uts	outputs
	BX130X is describe as follow. Heavy Duft Lone Reach Robot
	BA 1931A descence as too An Investigating the relay Value, Long register for relay Value, Value for relay Value, Value for relating the sear for relating the sear for relating the value of rela
	The Lat Floor Related at Fathers may be Frederick and Fred
me about BX130X	
	8X130X is describe as follow: Heavy Duty, Long Reach Robot
	The BX130X features a hollow wrist for housing cables and hoses and an extended reach arm. The robust, yet lightweight arm design provides functionality, flexibility and efficiency for maximum spot welding effectiveness and multiple-purpose usage.
I me about BX130X	
THE BOOK BAISON	BX130X is describe as follow: Heavy Duty, Long Reach Robot
II me about BX130X	The EXT XXV Returns a hollow mist for sun, many puls, mount in a character and the puls of
I me about Fanuc R-2000iC/165F	
	is describe as follow: The FANUC R-20000C165F is part of an extensive family of industrial notous offering a variety of psyloads and reaches. The six-axis robot offers a compact design with a thin wrist, allowing it to operate in tight workspaces. Featuring a 165kg psyload and 2,655mm reach, the nobot is a powerful and flexible solution for a variety of material handling and spot welding applications.
Il me about Arc Welding Robot ARC Mate 100iD	described as follow: This new generation of arc welding robots stands out based on its productivity advancements and rapid integration times. To utilize space more efficiently, the new ARC Mate 100i D has received a more sophisticated, curved design, which allows it to effortlessly operate in compact welding cells. It features a fully integrated welding hosepack
Il me about BA006N	describeds a follow. Through-Arm Cable Are Welding Robot. The BADDON are verified probable have received probable and reliable office teaching, Improve product quality while addressing labor shortsques with this high-performance mobil.
	The BULDOW at the Bending boots have a manufacture from a financial manufa
me about Paint Robot Paint Mate 200iA/5L	described as follow: Finishen Pend Finishen
me about KF121	The KF212 painting robot is the smaller groot groot is the smaller groot gr
I me about BIKE	described as follow, The BIKE platform is a magnetic wheeled robot capable of inspecting power plant facilities and multiple applications in the cil and gas industry, such as vessel or pipe inspection. BIKE can reach locations previously inaccessible to humans due to size constraints, temperature, immersion in liquids or safety reasons. It makes your inspections safer and more efficient.
	described as follow. This is the waterpoord inspection reason of the camera and a durable steel roll cage which offers protection in case of a rollower. High-powered auxiliary ligh-
	We construct the rebot chassis from 3003 aluminum coated with a durable epoxy bed liner paint. A combination of shaft seals and gaskets protects the robot chassis from water influsion. The tracks are motided (no splice), are axele mounted, and chain-driven by IGS2 gear motors.
ll me about Configurable - LT2-F-W Watertight	4 Augged endosed case houses the controller and includes a lourbarreen LCD. This remote provides live video and a combination of virtual and physical controls to control was observed. (Special provides and a new provided of the control of the con
I me about COBOTTA PRO	described as follows high-speed collaborative tools considered to consider the considered to the consi
	The COBOTTA PRO is designed not only to facilitate collaboration between humans workers and robots but also to consistently maximize productivity. It delivers a blend of productivity and safety for both simple tasks and multi-step processes like assembly and inspection work.
	described as follow:FANUC's CRX-64 food-grade collaborative robot is designed for the food and beverage industries. Equipped with NSF-H1 food-grade grease, white epoxy paint and rustichemical resistant plating, the CRX-54 food-grade cobot is an ideal solution for food handling, wet environments, or strict hygiene requirements.
