

Hierarchical models

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Grouped data

- ▶ Groups $j = 1, \dots, N$, and observations $Y = \{y_{ij}\}$, $i = 1, \dots, M$
- ▶ E.g. N subjects with M trials per subject
- ▶ (Number of observations need not be equal for all groups)
- ▶ Group parameters of interest θ_j , $y_{ij} \sim p(y_{ij}|\theta_j)$

Observations x Groups

$$\begin{bmatrix} y_{11} & y_{12} & y_{13} & \dots & y_{1N} \\ y_{21} & y_{22} & y_{23} & \dots & y_{2N} \\ \dots & \dots & \dots & \dots & \dots \\ y_{M1} & y_{M2} & y_{M3} & \dots & y_{MN} \end{bmatrix}$$

Complete pooling

Consider all θ_j equal

- ▶ $y_{ij} \sim p(y_{ij}|\theta)$
- ▶ Robust: uses all data to estimate θ
- ▶ Cannot look at inter-group differences
- ▶ Does not consider within vs between sources of variation

$$\theta = \theta_1 = \dots = \theta_N$$

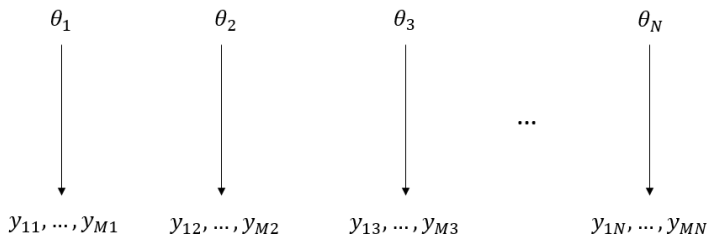


$y_{11}, \dots, y_{M1}, y_{12}, \dots, y_{M2}, y_{13}, \dots, y_{M3}, \dots, y_{1N}, \dots, y_{MN}$

No pooling

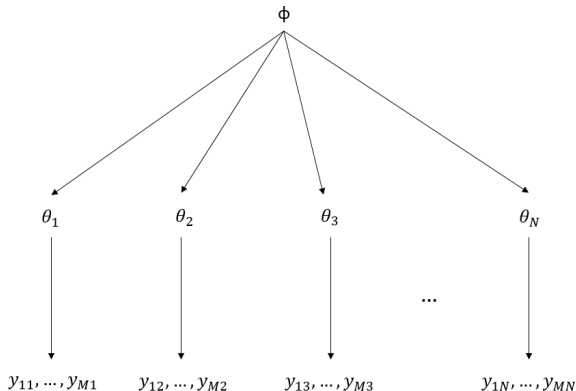
Model each group independently

- ▶ One θ_j per group
- ▶ $y_{ij} \sim p(y_{ij}|\theta_j)$
- ▶ Uses only a subset of the data to estimate θ_j
- ▶ Does not exploit similarity between θ_j



Hierarchical model

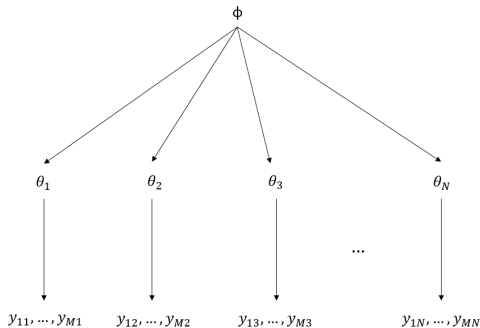
- ▶ Some parameters in the model may be related through a common distribution, $\theta_j \sim p(\theta_j|\phi)$
- ▶ $p(\theta_j|\phi)$ is governed by its own (hyper)parameters ϕ (population parameters)



Hierarchical model

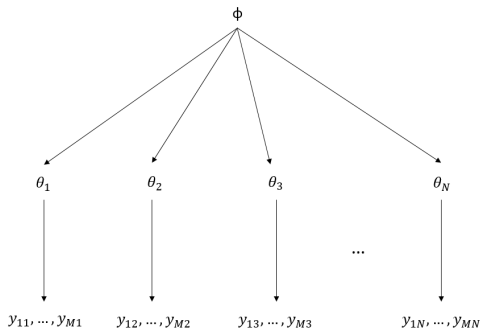
- ▶ We want to estimate θ_j (local/group parameters) and ϕ (global/population parameters)
- ▶ Joint distribution: $p(Y, \theta_1, \dots, \theta_N, \phi)$
- ▶ Inference: Bayes rule

$$p(\theta_1, \dots, \theta_N, \phi | Y) = \frac{p(\theta_1, \dots, \theta_N, \phi) p(Y | \theta_1, \dots, \theta_N, \phi)}{p(Y)}$$



Exchangeability

- ▶ θ_j exchangeable if we have no information to distinguish between them (e.g. no ordering or grouping)
- ▶ *Ignorance implies exchangeability*
- ▶ $(\theta_1, \dots, \theta_N)$ are exchangeable if the prior $p(\theta_1, \dots, \theta_N, \phi)$ is invariant to permutation of the indices (i.e. symmetric wrt θ_j)



Hierarchical model distributions

$$p(\theta_1, \dots, \theta_N, \phi | Y) = \frac{p(\theta_1, \dots, \theta_N, \phi) p(Y | \theta_1, \dots, \theta_N, \phi)}{p(Y)}$$

Assuming exchangeability, the simplest form for a hierarchical model (other possibilities exist):

- Prior:

$$p(\theta_1, \dots, \theta_N, \phi) = p(\phi) \prod_{j=1}^N p(\theta_j | \phi)$$

Need to specify a prior for ϕ (hyperprior)

