

# Introduction to Audio Content Analysis

Module 7.3.3: Fundamental Frequency Detection in Monophonic Signals

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# introduction

## overview

### corresponding textbook section

#### Section 7.3.3

#### ■ lecture content

- established approaches to monophonic pitch tracking in
  - ▶ time domain
  - ▶ frequency domain

#### ■ learning objectives

- define the task of monophonic pitch tracking
- summarize the principles of time-domain  $f_0$ -trackers and describe one approach in detail
- summarize the principles of frequency-domain  $f_0$ -trackers and describe one approach in detail



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# fundamental frequency

## introduction

### remember

Fourier series: every (quasi-)periodic sound is a combination of sinusoidals with integer frequency ratios

$$x(t) \approx x(t + T_0)$$

$$x(t) \approx \sum_{k=-\infty}^{\infty} a(k) e^{j\omega_0 k t}$$

$f_0$ : musically, perceptually most “relevant” frequency

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# pitch detection

## task definition

- detect the **fundamental frequency**  $f_0$
- monophonic: only **one** fundamental frequency at a time
- related **subtasks**:
  - *voice activity*: detect when there is no voice/no fundamental frequency
  - *note segmentation*
    - ▶ note start time and stop time
    - ▶ average note frequency
    - ▶ average note velocity
    - ▶ vibrato detection
  - frequency to *pitch mapping*

# monophonic fundamental frequency detection

## zero crossing rate

### ■ number of zero crossings per block (inaccurate)

$$T_0(n) = \frac{2 \cdot (i_e(n) - i_s(n))}{f_s \cdot \sum_{i=i_s(n)}^{i_e(n)} |\text{sign}[x(i)] - \text{sign}[x(i-1)]|}$$

### ■ average period length

$$T_0(n) = \frac{2}{Z-1} \sum_{j=0}^{Z-2} \Delta t_{ZC}(j).$$

### ■ variants:

- create histogram with distances and choose maximum
- use not (only) ZC but distance between local extrema

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# monophonic fundamental frequency detection

## auto correlation function

### ■ find **lag** of **ACF** maximum

$$r_{xx}(\eta, n) = \sum_{i=i_s(n)}^{i_e(n)-\eta} x(i) \cdot x(i + \eta)$$

### ■ variants:

- center clipping



# monophonic fundamental frequency detection

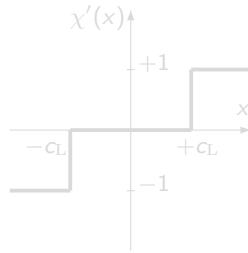
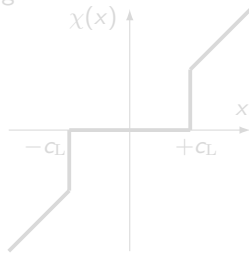
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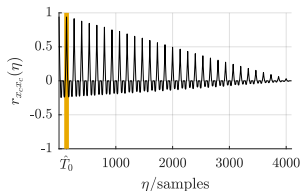
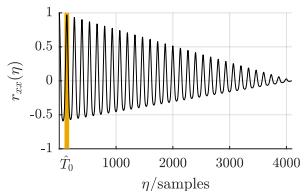
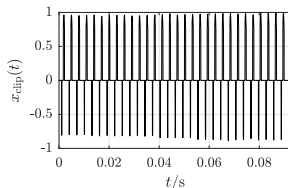
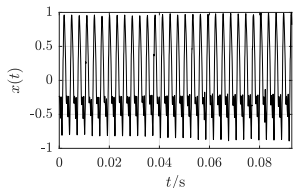
### ■ **variants:**

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# monophonic fundamental frequency detection

## auto correlation function



# monophonic fundamental frequency detection

## average magnitude difference function

### ■ find **lag of AMDF minimum**

$$\text{AMDF}_{xx}(\eta, n) = \frac{1}{i_e(n) - i_s(n) + 1} \sum_{i=i_s(n)}^{i_e(n)-\eta} |x(i) - x(i + \eta)|$$

