





- Construct a coarse grid over the volume (for example  $16^3$  voxels)
- Store minimum/maximum voxel values per resampled grid and test against transfer function





NYU

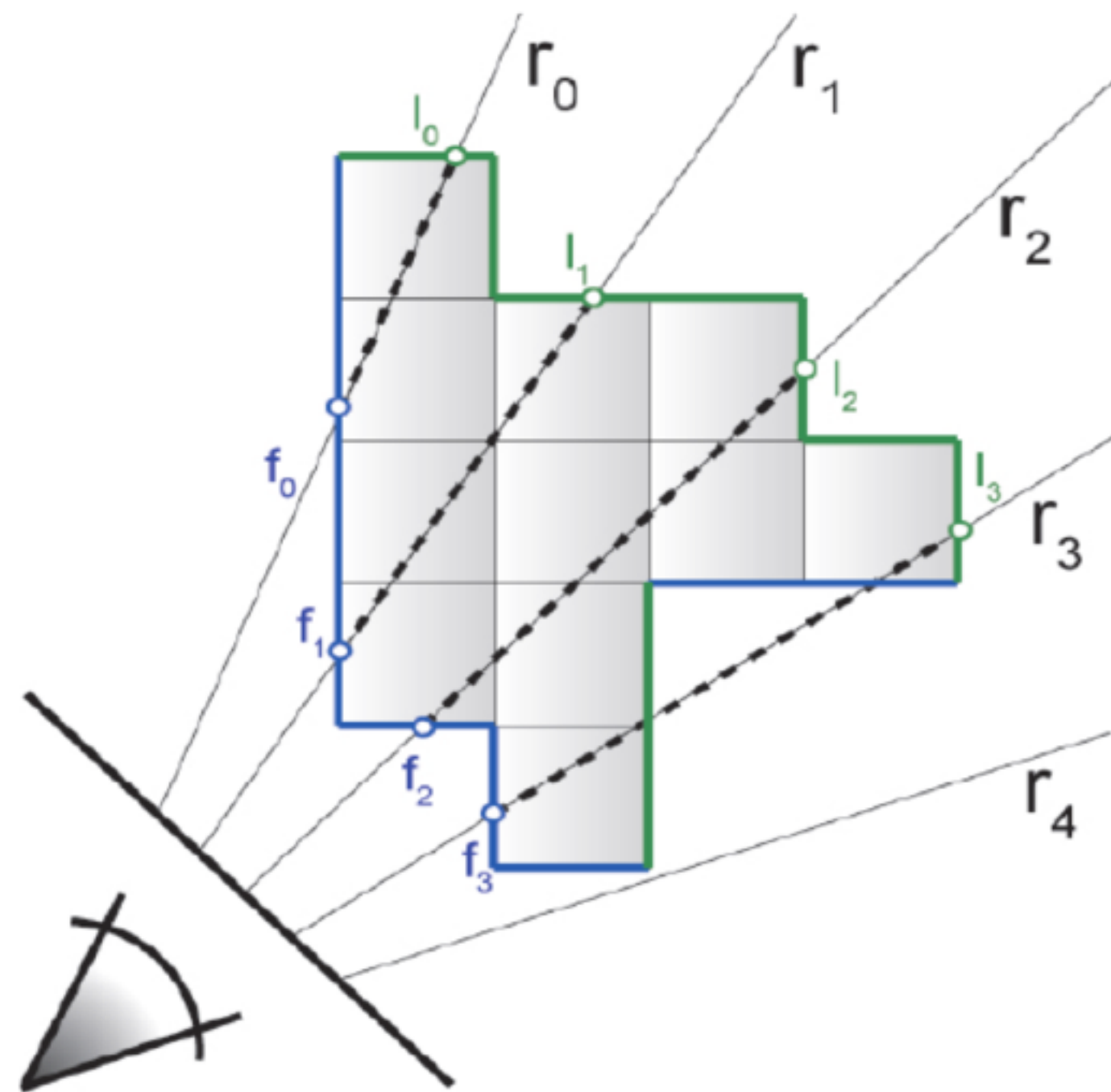
