

Apprentissage Artificiel (Statistical Machine-Learning)

General framework + Supervised Learning

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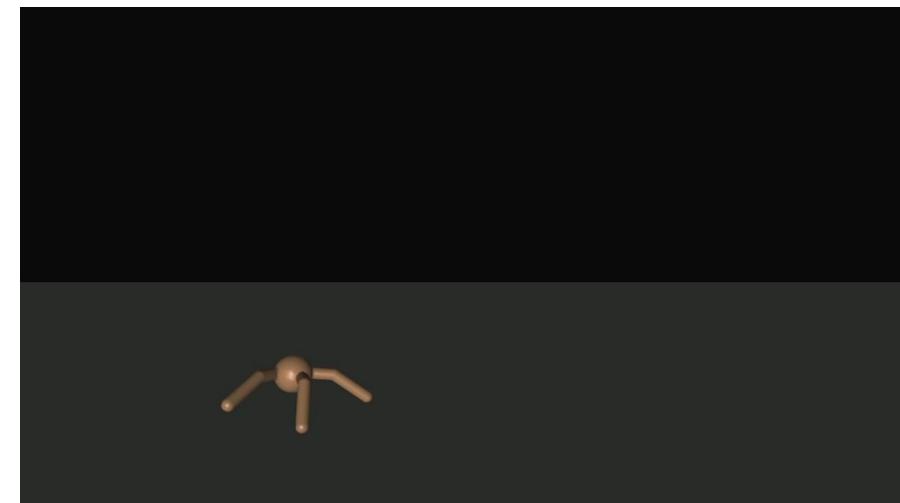
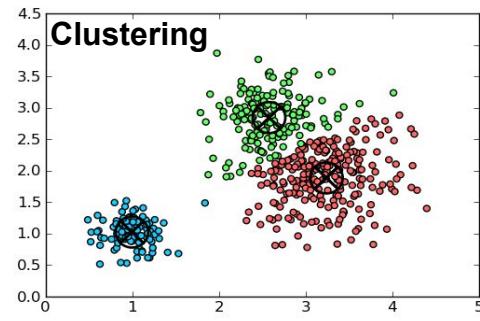
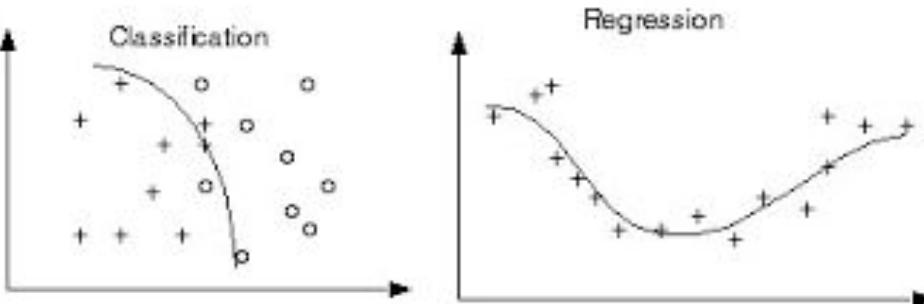
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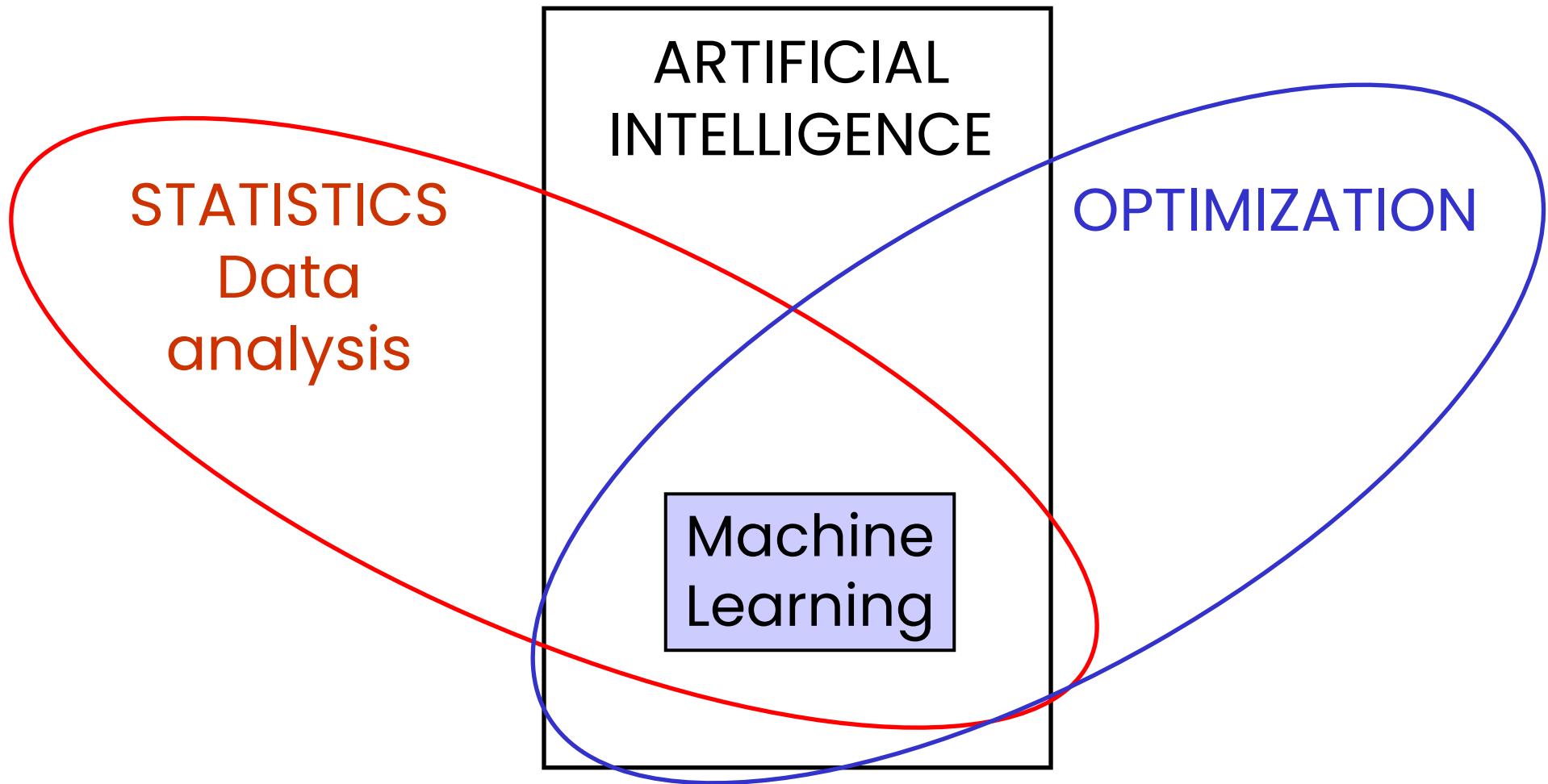
Outline

