

# Modeling Neuralink's Blindsight through a Synthetic Visual Cortex

- 
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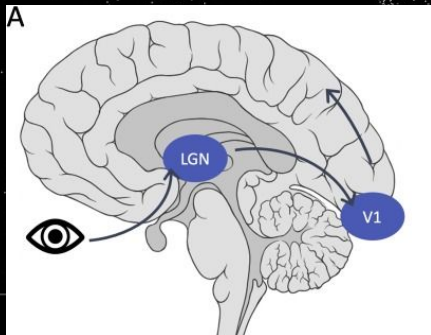


# What is the blindsight phenomenon?

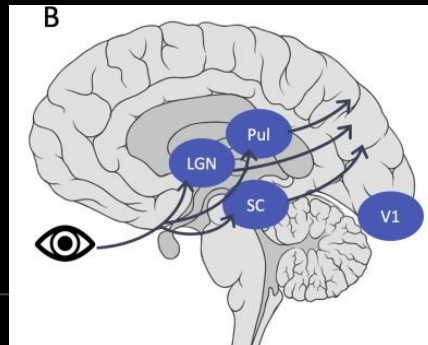
Blindsight is a symptom where people with *damage to their primary visual cortex* can respond to visual information—like detecting movement or locating objects—**without consciously seeing anything**.

They behave as if they can see, even though they report no visual experience.

No damage



Blindsight



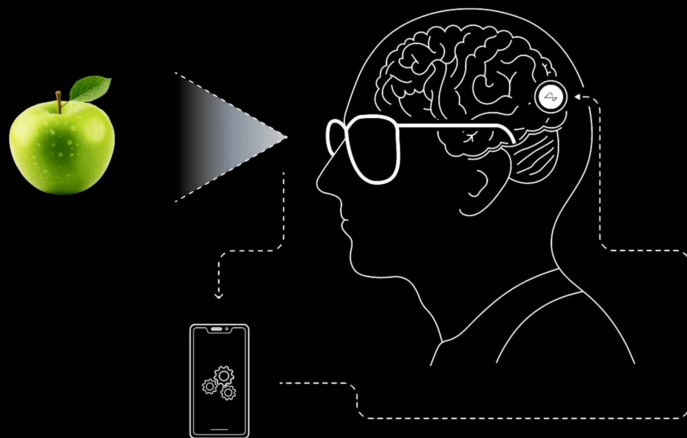


# 70%

of people with hemianopia (vision loss where 1/2 of the visual field is affected) have blindsight

# Neuralink's Blindsight

Bypassing the natural eye-to-brain pathway, Neuralink's Blindsight uses a video camera embedded in a pair of glasses to capture images of one's surroundings and wirelessly transmits them to the brain via their specialized implant, placed inside the visual cortex



# Our Goals

- Build a synthetic system that mimics early visual processing
- Replicate core computational logic of the visual cortex rather than using biological signals
- Transform camera-based sensory input into cortical-like neural activity
- Generate subjective "perceived" imagery based on modeled neural representations

# The Model

## MDPI2021 V1 Cortex Model

Layer 4 - 324 Spiny Stellate Cells (SS4)  
with intrinsic excitability

Layers 2/3 - 324 Pyramidal cells

Layer 5 - 81 Pyramidal cells

Layer 6 - 243 Pyramidal cells

Inhibitory and excitatory neurons in each layer



## Python Computational Model

Layer 4 - 144 Spiny Stellate Cells (SS4)  
*Simplified LIF neurons, no intrinsic excitability*

