Computer Vision HW8

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1 Primary Procedures

For Opening and Closing, I'll use the code in HW5.

1.1 Gaussian Noise

```
def gaussian_noise(lena,amplitude):
    m=len(lena)
    n=len(lena[0])
    res=[[0]*n for i in range(m)]
    for i in range(m):
        for j in range(n):
        res[i][j]=max(0,min(255,lena[i][j]+amplitude*random.gauss(0,1)))
    return res
```

1.2 Salt and Pepper Noise

```
def s_and_p_noise(lena,theshold):
    m=len(lena)
    n=len(lena[0])
2
3
          res=[[0]*n for i in range(m)]
4
          for i in range(m):
               for j in range(n):
                     tmp=random.random()
                     if tmp<theshold:
                     res[i][j]=0
elif tmp>1-theshold:
res[i][j]=255
9
10
11
12
                          res[i][j]=lena[i][j]
           return res
```

1.3 Box Filter (3*3)

```
def box_filter3(lena):
            m=len(lena)
n=len(lena[0])
 2
 3
             lena=expan(lena)
             res=[[0]*n for i in range(m)]
             for i in range(m):
                   tmp=lena[i][0]+lena[i+1][0]+lena[i+2][0]
tmp+=lena[i][1]+lena[i+1][1]+lena[i+2][1]
tmp+=lena[i][2]+lena[i+1][2]+lena[i+2][2]
9
                   res[i][0]=tmp//9
10
                   for j in range(1,n):

tmp-=lena[i][j-1]+lena[i+1][j-1]+lena[i+2][j-1]

tmp+=lena[i][j+2]+lena[i+1][j+2]+lena[i+2][j+2]
11
13
                          res[i][j]=tmp//9
14
15
             return res
```

1.4 Box Filter (5*5)

```
def box_filter5(lena):
 2
            m=len(lena)
            n=len(lena[0])
 3
             lena=expan(lena)
            lena=expan(lena)
 5
            res=[[0]*n for i in range(m)]
for i in range(m):
 6
                   tmp=lena[i][0]+lena[i+1][0]+lena[i+2][0]+lena[i+3][0]+lena[i+4][0]
                    \begin{array}{l} tmp += l\, ena\, [\,i\,]\, [\,1\,] + l\, ena\, [\,i\,+1\,]\, [\,1\,] + l\, ena\, [\,i\,+2\,]\, [\,1\,] + l\, ena\, [\,i\,+3\,]\, [\,1\,] + l\, ena\, [\,i\,+4\,]\, [\,1\,] \\ tmp += l\, ena\, [\,i\,]\, [\,2\,] + l\, ena\, [\,i\,+1\,]\, [\,2\,] + l\, ena\, [\,i\,+2\,]\, [\,2\,] + l\, ena\, [\,i\,+3\,]\, [\,2\,] + l\, ena\, [\,i\,+4\,]\, [\,2\,] \\ \end{array} 
 9
10
                   tmp+=lena[i][3]+lena[i+1][3]+lena[i+2][3]+lena[i+3][3]+lena[i+4][3]
11
                   tmp+=lena[i][4]+lena[i+1][4]+lena[i+2][4]+lena[i+3][4]+lena[i+4][4]
12
13
                   res[i][0]=tmp//25
                   for j in range(1,n): tmp -= lena[i][j-1] + lena[i+1][j-1] + lena[i+2][j-1] + lena[i+3][j-1] + lena[i+4][j-1]
15
                           \texttt{tmp+=lena[i][j+4]+lena[i+1][j+4]+lena[i+2][j+4]+lena[i+3][j+4]+lena[i+4][j+4] } 
16
                          res[i][j]=tmp//25
17
18
            return res
```

1.5 Median Filter (3*3)

```
def med_filter3(lena):
    m=len(lena)
    n=len(lena[0])
    lena=expan(lena)
    res=[[0]*n for i in range(m)]
    for i in range(m):
        for j in range(n):
        res[i][j]=sorted(lena[i][j:j+3]+lena[i+1][j:j+3]+lena[i+2][j:j+3])[4]
    return res
```

1.6 Median Filter (5*5)

```
def med_filter5(lena):
1
2
        m=len(lena)
        n=len(lena[0])
3
        lena=expan(lena)
        lena=expan(lena)
6
        res=[[0]*n for i in range(m)]
        for i in range(m):
            for j in range(n):
tmp=sorted(lena[i][j:j+5]+lena[i+1][j:j+5]+lena[i+2][j:j+5]+lena[i+3][j:j+5]+lena[i+4][j:j+5])
9
                 res[i][j]=tmp[12]
10
        return res
```

1.7 Computing Signal Noise Rate (SNR)

```
def SNR(origin,lena):
         m=len(origin)
3
         n=len(origin[0])
4
         mu = 0
         mu_n=0
5
         for i in range(m):
 6
             for j in range(n):
                  mu+=origin[i][j]
9
                   mu_n+=lena[i][j]-origin[i][j]
         m11/=m*n
10
         mu_n/=m*n
11
         vs=0
12
         vn=0
13
         for i in range(m):
             for j in range(n):
	vs+=(origin[i][j]-mu)**2
	vn+=(lena[i][j]-origin[i][j]-mu_n)**2
15
16
17
         vs/=m*n
18
19
         return 20*np.log10((vs**0.5)/(vn**0.5))
```

2 Result



Gaussian Noise (amplitude=10) SNR = 13.6130506044



Box Filter 3*3 SNR=15.4130851200



Box Filter 5*5 SNR=14.870670493



Median Filter 3*3 SNR=17.6862701444



Median Filter 5*5 SNR=15.9874514287



Opening-then-Closing SNR=6.4587138667



 $\begin{array}{l} {\rm Closing\text{-}then\text{-}Opening} \\ {\rm SNR}{=}5.29204632897 \end{array}$



Gaussian Noise (amplitude=30) ${\rm SNR}{=}4.1657734748$



Box Filter 3*3 SNR=12.5972301851



Box Filter 5*5 SNR=13.3031734220



Median Filter 3*3 SNR=11.0682457441



Median Filter 5*5 SNR=12.8832447983



Opening-then-Closing SNR=7.0260368184



Closing-then-Opening SNR=3.85076320620



Salt and Pepper Noise (threshold=0.05) $$\operatorname{SNR}=0.9043074295$$



Box Filter 3*3 SNR=9.4436221358



Box Filter 5*5 SNR=11.120614263



Median Filter 3*3 SNR=19.311863677



Median Filter 5*5 SNR=16.393028419



Opening-then-Closing SNR=3.64708160609



Closing-then-Opening SNR=2.75776652710



Salt and Pepper Noise (threshold=0.1) $$\rm SNR{=}\text{-}2.0969583441}$



Box Filter 3*3 SNR=6.352908846



Box Filter 5*5 SNR=8.5315483297



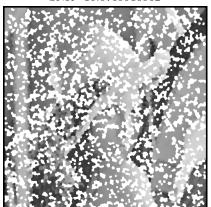
Median Filter 3*3 SNR=15.0759910952



Median Filter 5*5 SNR=15.745725733



Opening-then-Closing SNR=-2.3192932549702623



Closing-then-Opening SNR=-3.2127249492740066