

1 Definitions

$$\underbrace{\nabla_{\mathbf{x}}}_{n \times 1} f = \begin{bmatrix} \frac{\partial f}{\partial x_1} \\ \vdots \\ \frac{\partial f}{\partial x_n} \end{bmatrix} \quad (1)$$

$$\underbrace{J_{\mathbf{x}}}_{m \times n} \underbrace{\mathbf{f}}_{m \times 1} = \begin{bmatrix} \frac{\partial f_1}{\partial x_1} & \cdots & \frac{\partial f_1}{\partial x_n} \\ \vdots & \ddots & \vdots \\ \frac{\partial f_m}{\partial x_1} & \cdots & \frac{\partial f_m}{\partial x_n} \end{bmatrix} = \begin{bmatrix} \frac{\partial \mathbf{f}}{\partial x_1} & \cdots & \frac{\partial \mathbf{f}}{\partial x_n} \end{bmatrix} = \begin{bmatrix} (\nabla_{\mathbf{x}} f_1)^T \\ \vdots \\ (\nabla_{\mathbf{x}} f_m)^T \end{bmatrix} \quad (2)$$

$$\underbrace{\nabla^2_{\mathbf{x}}}_{n \times n} f = \begin{bmatrix} \frac{\partial^2 f}{\partial x_1^2} & \cdots & \frac{\partial^2 f}{\partial x_1 \partial x_n} \\ \vdots & \ddots & \vdots \\ \frac{\partial^2 f}{\partial x_n \partial x_1} & \cdots & \frac{\partial^2 f}{\partial x_n^2} \end{bmatrix} = \begin{bmatrix} \nabla_{\mathbf{x}} \frac{\partial \mathbf{f}}{\partial x_1} & \cdots & \nabla_{\mathbf{x}} \frac{\partial \mathbf{f}}{\partial x_n} \end{bmatrix} = \begin{bmatrix} \left(\frac{\partial}{\partial x_1} \nabla_{\mathbf{x}} f \right)^T \\ \vdots \\ \left(\frac{\partial}{\partial x_n} \nabla_{\mathbf{x}} f \right)^T \end{bmatrix} \quad (3)$$

2 Matrix-Vector Derivatives

$$\underbrace{\nabla_{\mathbf{x}} \mathbf{a}^T}_{n \times 1} \underbrace{\mathbf{x}}_{n \times 1} = \underbrace{\mathbf{a}}_{n \times 1} \quad (4)$$

$$\underbrace{\nabla_{\mathbf{x}} \mathbf{x}^T}_{n \times 1} \underbrace{A}_{n \times n} \underbrace{\mathbf{x}}_{n \times 1} = \underbrace{(A + A^T)}_{n \times n} \underbrace{\mathbf{x}}_{n \times 1} \quad (5)$$

$$\underbrace{\nabla_{\mathbf{x}}^2 \mathbf{x}^T}_{1 \times n} \underbrace{A}_{n \times n} \underbrace{\mathbf{x}}_{n \times 1} = \underbrace{A + A^T}_{n \times n} \quad (6)$$

$$\underbrace{J_{\mathbf{x}}}_{m \times n} \underbrace{A}_{m \times n} \underbrace{\mathbf{x}}_{n \times 1} = \underbrace{A}_{m \times n} \quad (7)$$

$$\underbrace{\nabla_X \mathbf{a}^T}_{1 \times m} \underbrace{X}_{m \times n} \underbrace{\mathbf{b}}_{n \times 1} = \underbrace{\mathbf{a}}_{m \times 1} \underbrace{\mathbf{b}^T}_{1 \times n} \quad (8)$$

$$\underbrace{\nabla_X \mathbf{a}^T}_{1 \times n} \underbrace{X^T}_{m \times n} \underbrace{\mathbf{b}}_{m \times 1} = \underbrace{\mathbf{b}}_{m \times 1} \underbrace{\mathbf{a}^T}_{1 \times n} \quad (9)$$

