Introduction to Audio Content Analysis

Module 7.3.3: Fundamental Frequency Detection in Monophonic Signals

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introduction overview

corresponding textbook section

Section 7.3.3

■ lecture content

- established approaches to monophonic pitch tracking in
 - ▶ time domain
 - frequency domain

■ learning objectives

- define the task of monophonic pitch tracking
- ullet summarize the principles of time-domain f_0 -trackers and describe one approach in detail
- summarize the principles of frequency-domain f_0 -trackers and describe one approximately describe the principles of frequency-domain f_0 -trackers and describe one approximately describe the principles of frequency-domain f_0 -trackers and describe one approximately describe the principles of frequency-domain f_0 -trackers and describe one approximately describe the principles of the principles of frequency-domain f_0 -trackers and describe one approximately describe the principles of the principles of

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Section 7.3.3

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- established approaches to monophonic pitch tracking in
 - ▶ time domain
 - frequency domain

■ learning objectives

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- summarize the principles of frequency-domain f_0 -trackers and describe one approain detail

fundamental frequency introduction

remember

Fourier series: every (quasi-)periodic sound is a combination of sinusoidals with integer frequency ratios

$$x(t) \approx x(t + T_0)$$

 $x(t) \approx \sum_{k=-\infty}^{\infty} a(k)e^{j\omega_0kt}$

f₀: musically, perceptually most "relevant" frequency

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pitch detection task definition

- \blacksquare detect the fundamental frequency f_0
- there is only one fundamental frequency at a time
- related subtasks:
 - detect when there is no fundamental frequency
 - segment into notes
 - start time and stop time
 - average note frequency
 - vibrato detection
 - map to pitch scale

monophonic fundamental frequency detection zero crossing rate

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number of zero crossings per block (inaccurate)

$$T_0(n) = rac{2 \cdot \left(i_{\mathrm{e}}(n) - i_{\mathrm{s}}(n)
ight)}{f_{\mathrm{S}} \cdot \sum\limits_{i=i_{\mathrm{s}}(n)} \left| \mathrm{sign}\left[x(i)
ight] - \mathrm{sign}\left[x(i-1)
ight]
ight|}$$

average period length

$$T_0(n) = \frac{2}{\mathcal{Z}-1} \sum_{j=0}^{\mathcal{Z}-2} \Delta t_{\mathrm{ZC}}(j).$$

- variants:
 - create histogram with distances and choose maximum
 - use not (only) ZC but distance between local extrema

monophonic fundamental frequency detection zero crossing rate

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monophonic fundamental frequency detection auto correlation function

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■ find lag of ACF maximum

$$r_{\mathsf{xx}}(\eta, n) = \sum_{i=i_{\mathsf{s}}(n)}^{i_{\mathsf{e}}(n)-\eta} x(i) \cdot x(i+\eta)$$

variants:

center clipping



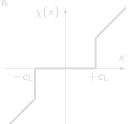
monophonic fundamental frequency detection auto correlation function

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variants:

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$$\chi'(x)$$
 $+1$
 $+c_L$
 $+c_L$

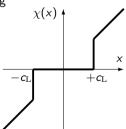
monophonic fundamental frequency detection auto correlation function

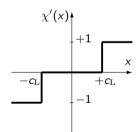
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variants:

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monophonic fundamental frequency detection average magnitude difference function

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■ find lag of AMDF minimum

$$\mathrm{AMDF}_{\mathsf{xx}}(\eta, n) = \frac{1}{i_{\mathrm{e}}(n) - i_{\mathrm{s}}(n) + 1} \sum_{i = i_{\mathrm{s}}(n)}^{i_{\mathrm{e}}(n) - \eta} |x(i) - x(i + \eta)|$$

- variants:
 - AMDF-weighted ACF

$$r'_{xx}(\eta, n) = \frac{r_{xx}(\eta, n)}{\text{AMDF}_{xx}(\eta, n) + 1}$$

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■ find lag of AMDF minimum

average magnitude difference function

$$\mathrm{AMDF}_{\mathsf{xx}}(\eta, \mathsf{n}) = \frac{1}{i_{\mathrm{e}}(\mathsf{n}) - i_{\mathrm{s}}(\mathsf{n}) + 1} \sum_{i=i_{\mathrm{s}}(\mathsf{n})}^{i_{\mathrm{e}}(\mathsf{n}) - \eta} |\mathsf{x}(i) - \mathsf{x}(i+\eta)|$$

