
Deep Reinforcement Learning to Minimize Long-Term Carbon Emissions and Electricity Cost in the Investment of Electricity Generation

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Abstract

A transition from a high-carbon emitting electricity power system to one based on renewables would aid in the mitigation of climate change. Decarbonization of the electricity grid would allow for low-carbon heating, cooling and transport. Investments in renewable energy, however, must be made over a long time horizon, with various uncertainties in future electricity demand and costs to consumers and investors.

To account for imperfect information of the future, we use the deep deterministic policy gradient (DDPG) deep reinforcement learning approach to optimize for a low-cost, low-carbon electricity supply using a modified version of the FTT:Power model. The DDPG algorithm is able to learn the optimum electricity mix through experience and achieves this between the years of 2017 and 2050. We find that a transition from fossil fuels and nuclear power to renewables, based upon wind, solar and wave would provide a cheap and low-carbon alternative.

1 Introduction

A transition from a high carbon electricity supply to a low-carbon system is central to avoiding catastrophic climate change [1]. A low-carbon electricity supply will aid in the decarbonization of the automotive and heating sectors. Such a transition must be made in a gradual approach to maintain grid reliability [2].

Renewable energy costs, such as solar and wind energy, have dropped recently, making them cost-competitive with fossil fuels. These price drops are projected to continue [3]. The future cost of generation, demand and fuel prices, however, remain uncertain over the long-term future. These uncertainties are risks which investors must analyze while making long-term investment decisions.

In this paper, we use the deep deterministic policy gradient (DDPG) reinforcement learning algorithm to simulate the behaviour of investors over a 33-year horizon, between 2017 and 2050 [4]. We started in the year 2017 due to the prior parameterization of the FTT:Power model. We projected until 2050 due to the fact that this is a frequent target for governments to reach zero carbon. The environment used was a modified version of the FTT:Power model [5]. FTT:Power is a global power systems model that uses logistic differential equations to simulate technology switching.

We modified the FTT:Power model to use the DDPG algorithm in place of the logistic differential equations to simulate investment decisions. In addition to this, we simulated two countries: the United Kingdom and Ireland. This was achieved through the use of the same FTT:Power model. We choose these due to the wealth of prior work on these countries which we can use for comparison [6, 7]. The DDPG algorithm allows us to simulate the decisions made by investors under imperfect

34 information over a 33-year period. This work enabled us to see whether a low-carbon mix is possible
35 over the next 33-years to avert climate change.

36 Prior work in this domain has tackled the capacity expansion problem. For example, Oliveira *et*
37 *al.* also use reinforcement learning for the capacity expansion problem [8]. They, however, focus
38 on a 20-year time horizon. Kazempour *et al.* use a mixed integer linear programming approach to
39 solve the generation investment problem [9]. Our approach is in contrast to a mixed-integer linear
40 programming problem, where full knowledge of the time-horizon is required. In our work, we address
41 a gap in the literature for the capacity expansion problem over a 33 year time period using deep
42 reinforcement learning to reduce both carbon emissions and electricity price.

43 Through this work, it is possible to assess whether a low cost, low-carbon electricity mix is viable
44 over the long-term using a deep reinforcement learning investment algorithm, as well as finding what
45 this optimum mix should be. This work enables us to closely match the investment behaviour of
46 rational agents, without knowledge of the future. It can help guide investors on which technologies to
47 invest in over the long-term, as well as the proportions to invest in.

48 2 Model and methodology

49 In this paper, we used the Future Technology Transformations for the power sector model (FTT:Power)
50 [5]. This model represents global power systems based on market competition, induced technological
51 change and natural resource use and depletion. Induced technological change occurs through
52 technological learning produced by cumulative investment and leads to nonlinear path dependent
53 technological transitions [5]. The model uses a dynamic set of logistic differential equations for
54 competition between technology options.

55 For this work we modified the FTT:Power model to use the deep reinforcement learning investment
56 algorithm, DDPG. That is, the size of the investment made in each technology was made by the
57 DDPG algorithm. In addition, we reduced the model to only consider the countries of Ireland and the
58 UK. This enabled us to iterate through enough episodes for the reinforcement learning to converge to
59 an optimal reward. With more time, however, it would be possible to undertake this optimisation for
60 the whole world.

61 Reinforcement Learning

62 The investment decision-making process can be formulated as a Markov Decision Process (MDP)
63 [10]. In an MDP environment, an agent receives an observation about the state of their environment
64 s_t , chooses an action a_t and receives a reward r_t as a consequence of their action and the resultant
65 change on the environment. Solving an MDP consists of maximizing the cumulative reward over the
66 lifetime of the agent.