$$\underbrace{\nabla_X \mathbf{a}^T}_{1 \times n} \underbrace{X}_{n \times m} \underbrace{D}_{m \times m} \underbrace{X}_{m \times n} \underbrace{\mathbf{b}}_{n \times 1} = \underbrace{D^T}_{m \times m} \underbrace{X}_{m \times n} \underbrace{\mathbf{a} \mathbf{b}^T}_{n \times n} + \underbrace{D}_{m \times m} \underbrace{X}_{m \times n} \underbrace{\mathbf{b} \mathbf{a}^T}_{n \times n} \quad (10)$$

$$\frac{\partial}{\partial x} |Y| = |Y| \operatorname{Tr} \left(Y^{-1} \frac{\partial Y}{\partial x} \right) \quad (11)$$

$$\frac{\partial}{\partial x} Y^{-1} = -Y^{-1} \frac{\partial Y}{\partial x} Y^{-1} \quad (12)$$

3 Product and Chain Rule

$$\underbrace{J_{\substack{\mathbf{x} \\ \uparrow \\ n \times 1}}}_{m \times n} \overset{m \times k}{\downarrow} C \substack{\mathbf{y} \\ \uparrow \\ k \times 1} = \underbrace{C}_{m \times k} \underbrace{J_{\mathbf{x}} \mathbf{y}}_{k \times n} \quad C \text{ is a constant} \quad (13)$$

$$\underbrace{J_{\substack{\mathbf{x} \\ \uparrow \\ n \times 1}}}_{m \times n} \substack{z \\ \uparrow \\ m \times 1} \substack{\mathbf{y} \\ \uparrow \\ m \times 1} = \underbrace{\mathbf{y}}_{m \times 1} \underbrace{(\nabla_{\mathbf{x}} z)^T}_{1 \times n} + z \underbrace{J_{\mathbf{x}} \mathbf{y}}_{m \times n} \quad (14)$$

$$\underbrace{\nabla_{\substack{\mathbf{x} \\ \uparrow \\ n \times 1}}}_{n \times 1} \overset{1 \times m}{\downarrow} \substack{\mathbf{y}^T \\ \uparrow \\ m \times 1} \substack{\mathbf{z} \\ \uparrow \\ m \times 1} = \underbrace{(J_{\mathbf{x}} \mathbf{y})^T}_{n \times m} \substack{\mathbf{z} \\ \uparrow \\ m \times 1} + \underbrace{(J_{\mathbf{x}} \mathbf{z})^T}_{n \times m} \substack{\mathbf{y} \\ \uparrow \\ m \times 1} \quad (15)$$

$$\underbrace{\frac{\partial}{\partial x} f(\mathbf{y})}_{1 \times 1} = \underbrace{(\nabla_{\mathbf{y}} f(\mathbf{y}))^T}_{1 \times k} \underbrace{\frac{\partial \mathbf{y}}{\partial x}}_{k \times 1} \quad (16)$$

$$\underbrace{\frac{\partial}{\partial x} \mathbf{f}}_{m \times 1} \substack{\substack{\downarrow \\ \mathbf{y}} \\ \uparrow \\ k \times 1} = \underbrace{(J_{\mathbf{y}} \mathbf{f}(\mathbf{y}))}_{m \times k} \underbrace{\frac{\partial \mathbf{y}}{\partial x}}_{k \times 1} \quad (17)$$

$$\underbrace{\nabla_{\substack{\mathbf{x} \\ \uparrow \\ n \times 1}}}_{n \times 1} \substack{f(\mathbf{y}) \\ \uparrow \\ m \times 1} = \underbrace{(J_{\mathbf{x}} \mathbf{y})^T}_{n \times m} \underbrace{\nabla_{\mathbf{y}} f(\mathbf{y})}_{m \times 1} \quad (18)$$

$$\underbrace{J_{\substack{\mathbf{x} \\ \uparrow \\ n \times 1}}}_{m \times n} \overset{m \times 1}{\downarrow} \substack{\mathbf{f} \\ \uparrow \\ k \times 1}(\mathbf{y}) = \underbrace{(J_{\mathbf{y}} \mathbf{f}(\mathbf{y}))}_{m \times k} \underbrace{J_{\mathbf{x}} \mathbf{y}}_{k \times n} \quad (19)$$