- Intro: What is Statistical Machine-Learning?
- Typology of Machine-Learning
- General formalism for SUPERVISED Learning
- Evaluating learnt models:
metrics for CLASSIFICATION
- Generalization vs. overfitting

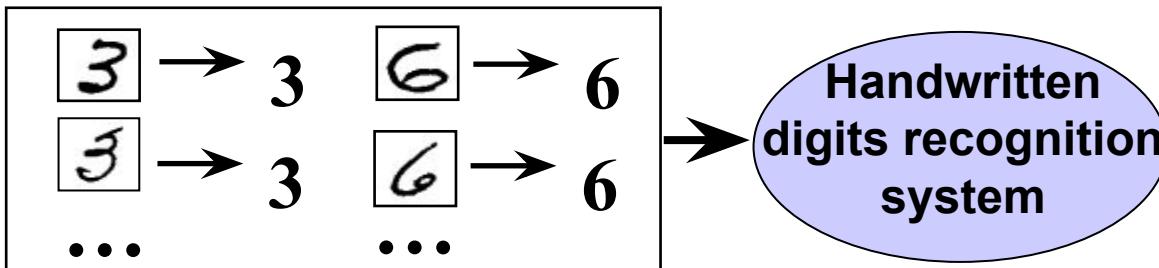
- One of many sub-fields of Artificial Intelligence
- Application of optimization methods to statistical modelling
- Data-driven mathematical modelling, for automated *classification, regression, partitioning/clustering, or decision/behavior rule*



What is Statistical Machine-Learning?



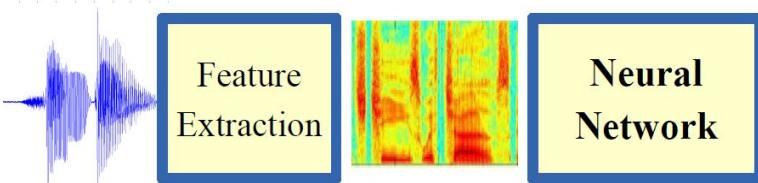
- Handwritten characters recognition



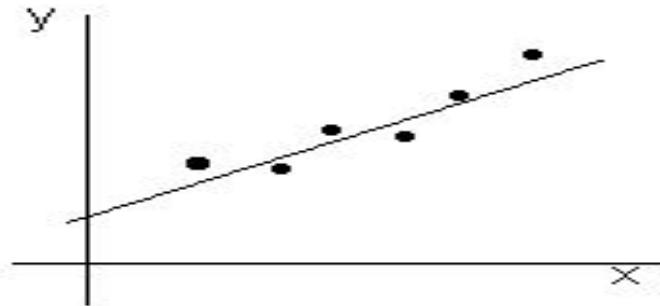
- Object category visual recognition



- Speech recognition



- Multi-factorial forecasting
- Natural Language understanding
- Playing GO!
- **MANY MANY MORE...**



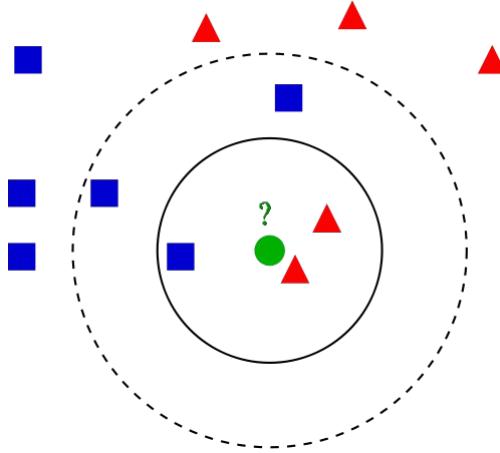
- **Model:** (straight) line $y=ax+b$ (2 parameters a and b)
- **Data:** n points with target value $(x_i, y_i) \in \mathbb{R}^2$
- **Cost function:** sum of squares of deviation from line

$$K = \sum_i (y_i - a \cdot x_i - b)^2$$

- **Algorithm:** direct (or iterative) solving of linear system

$$\begin{pmatrix} \sum_{i=1}^n x_i^2 & \sum_{i=1}^n x_i \\ \sum_{i=1}^n x_i & n \end{pmatrix} \cdot \begin{pmatrix} a \\ b \end{pmatrix} = \begin{pmatrix} \sum_{i=1}^n x_i y_i \\ \sum_{i=1}^n y_i \end{pmatrix}$$

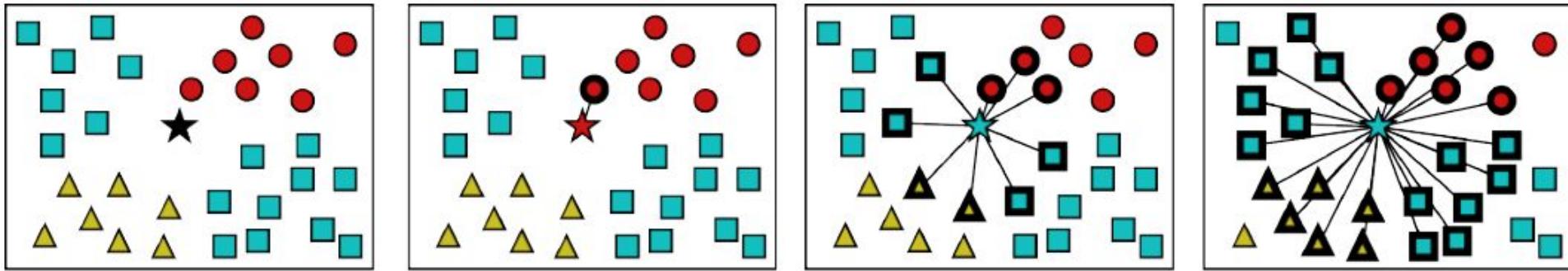
Simplest *classification* method: Nearest Neighbors algorithm



Principle of Nearest Neighbors (kNN) for classification

[What are the main drawbacks of this method??]

k-Nearest Neighbors



- Some outlier vectors get ‘outvoted’ with high enough number **k** of neighbors

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Supervised vs Unsupervised learning

Learning is called "supervised" when there are "target values for every example in training dataset:

$$\text{examples} = (\text{input}, \text{output}) = (\mathbf{x}_1, \mathbf{y}_1), (\mathbf{x}_2, \mathbf{y}_2), \dots, (\mathbf{x}_n, \mathbf{y}_n)$$

