深度學習Lab1 Report 309553012 黃建洲

I. Introduction

這一次的作業讓我們自行手刻一個簡單的neural network作為分類器。基本上是input/output layer加上兩層hidden layer的架構,並實作神經網路資料forward passing和back propagation,以及根據前兩者所得到的forward gradient和backward gradient合併計算出gradient後進行網路權重的更新。

測試資料為助教所提供的線性資料分布以及XOR資料分布。

使用語言為python, 不使用pytorch等現有深度學習package, 並使用CPU進行訓練。

II. Experiment Setup

A. Sigmoid functions:

由於輸入為matrix形式, 故使用numpy進行運算

```
# y = sigmoid(x):
    return 1.0 / (1.0 + np.exp(-x))
# y = sigmoid(x)

def derivative_sigmoid(y):
    return np.multiply(y, 1.0 - y)
```

B. Neural Network

神經網路架設的部分我學習常見的模板分為兩部分建立。

第一部分首先定義一個layer的元素: (給定該layer的input unit數量以及output unit數量)

- 1. 初始化: 根據layer的input unit數量以及output unit數量初始化一個極小的權重值。例如若input unit = 2, output unit = 4,則權重值矩陣大小為(2+1)*4,所加上的1代表bias。
- 2. Forward: 將內層的input陣列都補上一個1後(為了對齊weight加上的bias項), 將input矩陣與weight矩陣做矩陣乘法再用activation function計算得到該layer的output項
- 3. backward(back propagation): 根據wiki所提供的back propagation算法 如下

$$\overline{rac{dC}{da^L}\cdot (f^L)'}\cdot W^L \cdot (f^{L-1})'\cdot W^{L-1}\cdot \cdots (f^1)'\cdot W^1.$$

其中紅色框框的部分代表第一層的backward gradient, 左項為 derivative loss, 右項則為derivative activation function。而綠色框框我則解釋為要feed給上一層的derivative loss項, 是將backward gradient 與weight的轉置矩陣(為了使矩陣乘法合法)相乘。

以題目給予的基礎layer sizes[2,4,4,1]為例, 在output layer開始進行backward時, derivative loss matrix size為N x 1, derivative action function matrix size為N x 1, 作element wise乘法後為N x 1。而weight

- matrix size為2 x 1(因微分去除bias項),轉置後為1x2得feed backward 之derivative loss matrix為 N x 2。依此類推後皆合法。
- 4. update: 給予指定learning rate, 並利用在forward function中得到的 forward gradient與backward function中得到的backward gradient, 相 乘後算出total gradient, 並以learning rate為幅度對權重進行調整。

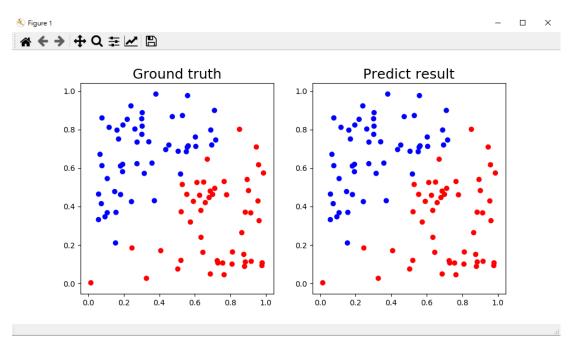
第二部分定義整個網路的流程:

- 1. 初始化: 根據指定的layer sizes來進行每一層的初始化。比如題目所給 定的[2,4,4,1], 我們需要以layer(input size, output size)的格式產生 layer(2,4), layer(4,4), layer(4,1)。
- 2. forward: 給定初始輸入值後,送入第一層layer計算,並依序將每一層的 output輸入給下一層的input, 直到最後一層算出整個網路的output為 止。
- 3. backward: 給定derivative loss值後,從最後一層layer開始進行 backward, 並將每一次算出的derivative loss值送入上一層進行計算, 直到第一層計算完成為止。
- 4. update: 單純在算出gradient(每一個layer自行暫存)後讓每一層layer進行一次update
- 5. Train: 將整個訓練的流程進行整理, 給定Max epoch數後以及loss threshold後, 每個epoch依序讓網路進行forward, backward, 以及 update的流程, 並計算該epoch的loss value。當loss value小於loss threshold或是epoch數大於max epoch數後訓練結束。

