Workaround for the NLFSR object definition: we need to fix the chosen underlying finite field and prepare indeterminates in the chosen field. The indeterminates will be used for the multivariable polynomial, which will define the NLFSR feedback. Current threshold is set by global MaxNLFSRLen = 100.

2.3.2 NLFSR

```
 > NLFSR(K, clist, mlist, len[, tap])  (function)  > NLFSR(K, fieldpol, clist, mlist, len[, tap])  (function)
```

Returns: An empty NLFSR with components init, state and numsteps

Different ways to create an NLFSR oblject, main difference is in creation of the underlying finite field.

NOTE: before creating the NLFSR, we must always create the indeterminates to be used for the feedback using ChooseField function call!!! please see example below

Inputs:

- F the underlying finite field (either an extension field or a prime field)
- fieldpol defifning polynomial of the extension field (must be irreducible)
- clist list of coefficients for the monomials in mlist
- mlist list of monomials
- 1en length of NLFSR

• tap - optional parameter: the output tap (must be a positive integer or a list of positive integers) and will be changed to the default S_0 if the specified integer is out of NLFSRrange.

NOTE: clist and mlist must be of same length, all elements in clist must belong to the underlying field. Monomials in mlist must not include any indeterminates that are out of range specified by len: stages of NLFSR are represented by indeterminants and the feedback is not allowed to use a stage that doesnt exist. A second constraint on mlist requires that it must contain at least one monomial of degree > 1, otherwise we must create an LFSR.

Compoents:

- init FFE vector of length n=deg(charpol), storing the initial state of the NLFSR, with indeces from n-1, ..., 0
- state FFE vector of length n=deg(charpol), storing the current state of the NLFSR, with indices from n-1, ..., 0
- numsteps the number of steps performed thus far (initialized to -1 when created, set to 0 when loaded using LoadFSR (2.1.5) and incremented by 1 with each step (using StepFSR (2.1.6)))

Attributes FieldPoly (2.1.2), UnderlyingFied (??), MultivarPoly, FeedbackVec (2.1.2), IndetList (2.3.4), Length (2.1.3) and OutputTap (2.1.2) and the property IsNonLinearFeedback are set during the construction of an NLFSR.

If there is something wrong with the arguments (e.g. attempting to create an extension field using a reducible poynomial), an error message appears and the function returns fail.

```
gap> F := GF(2);; clist := [One(F), One(F)];; mlist := [x_0*x_1, x_2];;
Error, Variable: 'x_0' must have a value
not in any function at line 2 of *stdin*
gap> test := NLFSR(F, clist, mlist, 3);
Error, Variable: 'mlist' must have a value
not in any function at line 3 of *stdin*
gap> ChooseField(F);
You can now create an NLFSR with up to 100 stages
with up to 100 nonzero terms
gap> mlist := [x_0*x_1, x_2];;
gap> test := NLFSR(F, clist, mlist, 3);
< empty NLFSR of length 3,
given by MultivarPoly = x_0*x_1+x_2>
```

2.3.3 IsNonLinearFeedback

```
▷ IsNonLinearFeedback(nlfsr) (property)
▷ IsNLFSR(nlfsr) (filter)
```

For the multivariate polynomial given by clist and mlist, DegreeOfPolynomial greter than 1 sets IsNonLinearFeedback to true. otherwise it prints out a warning that you need to use the LFSR constructor instead.

Filter IsNLFSR is defined as and-filter of IsFSR and IsNonLinearFeedback.

NOTE: at the same time IsLinearFeedback is set to *false* (for coding purposes).

2.3.4 MultivarPoly

```
▷ MultivarPoly(nlfsr) (attribute)
▷ IndetList(nlfsr) (attribute)
```

MultivarPoly holds the multivariate function defining the feedback of the NLFSR. IndetList holds all the indeterminates that are present in MultivarPoly and FeedbackVec holds only the nonzero coefficients (as opposed to the LFSR, where this field holds coefficients for all stages of the FSR). The feedback element is computed from MultivarPoly, IndetList and state, and not from FeedbackVec.

```
gap> MultivarPoly(test); IndetList(test);
x_0*x_1+x_2
[ 0, 1, 2 ]
```