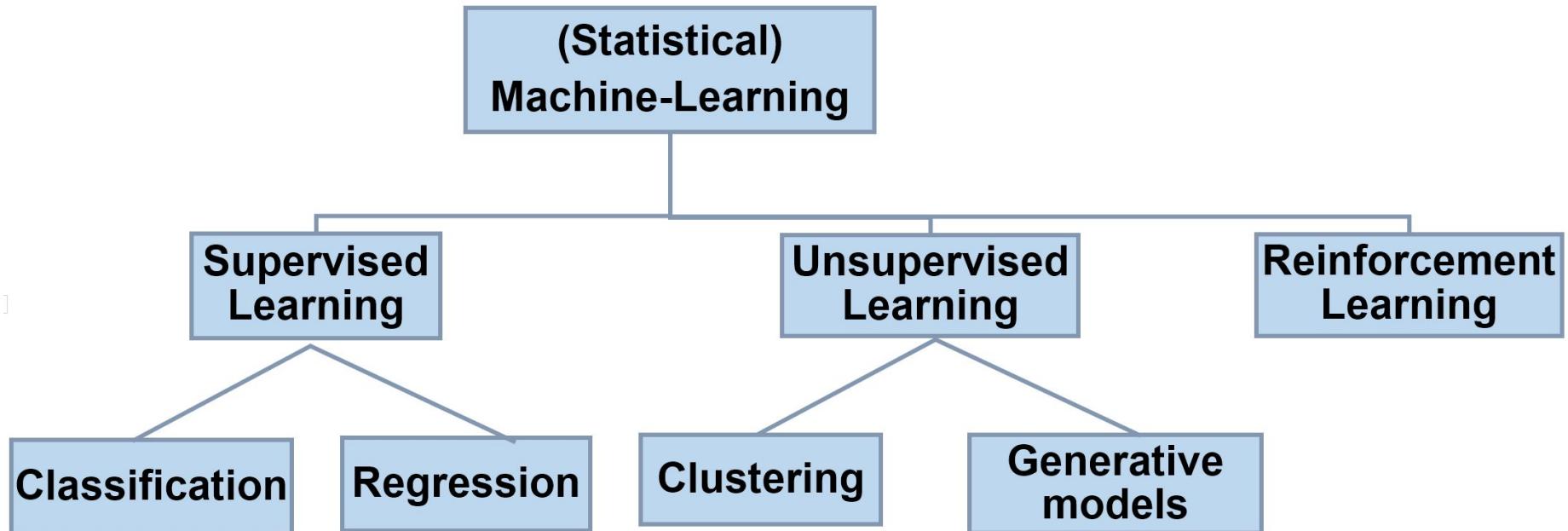
The goal is to build a (generally non-linear) approximate model for interpolation, in order to be able to GENERALIZE to input values other than those in training set

"Unsupervised" = when there are NO target values:

$$\text{dataset} = \{\mathbf{x}_1, \mathbf{x}_2, \dots, \mathbf{x}_n\}$$

The goal is typically either to do datamining (unveil structure in the distribution of examples in input space)

- **Availability of target output data?**
→ Supervised learning vs. Unsupervised learning
or *Reinforcement* Learning
- **Permanent adaptability?**
→ offline learning vs. online (life-long) learning
- **What kind of (mathematical) model?**
→ polynom/spline, decision tree, neural net, kernel machine, ...
- **Which objective function?**
→ cost function (quadratic error, ...), implicit criterium, ...
- **How to find the best-fitting model?**
→ algorithm type (exact solving, gradient descent,
quadratic optimization, heuristics, ...)



Un- or Self-Supervised Training?

Supervised

Dataset

Input



Label

Dog



Cat

Tasks (e.g., Classification, Regression)

Semi-Supervised

Dataset

Labelled



Label

Dog



Unlabelled



Tasks (e.g., Classification, Regression)

Un/Self?

Dataset

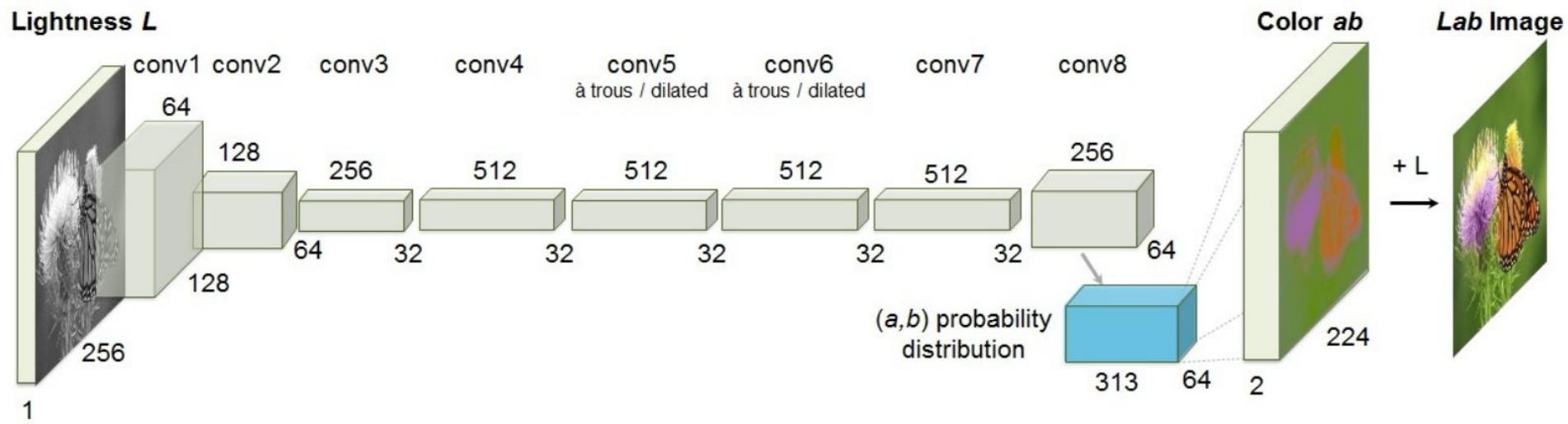


Tasks (e.g., Clustering)

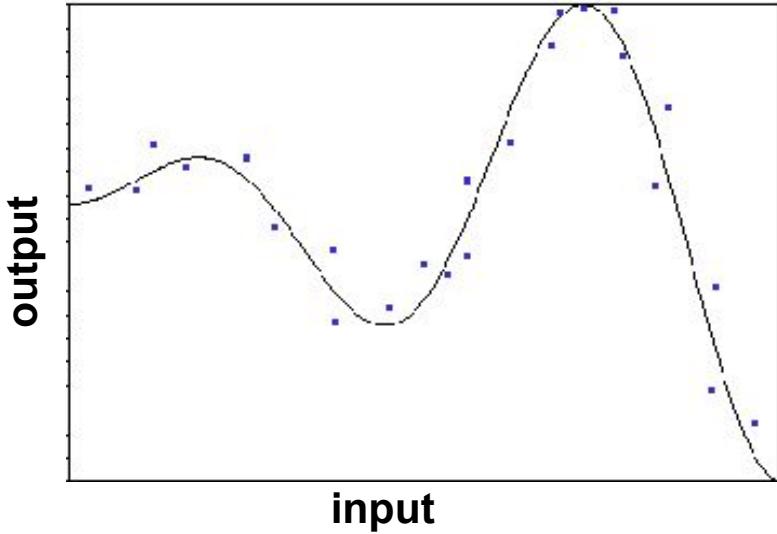
Use statistical properties of data itself without human labels.

