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1. http://wiki.ros.org/kinetic/Installation/Ubuntu
2. http://gazebosim.org/
3. Gazebo plugins in ROS

   http://gazebosim.org/tutorials?tut=ros_gzplugins

4. Installing gazebo_ros_pkgs

   http://gazebosim.org/tutorials?tut=ros_installing

5. SDF

   http://sdformat.org/

Useful Commands:

1. Git clone "url name from github"
2. rosrun tf view_frames

Keyboard teleop:

   http://wiki.ros.org/teleop_twist_keyboard
   https://github.com/ros-teleop/teleop_twist_keyboard
   https://github.com/lrse/ros-universal-teleop

Topic to explore for next lecture:

Mapping

http://wiki.ros.org/gmapping?distro=kinetic

Transforms

http://wiki.ros.org/tf