Level-Set Method to Solve the 2D Fisher–Stefan Model: Numerical Test Cases

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In this document, we provide numerical test cases for our level-set method used to solve the 2D Fisher–Stefan model. We compute solutions on circular domains $\Omega(t)$, and compare our results with Simpson [1], who solved the one-dimensional, radially-symmetric Fisher–Stefan problem on a disc. The numerical methods used are outlined in Simpson [1], and involve a change of variables to map the expanding or shrinking domain to the unit interval. The solutions of Simpson [1] were performed with 1001 grid points, yielding a grid spacing of $\Delta \xi = 0.001$, and a time step size of $\Delta t = 0.0001$. MATLAB code of this implementation is available in a public Github repository. To validate the level-set method, we consider both spreading and extinction solutions. In each, we consider the initial condition

$$u(x,y,0) = \begin{cases} \alpha & \text{if } \sqrt{(x - L_x/2)^2 + (y - L_y/2)^2} \le \beta \\ 0 & \text{otherwise,} \end{cases}$$
 (1)

where L_x and L_y are the computational domain widths in the x and y-directions respectively, β is the radius of the circular region $\Omega(0)$, and α is the initial density inside this region.

1 Spreading Solutions

We first consider a numerical solution with $\alpha = 0.5$, $\beta = 10$, and $\kappa = 1$, where κ is the Stefan parameter in the Fisher–Stefan model. We compute a numerical solution using our level-set method, with $N_x = N_y = 200$ grid intervals. The solution is computed until t = 30, with $L_x = L_y = 50$. To compare, we plot the one-dimensional solution obtained with the method of Simpson [1], with a one-dimensional slice at y = 25 of the two-dimensional level-set solution. This is illustrated in Figure 1.1. We obtain good agreement between the two-dimensional level-set solution and the one-dimensional solution using the method of Simpson [1]. For these parameters and initial conditions, the density u(x,t) evolves to a travelling-wave like profile, and spreads at a roughly-constant speed. Furthermore, the level-set method preserves the circular geometry as the solution progresses, as Figure 1.2 shows.

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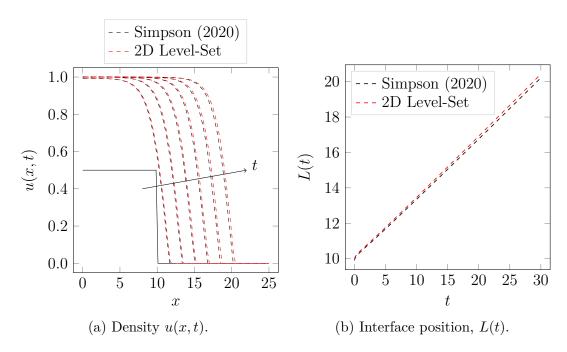


Figure 1.1: Numerical test of the level-set method with $\Delta t = 0.01$, $\Delta x = \Delta y = 0.25$, on a square grid of $L_x = L_y = 50$, i.e. a 201×201 spatial grid. Solution computed with $\kappa = 1$, D = 1, and $\lambda = 1$. (a) Density u(x,t) plotted at $t \in \{0,5,10,15,20,25,30\}$, where the solid curve denotes the initial condition, and the arrow indicates the direction of increasing t. For the 2D level-set solution, we plot the y = 25 slice, u(x,25,t). (b) Interface position, L(t). For the 2D level-set solution, the position L(t) is the zero level-set position, that is x such that $\phi(x,25,t) = 0$, which we compute by linear interpolation.

To ensure our results remain valid for different parameters, we computed a solution with the same initial condition as Figure 1.1, but with $\beta = 5$ and $\kappa = 20$. Again, we find good agreement between the radially-symmetric solution using the method of Simpson [1], and the two-dimensional level-set solution. These results are presented in Figure 1.3.

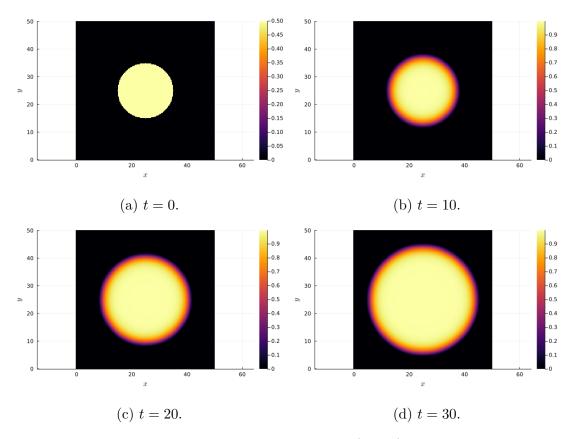


Figure 1.2: Two-dimensional evolution of the density u(x, y, t) in the spreading solution of Figure 1.1.