Chapter 3

Output formatting functions and TEX drawing functions

3.1 View/Display/Print/PrintAll

3.1.1 ViewObj

Different detail on nsr created either by LFSR (2.2.1) or NLFSR (2.3.2):

- Display/View:
 - for LFSR: show the CharPoly and wheter or not the fsr is empty
 - for NLFSR: show the MultivarPoly and wheter or not the fsr is empty
- Print: same as Display/View if fsr is empty, otherwise it also shows the values of components state, numsteps and basis
- PrintAll: same as Print if fsr is empty, otherwise it also shows the values of all four components init, state, numsteps and basis with additional information about the underlying field and the tap positions

Both Print and PrintAll can be used with optional parameter *b* for desiered output format: when true the output will used the currently chosen basis.

Examples below show different outputs for an LFSR:

```
gap> K := GF(2);; x := X(K, "x");;
gap> f := x^4 + x^3 + 1;; F := FieldExtension(K, f);;
gap> y := X(F, "y");; l := y^4+ y+ Z(2^4);;
gap> test := LFSR(K, f, l);;
gap> Print(test);
empty LFSR over GF(2^4) given by CharPoly = y^4+y+Z(2^4)
gap> ist := [ 0*Z(2), Z(2^4), Z(2^2), Z(2)^0 ];; LoadFSR(test, ist);
```

```
Z(2)^0
gap> Print(test);
LFSR over GF(2^4) given by CharPoly = y^4+y+Z(2^4)
with basis = [ Z(2)^0, Z(2^4)^7, Z(2^4)^14, Z(2^4)^6 ]
with current state = [0*Z(2), Z(2^4), Z(2^2), Z(2)^0]
after 0 steps
gap> RunFSR(test,5);
[ Z(2^2), Z(2^4), 0*Z(2), Z(2^4)^2, Z(2^4)^{11} ]
gap> Print(test);
LFSR over GF(2^4) given by CharPoly = y^4+y+Z(2^4)
with basis = [ Z(2)^0, Z(2^4)^7, Z(2^4)^14, Z(2^4)^6 ]
with current state = [Z(2^2), Z(2^4)^2, Z(2^4)^2, Z(2^4)^1]
after 5 steps
gap> PrintAll(test);
LFSR over GF(2^4) given by CharPoly = y^4+y+Z(2^4)
with basis = [Z(2)^0, Z(2^4)^7, Z(2^4)^14, Z(2^4)^6]
with feedback coeff = [0*Z(2), 0*Z(2), Z(2)^0, Z(2^4)]
with initial state = [0*Z(2), Z(2^4), Z(2^2), Z(2)^0]
with current state = [Z(2^2), Z(2^4)^2, Z(2^4)^2, Z(2^4)^{11}]
after 5 steps
with output from stage S_0
gap> PrintAll(test, true);
LFSR over GF(2^4) defined by FieldPoly=x^4+x^3+Z(2)^0 given by CharPoly = y^4
+y+Z(2^4)
with basis = [Z(2)^0, Z(2^4)^7, Z(2^4)^14, Z(2^4)^6]
with feedback coeff =[ [ 0, 0, 0, 0 ], [ 0, 0, 0, 0 ], [ 1, 0, 0, 0 ],
  [ 0, 1, 1, 0 ] ]
with initial state =[[0,0,0,0],[0,1,1,0],[1,1,0,1],
  [1,0,0,0]]
with current state =[[1, 1, 0, 1], [1, 0, 1, 1], [1, 0, 1, 1],
  [ 0, 1, 1, 1 ] ]
after 5 steps
with output from stage S_0
```

Examples below show different outputs for an NLFSR:

```
Example
gap> F := GF(2);; ChooseField(F);
You can now create an NLFSR with up to 100 stages
with up to 100 nonzero terms
gap> clist := [One(F), One(F)];; mlist := [x_0*x_1, x_2];;
gap> test := NLFSR(F, clist, mlist, 3);
< empty NLFSR of length 3 over GF(2),</pre>
  given by MultivarPoly = x_0*x_1+x_2>
gap> Display(test);
< empty NLFSR of length 3 over GF(2),</pre>
given by MultivarPoly = x_0*x_1+x_2>
gap> PrintAll(test,true);
empty NLFSR of length 3 over GF(2),
 given by MultivarPoly = x_0*x_1+x_2
with basis = [Z(2)^0]
with initial state =[[0],[0],[0]]
```

```
with current state =[[0],[0],[0]]
after initialization
with output from stage S_0
```

3.2 Writing to *.txt or *.tex

3.2.1 WriteAllFSR

```
▷ WriteAllFSR(output, fsr)
```

(function)

Equivalent to PrintAll, but it writes to an output stream. NOTE: The basis switch must be present and if *true*, the currently set basis of the *fsr* is used.

