Computational models of cognitive tasks

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Generative model

$$p(Y, \theta) = p(\theta)p(Y|\theta)$$

- Y observed variables (data)
 - Choices
 - Response times
- \blacktriangleright θ hidden, latent variables of interest (parameters)
- Designed by the analyst based on their assumptions

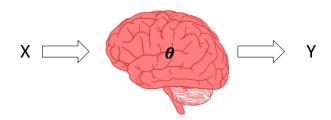


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Generative model

In our case:

▶ X predictors (e. g. information from stimuli) $\alpha = f(\theta, X)$ (function of the parameters and the predictors) $p(Y|\theta) = distribution(\alpha)$



Warnings

- Parameter names may change (literature, code)
- Some implementation decisions are technical (convenient to allow estimation of the model) and not theoretical

Computational models

- Delay discounting
- ► Two-alternative forced choice (Drift diffusion model)
- ▶ Two-armed bandit
- Probabilistic reversal learning

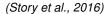
Delay discounting

- Preference for immediate over delayed rewards
- Smaller-but-sooner over larger-but-later
- Aka temporal discounting or inter-temporal choice
- ► (Relatively) stable trait, large inter-individual variability
- Related to impulsivity and self-control. Impulsive choice (impatience) vs impulsive action

Relevance

Relevant to psychiatry and behavioural economics

- Addiction
- ADHD
- Pathological gambling
- ► Tobacco, drug and alcohol use
- Risky sexual practices
- Large credit card debt
- ► Also: depression, mania, anorexia nervosa, schizophrenia...





Reasons for discounting

- ▶ Uncertainty in the delivery of future rewards
- Volatility of the environment
- Opportunity cost

Questionnaire

Do you prefer?

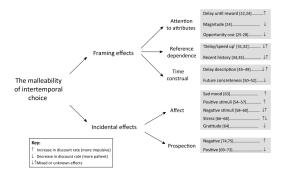
- 1. 1000 SEK now OR 2000 SEK in a month?
- 2. 1000 SEK now OR 1500 SEK in a month?
- 3. 1000 SEK now OR 2000 SEK in a year?
- 4. 10000 SEK in a week OR 20000 SEK in a year?

...

n. 10000 SEK now OR 20000 SEK in a year?

Limitations and manipulation

- Questionnaire decisions can be different from those faced in daily life
- ▶ Decisions are context-dependent
- Choices can be manipulated



Subjective value

$$V(R) = f(d, R)$$

f(d): decreasing function of the delay until R is received, e.g.:

$$V(1000 \ SEK) = f(1 \ month, 1000 \ SEK) = 900 \ SEK$$

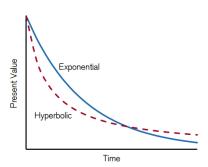


Exponential discounting

- Value declines exponentially with delay
- ▶ *k* is the *discount rate* (higher *k* = more impatient)
- Dynamic consistency:

Discount equally with shorter and longer delays 20 SEK in 1 week > 25 SEK in 2 weeks, 20 SEK in 9 weeks > 25 SEK in 10 weeks

$$V(R) = Re^{-kd}$$



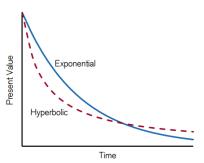
Hyperbolic discounting

- Value declines hyperbolically with delay
- Dynamic inconsistency:

Discount more steeply with shorter delays and more shallowly with longer delays

20 SEK in 1 week > 25 SEK in 2 weeks, but 25 SEK in 10 weeks > 20 SEK in 9 weeks

$$V(R) = \frac{R}{1 + kd}$$



Model

For trial t:

- ▶ Value V_{St} , reward R_{St} and delay d_{St} of sooner option
- ▶ Value V_{Lt} , reward R_{Lt} and delay d_{Lt} of later option

Value model:

$$V_{St} = \frac{R_{St}}{1 + kd_{St}} \qquad V_{Lt} = \frac{R_{Lt}}{1 + kd_{Lt}}$$



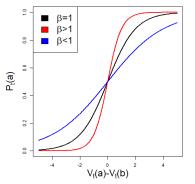
Action selection

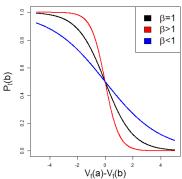
Softmax function

 $P_t(c)$: probability of choice $c \in a, b$

$$P_{t}(a) = \frac{e^{\beta V_{t}(a)}}{e^{\beta V_{t}(a)} + e^{\beta V_{t}(b)}} = \frac{1}{1 + e^{-\beta(V_{t}(a) - V_{t}(b))}}$$

$$P_{t}(b) = \frac{e^{\beta V_{t}(b)}}{e^{\beta V_{t}(a)} + e^{\beta V_{t}(b)}}$$