Images: <https://towardsdatascience.com/supervised-semi-supervised-unsupervised-and-self-supervised-learning-7fa79aa9247c>

Self-Supervised Learning



Regression

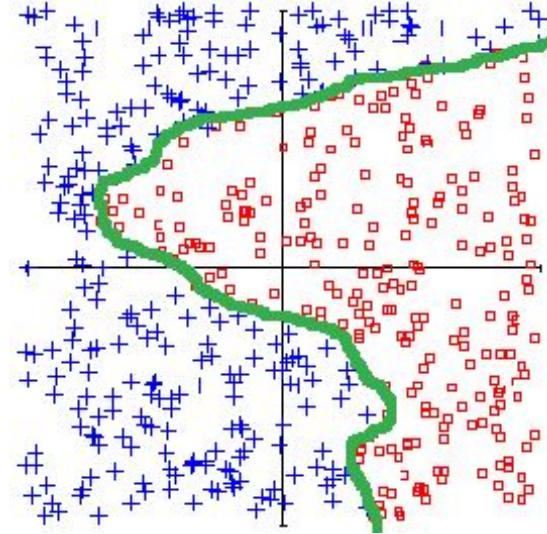


Examples $\{(x_i, y_i), i=1, \dots, N\}$
 $x_i = \text{input}$, $y_i = \text{target output}$

- Infer: curve = regression $y \approx h(x)$*

y: Continuous output(s)

Classification

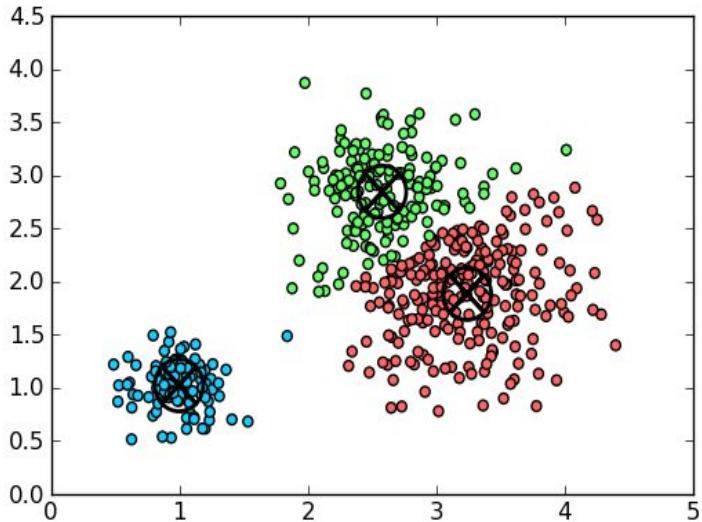


Input $\{x_i, i=1, \dots, N\} = \text{points positions}$
target Output = class label ($\square = -1, + = +1$)

- Infer: label = $h(x)$
 (and separation boundary)*

y: Discrete output(s)

Clustering



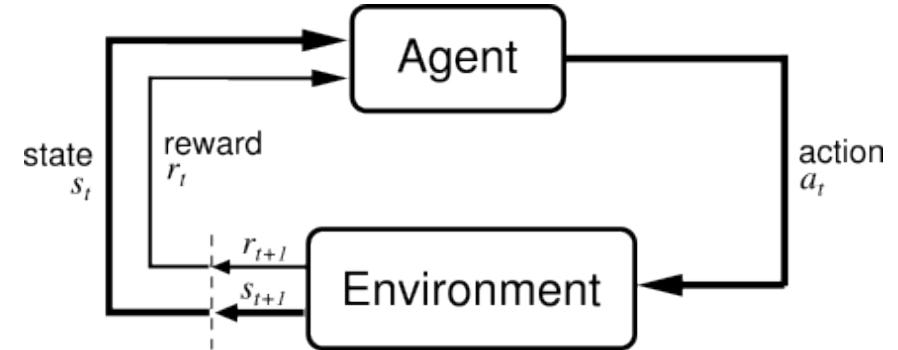
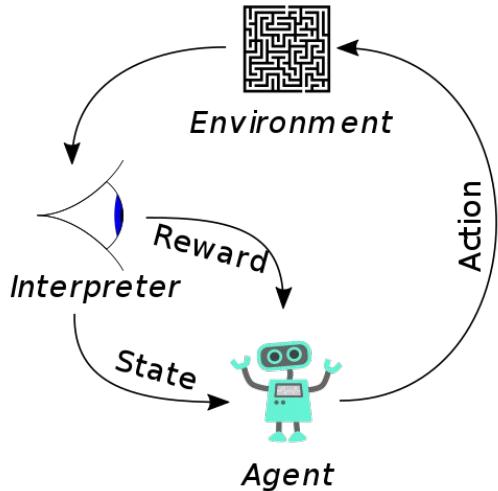
Points = examples