III. Result of your testing

這邊的epoch都以1000為單位

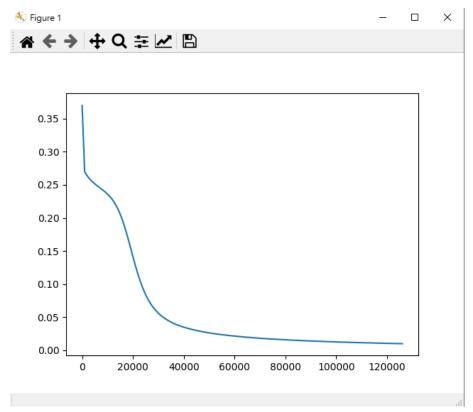
- (1) 線性分布資料:
- (2) 訓練epoch數: 115000
- (3) activation function: sigmoid
- (4) Accuracy: 100%(5) optimizer: MSE(6) loss threshold: 0.01(7) learning rate = 0.001
- 線性分布資料集
- 1. 比較圖



2. epoch與loss的對應資料



3. epoch與loss的曲線圖



4. prediction result

[[0.00663376] [0.00506767]	C:\Windows\system32\cmd.exe
[0.0026551]	[0.99663519]
[0.01800357]	[0.73271091]
[0.99081819]	[0.99195977] [0.98435304]
[0.99352481]	[0.96795217]
[0.00753079]	[0.002139]
[0.38513491]	[0.9939785]
[0.98284819]	[0.99431064]
[0.99637966]	[0.01550305]
[0.00254602]	[0.0020171]
[0.00272408]	[0.26531624]
[0.00235793]	[0.0023194]
[0.99688905]	[0.03301409]
[0.00477249]	[0.99240127]
[0.99580153]	[0.00736737]
[0.98439428]	[0.99436671]
[0.95459407]	[0.98632919]
[0.00265384]	[0.99529996]
[0.68578283]	[0.00335398]
[0.99460084]	[0.37702337] [0.02105504]
[0.01451278]	[0.03360579]
[0.99585349]	[0.29705883]
[0.00279724]	[0.9963015]
[0.99663519]	[0.01278765]
[0.73271091]	[0.99507411]
[0.99195977]	[0.00258661]
[0.98435304]	[0.99328216] [0.00219989]
[0.96795217]	[0.96074925]
[0.002139_]	[0.98667652]
[0.9939785] [0.99431064]	[0.00417628]
[0.01550305]	[0.99380916]
[0.0020171]	[0.97202288]
[0.26531624]	[0.99641823]
[0.0023194]	[0.99660829]
[0.03301409]	[0.00795012] [0.98111947]
[0.99240127]	[0.0035778]
[0.00736737]	[0.13566186]
[0.99436671]	[0.93790804]
[0.98632919]	[0.99038233]
[0.99529996]	[0.00342514]
[0.00335398]	[0.12410685]
[0.37702337]	[0.00491595]
[0.02105504]	[0.00199774]
[0.03360579]	[0.01513649] [0.66279223]
[0.29705883]	[0.01881173]
[0.9963015]	[0.95949494]
[0.01278765]	[0.03930079]
[0.99507411]	[0.01177177]
[0.00258661]	[0.99617042]
[0.99328216]	[0.99443888]
[0.00219989]	[0.98584451]
[0.96074925]	[0.99686588]
[0.98667652]	[0.98612347]
[0.00417628]	[0.00315208]
[0.99380916]	[0.00256404]
[0.97202288]	[0.90956309]
[0.99641823]	[0.01617071]
[0.99660829]	[0.95291382]
[0.00795012]	[0.10704857]
[0.98111947]	[0.99651885]
[0.0035778]	[0.99664428]
[0.13566186]	[0.00216037]
[0.93790804]	[0.97491221]
[0.99038233]	[0.73414702] [0.99602613]
[0.00342514]	[0.00465585]
[0.12410685]	[0.06865236]
[0.00491595]	[0.0122853]
[0.00199774]	[0.91771554]
[0.01513649]	[0.00232574]
[0.66279223]	[0.67108737]
[0.01881173] [0.95949494]	[0.99716828]]

● XOR 資料集:

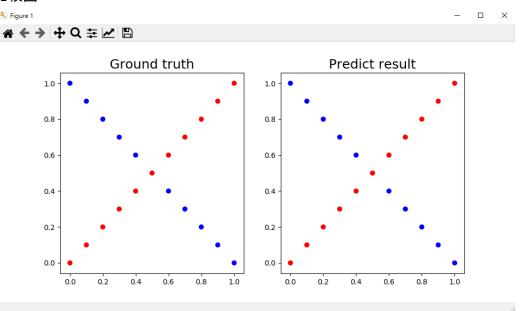
圖片:

(1) 訓練epoch數: 269000

(2) activation function: sigmoid

(3) Accuracy: 100%(4) optimizer: MSE(5) loss threshold: 0.01(6) learning rate = 0.001

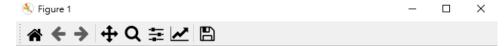
1. 比較圖

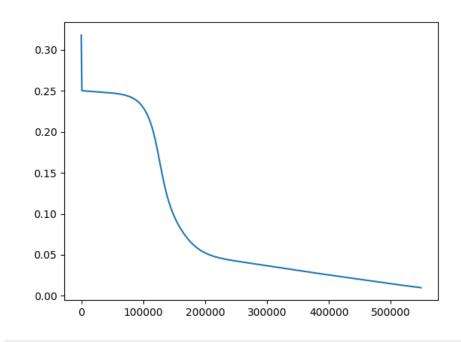


2. epoch與loss的對應資料



3. epoch與loss的曲線圖





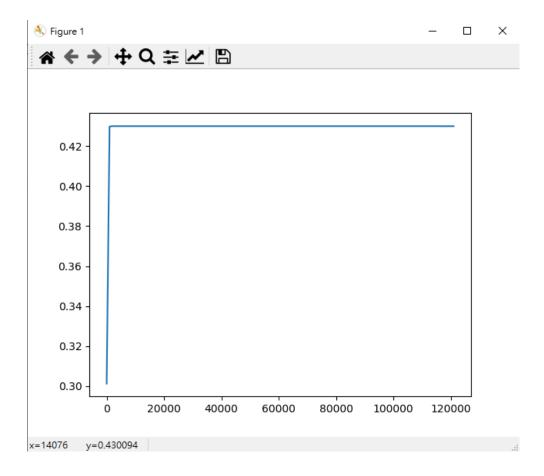
4. Prediction result

```
[[0.06087425]
[0.98639577]
[0.07151044]
[0.98545828]
[0.98248942]
[0.98277603]
[0.09209411]
[0.96984117]
[0.76426974]
[0.76426974]
[0.10292629]
[0.1041142]
[0.76536205]
[0.10330222]
[0.96243705]
[0.10119906]
[0.97642153]
[0.97642153]
[0.97949558]
[0.98048948]]
```

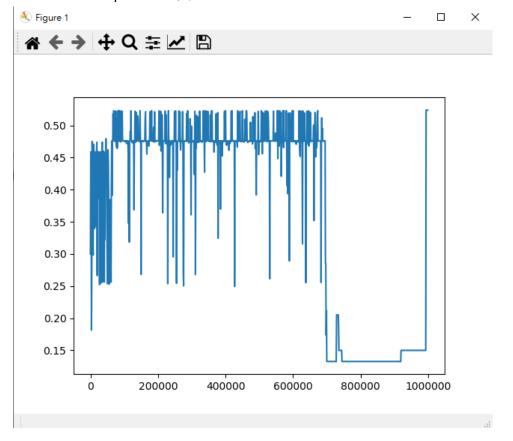
IV. Discussion

1. 嘗試不同的learning rate:

```
(a) Ir = 0.05 \rightarrow
                        線性分布
                                       XOR
        (i)
             epoch數量: 21000
                                       55000
       (ii)
             Accuracy: 100%
                                       100%
   (b) Ir = 0.5 \rightarrow
             epoch數量: 1000
                                        9000
        (i)
                                        100%
       (ii)
             Accuracy: 99%
   (c) Ir = 5 \rightarrow
             epoch數量: 0
        (i)
                                        100%
       (ii)
             Accuracy: 100%
   (d) lr = 50
        (i)
             epoch數量: 121000
                                        1000000
             Accuracy:
                                       47.6%
       (ii)
                        98%
      在Ir = 50時記錄到震盪的現象
線性分布的epoch-loss圖(機率發生)
(在120000的時候loss急速下降到threshold以下)
```



