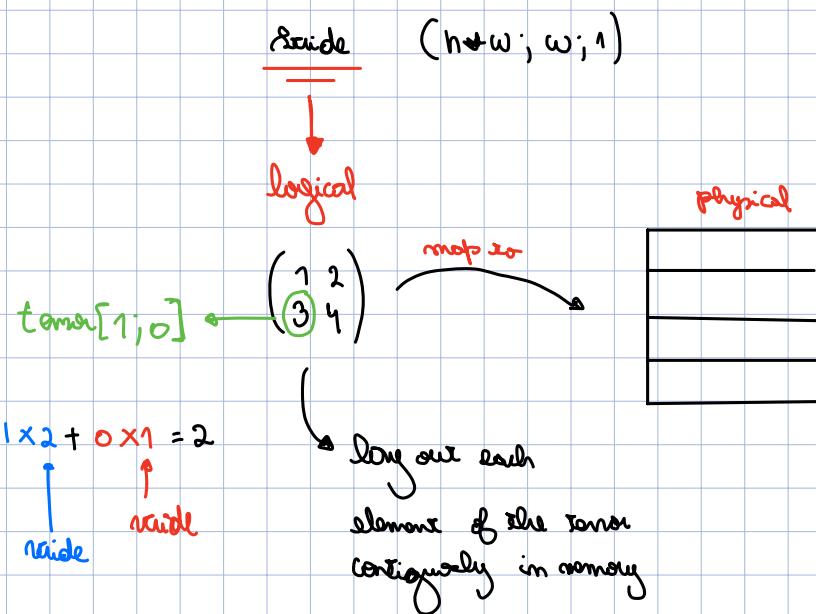
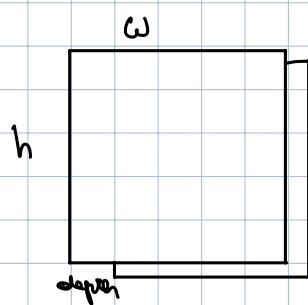
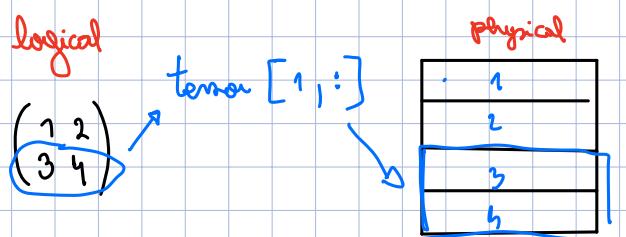


