132. Freier Fall einer rotierenden Hantel

$$m_1 = 1 \text{ kg};$$

$$\vec{v}_1 = (4, 0, 0) \text{ m/s};$$

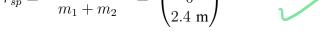
$$\vec{v}_1 = (4,0,0) \text{ m/s};$$
 $\vec{r}_1 = (0,0,2.5) \text{ m}$
 $\vec{v}_2 = (1,0,0) \text{ m/s};$ $\vec{r}_2 = (0,0,2.2) \text{ m}$

$$m_2 = 0.5 \text{ kg};$$

$$\vec{v}_2 = (1, 0, 0) \text{ m/s}$$

$$\vec{r}_2 = (0, 0, 2.2)$$
 m

$$\vec{r}_{sp} = \frac{m_1 r_1 + m_2 r_2}{m_1 + m_2} = \begin{pmatrix} 0\\0\\2.4 \text{ m} \end{pmatrix}$$



a) Im bewegten Bezugssystem, das sich mit 3 m/s mitbewegt reine Rotation

$$\Rightarrow \vec{r}_{sp}(t) = \begin{pmatrix} 0 \\ 0 \\ 2.4 \text{ m} \end{pmatrix} + \begin{pmatrix} 3 \text{ m/s} \\ 0 \\ 0 \end{pmatrix} t + \frac{1}{2} \begin{pmatrix} 0 \\ 0 \\ -9.81 \text{ m/s}^2 \end{pmatrix} t^2$$

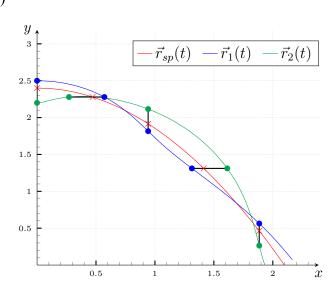


b) Im bewegten Bezugssystem: $\vec{v}_1 = (1, 0, 0) \text{ m/s}; \ \vec{v}_1 = (-2, 0, 0) \text{ m/s}$

$$\omega = \frac{|v_1|}{r_1} = \underline{\underline{10 \text{ s}}^{-1}}$$

$$T = \frac{2\pi}{\omega} = \frac{\pi}{5} = \underline{0.63 \text{ s}}$$

c)



d) Im Schwerpunktsystem:

$$\vec{r}_{1,sp}(t) = 0.1 \quad \begin{pmatrix} \sin(\omega t) \\ 0 \\ \cos(\omega t) \end{pmatrix} \text{ m}$$

$$\int \sin(\omega t) \lambda$$

$$\vec{r}_{2,sp}(t) = -0.2 \begin{pmatrix} \sin(\omega t) \\ 0 \\ \cos(\omega t) \end{pmatrix}$$
 m



Im Laborsystem:

$$\begin{split} \vec{r}_1(t) &= \vec{r}_{sp}(t) + \vec{r}_{1,sp}(t) \\ &= \underbrace{\begin{pmatrix} 0.1\sin(\omega t) \text{ m} \\ 0 \\ 0.1\cos(\omega t) \text{ m} + 2.4 \text{ m} \end{pmatrix}}_{0} + \underbrace{\begin{pmatrix} 3 \text{ m/s} \\ 0 \\ 0 \end{pmatrix}_{t} + \frac{1}{2} \begin{pmatrix} 0 \\ 0 \\ -9.81 \text{ m/s}^2 \end{pmatrix}_{t^2} \\ \vec{r}_2(t) &= \vec{r}_{sp}(t) + \vec{r}_{2,sp}(t) \\ &= \begin{pmatrix} -0.2\sin(\omega t) \text{ m} \\ 0 \\ -0.2\cos(\omega t) \text{ m} + 2.4 \text{ m} \end{pmatrix} + \begin{pmatrix} 3 \text{ m/s} \\ 0 \\ 0 \\ 0 \end{pmatrix} t + \frac{1}{2} \begin{pmatrix} 0 \\ 0 \\ -9.81 \text{ m/s}^2 \end{pmatrix} t^2 \end{split}$$

140. International Space Station

$$R_E = 6.37 * 10^6 \text{ m}; \quad m = 4.55 * 10^5 \text{ kg}; \quad h = 3.3 * 10^5 \text{ m}$$

a)
$$h = 0 \text{ m}$$

$$\begin{split} F_G &= mg \frac{1}{\left(1 + \frac{h}{R_E}\right)^2} \\ &= 4.55 * 10^5 \text{ kg} * 9.81 \text{ m/s}^2 \\ F_G &= \underbrace{4.46 * 10^6 \text{ kg m/s}^2}_{} \end{split}$$

b)
$$h = 3.3 * 10^5 \text{ m}$$

$$F_G = mg \frac{1}{\left(1 + \frac{h}{R_E}\right)^2}$$

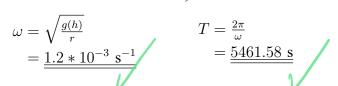
$$= 4.55 * 10^5 \text{ kg} * 9.81 \text{ m/s}^2 \frac{1}{\left(1 + \frac{3*10^5 \text{ m}}{6.37*10^6 \text{ m}}\right)}$$

$$F_G = \underbrace{4.03 * 10^6 \text{ kg m/s}^2}_{g(h) = \frac{g}{\left(1 + \frac{h}{R_E}\right)^2}}$$

$$g(3.3 * 10^5) = \underbrace{8.87 \text{ m/s}^2}_{g(3.3 * 10^5)}$$



$$v = r\omega; \quad a = \frac{v^2}{r} = r\omega^2; \quad r = R_E + h$$



$$T = \frac{2\pi}{\omega}$$
$$= \underline{5461.58 \text{ s}}$$

$$v = r\omega$$

$$= \underbrace{7707.91 \text{ m/s}}_{}$$

152. Komprimierter Metallblock

$$a = h = 0.2 \text{ m}$$

$$\Delta h = 1.3*10^{-6}~\mathrm{m} \qquad \quad m = 500~\mathrm{kg}$$

$$m = 500 \text{ kg}$$

$$V = 8 * 10^{-3} \text{ m}^3$$

$$\Delta V = 3 * 10^{-7} \text{ m}^3$$

$$V = 8*10^{-3} \; \mathrm{m}^3 \qquad \qquad \Delta V = 3*10^{-7} \; \mathrm{m}^3 \qquad \quad p = 2*10^6 \; \mathrm{kg/m} \, \mathrm{s}^2$$

a)
$$p = K \frac{\Delta V}{V}; \quad \frac{F}{A} = E \frac{\Delta h}{a}$$

$$K = p \frac{V}{\Delta V}$$

$$= \frac{\frac{16}{3} * 10^{10} \text{ kg/m s}^2}{V}$$

$$E = \frac{mga}{a^2 \Delta h}$$

= 1.89 * 10¹⁰ kg/m s²

fyi: Einheit der verschiedenen Module wird meist in N/m^2 angegeben.

b)
$$\Delta a = \mu \Delta h$$
 $K = \frac{E}{3(1-2\mu)}$

$$K = \frac{E}{3(1-2\mu)}$$

$$\frac{3K}{E} = \frac{1}{1-2\mu}$$

$$\mu = \frac{1}{2} - \frac{E}{6K}$$

$$= \underline{0.44}$$

$$\Delta a = \mu \Delta h$$
$$= \underline{5.73 * 10^{-7} \text{ m}}$$