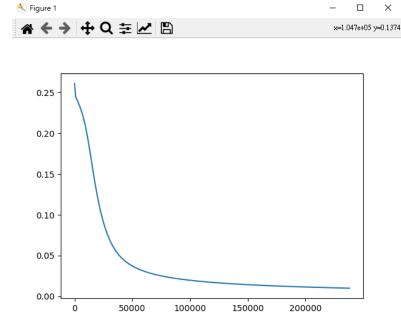
XOR的epoch-loss圖



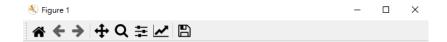
由於training是在方程式中尋找loss的最低點,因此learning rate越小,在方程式中開始 震盪的點loss值會越低。這次的作業中資料集都不算太難,甚至到learning rate = 5,los都還 可以正常的降到0.01以下。直到learning rate = 50,在XOR的資料中才可以比較顯著的看到 loss震盪的現象。

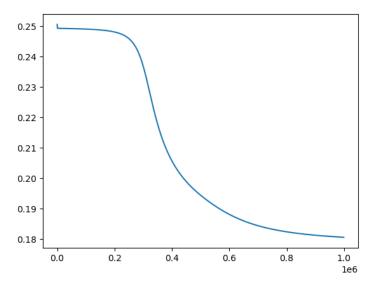
2. Try different number of hidden units

(a) layers size = [2,2,2,1], learning rate = 0.01, loss_threshold = 0.01 線性分布資料 → accuracy = 100%, epoch = 238000 loss-epoch 曲線圖

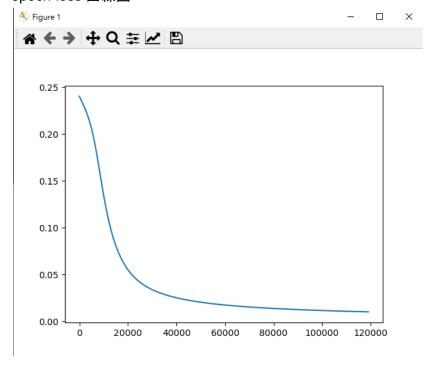


XOR資料 \rightarrow accuracy = 71.4%, epoch = 1000000(max_epoch) loss-epoch 曲線圖

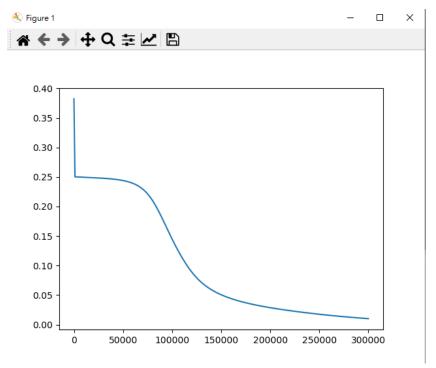




(b) layers size = [2,8,8,1], learning rate = 0.01, loss_threshold = 0.01 線性分布資料 \rightarrow accuracy: 100%, epoch \rightarrow 119000 epoch-loss 曲線圖



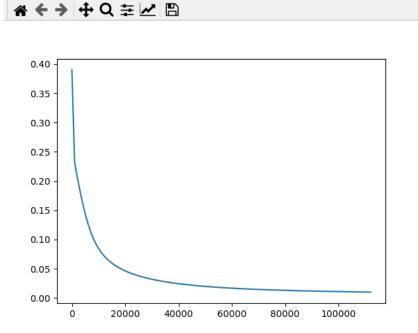
XOR資料 \rightarrow accuracy: 100%, epoch \rightarrow 300000 epoch-loss 曲線圖



(c) layers size = [2,8,8,1], learning rate = 0.01, loss_threshold = 0.01 線性資料分布 → accuracy: 99%, epoch: 112000 loss-epoch曲線圖