67 For our simulation environment, the agent makes a continuous investment decision for each energy
68 technology, in each region and each year, starting from 2017 until 2050. Technology switching is
69 modelled using a pairwise comparison of flows of market shares of different electricity generation
70 capacity. That is, how much capacity flows from one technology to another.

71 The agent's observation space is a vector consisting of the electricity produced by each technology,
72 total capacity, total CO₂ emissions over the simulation, levelized cost of electricity (LCOE) including
73 both taxes and without taxes, cumulative investment in each technology, investment in new capacity,
74 carrier prices by commodity, fuel costs and carbon costs.

75 The reward r is defined as:

$$r = - \left(1000 \times \text{CO}_{2e} + \frac{\text{LCOE}}{1000} \right), \quad (1)$$

76 where CO_{2e} is equal to total CO₂ emissions over the simulation The LCOE is calculated without
77 taxes. The scaling factors are used to place the LCOE and CO₂ on the same scale. The reward was
78 multiplied by -1 due to the RL algorithm maximizing reward and our requirement to reduce both
79 LCOE and CO₂ emissions.

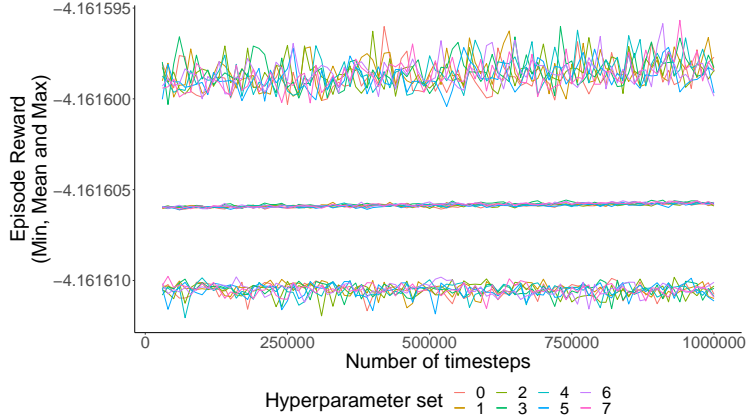


Figure 1: Training with different hyperparameters, displaying the minimum, mean and maximum rewards per episode.

80 RL approaches have been used to solve MDP [11]. In recent times, however, RL has been extended to
 81 incorporate Deep Reinforcement Learning (DRL). DRL relies on deep neural networks to overcome
 82 the problems of memory complexity and computational complexity [12].

83 We applied the deep deterministic policy gradient (DDPG) DRL algorithm [4] from the Ray RLlib
 84 package [13]. The DDPG algorithm is made up of an actor and critic network. We designed both
 85 of these to have two hidden layers, made up of 400 and 300 units per layer. The training batch size
 86 was set to 40,000. We chose these parameters as they were the default implementation in Ray RLlib.
 87 We trialled a variety of different configurations for number of neurons per layer. To increase speed
 88 of computation, we reduced the simulation to run from 2007 to 2017. We chose this number as it
 89 would allow for a transition in electricity mix. However, we found that the approach worked well
 90 irrespective of parameter choice, as shown by Figure 1.

91 3 Results

92 Our results show that our investment agent is able to increase its reward over time, as shown in Figure
 93 2. A total of $\sim 400,000$ steps were required to see a levelling off in reward. The total time taken to
 94 simulate $\sim 400,000$ steps was ~ 8 days. We stopped the training and simulation after this time due to
 95 diminishing returns and the cost of computation.

96 Figure 3 displays the results of reinforcement learning algorithm. Before the black vertical line
 97 (2017), the investments made are based upon historical data used by FTT:Power. The reinforcement
 98 learning algorithm starts to make investments after the black vertical line.

99 The historical electricity mix before 2017 is largely based on fossil fuels: coal, combined cycle gas
 100 turbine (CCGT) and oil. Additionally, nuclear is a major component of the electricity mix before
 101 2009. After reinforcement learning optimizes for LCOE and carbon emissions, a rapid transition
 102 occurs from fossil fuel and nuclear to renewable energy.

103 This rapid transition occurs due to the reinforcement learning algorithm not taking into account the
 104 technical and timeframe constraints embedded in the unmodified FTT:Power model. However, whilst
 105 it is likely that whilst the transition speed is unrealistic, the electricity mix found by the reinforcement
 106 learning algorithm is likely to be optimal, according to the reward function defined in Equation 1.

107 The primary source of energy after the reinforcement learning algorithm begins is offshore, followed
 108 by onshore, solar photovoltaics (PV) and wave. As can be seen by Figure 4, the carbon emissions
 109 reduce significantly at the time that the reinforcement learning algorithm begins to control investments.

110 This mix of renewable electricity generation across Ireland and the UK allows for demand to be met
 111 during the quarterly time periods of the model. The demand scenario is shown in Figure 5, where the
 112 demand can be seen to closely match the electricity mix shown by Figure 3.