Model

Value model:

$$V_{St} = \frac{R_{St}}{1 + kd_t} \qquad V_{Lt} = \frac{R_{Lt}}{1 + kd_t}$$

Choice model:

$$c_t \sim bernoulli(softmax(\beta(V_{Lt} - V_{St})))$$



Built-in functions

```
Constants: e(), pi(),...
min(x), max(x)
exp(x), log(x), pow(x , y)
cos(x), sin(x), tan(x)
logit(y), inv_logit(x)
inv_Phi(y), Phi(x), Phi_approx(x) //probit
```

Choice model implementation

Choice model:

```
c_t \sim bernoulli(softmax(\beta(V_{Lt} - V_{St}))) model { y \sim bernoulli(inv\_logit(beta * (V\_lt - V\_st))); \\ \dots } \\ model { <math display="block">y \sim bernoulli\_logit(beta * (V\_lt - V\_st)); \\ \dots } \\
```

Data and parameters

Data

- ► Choices c_t
- ▶ Rewards R_{St}, R_{Lt}
- ▶ Delays d_{St}, d_{Lt}

Parameters

- Discount rate k
- ▶ Inverse temperature β
- ▶ (Expected values V_{St} , V_{Lt})

Drift diffusion model (DDM)

- Response-time data (relationship between choice accuracy and response time)
- Two-alternative forced choice tasks (e.g. left / right)
- Comparison process is not deterministic, choices not always optimal
- Typically perceptual tasks, but also value-based decision making
- ► Intuitive and biologically plausible
- Sequential sampling models (SSM)
- No error feedback



Examples

Perceptual discrimination

Random dot motion perceptual discrimination task

Numerosity

- Between 31 and 70 asterisks placed in random positions in a 10 x 10 array
- ► Choices: Small (<=50); large (>50)
- 30 blocks x 40 trials

Recognition memory

- 26 study-test blocks
- Study: 16 words
- Test: 16 studied + 16 new words



Examples

Emotional flanker task

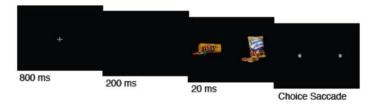
- ► Target affective words (positive/negative) with flanker words above and below (congruent, incongruent, neutral)
- Subjects judged if the target word was positively or negatively valenced
- ▶ 1 practice block x 20 trials + 4 blocks x 30 trials
- ► Total set of ffective words: 5 positive, 5 negative, 4 neutral



Examples

Food choices

- Choices between pairs of appetitive snack foods
- They had to eat the food that they chose in a randomly selected trial
- Items previously rated by the subjects
- ► High- and low-pressure conditions

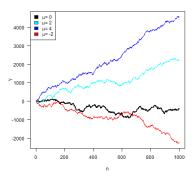


Model assumptions

- ► (Noisy) evidence about alternatives is accumulated over time
- ► Evidence = information from the environment or internal representations
- A choice is made when enough evidence has been gathered
- Non-decision time: not all response time is spent in accumulating evidence
- One of the responses may be more likely even before any evidence is observed
- Parameters are constant throughout the task

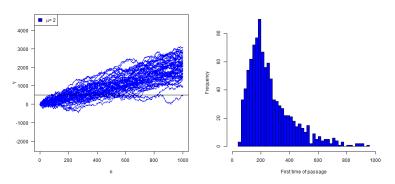
Evidence accumulation as a Wiener process

- ▶ $X_n \sim \mathcal{N}(\mu, \sigma^2)$, evidence at time step n
- ▶ $Y_0 = 0$; $Y_n = \sum_{k=1}^n X_k$, n > 1, total accumulated evidence at time step n



Evidence accumulation as a Wiener process

First passage time of the accumulation process



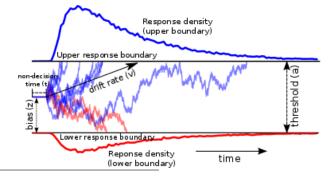
First passage time density function

$$p \sim W(a, v, z, t)$$

Choice model

Parameters

- Threshold a: Amount of evidence needed (response caution / speed-accuracy trade-off)
- Drift rate v: Rate of evidence accumulation (speed or efficiency of information processing / ability / task difficulty)
- ▶ Bias z: Information already present in favour of one of the choices (0 < z < 1, fraction of a)</p>
- ▶ Non-decision time *t*: perception + motor execution + ...