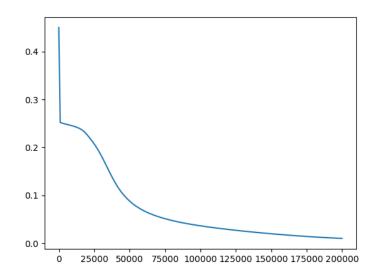
×

K Figure 1



XOR資料分布 → accuracy: 100%, epoch: 200000 loss-epoch曲線圖





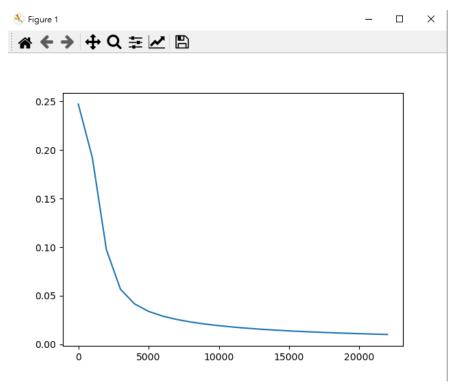
在這項實驗中我嘗試了三個不同的hidden layer的size, 分別是2x2、8x8、16x16, 而從XOR的實驗結果可以發現被hidden layer size影響最大的是開始收斂所需要的epoch數。size越大, 開始收斂所需要的epoch數量越少。但相對的, 由於網路架構變大, 因此每一次epoch所需要花費的時間也較多。

3. Without activation function

將forward的sigmoid部分移除, 並將新的activation function視為y = x, 故在backward 部分derivative activation function = 1。

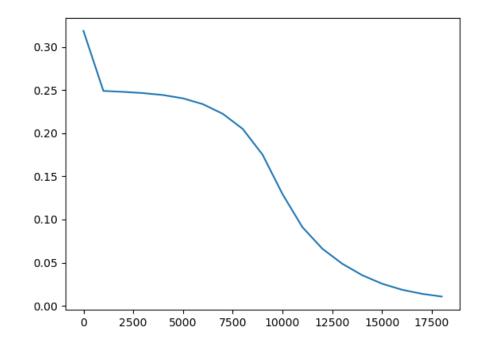
若將output layer的activation也移除會導致loss value為nan, 故保留為sigmoid

線性資料分布 → accuracy: 100%, epoch: 22000 epoch-loss曲線圖



XOR資料 \rightarrow accuracy: 100%, epoch: 18000 epoch-loss曲線圖





在不使用activation的情況下,於hidden layer中的資料會更為分散,導致權重在收斂上的難度也會提高。

V. Extra

1. Implement different optimizer:

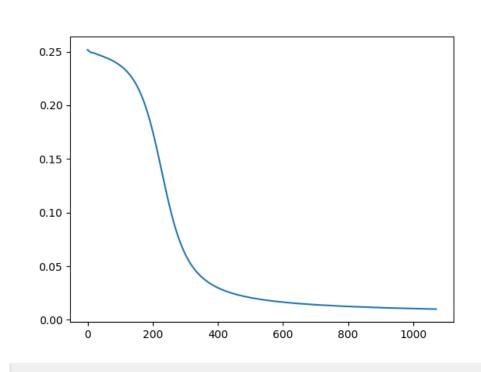
activation function: sigmoid, learning rate: 0.01

momentum

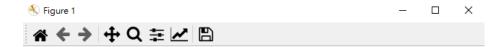
```
#momentum
self.momentum = 0.9 * self.momentum - lr * self.gradient
self.weight = self.weight + self.momentum

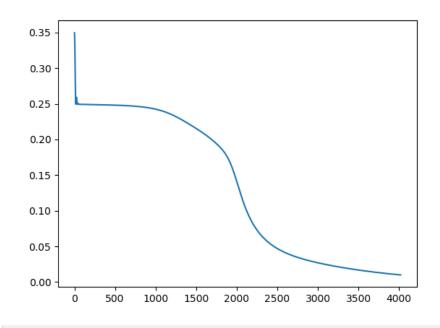
線性資料分布 →
accuracy:
accuracy: 100%, epoch: 1070

Figure 1 - □ ×
```



XOR資料 → accuracy: 100%, epoch:4021

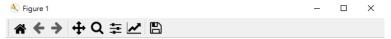


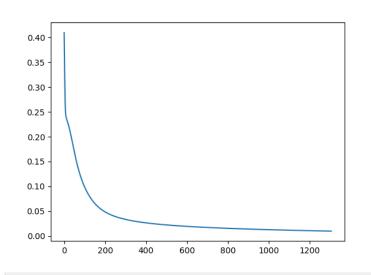


Adagrad

```
#adagrad
self.n += np.square(self.gradient)
n_lr = np.divide(lr, np.sqrt(self.n + 1e-8))
self.weight = self.weight - n_lr * self.gradient
```