3.2.2 WriteSequenceFSR

WriteSequenceFSR writes the sequence generated by some version of RunFSR(lfsr) to *.txt file, with addition of separating sequences from different taps and writing them in currently set basis of the fsr.

WriteTBSequenceFSR is a version of WriteSequenceFSR intended for testbenching purposes: the generated sequence is written to *.txt file, with sequences from different taps separated into *columns* separated by "\t". Again the currently set basis of the *fsr* is used. The order of columns is determined by OutputTap(*fsr*).

WriteTEXSequenceByGenerator is a *.tex version of WriteSequenceFSR but allows to write the sequence elements as powers of a chosen generator gen. Generator gen is used to get the exponents of the elements, and the elements themselfs are printed as $\star \$ where strGen must be a string representing a greek letter in *.tex, for example strGen "alpha" will give α .

3.2.3 WriteRunFSR

```
▷ WriteRunFSR(output, lfsr, ist, numsteps) (function)
▷ WriteNonlinRunFSR(output, lfsr, ist, numsteps) (function)
```

WriteRunFSR is an output to *.txt version of RunFSR(fsr, ist, num), with addition of separating sequences from different taps and writing them in currently set basis of the fsr. Before the run begins and after loading, the WriteAllFSR(output, x, true) is called to record the FSR being used. When the run is finished, WriteSequenceFSR is called to record the output sequence in compact version. WriteRunFSR returns the sequence generated by this run.

WriteNonlinRunFSR is an output to *.txt version of RunFSR(fsr, ist, elmvec). WriteNonlinRunFSR returns a sequence generated by this run, however, the length of returned sequence is Length(elmvec)+1, because the first element of the output sequence is the element that was loaded with ist.

3.2.4 WriteTEXRunFSR

```
▷ WriteTEXRunFSR(output, fsr, ist, numsteps) (function)
▷ WriteTEXNonlinRunFSR(output, fsr, ist, numsteps) (function)
▷ WriteTEXRunFSRByGenerator(output, fsr, ist, numsteps, strGen, gen) (function)
```

WriteTEXRunFSR is an output to *.tex version of RunFSR(fsr, ist, num), which writes a table that can be included directly (except for the label). Rows of the table represent the steps of the FSR and include the state of the FSR and the elements from stages specified by outputTap, that is the sequence outputs at this step. The table entries (FFEs) are printed using currently set basis of the fsr. When the run is finished, WriteTEXSequenceByGenerator is called to record the output sequence in compact version. WriteTEXRunFSR returns the sequence generated by this run.

WriteTEXNonlinRunFSR TO DO

WriteTEXRunFSRByGenerator is a *.tex version of WriteTEXRunFSR but instead of using the currently set basis of the fsr, the table entries are printed as powers of a chosen generator gen. Generator gen is used to get the exponents of the elements, and the elements themselfs are printed as σ^{en} as σ^{en} must be a string representing a greek letter in *.tex, for example σ^{en} alpha" will give σ .

3.2.5 WriteTEXElementTableByGenerator

WriteTEXElementTableByGenerator provides the context information for WriteTEXSequenceByGenerator and WriteTEXRunFSRByGenerator. Its output is a *.tex file with a table containing the elements of F represented in basis B and their representation as powers of a chosen generator gen, printed as \$\strGen^{exponent}\$, where by the greek letter passed to the function as a string strGen. There is an extra table column containing the order of each element.

The output file contains additional information: defining polynomial of F, basis elements of B as powers of generator gen, and information whether or not gen is a root of the defining polynomial.