Layers 2/3 - 144 Pyramidal cells  
*Reduced grid (12×12) for real-time speed*

Layer 5 - 81 Pyramidal cells  
*Feedforward only (no lateral dynamics)*

Layer 6 - 243 Pyramidal cells  
*No synaptic delays, simplified update rules*

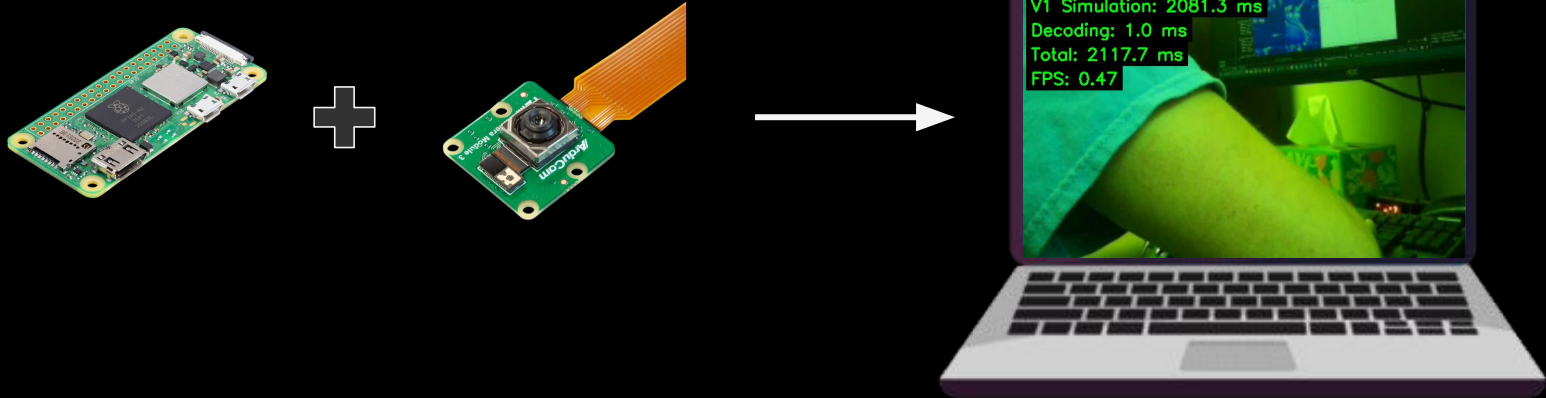
Inhibitory neurons present but disconnected  
*(no inhibitory or lateral pathways)*

# Methodology



# Step 1: Setting Up Camera

Paired a Pi Zero 2 W with a 12-megapixel Arducam module to capture real-time visual scenes.



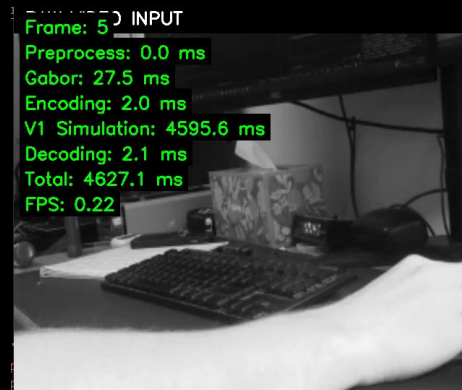


# Step 2: Early Processing

Converted the Pi camera image to grayscale (V1 doesn't care about color)

Cut the image into an  $12 \times 12$  grid = 144 pieces (**input layer**)

- Each piece is one "receptive field" simulating a retinal ganglion cell/LGN neuron



This step replicates simple retinal processing before cortical input.

# Step 3: Applying Gabor Filters

**Gabor Filter:** a linear filter used for edge detection

Applied 4 Gabor filters to each patch (1 for each orientation)

0°

45°

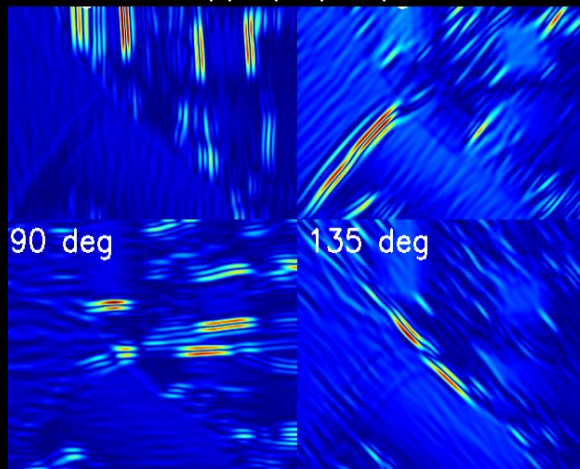
90°

135°

The output tells you:

- Is there an edge?
- Which direction is the edge pointing?
- How strong is it?