### ■ **variants:**

- AMDF-weighted ACF

$$r'_{xx}(\eta, n) = \frac{r_{xx}(\eta, n)}{\text{AMDF}_{xx}(\eta, n) + 1}$$

# monophonic fundamental frequency detection

## average magnitude difference function

### ■ find **lag** of **AMDF** minimum

$$\text{AMDF}_{xx}(\eta, n) = \frac{1}{i_e(n) - i_s(n) + 1} \sum_{i=i_s(n)}^{i_e(n)-\eta} |x(i) - x(i + \eta)|$$

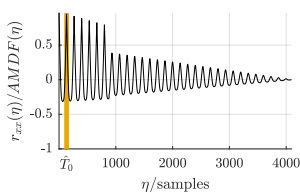
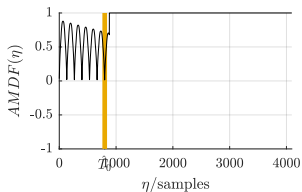
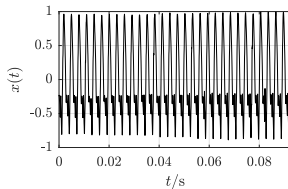
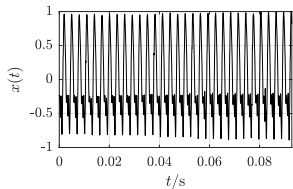
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# monophonic fundamental frequency detection

## average magnitude difference function

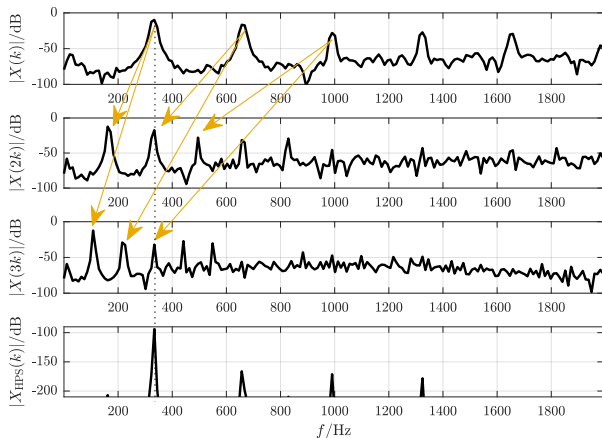


# monophonic fundamental frequency detection

## harmonic product spectrum 1/2

$$X_{\text{HPS}}(k, n) = \prod_{j=1}^{\infty} |X(j \cdot k, n)|^2$$

first published in the 1960s by Noll

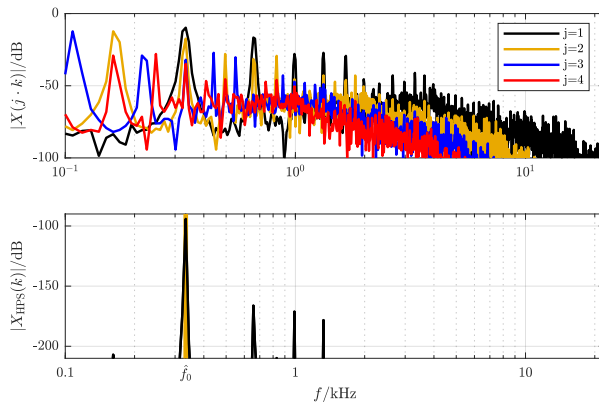


<sup>1</sup>A. M. Noll, "Pitch Determination of Human Speech by the Harmonic Product Spectrum, the Harmonic Sum Spectrum, and a Maximum Likelihood Estimate," in *Proceedings of the Symposium on Computer Processing in Communications*, vol. 19, Brooklyn: Polytechnic Press of the City University of New York, 1968, pp. 177-183.



# monophonic fundamental frequency detection

## harmonic product spectrum 2/2



# monophonic fundamental frequency detection

## harmonic sum spectrum

- sum instead product sum

$$X_{\text{HSS}}(k, n) = \sum_{j=1}^{\mathcal{O}} |X(j \cdot k, n)|^2$$

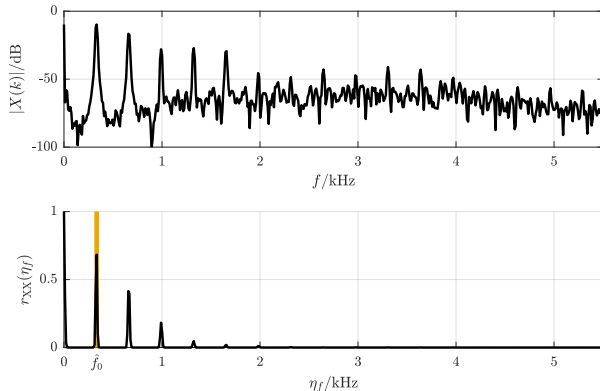
- **advantage**
  - ▶ robust against missing harmonics
- **disadvantage**
  - ▶ less pronounced peak