θ_j are independent given ϕ

- Likelihood:

$$p(Y | \theta_1, \dots, \theta_N, \phi) = \prod_{j=1}^N p(y_{ij} | \theta_j) = \prod_{j=1}^N p(y_{ij} | \theta_j)$$

y_{ij} in each group j are independent given θ_j

Likelihood does not depend on ϕ given θ_j

Hierarchical model with normal likelihoods and group distributions

(Hierarchical structure only for means):

- ▶ Data y_{ij}
- ▶ Group-level parameters: $\theta_j = (\mu_j, \sigma)$, $i = 1, \dots, N$
- ▶ Hyperparameters: $\phi = (\mu_p, \sigma_p)$
- ▶ Likelihood: $p(y_{ij}|\theta_j) = \mathcal{N}(y_{ij}; \mu_j, \sigma^2)$ (*common* σ)
- ▶ Group distributions $p(\theta_j|\phi)$:
 $p(\mu_j|\phi) = \mathcal{N}(\mu_j; \mu_p, \sigma_p^2)$; $p(\sigma|\phi) = p(\sigma) \propto 1$
- ▶ Hyperprior distribution $p(\phi)$: $p(\mu_p) = \mathcal{N}(\mu_p; \mu_0, \sigma_0^2)$; $p(\sigma_p) \propto 1$
(μ_0 and σ_0 are fixed)

Example: Eight schools

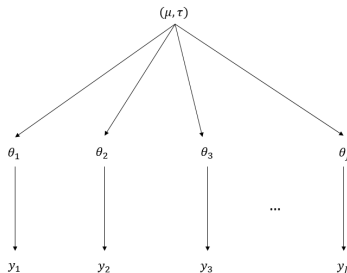
y_j, σ_j : mean and std of the effect of coaching on school performance in school j

$$\mu \sim \mathcal{N}(0, 5^2)$$

$$\tau \sim \text{Half - Cauchy}(0, 5)$$

$$\theta_j \sim \mathcal{N}(\mu, \tau^2)$$

$$y_j \sim \mathcal{N}(\theta_j, \sigma_j^2)$$



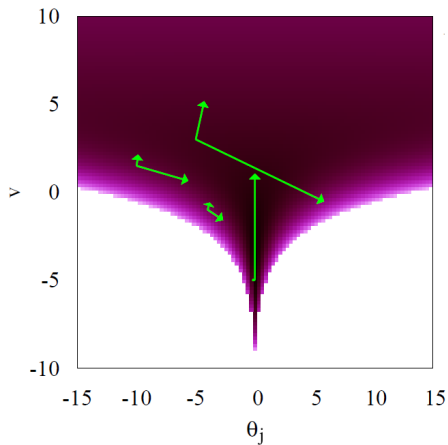
Example: Eight schools

```
data {  
  int<lower=0> J;  
  real y[J];  
  real<lower=0> sigma[J];  
}  
parameters {  
  real mu;  
  real<lower=0> tau;  
  real theta[J];  
}  
model {  
  mu ~ normal(0, 5);  
  tau ~ cauchy(0, 5);  
  theta ~ normal(mu, tau);  
  y ~ normal(theta, sigma);  
}
```

Funnel geometry

$$\theta_j \sim \mathcal{N}(\mu, \tau^2)$$

$$v = \log(\tau^2)$$



Example: Eight schools, non-centered parameterization (aka Matt trick)

$$\mu \sim \mathcal{N}(0, 5^2)$$

$$\tau \sim \text{Half - Cauchy}(0, 5)$$

$$\tilde{\theta}_j \sim \mathcal{N}(0, 1)$$

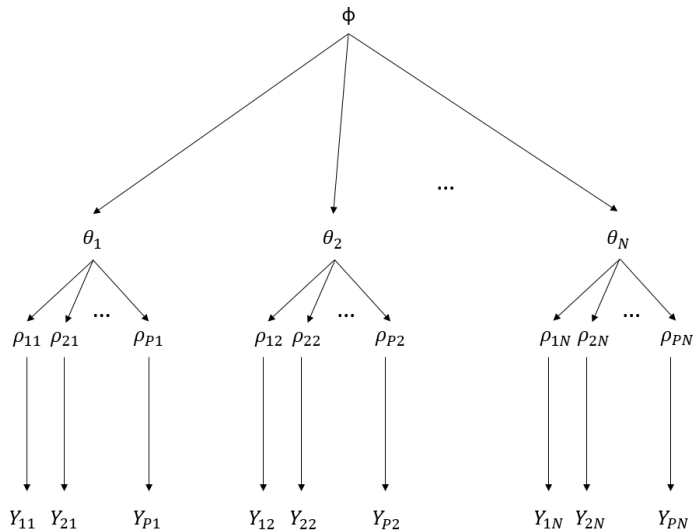
$$\theta_j = \mu + \tau \tilde{\theta}_j$$

$$y_j \sim \mathcal{N}(\theta_j, \sigma^2)$$

Example: Eight schools, non-centered parameterization

```
data {  
  int<lower=0> J;  
  real y[J];  
  real<lower=0> sigma[J];  
}  
parameters {  
  real mu;  
  real<lower=0> tau;  
  real theta_tilde[J];  
}  
transformed parameters {  
  real theta[J];  
  for (j in 1:J)  
    theta[j] = mu + tau * theta_tilde[j];  
}  
model {  
  mu ~ normal(0, 5);  
  tau ~ cauchy(0, 5);  
  theta_tilde ~ normal(0, 1);  
  y ~ normal(theta, sigma);  
}
```

Multiple levels



Comments

- ▶ Hierarchical models tend to *shrink* group parameters (compared to no pooling): tension between data and group mean
- ▶ Hierarchical structure most useful when few observations per group (no pooling tends to overfit)
- ▶ Hierarchical structure is prior information
- ▶ Sampling the posterior is difficult (Hamiltonian Monte Carlo...)