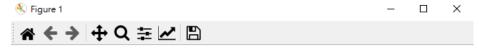
線性資料分布 →

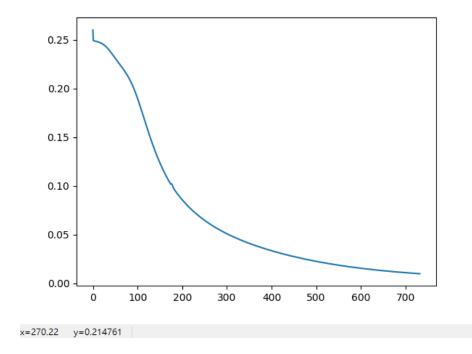




XOR資料 →

accuracy: 100%, epoch: 732

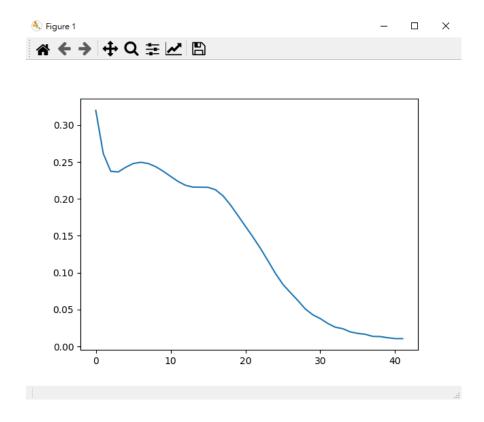




• Adam

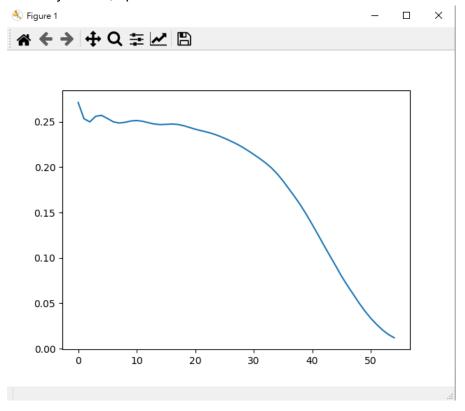
```
#adam
self.mt = self.b1 * self.mt + (1 - self.b1) * self.gradient
self.vt = self.b1 * self.vt + (1 - self.b2) * np.square(self.gradient)
mt_hat = np.divide(self.mt, 1 - self.b1 ** self.t)
vt_hat = np.divide(self.vt, 1 - self.b2 ** self.t)
self.t += 1
self.weight = self.weight - lr * np.divide(mt_hat, np.sqrt(vt_hat) + 1e-8)
```

線性資料分布 →





accuracy: 100%, epoch: 54



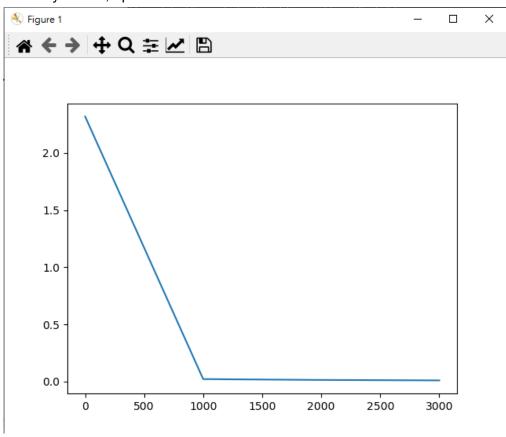
2. Implement different activation functions:

Tanh

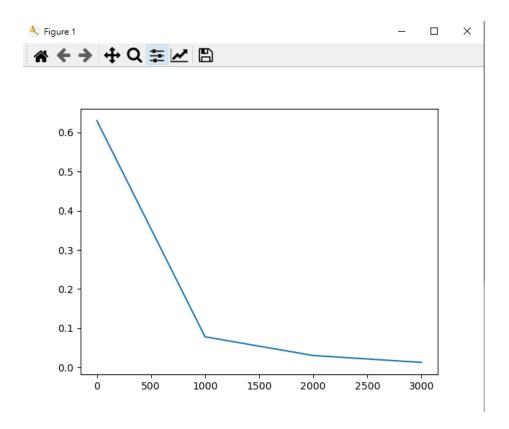
```
def tanh(x):
    return (np.exp(x) - np.exp(-x)) / (np.exp(x) + np.exp(-x))

def derivative_tanh(y):
    return 1 - np.multiply(y,y)
```

