CSCI 1550: PROBABILISTIC METHODS IN CS NOTES

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1. Events and Probability

Definition. A probability space has three components:

- (1) a sample space Ω , which is the set of all possible outcomes of the random process modeled by the probability space;
- (2) a family of sets \mathcal{F} representing the allowable events, where each set in \mathcal{F} is a subset of the sample space Ω ; and
- (3) a probability function $Pr: \mathcal{F} \to \mathbb{R}$ satisfying the following definition.

Definition. A probability function is any function $Pr : \mathcal{F} \to \mathbb{R}$ that satisfies the following conditions:

- (1) for any event E, $0 \le \Pr(E) \le 1$;
- (2) $Pr(\Omega) = 1$; and
- (3) for any finite or countably infinite sequence of pairwise mutually disjoint events E_1, E_2, E_3, \ldots ,

$$\Pr\left(\bigcup_{i\geq 1} E_i\right) = \sum_{i\geq 1} \Pr(E_i).$$

Lemma. For any two events E_1 and E_2 ,

$$\Pr(E_1 \cup E_2) = \Pr(E_1) + \Pr(E_2) - \Pr(E_1 \cap E_2).$$

Lemma (Union Bound). For any finite or countably infinite sequence of events E_1, E_2, \ldots ,

$$\Pr\left(\bigcup_{i\geq 1} E_i\right) \leq \sum_{i\geq 1} \Pr(E_i).$$

Lemma (1.3). Let E_1, \ldots, E_n be any n events. Then

$$\Pr\left(\bigcup_{i=1}^{n} E_{i}\right) = \sum_{i=1}^{n} \Pr(E_{i}) - \sum_{i < j} \Pr(E_{i} \cap E_{j}) + \sum_{i < j < k} \Pr(E_{i} \cap E_{j} \cap E_{k})$$
$$- \dots + (-1)^{l+1} \sum_{i_{1} < i_{2} < \dots < i_{l}} \Pr\left(\bigcap_{r=1}^{l} E_{i_{r}}\right) + \dots$$

Definition. Two events E and F are independent if and only if

$$\Pr(E \cap F) = \Pr(E) \cdot \Pr(F).$$

More generally, events E_1, E_2, \ldots, E_k are mutually independent if and only if, for any subset $I \subseteq [1, k]$,

$$\Pr\left(\bigcap_{i\in I} E_i\right) = \prod_{i\in I} \Pr(E_i).$$

Definition. The conditional probability that event E occurs given that event F occurs is

$$\Pr(E \mid F) = \frac{\Pr(E \cap F)}{\Pr(F)}.$$

The conditional probability is well-defined only if Pr(F) > 0.

Theorem (Law of Total Probability). Let E_1, E_2, \ldots, E_n be mutually disjoint events in the sample space Ω , and let $\bigcup_{i=1}^n E_i = \Omega$. Then

$$\Pr(B) = \sum_{i=1}^{n} \Pr(B \cap E_i) = \sum_{i=1}^{n} \Pr(B \mid E_i) \Pr(E_i).$$

Theorem (Bayes' Law). Assume that E_1, E_2, \ldots, E_n are mutually disjoint events in the sample space Ω such that $\bigcup_{i=1}^n E_i = \Omega$. Then

$$\Pr(E_j \mid B) = \frac{\Pr(E_j \cap B)}{\Pr(B)} = \frac{\Pr(B \mid E_j) \Pr(E_j)}{\sum_{i=1}^n \Pr(B \mid E_i) \Pr(E_i)}.$$

2. DISCRETE RANDOM VARIABLES AND EXPECTATION

Definition. A random variable X on a sample space Ω is a real-valued (measurable) function on Ω ; that is, $X : \Omega \to \mathbb{R}$. A discrete random variable is a random variable that takes on only a finite or countably infinite numbers of values.

Definition. Two random variable X and Y are independent if and only if

$$\Pr((X=x) \cap (Y=y)) = \Pr(X=x) \cdot \Pr(Y=y)$$

for all values x and y. Similarly, random variables X_1, X_2, \ldots, X_k are mutually independent if and only if, for any subset $I \subseteq [1, k]$ and any values $x_i, i \in I$,

$$\Pr\left(\bigcap_{i\in I}(X_i=x_i)\right) = \prod_{i\in I}\Pr(X_i=x_i).$$

Definition. The expectation of a discrete random variable X, denoted by $\mathbf{E}[X]$, is given by

$$\mathbf{E}[X] = \sum_{i} i \Pr(X = i),$$

where the summation is over all values in the range of X. The expectation is finite if $\sum_{i} |i| \Pr(X = i)$ converges; otherwise, the expectation is unbounded.

