Programming Assignment #5: CUDA

CS 3220 / CS 5220 Spring 2024 20 points due Tuesday, Apr. 30th, 11:59 pm

CUDA Programs

You'll write two CUDA programs. You may work with a partner, but graduate students must work individually.

Do not wait until the last minute! The use of the systems in the VACC is unpredictable, and there could be a surge in use at the end of the semester!

Or, if you have a system with an Nvidia GPU, you can download and install the CUDA development environment and do the work on your own system.

See specific instructions and examples in the CUDA: How-To presentation.

For this assignment, use cudaMalloc() and cudaMemcpy(). (Don't use unified memory.)

(1) Dot product

Do the dot-product example from class: compute the dot product of two float vectors of length N. Calculate the elapsed time for the GPU computation and for the same computation on the CPU. Calculate the GPU elapsed time two ways: not including the memory copies, and then including the memory copies. Set the values of the u and v vectors to random numbers in the range (0,1). (Use the Linux drand48() function.)

The first part of Lecture 4-E (CUDA Part Three) shows how to measure elapsed time on the GPU, and Lecture 4-F (CUDA How-To) shows how to measure time on the CPU.

Implement this function:

```
__global__
void dotp( float *u, float *v, float *partialSums, int n );
```

Use 256 threads per thread block and 256 blocks.

Accumulate each thread block's result in shared memory, and do parallel reduction on the shared memory, as described in the lectures.

Also, compute the relative error. The relative error between two scalar values x and y is |x-y|/|x|, with $x \neq 0$. (Compute the relative error on the CPU.) You should see a relative error of about 1×10^{-6} .

Do this for n = 256 * 256.

You do not need to use a grid-stride loop.

(2) Matrix-vector product

Implement a matrix-vector product function:

```
__global__
void MxV( float *M, float *x, float *y, int n);
```

This will do the calculation y = Mx, given the $n \times n$ matrix M and the $n \times 1$ vector x.

Each thread will do a dot product: thread i will do the dot product of row i of M with the vector x and put the result in y[i]. (This is a separate program altogether from the first program—you're not using your dot-product function here.)

Don't use a grid-stride loop: assume that n is less than #blocks \times #threads per block. Use 256 threads per thread block, and pick a value of n such as n = 5000.

This matrix-vector multiplication will require a huge number of floating-point operations: each entry in y will require n multiplications and n additions; so the total number of multiplications will be n^2 , and the total number additions will be n^2 .

Calculate the elapsed time for the GPU computation and for the same computation on the CPU. Calculate the GPU elapsed time two ways: not including the memory copies, and then including the memory copies. Set the entries of M and of x to uniformly distributed random numbers in the range (0,1).

```
Again, use cudaMalloc() and cudaMemcpy(). (Don't use unified memory.)
```

Write a function to do the matrix-vector product on the CPU, and compute the relative error between your two solutions. The relative error between two vectors u and v is given by

$$relerr = ||u - v|| / ||v||, \tag{1}$$

assuming v is not zero. $||\cdot||$ is the norm of a vector; the two-norm ||u|| is given by $||u|| = (\sum_{i=1}^{n} u_i^2)^{1/2}$.

When I run, I see about a 3x speedup with n = 5000, and my relative error is on the order of 1×10^{-8} . My GPU time is about 40 ms including the memory copying and less that 1 ms without the memory copies.

Graduate Students

Implement matrix multiplication: the kernel to multiply two $n \times n$ matrices is straightforward:

```
// computing C = A*B
float sum = 0.0;
int col = threadIdx.x + blockDim.x * blockIdx.x;
int row = threadIdx.y + blockDim.y * blockIdx.y;
int numEltsPerRow = n; // #elements in each row
if (col < n && row < n) {
   sum = 0.0;
   for (k = 0; k < n; k++)
        sum += A[row * numEltsPerRow + k] * B[k * numEltsPerRow + col];
   C[row * numEltsPerRow + col] = sum;
}</pre>
```

This kernel computes a single matrix element in the product.

And as long as $n \le 16$, all of this will fit in a single thread block:

```
dim3 dimGrid(1, 1);
dim3 dimBlock(n, n);
mxmKernel<<<dimGrid, dimBlock>>>( d_A, d_B, d_C, n);
```

Write a CUDA program to do this. Give A and B random values in the range (0,1). Use pitched memory allocation. Read the description of pitched memory allocation in the lecture notes carefully.

Compute the relative error between the CPU solution and the GPU solution. The relative error between two matrices A and B is given by

$$relerr = ||A - B|| / ||A||, \tag{2}$$

assuming ||A|| is not zero. The norm of a matrix is given by $||A|| = (\sum_{i=1}^{n} \sum_{j=1}^{n} (a_{i,j})^2)^{1/2}$. (This is the Frobenius norm.)

You'll do the error computation on the CPU, after you call the GPU kernel. You'll also have to do the matrix multiplication on the CPU, so that you have a result with which to compare the GPU result.

Then, do this with blocking. Pick a block size TILESIZE such that $n/TILESIZE \leq 16$, and use 256 threads per thread block. Try this with n=16,64,256; and make a table comparing CPU runtimes to GPU runtimes for each of these values of n. It's OK to omit the memory copying from the GPU timings. Undergraduates may also do this for a little extra credit.

Now, each thread block will do the multiplication for a submatrix of with dimensions $TILESIZE \times TILESIZE$. The thread at position i, j in the output array still needs to do the dot product of the full i^{th} row of X and the j^{th} column of Y.

So for example, if I have problem size n=256, then I must pick TILESIZE to be greater or equal to 256/16=16.

Here's how to set this up for blocking:

```
int threadsPerBlock = 256;
assert((n/TILESIZE)*(n/TILESIZE) <= threadsPerBlock);
dim3 dimGrid(n/TILESIZE, n/TILESIZE);
dim3 dimBlock(TILESIZE, TILESIZE);
printf("numBlocks = %d %d\n", dimGrid.x, dimGrid.y);
printf("threadsPerBlock = %d %d\n", dimBlock.x, dimBlock.y);
assert((N/TILESIZE)*(N/TILESIZE) <= threadsPerBlock);</pre>
```

Developing and Testing

Use either the computing resources in the VACC or use your own system. See the <u>CUDA How-To</u> slides for a description of how to compile and run programs on the VACC machine.

If you use your own system, then get the program get-device-info.cu from the course gitlab, compile and run it, and save the output and submit it with your code.

What to Submit

Submit your source code. (No graphs or tables necessary unless you did the third program.)

In addition, forward to me an example email notification that you receive from the slurm scheduler when your dot-product program ends and when your matrix-multiply program ends on the VACC cluster (as shown in the CUDA How-To lecture slides).