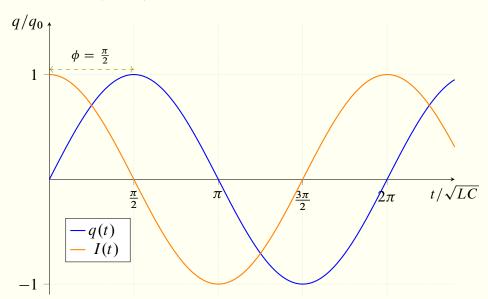
1. LC-Schaltkreis mit/ohne Wechselstrom

(a)

$$\frac{q(t)}{C} = L \frac{\mathrm{d}^2 q}{\mathrm{d}t^2}$$
$$q(t) = q_0 \cos\left(\frac{1}{\sqrt{LC}}t\right)$$



(b)
$$U(t) = U_{max} \cos(\omega t); \quad U_{max} = 100 \text{ V}$$

$$I_L = \underline{\frac{U_0}{L\omega}}$$

$$I_C = \frac{\overline{\underline{U_0 C \omega}}}{\underline{\psi_L}}$$

$$\phi_L = \frac{\pi}{\underline{\underline{2}}}$$

$$\phi_L = -\frac{\pi}{\underline{2}}$$

$$\phi_L = \frac{\pi}{2}$$

$$\phi_L = \frac{\pi}{2}$$

$$\omega L = \frac{1}{\omega C}$$

$$\omega = \sqrt{\frac{1}{cL}} = 100 \text{ s}$$

$$I_C(t) = -U_0 C \omega \sin(\omega t)$$

$$I_C(t) = \frac{-U_0 C \omega \sin(\omega t)}{U_0 \sin(\omega t)}$$

$$I_L(t) = \frac{U_0}{L \omega} \sin(\omega t)$$

2. Serienschwingkreis

$$L = 0.1 \text{ H}; \quad R = 100 \Omega; \quad C = 0.47 \text{ }\mu\text{F}; \quad U_0 = 3 \text{ V}$$

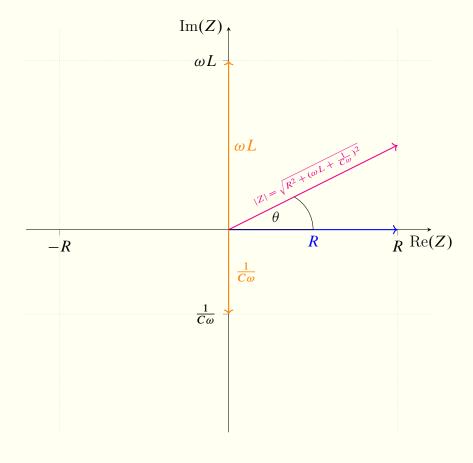
(a)
$$U(t) = U_0 e^{i\omega t}; \quad q(t) = \frac{I_0}{\omega i} e^{i\omega t}$$

$$U(t) = R \frac{dq}{dt} + \frac{q(t)}{C} + L \frac{d^2 q}{dt^2}$$

$$U_0 = RI_0 + \frac{I_0}{\omega iC} + LI_0 \omega i$$

$$I_0 = \frac{U_0}{R + L\omega i - \frac{i}{\omega C}}$$

(b)
$$Z = \frac{U}{I} = R + L\omega i - \frac{i}{\omega C} = R + i \left(\omega L - \frac{1}{C\omega}\right)$$

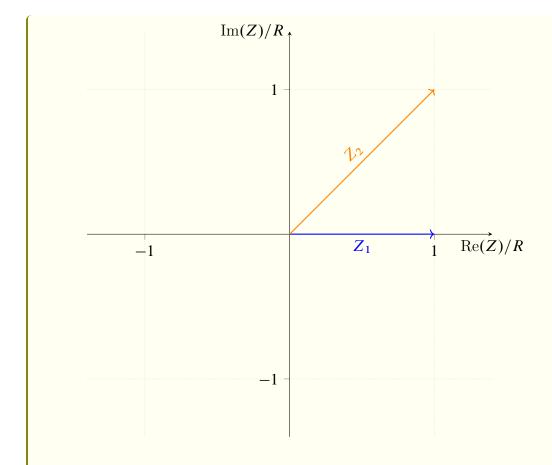


For:
$$\omega L = \frac{1}{C\omega}$$

For:
$$R = \omega L - \frac{1}{C\omega}$$

$$\Rightarrow$$
 $Z_1 = R$

$$\Rightarrow Z_2 = R + i R$$



(c)

$$\operatorname{Im}(Z) = 0 \quad \Rightarrow \quad \omega L = \frac{1}{C\omega}$$

$$\omega = \sqrt{\frac{1}{cL}} = 4612.67 \text{ s}$$

$$\phi = \frac{\pi}{2}$$

3. Elektrische Verschiebung

$$\epsilon_1 = 2; \quad \epsilon_2 = 1.5$$

(a)

$$\vec{D}_1 = \vec{D}_2 = \underline{\underline{\sigma}\hat{z}}$$

(b)

$$\vec{E}_1 = \frac{\vec{D}_1}{\epsilon_1} = \underbrace{\frac{\sigma}{\epsilon_1} \hat{z}}_{\underline{\epsilon_1}}$$

$$\vec{E}_2 = \underbrace{\frac{\vec{D}_2}{\epsilon_2}}_{\underline{\epsilon_2}} = \underbrace{\frac{\sigma}{\epsilon_2} \hat{z}}_{\underline{\epsilon_2}}$$

(c)

$$\vec{P}_1 = \vec{D}_1 - \epsilon_0 \vec{E}_1 = \underbrace{\frac{\sigma(1 - \frac{\epsilon_0}{\epsilon_1})\hat{z}}{\vec{E}_1}}_{\vec{P}_1 = \vec{D}_1 - \epsilon_0 \vec{E}_1 = \underbrace{\frac{\sigma(1 - \frac{\epsilon_0}{\epsilon_1})\hat{z}}{\sigma(1 - \frac{\epsilon_0}{\epsilon_1})\hat{z}}}_{\vec{E}_1 = \underbrace{\vec{E}_1 - \frac{\epsilon_0}{\epsilon_1}\hat{z}}$$

(d)

$$C = \frac{1}{\frac{a}{A\epsilon_1} + \frac{a}{A\epsilon_2}} = \frac{A\epsilon_1\epsilon_2}{a(\epsilon_1 + \epsilon_2)}$$

$$U = \frac{Q}{C} = \underbrace{\sigma \frac{a(\epsilon_1 + \epsilon_2)}{\epsilon_1\epsilon_2}}_{\epsilon_1\epsilon_2}$$

(e)

(f)