Dronezz

description

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Data

The images for this project were collected using a commerical Parrot Anafi quadcopter, utilizing the onboard color camera and Pix4Dcapture missiong planning. Each image was taken at an altitude of 40m resulting in a ground resultion of 1.34 cm/pixel. The area in question spans 79x82m resulting in 54 overlapping images that were combined to form a single image using Pix4Dmapper.

Histogram Normalized

Histogram normalization was applied to best remove the variation in brightness due to the Sun and clouds. Mission 2 was used as the reference mission for each normalization.

Bounding Boxes

text

Anomaly Detection

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Heatmaps

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Results

text