6.439 Problem Set 3

Xudong Sun

4.1

(a)

In a prediction process using Gaussian process with N training input and output pairs (X, Y), and T test inputs X_T , the joint training and test marginal likelihood:

$$P(Y, Y_T) = N(0, K_{N+T}), K_{N+T} = \begin{bmatrix} K_N & K_{NT} \\ K_{TN} & K_T \end{bmatrix}$$

(Suppose the data are centered to $\mu = 0$)

Condition on training outputs:

$$P(Y_T|Y) = \frac{P(Y, Y_T)}{P(Y)} = N(\mu_T, \Sigma_T)$$

$$\mu_T = \mu + K_{TN} K_N^{-1} Y$$

$$\Sigma_T = K_T - K_{TN} K_N^{-1} K_{NT}$$

When N is large, the inverse of the covariance matrix K_N will be computationally expensive. The complexity of n by n matrix inversion is $O(n^3)$

(b)

We can reduce the rank of the covariance using following approximation:

Given a positive definite matrix K of order $n \times n$ and a randomly generated Johnson -Lindenstrauss matrix Ω of order $r \times n$, we find the projection matrix Φ of order $m \times n$ which approximates the range and compute the approximate SVD decomposition via Nystrom approximation with Φ .¹

1. $Φ^T$ = left factor of the rank m spectral projection of KΩ

$$2.K_1 = \Phi K \Phi^T$$

3. Choleski Factorization, $K_1 = BB^T$

4. Nystrom factor $C = K\Phi^{T}(B^{T})^{-1}$, spectual decomposition $C = UDV^{T}$

$$K \approx UD^{2}U^{T} = UDV^{T}VDU^{T} = K\Phi^{T}(B^{T})^{-1}B^{-1}\Phi K$$

= $K\Phi^{T}K_{1}^{-1}\Phi K = (\Phi K)^{-1}(\Phi K\Phi^{T})^{-1}\Phi K$

Consider the Gaussian Process with (Gaussian) noisy observations:

$$\mu_{T} = \mu + K_{TN}(K_{N} + \sigma^{2}I)^{-1}Y$$

$$\Sigma_{T} = K_{T} - K_{TN}(K_{N} + \sigma^{2}I)^{-1}K_{NT} + \sigma^{2}I$$

¹ Banerjee, Anjishnu, David B. Dunson, and Surya T. Tokdar. "Efficient Gaussian process regression for large datasets." Biometrika 100.1 (2012): 75-89.

6.439 Problem Set 3

Xudong Sun

Using the Sherman-Morrison-Woodbury matrix inversion lemma,

$$K_N \approx UD^2U^T$$

$$(K_N + \sigma^2 I)^{-1} = \sigma^{-2}I - \sigma^{-2}U(D^{-2} + \sigma^{-2}U^TU)^{-1}U^T\sigma^{-2}$$

$$= \sigma^{-2}I - \sigma^{-4}U(D^{-2} + \sigma^{-2}I)^{-1}U^T$$

In the above $(D^{-2} + \sigma^{-2}I)^{-1}$ is a diagonal matrix and the matrix inversion is avoided.