me about CRX-5iA Food-Grade Collaborative Robot	The CRX.SA food grade cobot has a Sig payload and 994mm reach. Its Tablet Teach Pendant (TP) offers customers a quick and easy way to program with user-friendly features and intuitive drap-and-drop functionality. Easy programming paired with FANLIC's world-renowned technology, power reliability, and sentifies contact detection allows the CRX.SA food-grade cobot to work safely allongaide people – even in fight workspaces. FANLIC's series of CRX collaborative robots provide the utmost reliable reach food grade cobot to work safely allongaide people – even in fight workspaces. FANLIC's series of CRX collaborative robots provide the utmost reliable reach food grade cobot to work safely allongaide people – even in fight workspaces. FANLIC's series of CRX collaborative robots provide the utmost reliable reach food grade cobot to work safely allongaide people – even in fight workspaces. FANLIC's series of CRX collaborative robots provide the utmost reliable reach food grade cobot to work safely allongaide people – even in fight workspaces. FANLIC's series of CRX collaborative robots provide the utmost reliable reach food grade cobot to work safely allongaide people – even in fight workspaces. FANLIC's series of CRX collaborative robots provide the utmost reliable reach food grade cobot to work safely allongaide people – even in fight workspaces. FANLIC's series of CRX collaborative robots provide the utmost reliable reach food grade cobot to work safely allongaide people – even in fight workspaces. FANLIC's series of CRX collaborative robots provide the utmost reliable reach food grade cobot to work safely allongaide people – even in fight workspaces. FANLIC's series of CRX collaborative robots provide the utmost reliable reach food grade cobot to work safely allong the utmost reach food grade cobot to work safely allong the utmost reach food grade cobot to work safely allong the utmost reach food grade cobot to work safely allong the utmost reach food grade cobot to work safely allong the utmost reach food grade cobo
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me about UR20	
Il me about MYS650LF	Described as blow Described Solvor Descr
ell me about MYS650LF	Described as follow 4-axis SCARA robot ideal for high-speed handling and assembly systems. Offers superior performance in applications such as assembly, dispensing, part kitting, small part handling, case packing, lab automation, packaging, solar and semiconductor processing.
Il me about MYS650LF	Described as follow 4 axis SCAPA robot ideal for high-speed handling and assembly systems. Offer superior performance in applications such as assembly, depressing, part killing, small part handling, case packing, lab automation, packaging, solar and semiconductor processing. Highly vessalle, the sax-axis GA60 robot is well-surfed for laser welding, laser cutting, plasma cutting and dispensing basis. Featuring fast access speeds and acceleration capabilities, this robot can reduce cycle time and increase production throughout. High rigidity and precision drives offer exceptional path accuracy, and a high payload capacity supports the use of a Remote Laser Welding head, when needed. A reduced interference design enables close proximity placement to other robots and equipment.
Il me about MYS650LF	Described as Bloar 4-axis SCARA robot ideal for high-speed handling and assembly systems. Offers superior performance in againstance and assembly superior in the superior performance in against in the superior performance in the superior performance in against in the superior performance in the superior performance in the superior performance in the superior performance in the su
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Il me about MYS650LF	Described as Blook 4-axis SCARA Noted Ideal for high-speech handing and assembly systems. Offers superior performance in againstance use assembly despending and assembly systems. Offers superior performance in againstance use assembly superior performance in againstance use assembly superior performance in againstance assembly superior performance in against in a state of a second and a state of a second and a state of a second and a second and second and a second and
ill me about MYS650LF ill me about GA50	Described as foliars 4-axis SCARA rotor ideal for high-speed handling and assembly systems. Offers superior performance: in againstance in a seasonshy, dispersing part atting, seen parking, bits unternation, parkaging, solar and emicrodisticity processing. Highly versalite, the sai-axis SCARA rotor ideal for high-speed parking basis. Featuring tasks. Featuring tasks. Featuring tasks. Featuring tasks access seeds and acceleration capabilities, his rotor can reduce cycle time and increase production throughput. High rigidity and precision drives offer exceptional path accuracy, and a high payload capacity supports the use of a Remote Laser Welding head, when needed. A reduced interference design enables close proximity placement to other robots and equipment proximates. Available with a lemma wrist, this robot has an inside diameter of 70 mm, making it well-suited for mounting spray equipment applications. Robot is Factory Multual approved for use in Class I, Div. 1 hazardous environments, and can be floor, wall- or ceiling encounted for layout flexibility.
