FP1: EOM, extra notes, by Bo Huang

Polarization of medium

We consider the polarisation density induced linearly by E field. P:= Eo X E; then X is a 3×3 Tensor.

Pi=InijEj &

$$\vec{D} := P + \Sigma \vec{E} = \mathcal{E}_0 (\vec{I} + \vec{\bar{\chi}}) \cdot \vec{E} := \mathcal{E}_0 \cdot \vec{E}$$

$$\vec{P}_i = \mathcal{E}_0 \mathcal{E}_{ij} \cdot \vec{E}_j$$

$$\vec{P}_i = \mathcal{E}_0 \mathcal{E}_{ij} \cdot \vec{E}_j$$

for symmetric Ei, we can diagonalise it as. $\stackrel{=}{\xi} = \begin{pmatrix} \xi_{11} & 0 & 0 \\ 0 & \xi_{22} & 0 \\ 0 & 0 & \xi_{33} \end{pmatrix} \text{ with a proper choice of coordinates.}$

Then $D_i = \mathcal{E}_0 \ \mathcal{E}_{ij} \ \mathcal{E}_{j}$

The corresponding Maxwell egns, and wave equation:

(2)
$$\nabla \cdot \vec{B} = 0$$

(3) $\nabla \times \vec{E} = -\frac{\partial \vec{B}}{\partial t}$ | ignore magnetisation

$$\begin{cases} i \vec{k} \times \vec{E} = i \omega \vec{B} \\ i \vec{k} \times \vec{B} = -i \omega \quad \mu_0 \mathcal{E}_0 \vec{E} \cdot \vec{E} \end{cases} ; \quad c^2 = \frac{1}{\mu_0 \mathcal{E}_0}$$

$$= \frac{1}{2} \times (2 \times \overline{E}) = -\frac{\omega^2}{C^2} = \overline{E} \cdot \overline{E} ,$$

$$=) \mathcal{L}(\mathcal{L} \cdot \dot{\mathcal{E}}) - \dot{\mathcal{E}} k^{2} = -\frac{\omega^{2}}{c^{2}} \dot{\mathcal{E}} \cdot \dot{\mathcal{E}}; \quad \mathcal{L} = k \dot{\mathcal{I}}; \quad |\dot{\mathcal{I}}| = 1$$

$$=) \left(\hat{\mathcal{I}} \dot{\hat{\mathcal{I}}} - \dot{\mathcal{I}} + \frac{\dot{\mathcal{E}}}{n^{2}} \right) \cdot \dot{\mathcal{E}} = 0 \qquad \qquad \frac{\omega^{2}}{k^{2}} \dot{\mathcal{L}} := n^{-2}$$

2022 FP1 Page 1

given \hat{q} , the direction of \bar{k} , we need $\bar{E} \neq 0$, so: $\det \left| \hat{q} \hat{q} - \bar{I} + \frac{\bar{E}}{n^2} \right| = 0 \iff \text{equation for } \mathcal{N}(\hat{q})$

In general, $\nabla \cdot \vec{D} = P_{\text{free}}$; if $P_{\text{free}} = 0$, we get $i\vec{k} \cdot \vec{D} = 0$; $\vec{k} \perp \vec{D}$ Define $\gamma = \varepsilon^{-1}$ where $: \begin{cases} \vec{D} = \varepsilon_0 \bar{\varepsilon} \cdot \vec{E} \\ \vec{E} = \varepsilon_0^{-1} \bar{\eta} \cdot \vec{D} \end{cases}$

choose the coordinates which diagonalize \vec{E} ; then $\tilde{\xi} = \begin{pmatrix} \xi_1 & 0 & 0 \\ 0 & \xi_2 & 0 \\ 0 & D & \xi_3 \end{pmatrix} \quad \text{and} \quad \tilde{\eta} = \begin{pmatrix} \xi_1^{-1} & 0 & 0 \\ 0 & \xi_2^{-1} & 0 \\ 0 & 0 & \xi_3^{-1} \end{pmatrix} = \begin{pmatrix} \eta_1 & 0 & 0 \\ 0 & \eta_2 & 0 \\ 0 & 0 & \eta_3 \end{pmatrix}$ $\hat{q}\hat{q} \cdot \vec{E} - \vec{E} + \frac{\vec{D}/\xi_0}{n^2} = 0 \qquad \Rightarrow \qquad \vec{D} \cdot \vec{E}\xi + \frac{|\vec{D}|^2}{n^2} = 0$ set $|\vec{D}|^2 = 1$, $\vec{D} = (D_1, P_2, P_3)$