Model predictions

DDM provides a simultaneous account of response time and accuracy

Noise can push the process toward the opposite direction, leading to an erroneous choice

Difficult decisions (small drift rate)

- Low accuracy
- Long response times

Easy decisions (large drift)

- High accuracy
- Short response times

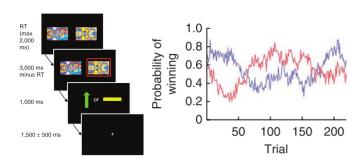
Effect of parameters

Model parameters affect differently RT and accuracy

- Increasing non-decision time increases RT
- Increasing drift rate decreases RT and increases accuracy
- Increasing the threshold increases both RT and accuracy

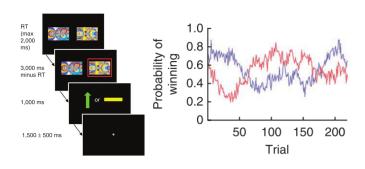
Two-armed bandit task

- Subjects choose between two options (bandits) on each trial, and receive a reward or punishment after the choice
- Subjects are instructed to maximize rewards
- ► The probability of obtaining a reward associated with each option varies on a trial-by-trial basis according to e.g. a Gaussian random walk



Two-armed bandit task

- ► Assumption: to solve the task, subjects must keep an internal representation of the value of the stimuli, *V*_t
- ▶ We are interested in the learning rate α (how much subjects update their value representation based on rewards/punishments)
- Model can be extended in many ways





Definitions

- ▶ c_t : choice (chosen stimulus) on trial $t, c_t \in \{a, b\}$
- ▶ r_t : reward on trial t, $r_t \in \{-1, 1\}$
- ▶ $V_t(c)$: value of choice $c \in \{a, b\}$ on trial t

Value model

Reward prediction error, Rescorla-Wagner rule:

$$\delta_t = r_t - V_t(c_t)$$

Value update (only chosen option is updated):

$$V_{t+1}(c_t) = V_t(c_t) + \alpha \delta_t$$

Choice model

Softmax function

 $P_t(c)$: probability of choice $c \in a, b$

Data and parameters

Data

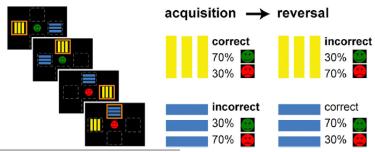
- ► Choices c_t
- ▶ Rewards *r*_t

Parameters

- ightharpoonup Learning rate α
- ▶ Inverse temperature β
- ► (Expected values *V_t*)

Probabilistic reversal learning task

- ► Correct choices lead to monetary gains with probability p and losses with probability q = 1 p (e. g. p = 0.7 and q = 0.3)
- Incorrect choices lead to monetary gains with probability q and losses with probability p
- Subjects instructed to learn by trial and error to maximize reward
- Reward contingencies reverse at fixed points (e.g. 40 trials acquisition + 40 trials reversal) or after a number of consecutive correct choices
- Stimuli presented randomly at different spatial locations





Reversal learning

 Main interest is in adaptation to changes in stimulus-reward contingencies to study perseverative behaviour (Parkinson's disease, association with neurotransmitters)

Reward-punishment model

- Hypothesis: perseverative behaviour caused by reduced learning from punishment
- ▶ Separate learning rates for punishment α_p and reward α_r

Reward prediction error:

$$\delta_t = r_t - V_t(c_t)$$

Value update (only chosen option is updated): If $r_t = 0$ (punished)

$$V_{t+1}(c_t) = V_t(c_t) + \alpha_p \delta_t$$

If $r_t = 1$ (rewarded)

$$V_{t+1}(c_t) = V_t(c_t) + \alpha_r \delta_t$$

Action selection: softmax function

(den Ouden et al., 2013)



Data and parameters

Data

- ► Choices c_t
- Rewards r_t

Parameters

- ▶ Learning rates α_r , α_p
- ▶ Inverse temperature β
- ► (Expected values *V_t*)

Experience-weighted attraction model

Hypothesis: perseveration on reversal is produced by an increasing reluctance to update the value of stimuli/choices every time they are chosen

Experience weight:

$$w_{t+1}(c_t) = w_t(c_t)\rho + 1$$

Value update:

$$V_{t+1}(c_t) = \frac{V_t(c_t)\varphi w_t(c_t) + r_t}{w_{t+1}(c_t)}$$

Action selection: softmax function

⁽Camerer et al., 1999)

Experience-weighted attraction model

Data

- ► Choices ct
- ▶ Rewards r_t

Parameters

- Learning rate ϕ (= 1 α)
- Experience decay factor ρ
- ▶ Inverse temperature β
- ► (Experience weights *w*_t)
- (Expected values $\overline{w_t}$)

Fitting models using hBayesDM

```
library(hBayesDM)
output = dd_hyperbolic("data/dd_exampleData.txt",
    niter=3000,
    nwarmup=1000,
    nchain=4,
    ncore=4)
```

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