ill me about MYS650LF Il me about GA50	Described as folior 4-axis SCARA from tited for high-speed handing and assembly systems. Offers superior performance in againstance in againstance with assembly systems. Offers superior performance in againstance in a second performance in againstance in against and interference design entables close proximity placement to other robots and equipment and performance in against interference design entables close proximity placement to other robots and equipment against interference design entables close proximity placement to other robots and equipment against interference design entables close proximity placement to other robots and equipment against interference design entables close proximity placement to other robots and equipment against interference design entables close proximity placement to other robots and equipment against interference design entables close proximity placement to other robots and equipment against interference design entables close proximity placement to other robots and equipment against interference design entables close proximity placement to other robots and equipment against interference design entables close proximity placement to other robots and equipment against interference design entables close proximity placement to other robots and equipment against a
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I me about MPXL2800 If me about GA50 If me about MPXL2800 If me about SG650	Described as folior 4-axis SCARA robot lead for high-speech harding and assembly systems. Offers superior performance in againstance such as assembly, described the state vestigated for test vestigations. Early fair plant cases production from production processing. Highly vestable for test vestigations acts (AGA) robot is useful useful case under such as assembly, described and such as assembly subject to the vestigations. Feature flat accuracy, and a high payload capacity supports the use of a Remote Laser Welding head, when needed. A reduced interference design enables close proximity placement to other robots and equipm Providing smooth, consistent finishes with outstanding efficiency for painting and dispersing applications, the extremely reliable six axis MPXI.2000 robot is ideal for coasing continued parts such as interior-leaderior surfaces. Available with a lemma wind, this tool has an inside diameter of 70 mm, making it web-suited for mourting space quipment applications. The MPXI.2000 features the DXDOPA for doctor-leader with an easily outcomedia, and can be floor, wall- or ceiling mounted for layout feelbillly. The MPXI.2000 features the DXDOPA for doctor-leader with an easily occurrence with a seasy to use to the control of the paylor of the control of the paylor of
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il me about MYS600LF il me about MSVL2000 il me about MSVL2000 il me about MSVL2000 il me about MSVL2000	Described as folior 4-axis SCARA rotool (seel for high-speed pandring and assembly by systems. Offers superior performance in againstance in third, are all part handing, case pandring. Be advantance, palabagine, salve and seem of the receptional path accuracy, and a high payload capacity supports the use of a Remote Laser Welding head, when needed. A reduced interference design enables close proximity placement to other robots and equipment. Providing smooth, consistent finishes with outstanding efficiency for painting and dispensing applications, the externey reliable six axis MPXL2000 robot is ideal for coating contoured parts such as interioriseletion surfaces. Available with a lemma wind, this olds has an inside dismenter of 70 mm, making at well-surface of the coating contoured parts such as interioriseletion surfaces. Available with a lemma wind, this olds has an inside dismenter of 70 mm, making at well-surface of the coating contoured parts such as interioriseletion surfaces. Available with a lemma wind, this olds has an inside dismenter of 70 mm, making at well-surface of the coating contoured parts such as interioriseletion surfaces. Available with a lemma wind, this olds has an inside dismenter of 70 mm, making at well-surface of the coating proved for use in Class I, this, 1 hazardous environments, and can be floror, well or ceiling enumerated for layout flexibility. The MPXL2000 flexibuses the DXOD-FA for doct controler with an easily occurred with an easily occurred with an easily occurred for layout flexibility. The MPXL2000 flexibuses the DXOD-FA for doct controler with an easily occurred with a easily occurred from the control of the provision of the provision of the control of the provision of the contro
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me about MY-9600LF me about MP-X1.2000 me about S6050 me about HC30PL me about PL500	Described as flotor 4 axis SCARA/hoot is east for high-speech audring and assembly, paterns. Offers support preformance in againstance with a sastenthy described, be automation, packaging, about and seminoductor processing. Highly vestable, the size of activated AGA/hoot does the freely personal for large and speembly packaged capacity supports the use of a Remote Laser Weiding head, when needed. A reduced interference design enables close proximity placement to other notices and equipment against the same and the control of the same and the control of the same and the
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