 $\vdots \quad \vec{D} \cdot \vec{\eta} \cdot \vec{D} = \frac{1}{n^2} \Rightarrow \frac{3}{i^{-1}} D_i^2 J_i = \frac{1}{n^2} \quad \text{or} \quad \frac{3}{i^{-1}} D_i^2 / \mathcal{E}_i = \frac{1}{n^2}$

many people write $|\hat{D}|=1$ and $\hat{D}=(x, y, Z)$

and:

 $\frac{\chi^{2}}{\xi_{II}} + \frac{y^{2}}{\xi_{zz}} + \frac{3^{2}}{\xi_{zz}} = \frac{1}{n^{2}} \quad \text{or} \quad \frac{\chi^{2}}{n_{x}^{2}} + \frac{y^{2}}{n_{y}^{2}} + \frac{3^{2}}{n_{x}^{2}} = \frac{1}{n^{2}}$

where $N_i^2 = \epsilon_{ii}$. This is the "Index Ellipsoid".

With this Ellipsoid, we can calculate n from the direction of $\vec{D} = (x, y, z)$ and (n_x, n_y, n_z) of the material. Note: $\vec{D} \perp \vec{R}$

For Example, $n_x = n_y = n_o$; $n_z = n_e$.

In this case, 3 is the symmetry axis. If we apply a static (much slower than optical frequency) field E along 3, The leading terms of new Ne and No are:

 $\begin{array}{lll} \bigcap_{e} = n_{e} + \frac{1}{2} \sum_{e} n_{e}^{3} E_{z} & \text{ there we assume no "mixing" included} \\ \bigcap_{e} = n_{o} + \frac{1}{2} \sum_{e} n_{o}^{3} E_{z} & \text{ by } E_{z}, i.e. \text{ no off-diagonal terms} \\ & \text{ in } \overline{\epsilon}. & \\ & 1_{s+} \text{ Taylor term} \end{array}$

Further Examples.

Direction-dependened Refractive Index:

$$M := \begin{pmatrix} q^{2} & q_{1}q_{2} & q_{2}q_{3} \\ q_{1}q_{1} & q^{2} & q_{2}q_{3} \\ q_{3}q_{1} & q_{3}q_{2} & q^{2} \\ q_{3}q_{1} & q_{3}q_{2} & q^{2} \end{pmatrix} - I + \frac{1}{n^{2}} \begin{pmatrix} \mathcal{E}_{11} & \circ & \circ \\ \circ & \mathcal{E}_{22} & \circ \\ \circ & \circ & \mathcal{E}_{23} \end{pmatrix}; \quad note : \mathcal{E}_{11} = \mathcal{N}_{1}^{2}$$

$$\mathcal{E}_{22} = \mathcal{N}_{2}^{2}$$

$$\mathcal{E}_{33} = \mathcal{N}_{3}^{2}$$

we want. $\vec{H} \cdot \vec{E} = 0$, but $\vec{E} \neq 0$

Consider
$$\mathcal{E}_{11} \neq \mathcal{E}_{22} = \mathcal{E}_{33}$$

$$\stackrel{?}{R} // \stackrel{?}{q} = \begin{pmatrix} \cos \theta \\ \sin \theta \\ 0 \end{pmatrix}$$

$$M = \begin{pmatrix} -\sin^2 \theta & \sin \theta \cdot \cos \theta & 0 \\ \sin \theta \cdot \cos \theta & -\cos^2 \theta & 0 \\ 0 & 0 & -1 \end{pmatrix} + \frac{1}{n^2} \begin{pmatrix} \xi_{11} \\ \xi_{22} \\ \xi_{22} \end{pmatrix}$$

Case I:
$$\overrightarrow{E} = \begin{pmatrix} 0 \\ 0 \\ E \end{pmatrix}$$
 $\underbrace{\mathcal{E}_{11} = \mathcal{N}_1^2}_{\mathcal{E}_{22} = \mathcal{N}_2^2}$

$$\mathcal{E}_{zz} = n_z^2$$

$$M.E=0$$
 =) $\frac{\mathcal{E}_{zz}}{n^2}=1$ =) $n=n_z^2$

Case I:
$$E = \begin{pmatrix} E_1 \\ E_2 \\ 0 \end{pmatrix}$$

$$M \cdot E = 0 =$$
 $\begin{vmatrix} -\sin^2\theta + \frac{N_1^2}{N^2} & \sin\theta\cos\theta \\ \sin\theta\cdot\cos\theta & -\cos^2\theta + \frac{N_2^2}{N^2} \end{vmatrix} = 0$

$$=) \frac{\sin^2 0}{\eta_1^2} + \frac{\cos^2 0}{\eta_2^2} = \frac{1}{\eta_{(\theta)}^2}$$

$$if \theta = 0 \qquad \eta^2 = n_2^2$$

$$\theta = \frac{\pi}{2}$$
 $n^2 = n_1^2$