- variants:
 - AMDF-weighted ACF

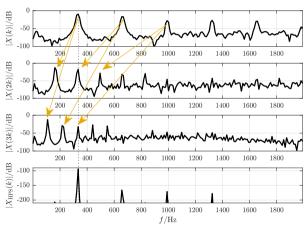
$$r'_{xx}(\eta, n) = \frac{r_{xx}(\eta, n)}{\text{AMDF}_{xx}(\eta, n) + 1}$$

monophonic fundamental frequency detection harmonic product spectrum 1/2

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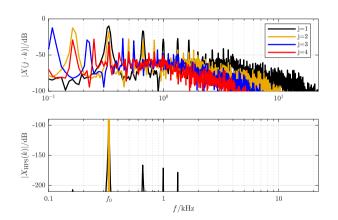
$$X_{\mathrm{HPS}}(k,n) = \prod_{j=1}^{\mathcal{O}} |X(j \cdot k,n)|^2$$

first published in the 1960s by Noll



[.] A. M. Noll, "Pitch Determination of Human Speech by the Harmonic Product Spectrum, the Harmonic Sum Spectrum, and a Maximum

monophonic fundamental frequency detection harmonic product spectrum 2/2



monophonic fundamental frequency detection harmonic sum spectrum

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■ sum instead product sum

$$X_{ ext{HSS}}(k,n) = \sum_{j=1}^{\mathcal{O}} |X(j \cdot k,n)|^2$$

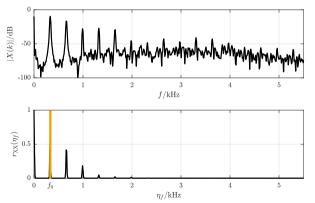
- advantage
 - robust against missing harmonics
- disadvantage
 - less pronounced peak

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monophonic fundamental frequency detection ACF of magnitude spectrum

$$r_{XX}(\eta, n) = \sum_{k=-K/2}^{K/2-1} |X(k, n)| \cdot |X(k+\tau)|$$

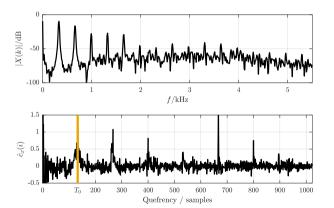
⇒ detect maximum location



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monophonic fundamental frequency detection cepstral pitch detection

- 1 compute cepstrum
- detect periodicities



monophonic fundamental frequency detection spectral maximum likelihood

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- create **template matrix** with (smoothed) delta pulses for all possible frequencies
- lacktriangle compute the **cross correlation** (lag = 0) between spectrum and all templates
- \blacksquare pick the result with the **highest correlation** \Rightarrow frequency estimate (graph see²)

²P. de la Cuadra, *Pitch detection methods review*, [Online]. Available: https://ccrma.stanford.edu/~pdelac/154/m154paper.htm (visited on /04/2015)

monophonic fundamental frequency detection spectral maximum likelihood

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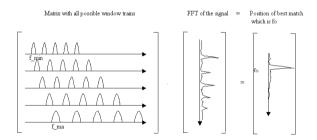
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- 1 filterbank of band pass filters (e.g., mel scale)
- 2 HWR
- 3 smoothing
- 4 within-band periodicity estimate (e.g. ACF)
- **5** combination of bands

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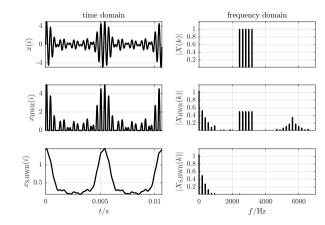
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1 filterbank output

half wave rectification

3 smoothed output



■ basic commonality

- all approaches look for periodicity
 - waveform similarity in time domain
 - equidistant harmonics/peaks in freq domain

■ state-of-the-art

- despite the age of the presented methods, tweaked versions of the presented approaches are still often considered state-of-the-art
- combinations of different approaches can be robust