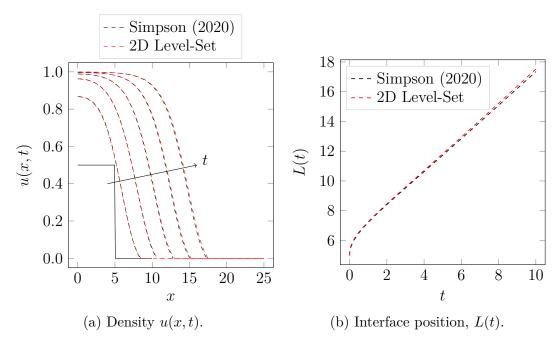


Figure 1.3: Numerical test of the level-set method with $\Delta t = 0.01$, $\Delta x = \Delta y = 0.25$, on a square grid of $L_x = L_y = 50$, i.e. a 201×201 spatial grid. Solution computed with $\kappa = 20$, D = 1, and $\lambda = 1$. (a) Density u(x,t) plotted at $t \in \{0, 2, 4, 6, 8, 10\}$, where the solid curve denotes the initial condition, and the arrow indicates the direction of increasing t. For the 2D level-set solution, we plot the y = 25 slice, u(x, 25, t). (b) Interface position, L(t). For the 2D level-set solution, the position L(t) is the zero level-set position, that is x such that $\phi(x, 25, t) = 0$, which we compute by linear interpolation.

2 Extinction Solution

In addition to the spreading solutions in §1, the Fisher–Stefan model admits solutions where density decreases with time [1, 2]. This arises from a competition between growth mediated by the source term, and mass loss at the interface due to the Stefan condition. In the radially-symmetric disc problem, spreading occurs if at any time the disc radius exceeds the first zero of the zeroth-order Bessel function of the first-kind, $J_0(x)$ [1]. Extinction occurs if the disc radius never exceeds this critical length, $L_c \approx 2.405$. To investigate whether our level-set method is accurate for solutions with extinction, we computed a solution with $\beta = 1.5$. As Figure 2.1 shows, the two-dimensional level-set solution correctly predicts population extinction. In the extinction solution, we obtained best results by solving the velocity extension and reinitialisation PDEs until at least $\tau = 20\Delta\tau$.

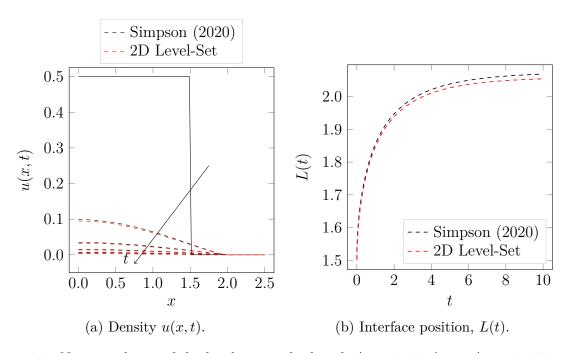


Figure 2.1: Numerical test of the level-set method with $\Delta t = 0.01$, $\Delta x = \Delta y = 0.025$, on a square grid of $L_x = L_y = 5$, *i.e.* a 201 × 201 spatial grid. Solution computed with $\kappa = 1$, D = 1, and $\lambda = 1$. (a) Density u(x,t) plotted at $t \in \{0,2,4,6,8,10\}$, where the solid curve denotes the initial condition, and the arrow indicates the direction of increasing t. For the 2D level-set solution, we plot the y = 2.5 slice, u(x,2.5,t). (b) Interface position, L(t). For the 2D level-set solution, the position L(t) is the zero level-set position, that is x such that $\phi(x,2.5,t) = 0$, which we compute by linear interpolation.

References

- [1] M. J. Simpson, "Critical length for the spreading-vanishing dichotomy in higher dimensions", ANZIAM Journal 62 (2020), pp. 3–17, DOI: 10.1017/S1446181120000103.
- [2] M. El-Hachem, S. W. McCue, J. Wang, Y. Du, and M. J. Simpson, "Revisiting the Fisher–Kolmogorov–Petrovsky–Piskunov equation to interpret the spreading– extinction dichotomy", *Proceedings of the Royal Society of London Series A* 475, 20190378 (2019), DOI: 10.1098/rspa.2019.0378.