Theorem (Linearity of Expectations). For any finite collection of discrete random variables X_1, X_2, \ldots, X_n with finite expectations,

$$\mathbf{E}\left[\sum_{i=1}^{n} X_i\right] = \sum_{i=1}^{n} \mathbf{E}[X_i].$$

Lemma. For any constant c and discrete random variable X.

$$\mathbf{E}[cX] = c\mathbf{E}[X].$$

Definition. Consider a sequence of n independent experiments, each of which succeeds with probability p. If we let X represent the number of successes in the n experiments, then X has a binomial distribution. A binomial random variable X with parameters n and p, denoted by B(n,p), is defined by the following probability distribution on $j=0,1,2,\ldots,n$:

$$\Pr(X = j) = \binom{n}{j} p^j (1 - p)^{n-j}.$$

That is, the binomial random variable X equals j when there are exactly j successes and n-j failures in n independent experiments, each of which is successful with probability p.

Lemma. For a binomial random variable X with parameters n and p,

$$\mathbf{E}[X] = np.$$

Definition.

$$\mathbf{E}[Y \mid Z = z] = \sum_{y} y \Pr(Y = y \mid Z = z),$$

where the summation is over all y in the range of Y.

Lemma. For any random variables X and Y,

$$\mathbf{E}[X] = \sum_{y} \Pr(Y = y) \mathbf{E}[X \mid Y = y],$$

where the sum is over all values in the range of Y and all of the expectations exist.

Lemma. For any finite collection of discrete random variables X_1, X_2, \ldots, X_n with finite expectations and for any random variable Y,

$$\mathbf{E}\left[\sum_{i=1}^{n} X_i \mid Y = y\right] = \sum_{i=1}^{n} \mathbf{E}[X_i \mid Y = y].$$

Definition. The expression $\mathbf{E}[X \mid Y]$ is a random variable f(Z) that takes on the value $\mathbf{E}[Y \mid Z = z]$ when Z = z.

Theorem.

$$\mathbf{E}[Y] = \mathbf{E}[\mathbf{E}[Y \mid Z]].$$

Definition. We perform a sequence of independent trials until the first success, where each trial succeeds with probability p. A geometric random variable X with parameter p is given by the following probability distribution on $n = 1, 2, \ldots$:

$$\Pr(X = n) = (1 - p)^{n-1}p.$$

That is, for the geometric random variable X to equal n, there must be n-1 failures, followed by a success.

Lemma. For a geometric random variable X with parameter p and for n > 0,

$$\Pr(X = n + k \mid X > k) = \Pr(X = n).$$

Lemma. Let X be a discrete random variable that takes on only non-negative integer values. Then

$$\mathbf{E}[X] = \sum_{i=1}^{\infty} \Pr(X \ge i).$$

Lemma. For a geometric random variable X with parameter p,

$$\mathbf{E}[X] = \frac{1}{p}.$$

Lemma. The harmonic number $H(n) = \sum_{i=1}^{n} 1/i$ satisfies $H(n) = \ln n + \Theta(1)$.

3. Moments and Deviations

Theorem (Markov's Inequality). Let X be a random variable that assumes only non-negative values. Then, for all a > 0,

$$\Pr(X \ge a) \le \frac{\mathbf{E}[X]}{a}.$$

Definition. The kth moment of a random variable X is $\mathbf{E}[X^k]$.

Definition. The variance of a random variable X is defined as

$$Var[X] = E[(X - E[X])^{2}] = E[X^{2}] - (E[X])^{2}.$$

The standard deviation of a random variable X is

$$\sigma[X] = \sqrt{\mathbf{Var}[X]}.$$

Definition. The covariance of two random variables X and Y is

$$Cov(X, y) = \mathbf{E}[(X - \mathbf{E}[X])(Y - \mathbf{E}[Y])].$$

Theorem. For any two random variables X and Y,

$$\mathbf{Var}[X+Y] = \mathbf{Var}[X] + \mathbf{Var}[Y] + 2\mathbf{Cov}(X,Y).$$

Theorem. If X and Y are two independent random variables, then

$$\mathbf{E}[X \cdot Y] = \mathbf{E}[X] \cdot \mathbf{E}[Y].$$

Corollary. If X and Y are independent random variables, then

$$Cov(X, Y) = 0$$

and

$$\mathbf{Var}[X+Y] = \mathbf{Var}[X] + \mathbf{Var}[Y].$$

Theorem. Let X_1, X_2, \ldots, X_n be mutually independent random variables. Then

$$\operatorname{\mathbf{Var}}\left[\sum_{i=1}^n X_i\right] = \sum_{i=1}^n \operatorname{\mathbf{Var}}[X_i].$$

Lemma. For a binomial random variable X with parameters n and p,

$$\mathbf{Var}[X] = np(1-p).$$

Theorem (Chebyshev's Inequality). For any a > 0,

$$\Pr(|X - \mathbf{E}[X]| \ge a) \le \frac{\mathbf{Var}[X]}{a^2}.$$

Corollary. For any t > 1,

$$\Pr(|X - \mathbf{E}[X]| \ge t \cdot \sigma[X]) \le \frac{1}{t^2} \text{ and}$$
$$\Pr(|X - \mathbf{E}[X]| \ge t \cdot \mathbf{E}[X]) \le \frac{\mathbf{Var}[X]}{t^2(\mathbf{E}[X])^2}.$$

 $\textbf{Lemma.} \ \textit{For a geometric random variable X with parameter p,} \\$

$$\mathbf{Var}[X] = (1 - p)/p^2.$$