- partitioning in “groups” (colors)
based on similarity**

Generative model

*From examples x_n , estimate the
PROBABILITY DISTRIBUTION $p(x)$*

- Can GENERATE new examples
SIMILAR to those in training set**



Goal: find a “policy” $a_t = \pi(s_t)$ that

maximizes
$$R_t = \sum_{k=0}^{\infty} \gamma^k r_{t+k}, \gamma \in [0, 1[$$

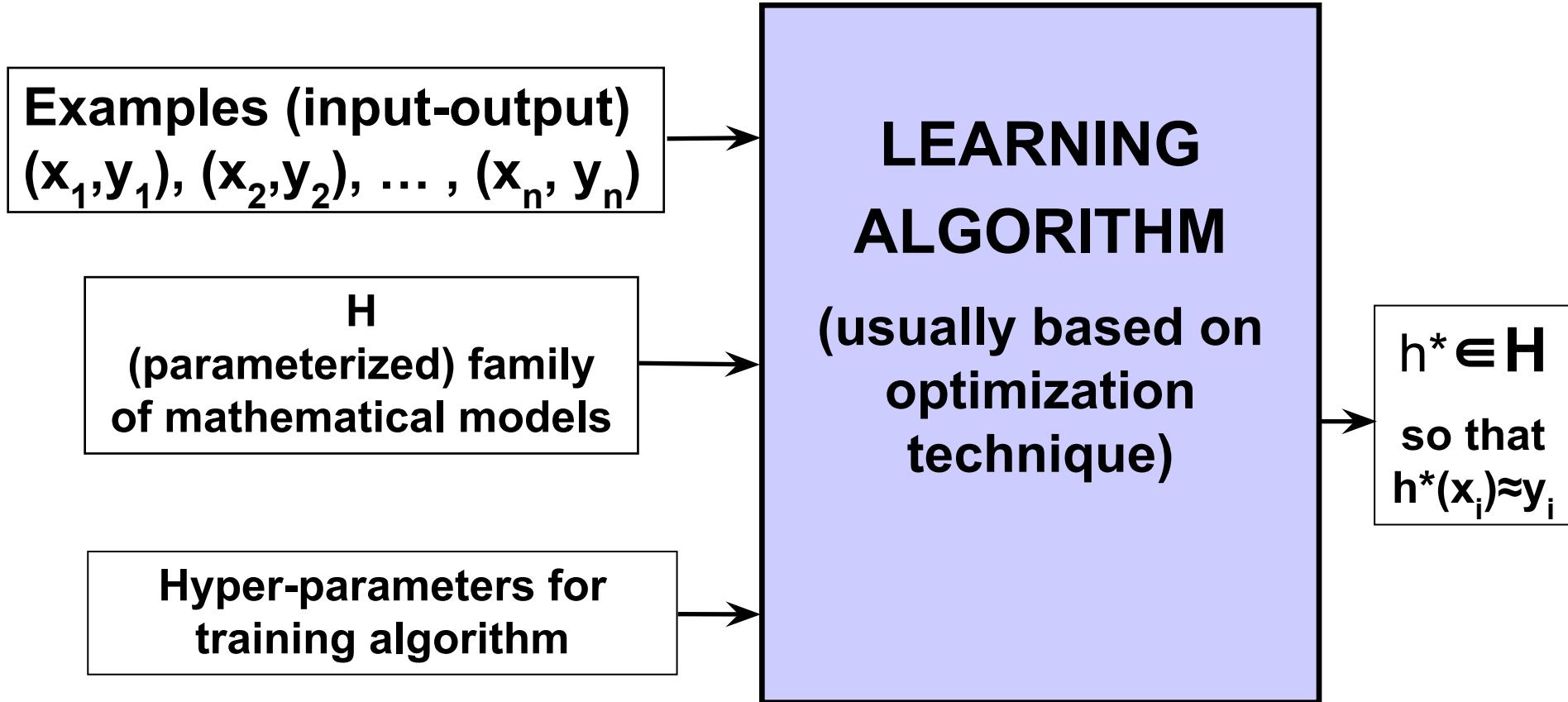
Typical use of RL: learn a BEHAVIOR

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Many different supervised ML approaches & algorithms

- Linear regressions
- Decision trees (ID3 or CART algorithms)
- Bayesian (probabilistic) methods
- ...
- Multi-layer neural networks trained with gradient backpropagation
- Support Vector Machines
- Boosting of "weak" classifiers
- Random forests
- Deep Learning (Convolutional Neural Networks,...)
- ...



In most cases, $h^* = \arg\min_{h \in H} K(h, \{(x_i, y_i)\})$ where $K = \text{cost}$
 $K = \sum_i \text{loss}(h(x_i), y_i)$ [+ regularization-term] and $\text{loss} = \|h(x_i) - y_i\|^2$

Cost function and loss function

Most *supervised* Machine-Learning algorithms work by minimizing a "cost function"

- The cost function is generally the average over all training examples of a "loss function"

$$K = \sum_i \text{loss}(h(x_i), y_i)$$

(+ sometimes an additional « regularization » term)

- The *loss function* is usually some measure of the difference between target value and prediction by the output of the learnt model

Linear Regression, Mean Square Loss:

- decision rule: $y = W'X$
- loss function: $L(W, y^i, X^i) = \frac{1}{2}(y^i - W'X^i)^2$
- gradient of loss: $\frac{\partial L(W, y^i, X^i)}{\partial W}' = -(y^i - W(t)'X^i)X^i$
- update rule: $W(t + 1) = W(t) + \eta(t)(y^i - W(t)'X^i)X^i$
- direct solution: solve linear system $[\sum_{i=1}^P X^i X^{i'}]W = \sum_{i=1}^P y^i X^i$

[From slide by Y. LeCun: Machine Learning and Pattern Recognition]

If target output is binary (classification)

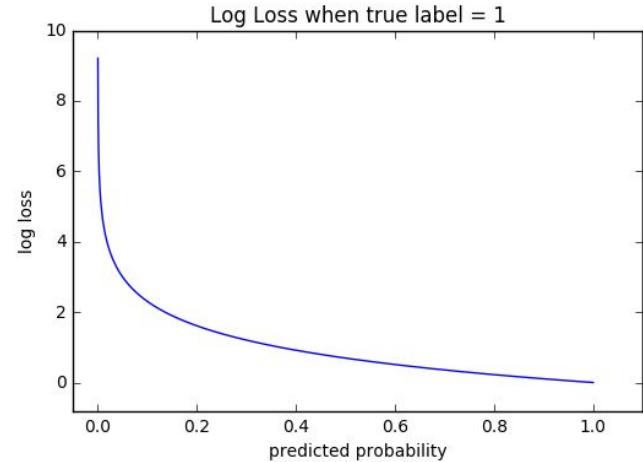
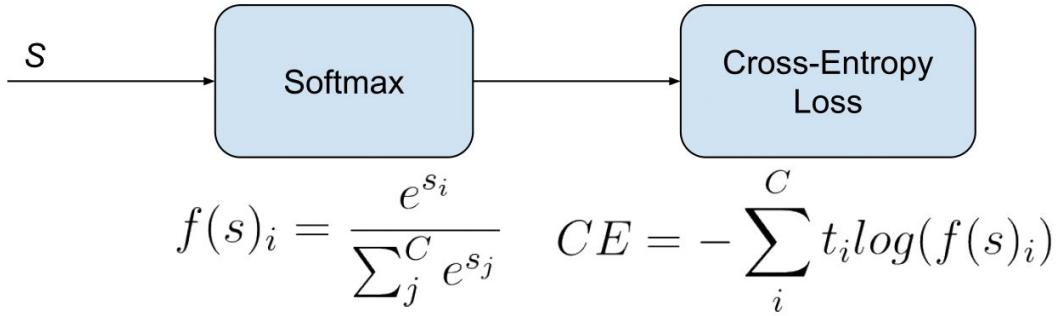
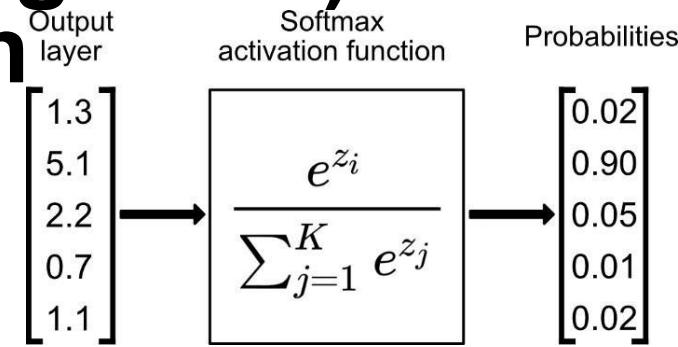
Logistic Regression, Negative Log-Likelihood Loss function:

- decision rule: $y = F(W'X)$, with $F(a) = \tanh(a) = \frac{1-\exp(a)}{1+\exp(a)}$
Or Sigmoid
- loss function: $L(W, y^i, X^i) = 2 \log(1 + \exp(-y^i W' X^i))$
- gradient of loss: $\frac{\partial L(W, y^i, X^i)}{\partial W}' = - (Y^i - F(W' X)) X^i$
- update rule: $W(t+1) = W(t) + \eta(t) (y^i - F(W(t)' X^i)) X^i$

[From slide by Y. LeCun: Machine Learning and Pattern Recognition]

Cross Entropy Loss (Log Loss) for Classification

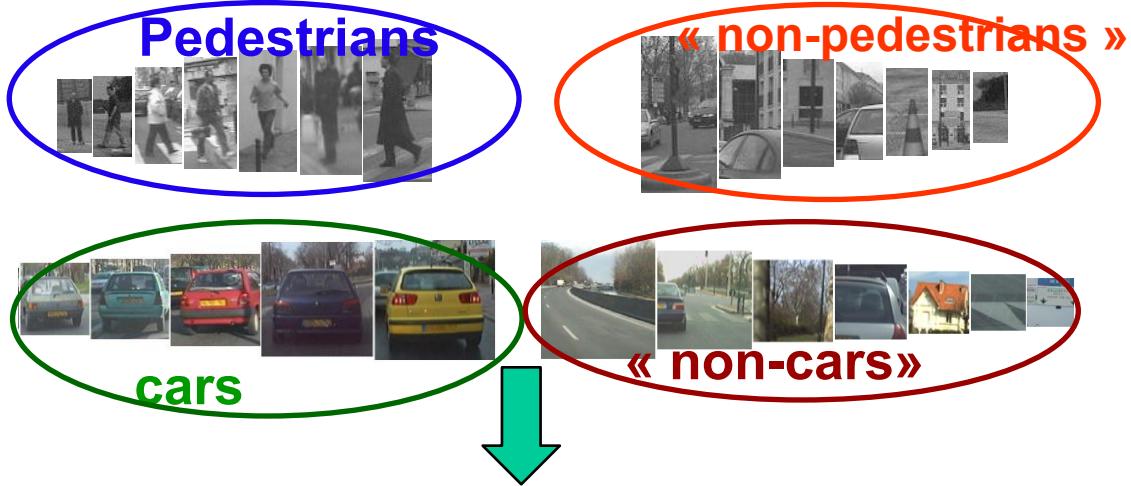
- If true label 1: Prediction lower than 0.5 is **confident and wrong** answer
→ penalize heavily



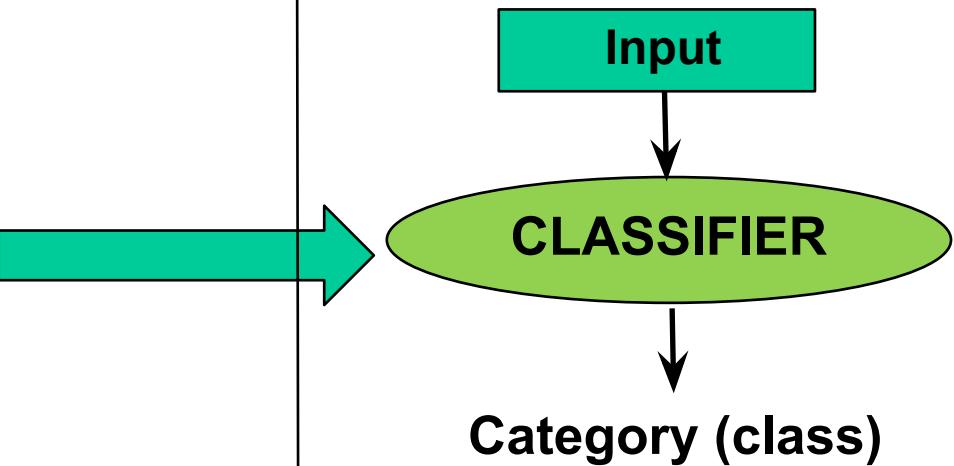
Compare: https://ml-cheatsheet.readthedocs.io/en/latest/loss_functions.html

Usual two distinct phases of supervised Machine-Learning

Training



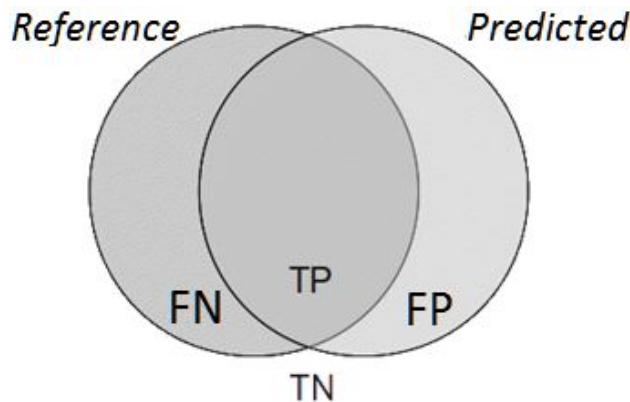
Recognition



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Different types of classification errors

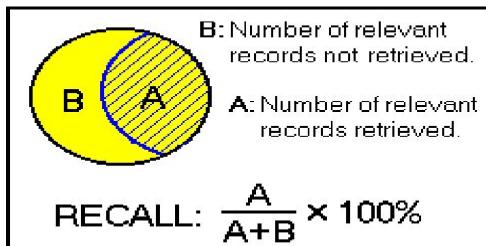


	predicted as positive	predicted as negative
positive	TP	FN
negative	FP	TN

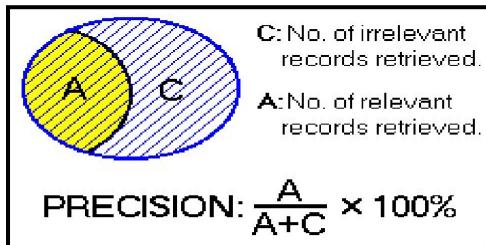
Error rate =

$$(FP+FN) / (TP+TN+FP+FN)$$

BUT: False Negatives ("missed") ≠ False Positives!