GABOR FILTERS (0/45/90/135)



This step models V1 simple cells that detect oriented edges & how our brains decompose scenes into oriented components.

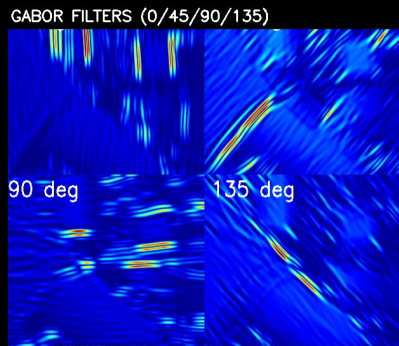
# Step 4: Converting into Spikes

We need to feed our model **spike trains**: times when simulated neurons fire

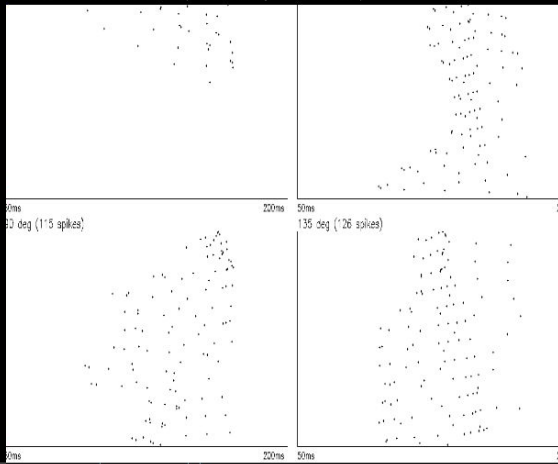
Converted each patch's strongest response into spikes

- Brighter / stronger edges → earlier spikes
- Weaker edges → later spikes

This imitates how real V1 neurons encode stimulus strength through spike timing.



SPIKE TRAINS (Latency Coded)



# Step 5: Feeding into V1 Model

## Model Inputs:

Spike trains



## Model Outputs:

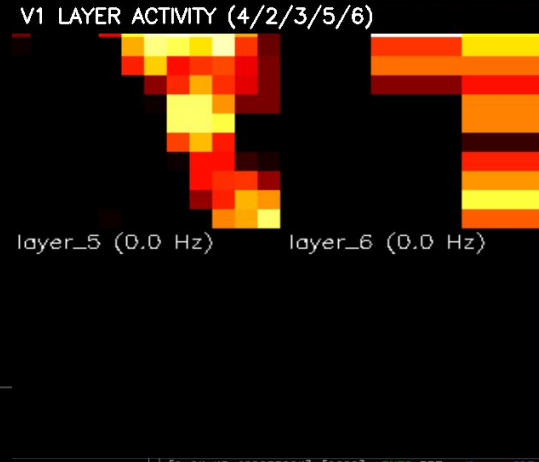
12 x 12 map of spiking activity  
where the intensity of firing tells you  
**which orientation is present and  
how strongly**

# Step 6: V1 Simulation

The model includes multiple laminar layers of V1 simulating a real brain structure:

- Layer 4 → main thalamic input
- Layers 2/3 → feature integration
- Layer 5 & 6 → feedback and long-range projections

The heatmaps show **activity levels in each layer (spikes per region)**.



# Step 7: V1 Orientation Map

A map showing **which orientation each spatial patch of the V1 model prefers**.

- Each pixel represents a group of V1 neurons
- The colors indicate which orientation fired most strongly:
  - Red =  $45^\circ$
  - Green =  $90^\circ$
  - Cyan =  $135^\circ$



# Thank you!