# monophonic fundamental frequency detection

## ACF of magnitude spectrum

$$r_{XX}(\eta, n) = \sum_{k=-K/2}^{K/2-1} |X(k, n)| \cdot |X(k + \eta, n)|$$

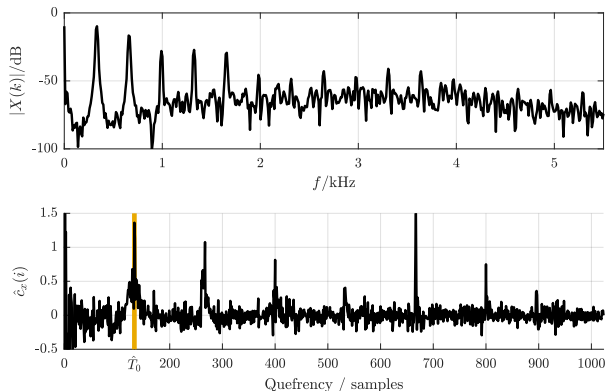
⇒ **detect maximum location**



# monophonic fundamental frequency detection

## cepstral pitch detection

- 1 compute cepstrum
- 2 detect periodicities



# monophonic fundamental frequency detection

## spectral maximum likelihood

- create **template matrix** with (smoothed) delta pulses for all possible frequencies
- compute the **cross correlation** ( $lag = 0$ ) between spectrum and all templates
- pick the result with the **highest correlation**  $\Rightarrow$  frequency estimate (graph see<sup>2</sup>)

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<sup>2</sup>P. de la Cuadra, *Pitch detection methods review*, [Online]. Available: <https://ccrma.stanford.edu/~pdelac/154/m154paper.htm> (visited on 08/04/2015).

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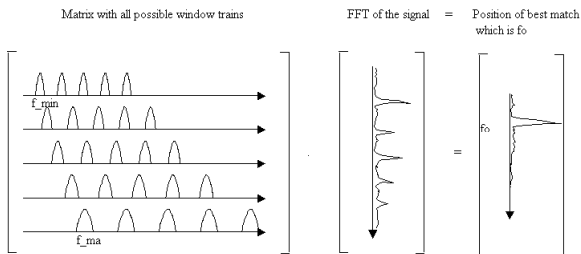
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# monophonic fundamental frequency detection

## auditory-motivated pitch tracking 1/2

- 1 filterbank** of band pass filters (e.g., mel scale)
- 2 HWR
- 3 smoothing
- 4 within-band periodicity estimate (e.g. **ACF**)
- 5 **combination** of bands



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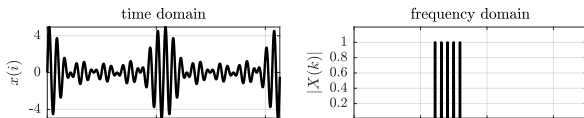
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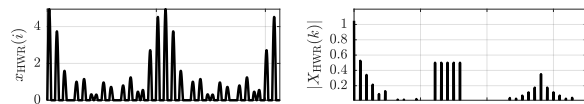
# monophonic fundamental frequency detection

## auditory-motivated pitch tracking 2/2

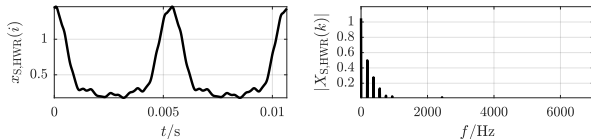
### 1 filterbank output



### 2 half wave rectification



### 3 smoothed output



# summary

## lecture content

### ■ basic commonality

- all approaches look for **periodicity**
  - ▶ waveform similarity in time domain
  - ▶ equidistant harmonics/peaks in freq domain

### ■ state-of-the-art

- despite the age of the presented methods, tweaked versions of the presented approaches are still often considered state-of-the-art
- combinations of different approaches can be robust

