## temp\_model States Subsystem Beam Ball Beam1 Ball1 Global Configuration f(x) = 0Transform Center Transform Beam Transform Ball Solver Configuration Rigid Transform system\_states World Frame K\*u ◀ Integral Compensation u = Kx Mechanism Configuration 0 x ref e\_ss = (x\_ref - x\_1) printed 03-Dec-2024 12:24 page 1/1