Recall: percentage of relevant examples successfully predicted/retrieved



Precision: percentage of actually relevant examples among all those returned by the classifier

Accuracy, recall & precision formulas

	predicted as positive	predicted as negative
positive	TP	FN
negative	FP	TN

Accuracy ("correctness") = $\frac{\text{# of correct predictions}}{\text{Total # of examples}} = \frac{TP + TN}{TP + TN + FP + FN}$

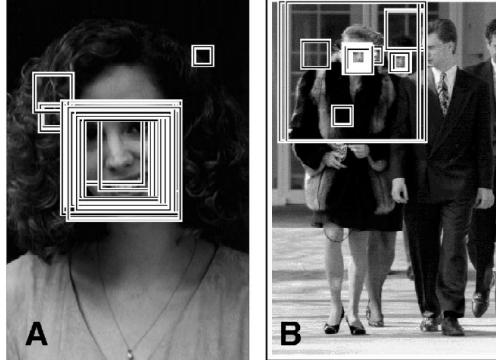
[*en français, exactitude*]

Recall (sensitivity) = $\frac{\text{# of correct } \underline{\text{positive}} \text{ predictions}}{\text{# of } \underline{\text{real}} \text{ positives}} = \frac{TP}{TP + FN}$

True Positive rate

Precision (specificity) = $\frac{\text{# of } \underline{\text{correct positive}} \text{ predictions}}{\text{# of } \underline{\text{positive predictions}}} = \frac{TP}{TP + FP}$

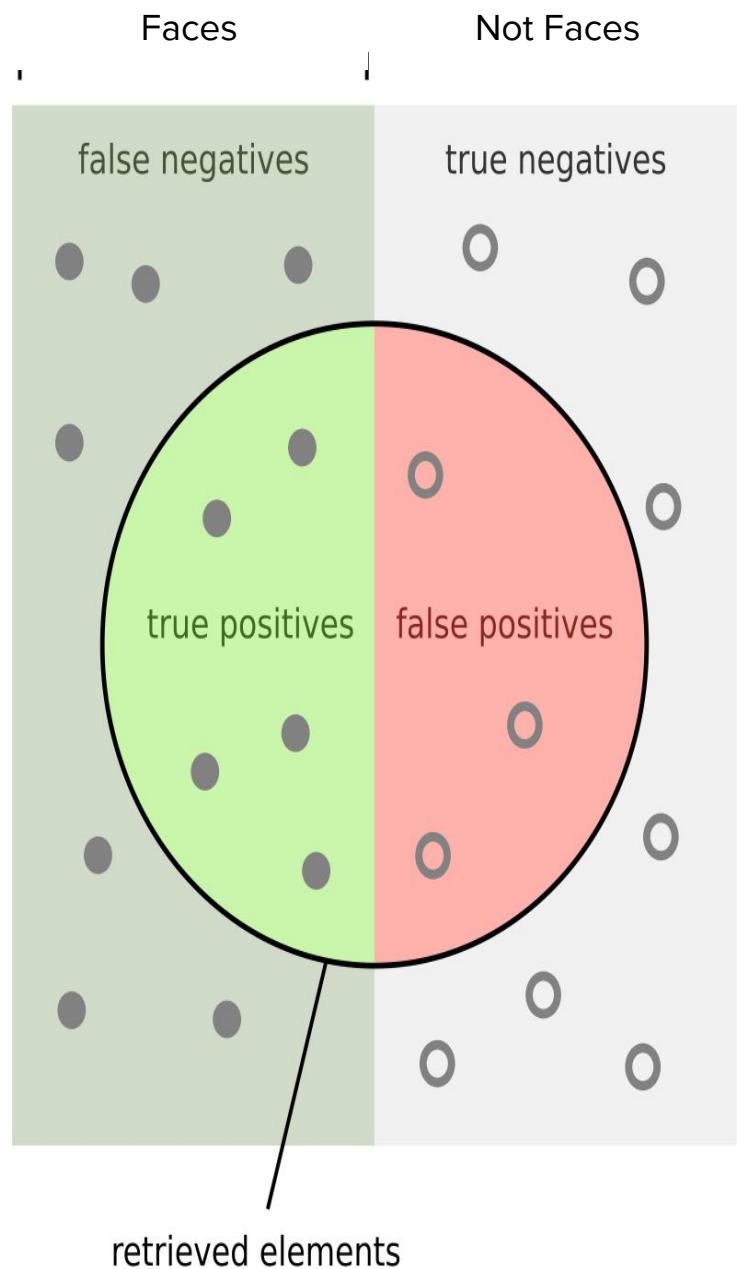
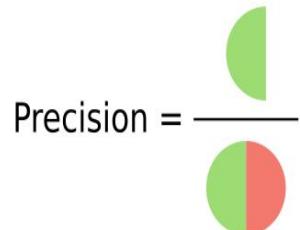
Precision



True Positives

$$\text{Precision} = \frac{\text{True Positives}}{\text{True Positives} + \text{False Positives}}$$

How many retrieved boxes
show faces?

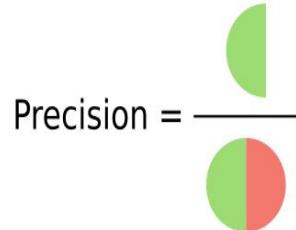


Precision, Recall

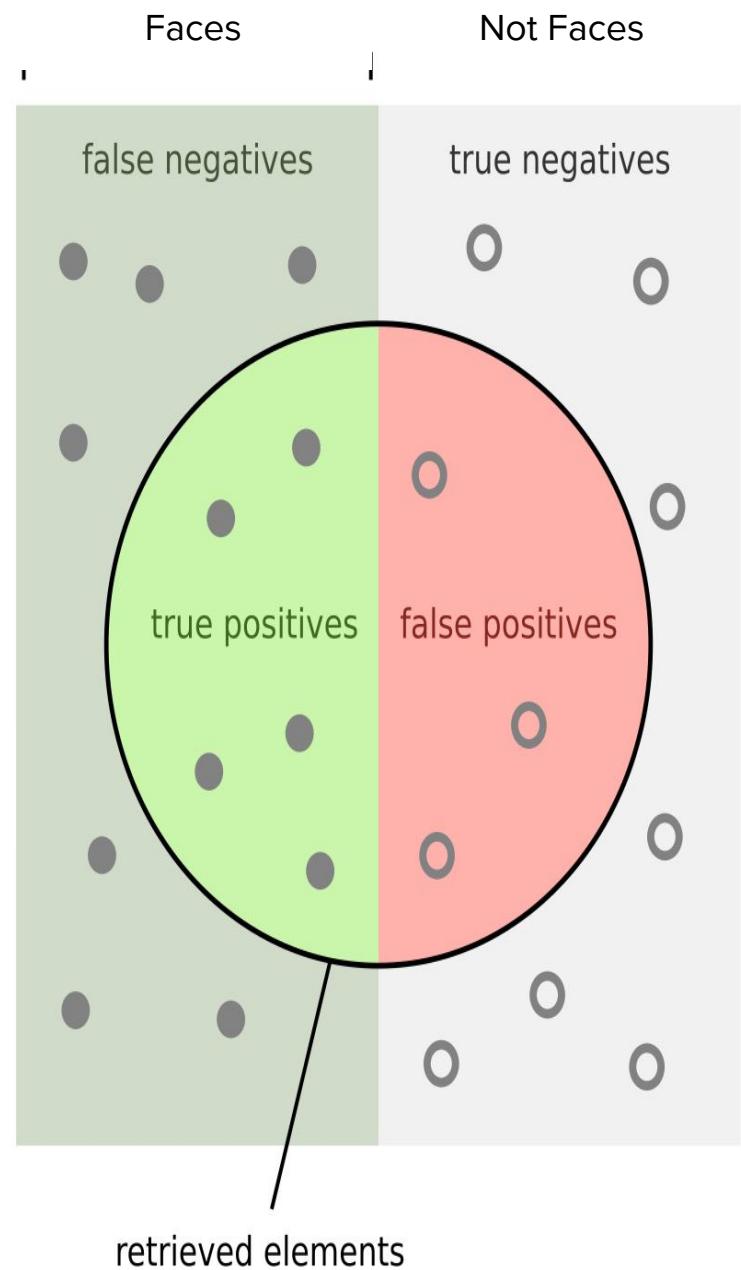
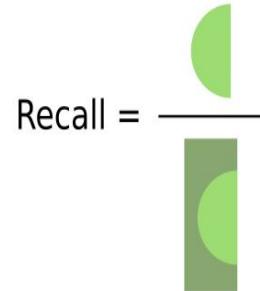
$$\text{Precision} = \frac{\text{True Positives}}{\text{True Positives} + \text{False Positives}}$$

