

# Alexander Faché

afache3@gatech.edu | 650-933-0061 | Citizenship: USA, Belgium  
youtube.com/c/AlexFache | alexanderfache6.github.io | linkedin.com/in/alexanderfache

## OBJECTIVE

Master's electrical engineering student with a passion for drones seeking engaging full-time summer 2021 internship position within robotics, autonomy, and vision. Current coursework in non-linear systems & controls theory, computer vision, and image processing.

## EDUCATION

Georgia Institute of Technology (Georgia Tech) | Atlanta, GA

M.S., Electrical Engineering

01/2021 - Present

B.S., Electrical Engineering

08/2016 - 12/2020

- GPA: 3.83 / 4.00
- Minor: Computer Science - Intelligence, Robotics

## SKILLS

**Programming:** Python, Matlab, JavaScript, C, C++, Java, HTML/CSS

**Software:** Git, Jupyter, MongoDB, React.JS, MERN web stack, Heroku, Android Studio, ROS, Firebase, Inventor, Illustrator, Blender

**Hardware:** Arduino, Raspberry Pi, Pixhawk 4, soldering, benchtop electronics equipment

**Fabrication and Machining:** 3D printing, laser cutting, woodshop

**Coursework:** linear/non-linear systems and controls theory, image processing, computer vision, machine learning, game AI, convex optimization, data structures and algorithms

**Communication:** public speaking, technical presentations, technical writing, lead group discussions

**Interests:** quadcopter FPV flying, investing, ultimate frisbee (Division I), scuba diving (PADI open water certified)

**Spoken Languages:** English (native), Flemish (native)

**YouTube:** Drone tutorials, builds, flights. 350+ subscribers, 30,000+ views

## RESEARCH EXPERIENCE

Undergraduate Research Assistant | Intelligent Vision and Automation Laboratory (IVALab) | Georgia Tech 08/2018 - 04/2020

- PI: Dr. Patricio Vela, ivalab.gatech.edu
- Prototyped rectilinear motion primitive commands in Matlab for a robotic snake then transcribed to ROS-Python.
- Developed a head scan motion primitive to increase the field of view for increased SLAM keypoint detection.
- Tracked robotic snake with a Turtlebot Kobuki using web camera, magenta markers, linear and angular PID control.

## PUBLICATIONS

A. Faché, et al., "Marsupially-Aided Robotic Snake Exploration and Navigation of Cluttered Environments," in *Proc. Nat. Conf. Undergraduate Res.*, Kennesaw, GA, USA, Oct. 2019, pp. 526-536.

## INTERNSHIP EXPERIENCE

Software Engineering Intern - Avionics Integration | Bell Textron Inc | Fort Worth, TX 07 - 08/2020

- Researched air-launched effects integration requirements for FARA mission via technical data sheets and development meetings.
- Implemented and validated fuzz burn chip detect module through loopback testing for early engine failure warning for DCU.

R&D Intern - Center for Cyber Defenders | Sandia National Laboratories | Albuquerque, NM 05 - 07/2019

- Engineered functionality of an automated hardware tester to increase efficiency of chip testing and analysis for an internal lab.
- Constructed ontologies and developed natural language processing techniques to categorize and structure PDF data.

## PROJECTS

Workout planner using MERN full-stack web application framework | Personal Project 01/2021 - Present

- Learned, developed, and deployed a MERN web application on Heroku allowing logged in users to create and track workouts.

US Traffic Accidents and Weather Events Analysis | Machine Learning | Georgia Tech 02 - 04/2020

- Analyzed weather conditions and road factors to predict traffic accident crash severity using several supervised learning models.

Kidney Cancer Clinical Decision Support | Introduction to Medical Image Processing | Georgia Tech 02 - 04/2020

- Used patient tissue samples to perform preprocessing, feature extraction, and supervised learning to develop predictive models.

Property Management via Aerial Drone Imaging, Processing, Change Detection | ECE Capstone | Georgia Tech 01 - 12/2020

- Data capture via Parrot Anafi drone. Anomaly detection through preprocessing, image differencing, grass health score analysis.

PID Ball Balancer | Introduction to Automation and Robotics | Georgia Tech 10 - 12/2019

- Assembled and programmed 3-legged platform capable of stabilizing ping pong ball using camera feed input and PID control laws.

Freestyle FPV Quadcopter and Pixhawk 4 Autonomous Quadcopter | Personal Project 01/2019 - Present

- Built freestyle quadcopter. Built autonomous drone using Pixhawk 4 flight controller. Created complementary YouTube tutorials.

## LEADERSHIP

Peer Instructor | The Hive - Electrical and Computer Engineering Makerspace | Georgia Tech 09/2018 - Present

- Teach and assist students to use prototyping equipment and tools for hands-on projects and engineering development.