+ error

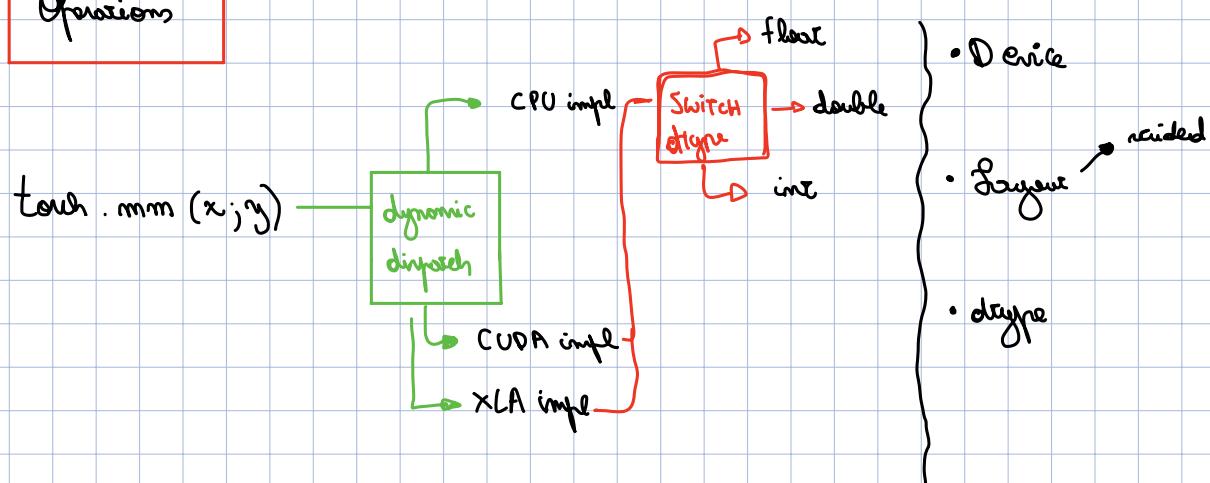


other example



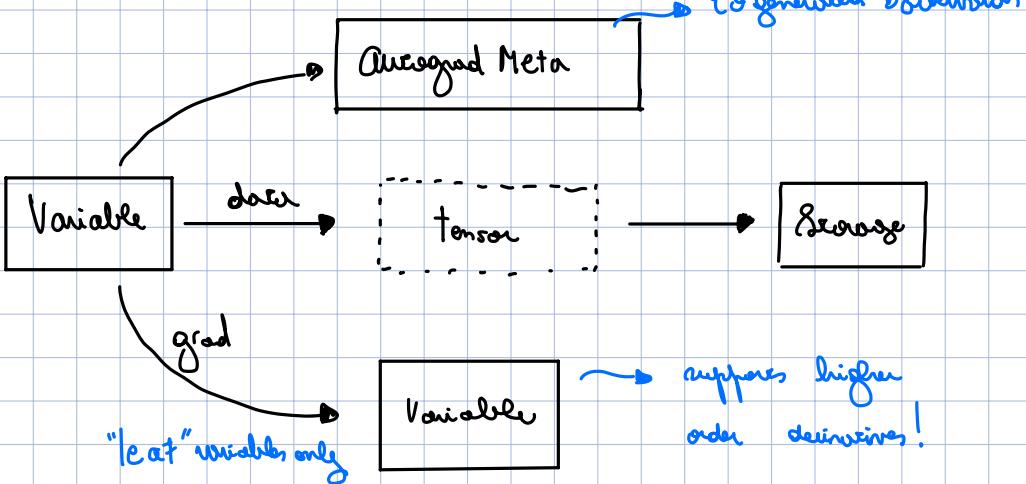
DOES NOT CREATE A NEW TENSOR

Operations



Autograd (automatic differentiation)

automatic differentiation on tensors



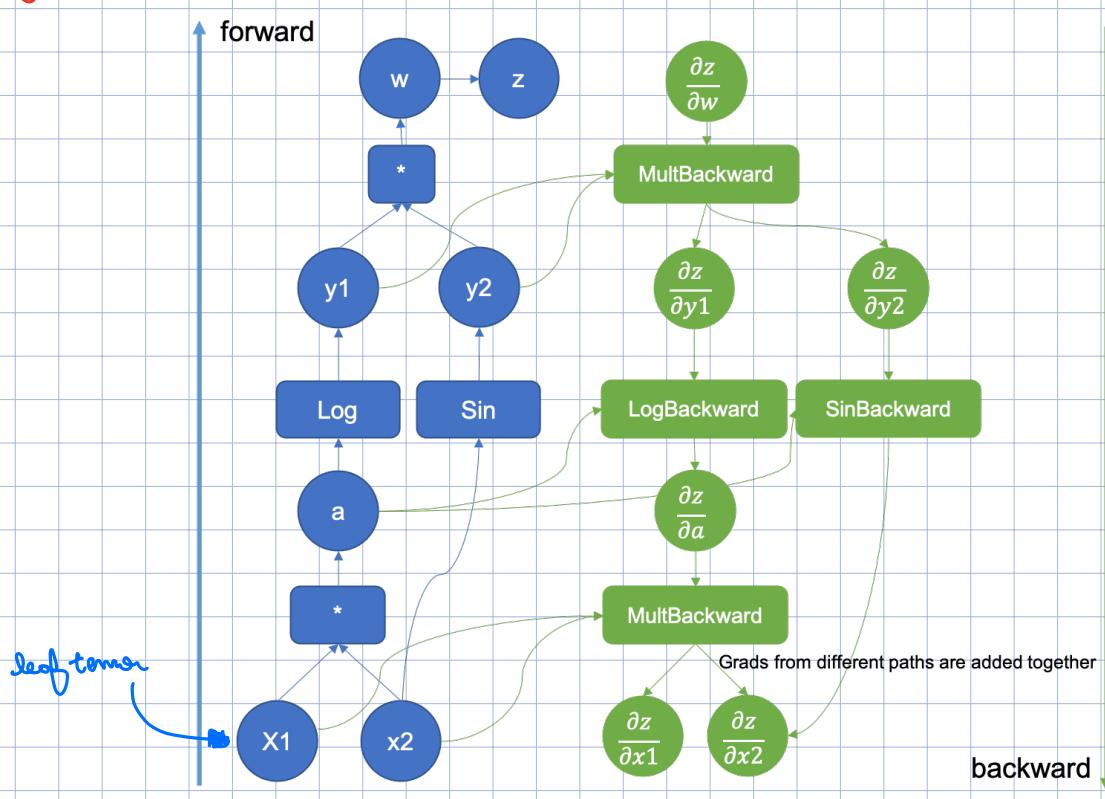
→ supports higher order derivatives!

