Jinoh Lee was born in Seoul, South Korea. He received the B.Sc. degree in mechanical engineering from Hanyang University, Seoul, South Korea, in 2003 (awarded Top 2% Academic Excellence) and the M.Sc. and the Ph.D. degrees in Mechanical Engineering from Korea Advanced Institute of Science and Technology (KAIST), Daejeon, South Korea, in 2012. Since 2012, he has joined the Department of Advanced Robotics, Istituto Italiano di Tecnologia (IIT), Genoa, Italy, as a postdoctoral researcher, and was awarded a competitive grant from the National Research Foundation (NRF) of Korean Government, titled as ‘Fostering next generation researchers program’ from 2013-2014.

He is currently a Senior Postdoctoral Researcher involved in projects such as Safe and Autonomous Physical Human-Aware Robot Interaction (SAPHARI) and Whole-body Adaptive Locomotion and Manipulation (WALK-MAN) funded under the European Community's 7th Framework Programme. In particular, he is a team member of WALK-MAN participating to final DARPA Robotics Challenge (DRC) on 5-6 June, 2015, Pomona USA, where contributions have been made to develop various manipulation skills on the humanoid. His research has been concerned with whole body manipulation of humanoid robots, compliant robotic system control for safe human-robot interaction, dual-arm dexterous manipulation, robust control of highly nonlinear systems, and smart and soft actuators. Since 2014, Dr. Lee has participated in Technical Committee member of International Federation of Automatic Control (IFAC), TC4.3 Robotics. He is also a member of IEEE Robotics and Automation, Control Systems, and Industrial Electronics Societies and the Program Committee of 2016 IEEE International Conference on Robotics and Biomimetics (ROBIO).