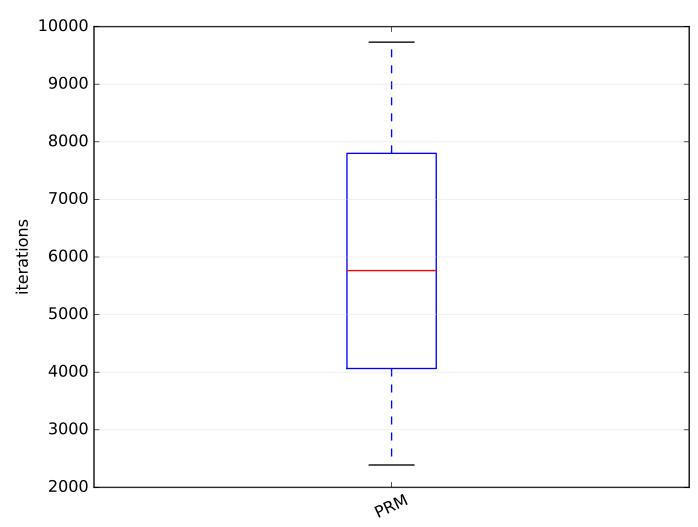
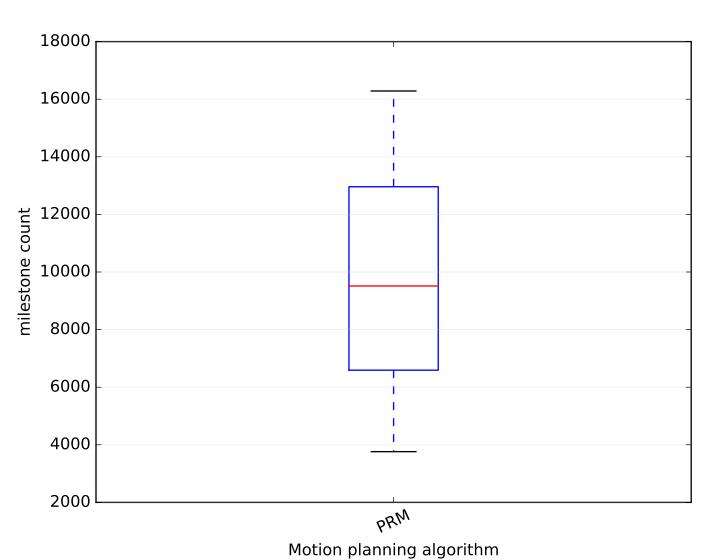
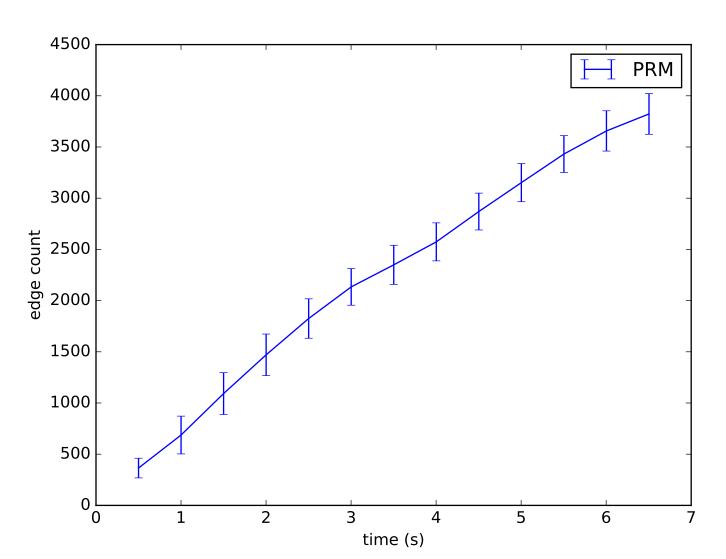


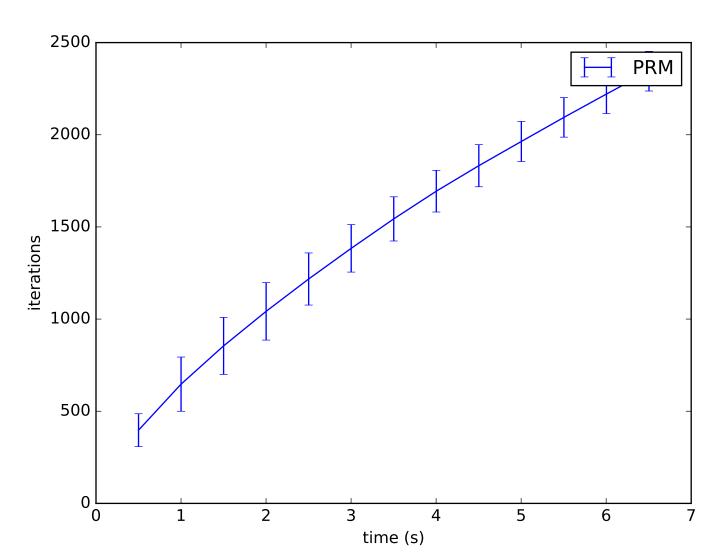
Motion planning algorithm

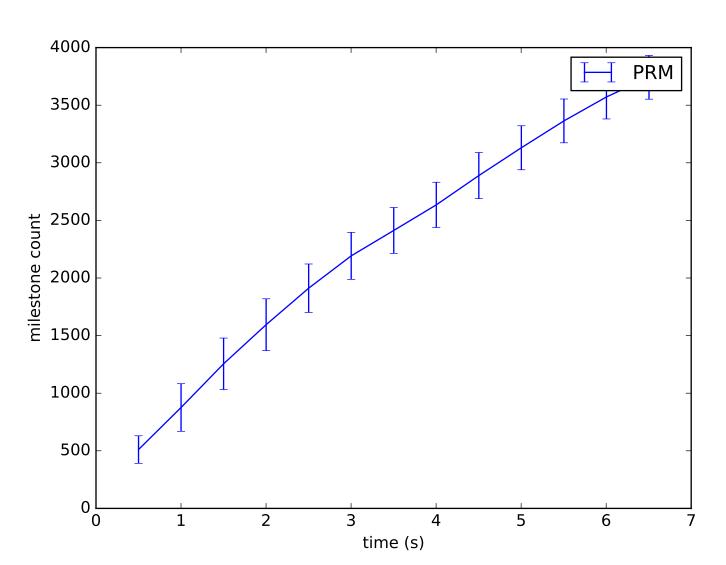


Motion planning algorithm









Experiment "KinematicChain"

Number of averaged runs: 20

Time limit per run: 60 seconds

Memory limit per run: 1024 MB