3.3 TEX drawing functions

Chapter 4

misc - helper functions

4.1 Output formatting functions

There are two types of functions: ones that return the input in a human friendly version (as strings or list of strings), and ones that write the human friendly version of the input into a file (txt or tex)

4.1.1 IntFFExt

IntFFExt takes the *ffe* and writes it as an integer of the prime field if *ffe* is an element of the prime field (same as Int(ffe)), or writes it as a vector of integers from the prime subfield if *ffe* is an element of an extension field, using the given basis *B* or canonical basis representation of *ffe* if no basis is provided.

IntVecFFExt takes the vector *vec* of FFEs and writes it in a human friendly version: as a vector of integers from the prime field if all components of *vec* belong to a prime field, or as a vector of vectors of integers from the prime subfield, if the components belong to an extension field, using the given basis *B* or canonical basis representation of *ffe*, if no basis is provided. (note: all components are treated as elements of the largest field).

IntMatFFExt takes a matrix M and returns its human friendly version: a matrix of vectors of integers from the prime field if all components of M belong to a prime field, or a vector of row vectors, whose elements are vectors of integers from the prime subfield, if the components belong to an extension field, using the given basis B or canonical basis representation of components of M.

NOTE: the non-basis versions return a representation in the smallest field that contains the element. For representation in a specific field, use the basis version with desired basis.

4.1.2 VecToString

```
    VecToString([B, ]vec) (method)
```

Writes a FFE verctor or matrix as string or list of strings using the given basis *B* or canonical basis representation of *ffe* if no basis is provided. This mathod calls methods IntFFExt, IntVecFFExt

and IntMatFFExt from section LINK. The list of strings is more practically useful: we wish to have the components as srings, therefore the human friendly version of a matrix is not an actual string.

NOTE: the non-basis versions return a representation in the cononical basis of the smallest field that contains the element. For representation in a specific field, use the basis version with desired basis.

4.1.3 WriteVector (for a FFE and given basis)

```
    ∀riteVector(output, B, vec)
```

(function)

Writes the human friendly version of vector *vec* represented in basis *B*, to the output file *output*. Also works if *vec* is an integer or FFE. can be used to write the sequence produced by the FSR to a file, make sure that the sequence does not contain any subsequences (ie if merging two runs of the FSR, must use Append(seq,seq1), if adding new step to a run must use Add(seq, elm1))

NOTE: the basis MUST be provided.

Also works for writing matrices, but writes them as a row vector, not as a rectangle.

4.1.4 WriteMatrix (for a matrix of FFE and given basis)

```
▷ WriteMatrix(output, B, M)
```

(function)

Writes the human friendly version of matrix M represented in basis B to the output file output nicely formatted (rectangular, each row in a new line).

NOTE: the basis MUST be provided.

4.1.5 WriteMatrixTEX

▷ WriteMatrixTEX(output, M)

(function)

Writes the TEX code for matrix M over a prime field to the output file output.

NOTE: Only works for matrices over a prime field !!!

4.2 misc - helper functions

4.2.1 MonomialsOverField (for an NLFSR)

▷ MonomialsOverField(F, poly)

(method)

MonomialsOverField reduces takes a monomial or a list of monomials, and reduces all the exponents modulo (Size(F)-1) for all extension fields and prime fields except for F=(F)₂. For (F)₂ all the exponents are set to 1.

4.2.2 DegreeOfPolynomial (DegreeOfPolynomial)

▷ DegreeOfPolynomial(F, poly)

(method)

DegreeOfPolynomial as follows for both monomial of form $p = \prod x_i^{e_i}$ and polynomial of form $P = \sum c_j \cdot j$ where $p_j = \prod_i x_i^{e_i}$ DegreeOfPolynomial for a monomial: $= \sum e_i$, where i runs through all indeterminates present in this monomial

DegreeOfPolynomial for a polynomial:= $\max(DegreeOfPolynomial(p_j))$, where max runs through all monomials p_j present in this polynomial so an actual extra function called DegreeOf-Monomial is not needed

4.2.3 GeneratorOfUnderlyingField

▷ GeneratorOfUnderlyingField(F)

(method)

GeneratorOfUnderlyingField returns the first element \ni : order(x) = Size(F) - 1

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