



Joint i	θ_i	d_i	a_i	α_i
1	θ_1	d_1	0	$\frac{\pi}{2}$
2	θ_2	0	a_2	0
3	θ_3	0	a_3	0
4	θ_4	d_4	0	$\frac{\pi}{2}$
5	θ_5	d_5	0	$-\frac{\pi}{2}$
6	θ_6	d_6	0	0