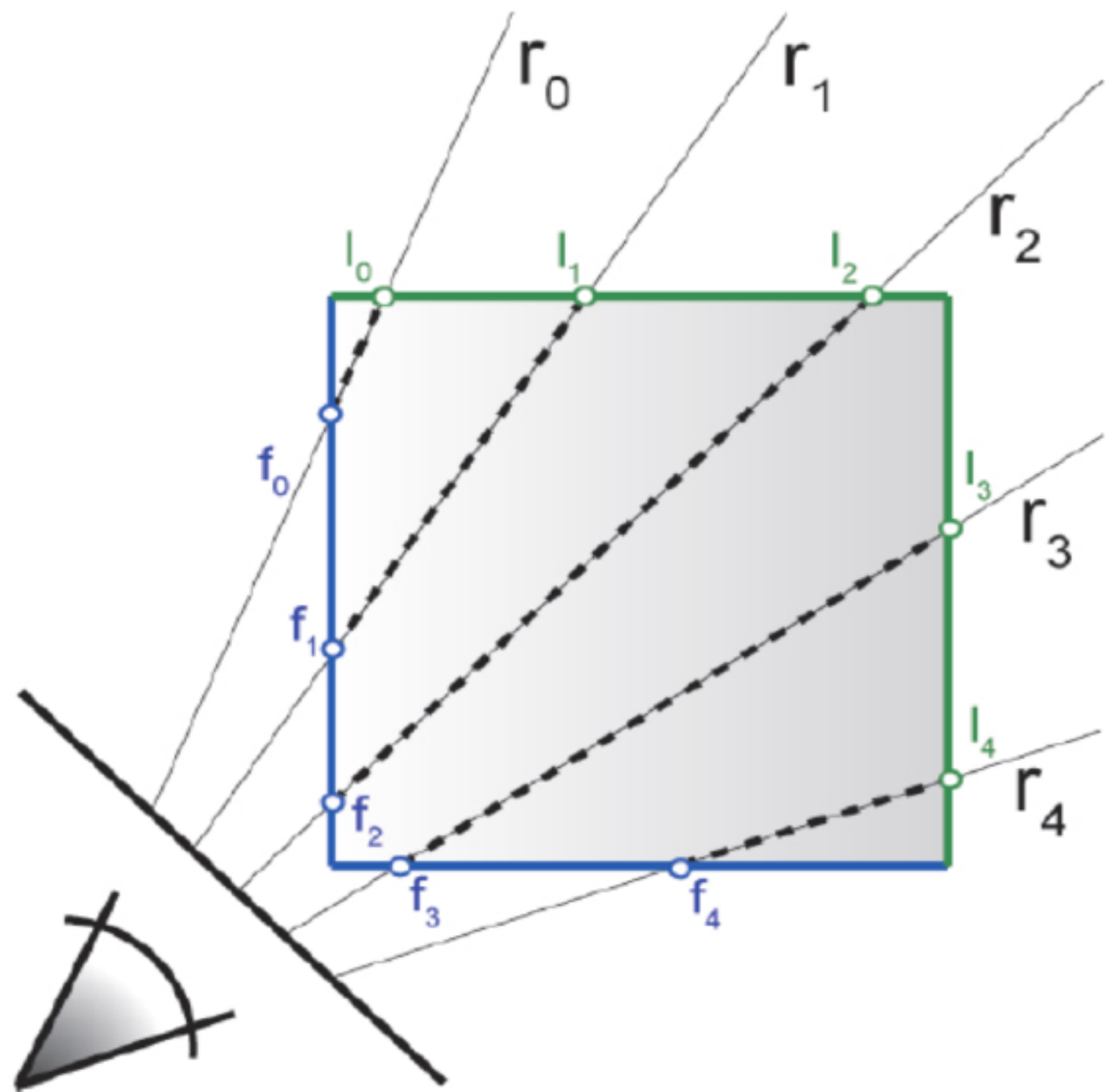






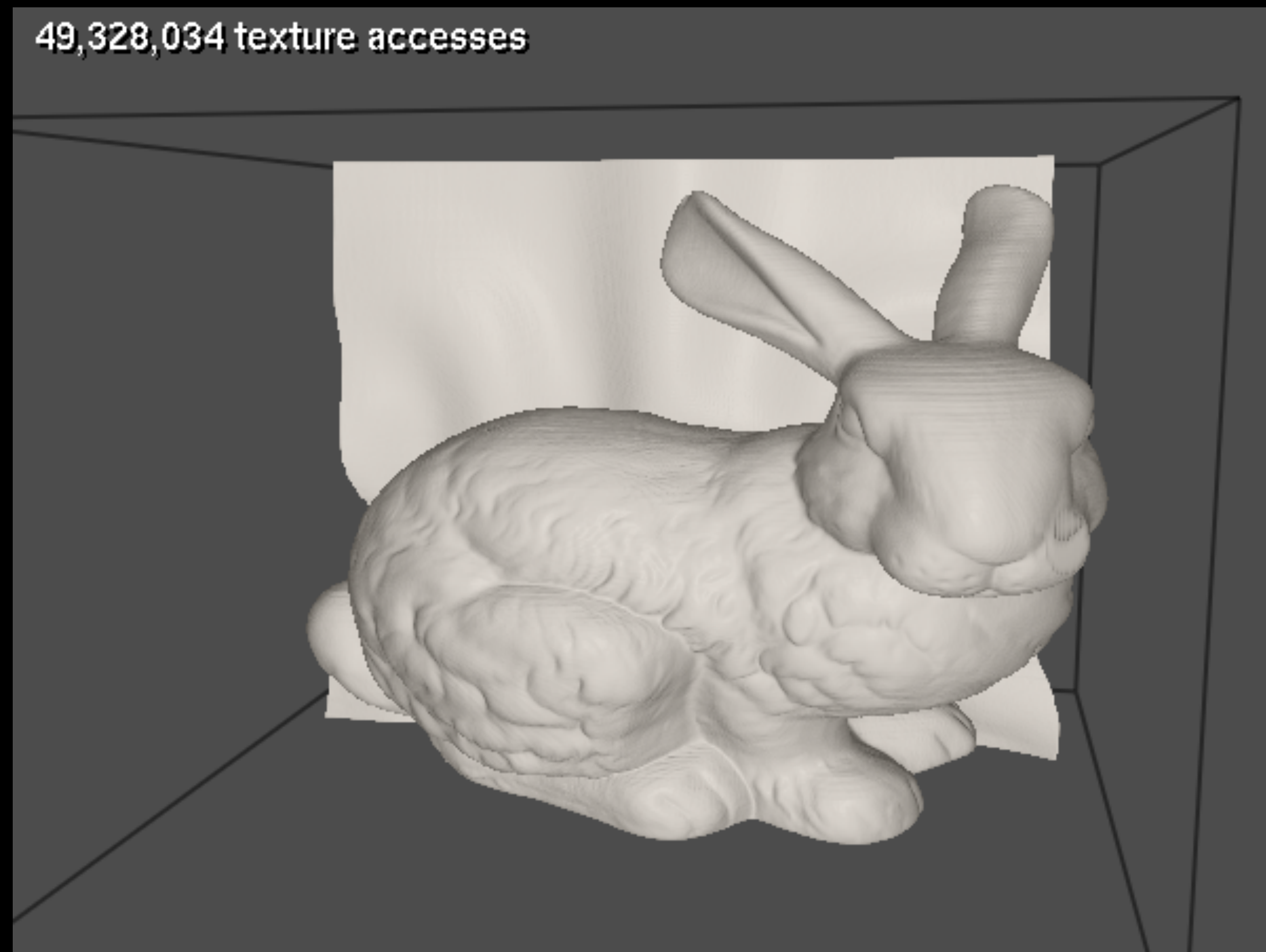






# OBJECT-ORDER EMPTY SPACE SKIPPING

