

# Contributions

## Andreas Huber

Andreas contributed to the project by assisting in the development of the algorithmn and also the development of the ros node. Andreas also had a key part in developing the final version of the algorithm.

## Filip Dilber

His contribution for the project contains the work on the inverse kinematic as well as the forward kinematic algorithmn, and the mathematical background for the calculations. He also helped the team through the debugging process to help reduce the number of errors we got while developing the code.

## Alexander Moser

He contributed to the project with the first draft of the inverse kinematics algorithm which had a lot of erros in it. Alexander also helped developing the final version of the inverse kinematic algorithm. Also he made sure that the infrastructure of the project is up and running (Git-Repo, Launch-Files, the node). This process made developing easier.