線性資料分布 →



XOR分布 → accuracy: 100%, epoch: 3000

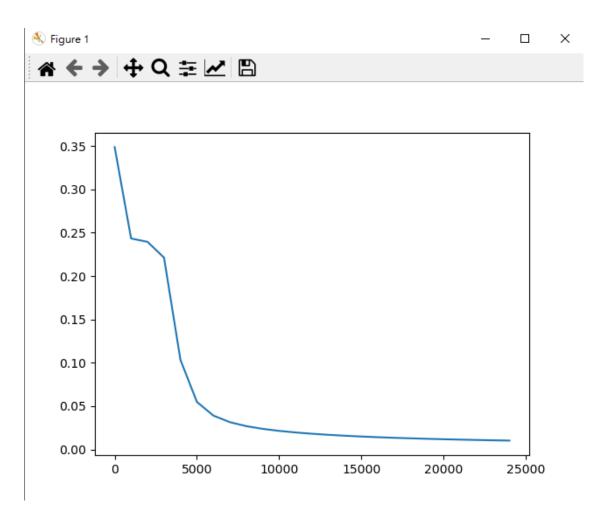


● Relu(output layer使用sigmoid)

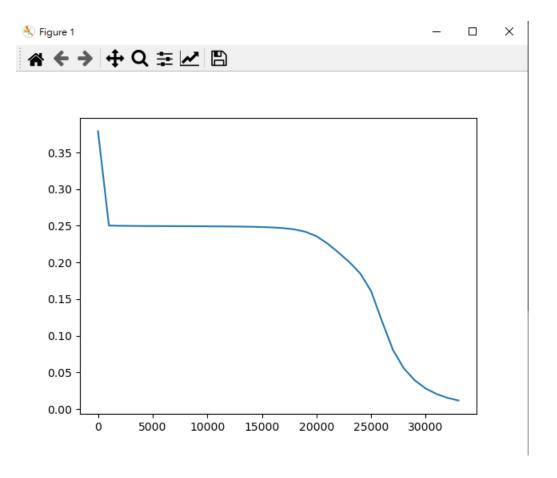
```
def relu(x):
    return np.maximum(0,x)

def derivative_relu(x):
    x[x <= 0] = 0
    x[x > 0] = 1
    return x
```

線性分布資料 →



XOR資料 \rightarrow accuracy: 100%, epoch \rightarrow 33000

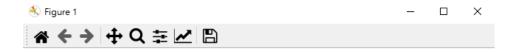


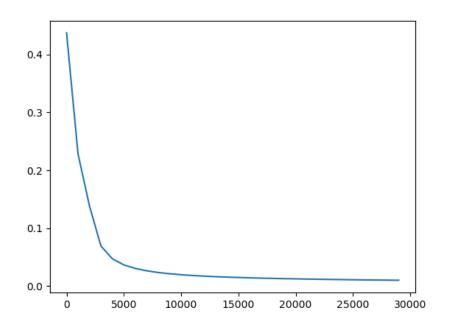
• Leaky-Relu(output layer使用sigmoid)

```
def leaky_relu(x):
    return np.maximum(0,x) + np.minimum(0, 0.01 * x)

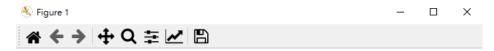
def derivative_leaky_relu(x):
    x[x <= 0] = 0.01
    x[x > 0] = 1
    return x
```

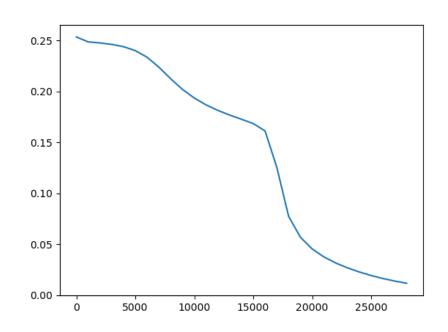
線性分布資料 →





XOR資料 → accuracy: 100%, epoch: 28000





結論而言,在實驗中經過多次嘗試後,我在這次作業中嘗試出最有效果的 activation function是tanh,收斂速度最快並且所需要的epoch數量最少。

Relu和Leaky-Relu的話在這次實驗中相對表現比較不穩定, 若不將output layer維持sigmoid或是tanh的話常常會發生dead relu problem, 或甚至是根本無法產生loss值。