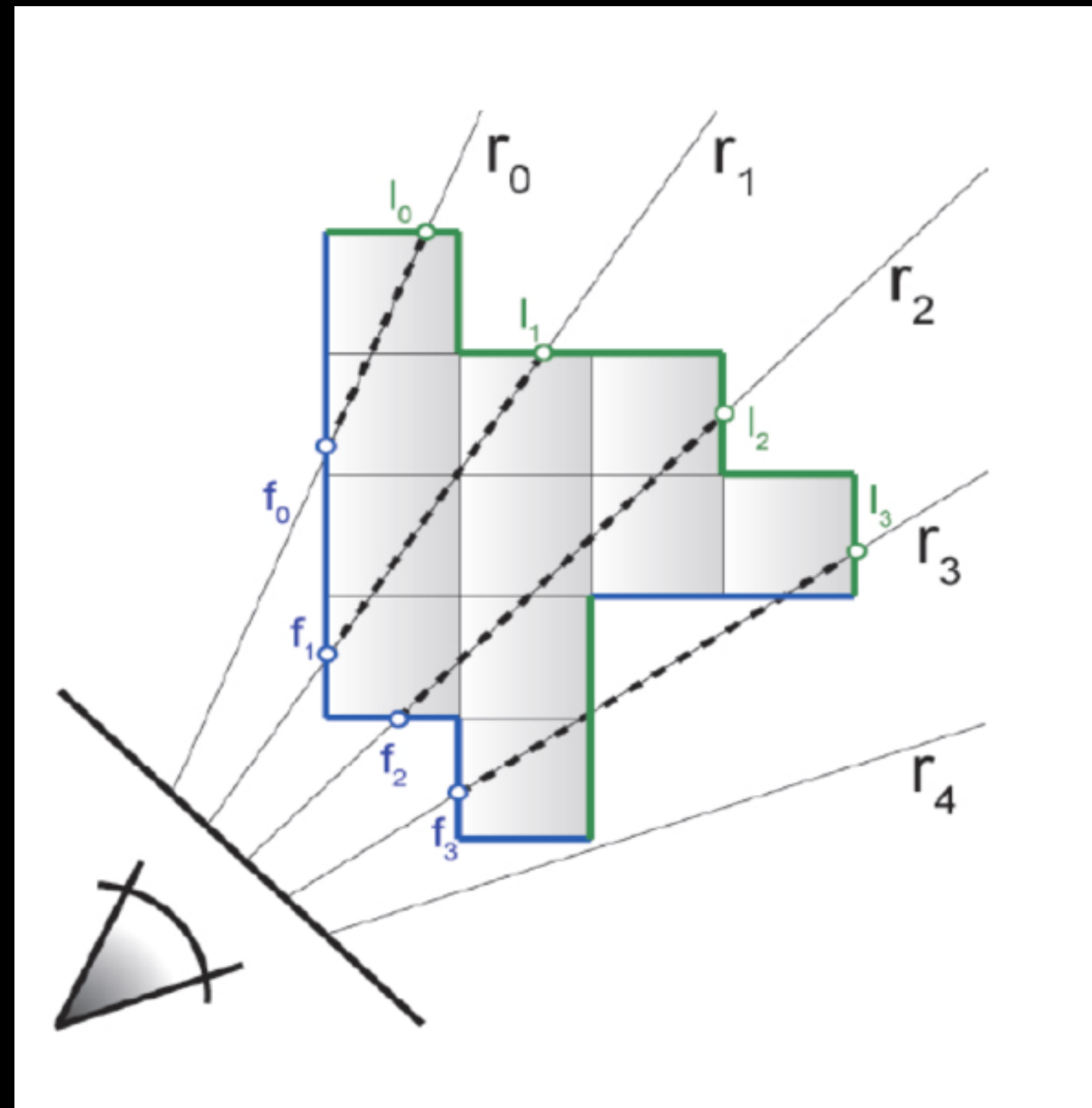
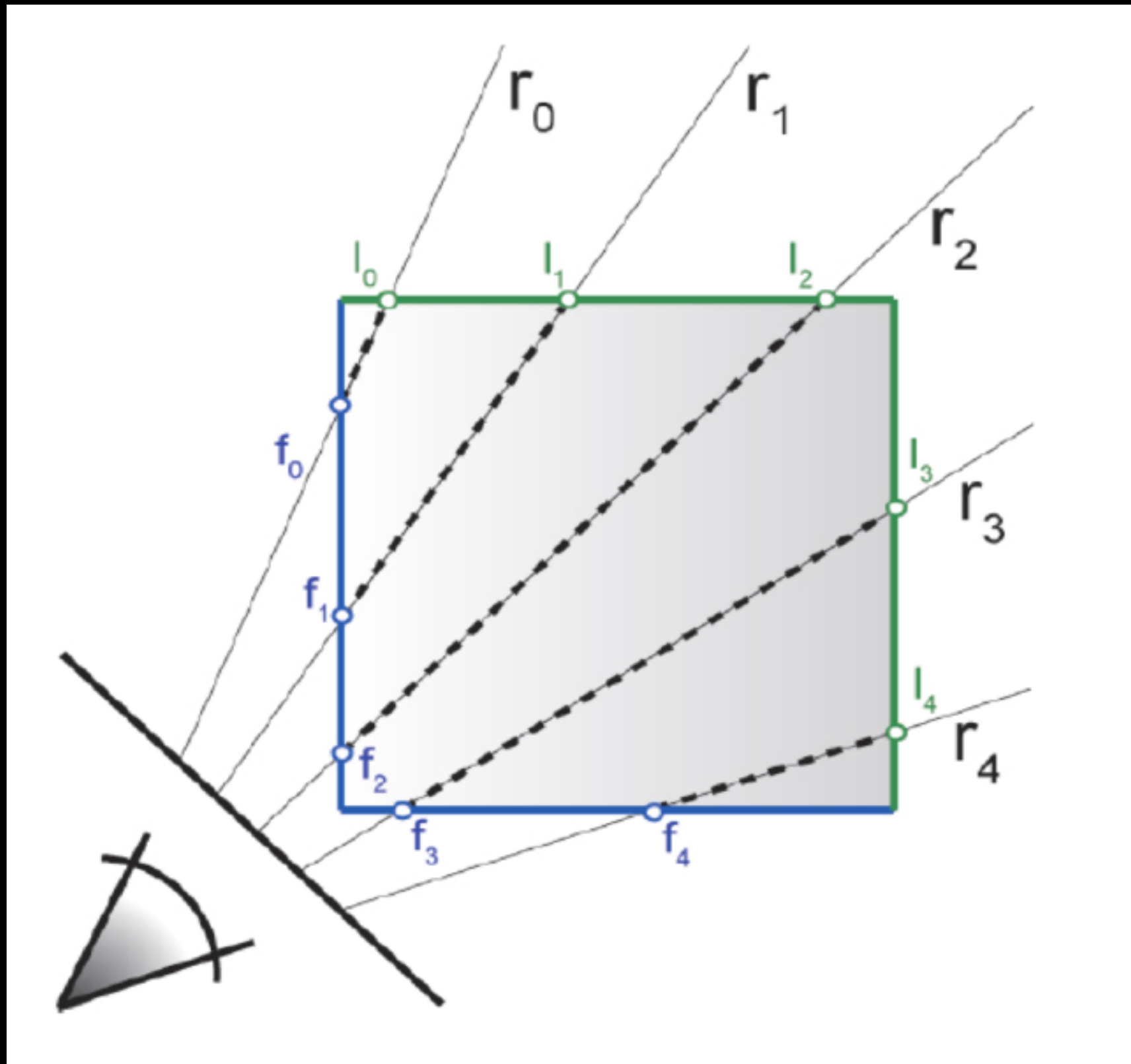
- Volume rendering



Images from <http://haferburg.github.io>

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Images from  
Stefan Bruckner