Computational graphs

→ torch.autograd.Function → class to write your own differentiable functions

perform function, vector product, iteration

Graph creation



if requires - good in one item on Assigned Meta will be allowed

- Composed grad. curves
 - grad-fn \rightarrow differentiable function

```
import torch

# Create input tensors
x = torch.tensor([2.0], requires_grad=True)
y = torch.tensor([3.0], requires_grad=True)

# Perform addition
z = x + y # z is the result of addition
print("z.grad_fn:", z.grad_fn) # Output: <AddBackward0>

# Perform multiplication
w = z * 2 # w is the result of multiplication
print("w.grad_fn:", w.grad_fn) # Output: <MulBackward0>
```

→ Represents a node in comp graph
!!! Uses chain rule

- input layers that are connected
 - compute gradients (forward direction)

(tenses)

The grad_fn will hold them using the next-edge.

Applies similarly to
Augmented Mera

Differentiation in Autograd

requires_grad = True → signals that every operation on them should be tracked

$$Q = 3 \cdot a^3 \cdot b^2$$

assume it to be the error in a NN

$$\frac{\partial Q}{\partial a} = 9a^2$$

calculates these grads and stores them in .grad

$$\frac{\partial Q}{\partial b} = -2b$$

$$a = (2; 3)$$

$$Q(a, b) = 3a^3 \cdot b^2$$

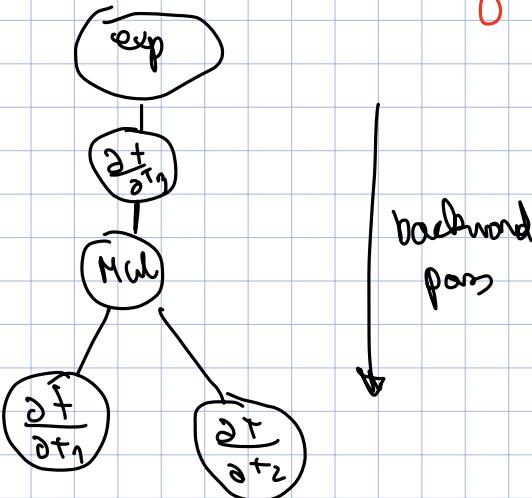
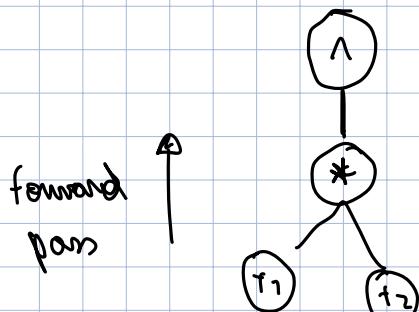
$$b = (6; 4)$$

$$Q: \mathbb{R}^2 \rightarrow \mathbb{R} \quad (\text{should always be an scalar func})$$

$$\vec{\nabla} Q = \left(\frac{\partial Q}{\partial a} \mid \frac{\partial Q}{\partial b} \right)$$

Computational graph

stored in a directed acyclic graph (DAG)



When you done more to compute gradients of certain parameters you **freeze** them

Bosch normalization $\xrightarrow{\text{couples example}}$ (avoid)

Linearity \longrightarrow Normalization \longrightarrow Non-linearity