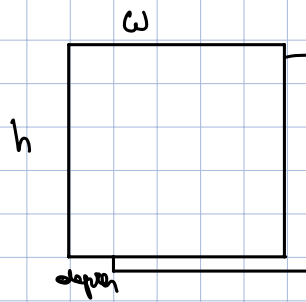


+ error



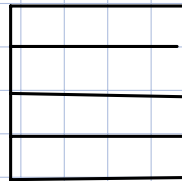
stride $(h \times w; w; 1)$

logical

$\begin{pmatrix} 1 & 2 \\ 3 & 4 \end{pmatrix}$

map to

physical



tensor[1;0]

$$1 \times 2 + 0 \times 1 = 2$$

stride

stride

lay out each element of the tensor contiguously in memory

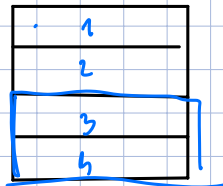
other example

logical

$\begin{pmatrix} 1 & 2 \\ 3 & 4 \end{pmatrix}$

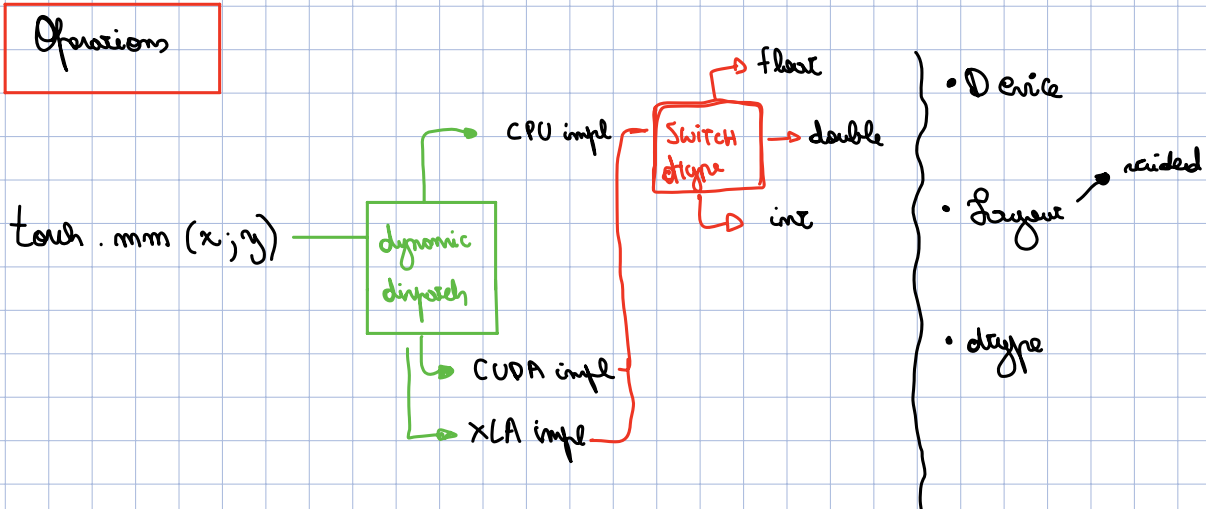
tensor[1,:]

physical



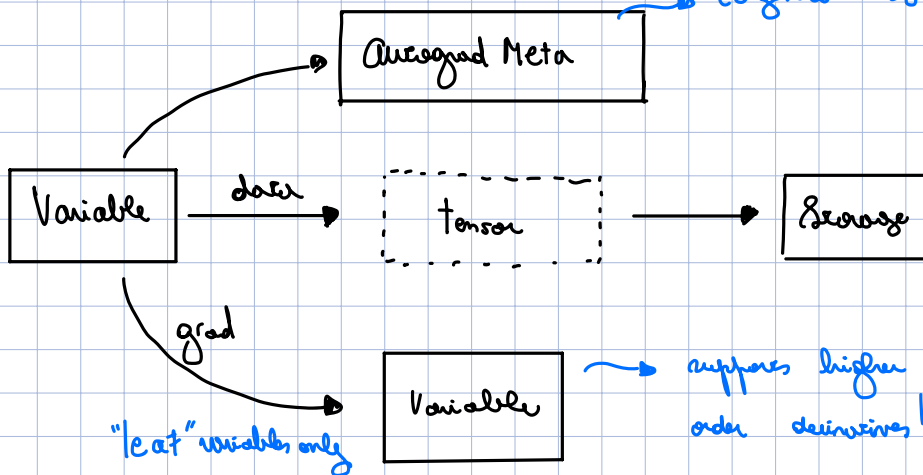
DOES NOT CREATE A NEW TENSOR

Operations



Autograd (automatic differentiation)