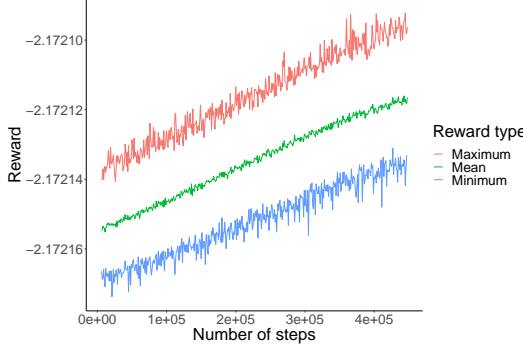


Figure 2: Mean, minimum and maximum rewards over run time.

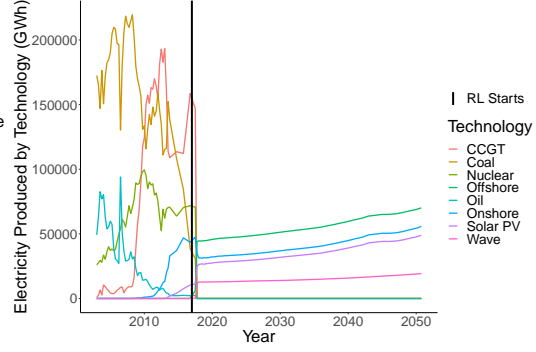


Figure 3: Electricity mix over time.

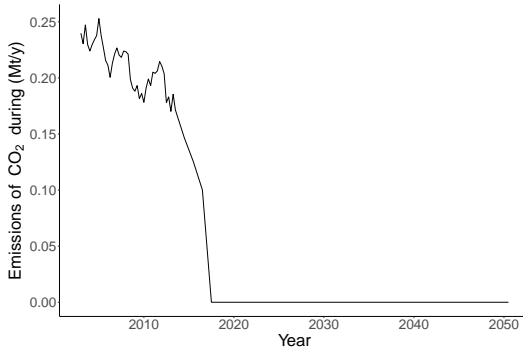


Figure 4: Carbon emissions.

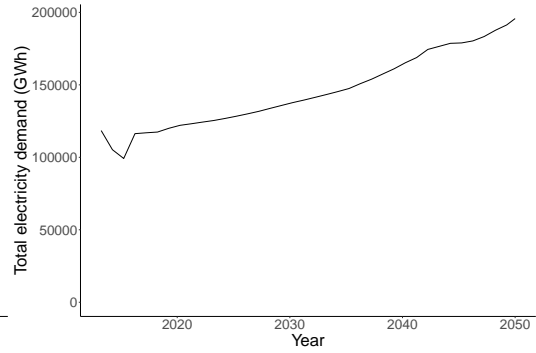


Figure 5: Demand scenario over simulation.

113 4 Discussion

114 A transition from a high carbon-emitting electricity grid to a low-carbon system is required. In order
 115 to achieve this, investments in electricity generators must be made whilst taking into account future
 116 uncertainty. In this paper, we have modelled a central agent which makes investment decisions in an
 117 uncertain environment to find an optimal low-cost, low-carbon electricity mix. To achieve this, we
 118 used the reinforcement learning algorithm, DDPG. The environment is modelled using FTT:Power.

119 Through this exercise, we are able to see the optimal electricity mix in the UK and Ireland. We found
 120 that a mixture of renewable sources such as wind, solar and wave power would meet demand at
 121 quarter year intervals, as well as providing a cost-effective and low-carbon system.

122 A limitation of this work is the fact that the investment algorithm does not take into account the
 123 technical and timeframe constraints of transitions between technologies. It is for this reason that
 124 the reinforcement learning algorithm is able to make such a rapid transition in 2017. However, we
 125 believe that the investment algorithm is able to find a general solution to the problem of investing in a
 126 cost-efficient and low-carbon system over a long time horizon.

127 In future work, we would like to increase the number of steps of the FTT:Power model to more
 128 adequately model the investment behaviour introduced by the reinforcement learning algorithm. A
 129 lower number of simulated time steps leads to an overestimation of the supply of renewables and
 130 underestimation of storage and dispatchable technologies [14]. In addition, an increase in the number
 131 of countries modelled would enable us to see a global picture of how different, interdependent regions
 132 may evolve in a new climate of a requirement of low-carbon emissions. This would require an
 133 exponentially longer runtime for the reinforcement learning algorithm to converge. This is due to
 134 the increased number of decisions that the reinforcement learning algorithm would need to make to
 135 account for the different countries. Finally, we would like to incorporate the technical and timeframe
 136 constraints for technology switching. This could be undertaken by modifying the reward function to
 137 ensure the transition remains within these constraints.

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