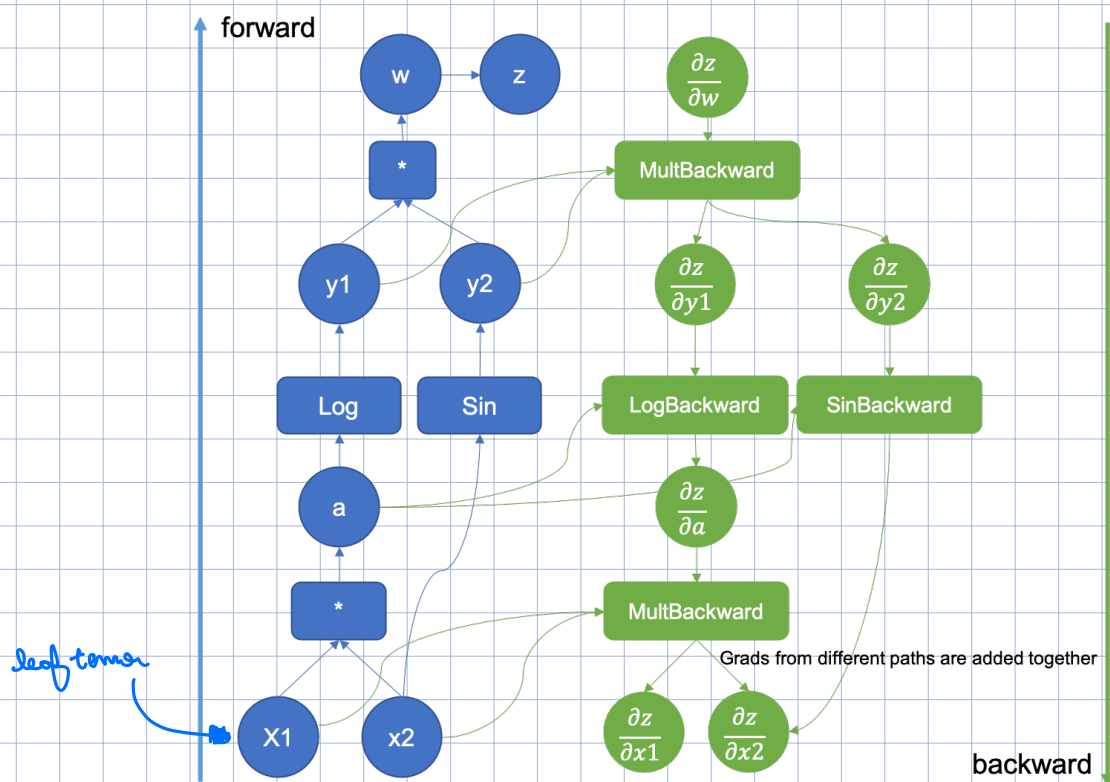
automatic differentiation on tensors → to generate backwards



Computational graphs

- torch.autograd.Function → class to write your own differentiable functions
- perform function vector product, inversion

Graph creation



if requires_grad is set then an AutogradMeta will be allocated

- Confused grad accum
- grad-fn \rightarrow differentiable function

```
import torch
```

```
# Create input tensors
```

```
x = torch.tensor([2.0], requires_grad=True)
```

```
y = torch.tensor([3.0], requires_grad=True)
```

```
# Perform addition
```


```
z = x + y # z is the result of addition
```

```
print("z.grad_fn:", z.grad_fn) # Output: <AddBackward0>
```

```
# Perform multiplication
```

```
w = z * 2 # w is the result of multiplication
```

```
print("w.grad_fn:", w.grad_fn) # Output: <MulBackward0>
```

- \downarrow  Represents a node in comp graph
Uses chain rule
- inputs tensors that are connected
 - compute gradients (partial derivative)

The grad-fn will hold them ^(tensors) using the next-edge
 \downarrow
copies tensors to AutogradMeta

Differentiation in Autograd

requires_grad=True → signals that every operation on them should be tracked

$$Q = 3 \cdot a^3 \cdot b^2$$

assume it to be the error in a NN

$$\frac{\partial Q}{\partial a} = 9a^2$$

calculates error grads and store them in .grad

$$\frac{\partial Q}{\partial b} = -2b$$

$$a = (2; 3)$$

$$b = (6; 4)$$

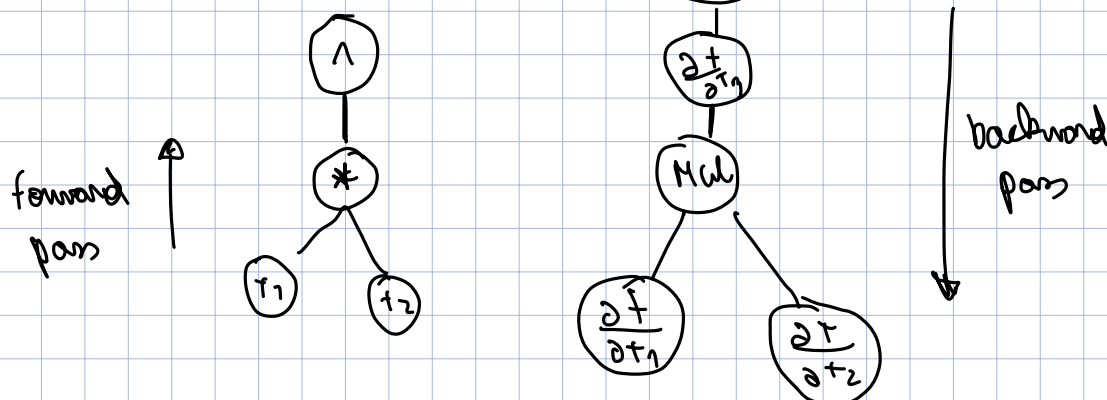
$$Q(a, b) = 3a^3 \cdot b^2$$

$$Q: \mathbb{R}^2 \rightarrow \mathbb{R} \quad (\text{should always be on scalar func})$$

$$\vec{\nabla} Q = \left(\frac{\partial Q}{\partial a} ; \frac{\partial Q}{\partial b} \right)$$

Computational graph

stored in a directed acyclic graph (DAG)



When you done want to compute gradients of certain parameters you freeze them

Batch normalization → couples example
(avoid)

Linearity → Normalization → Non-linearity