$$\text{Recall} = \frac{\text{True Positives}}{\text{True Positives} + \text{False Negatives}}$$

How many retrieved boxes show faces?



How many faces are retrieved?



F1 - Score

- Single metric of ‘harmonic mean’
- Mostly used to compare classification results
- Precision and Recall usually inversely related

$$F_1 = 2 \cdot \frac{Precision \cdot Recall}{Precision + Recall}$$

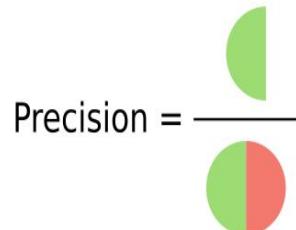
Case: High Precision, Low Recall

All boxes contain faces but did not find a lot ->
Classifier too careful, underestimating count of faces

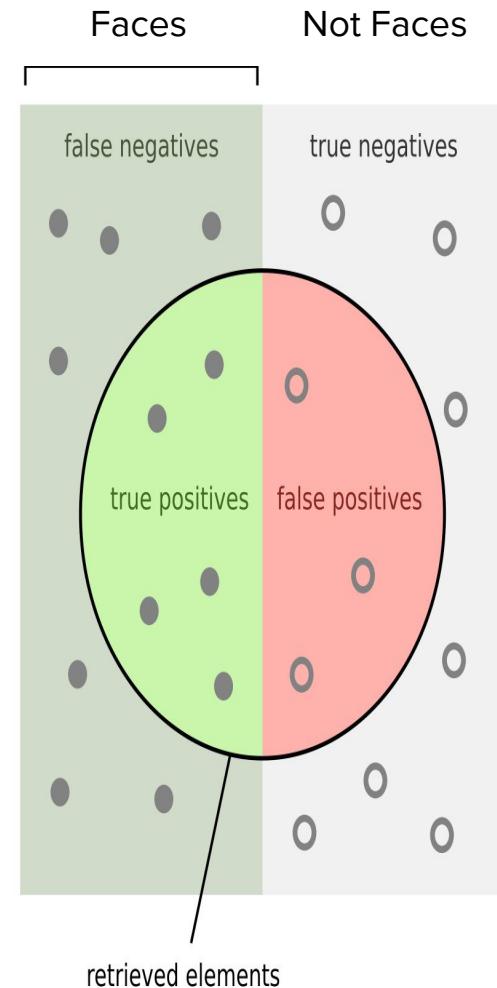
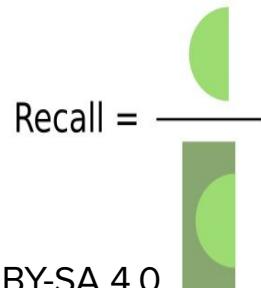
F1 Score -> Numerator goes down due to low recall

$$F_1 = 2 \cdot \frac{Precision \cdot Recall}{Precision + Recall}$$

How many retrieved boxes
show faces?



How many faces
are retrieved?



Other Case: Low Precision, High Recall

High Recall: No false negatives -> All faces were found

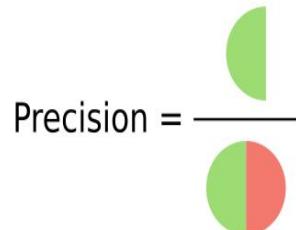
Low Precision: Also, many false positives

Classifier sees faces everywhere

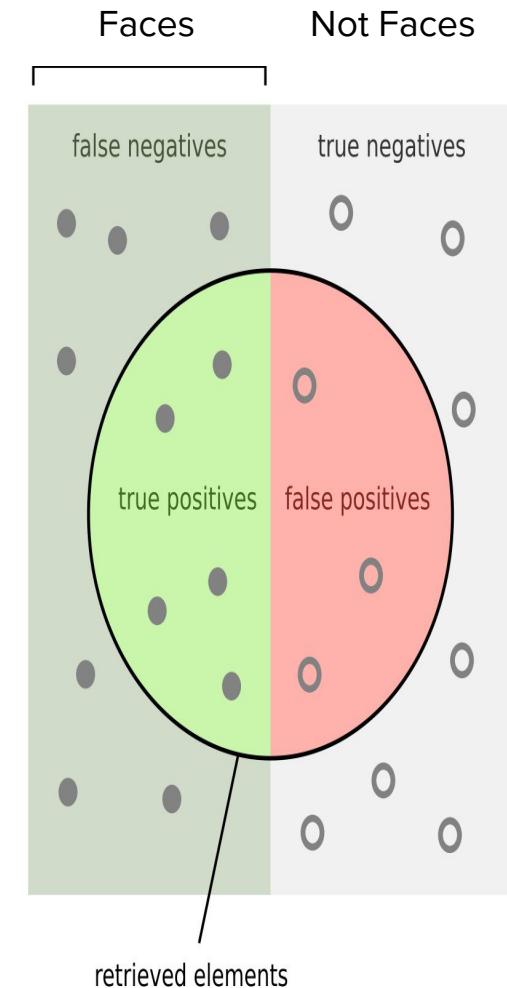
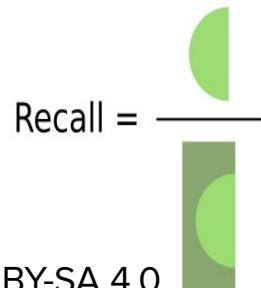
F1 Score -> Numerator goes down due to low precision

$$F_1 = 2 \cdot \frac{Precision \cdot Recall}{Precision + Recall}$$

How many retrieved boxes
show faces?



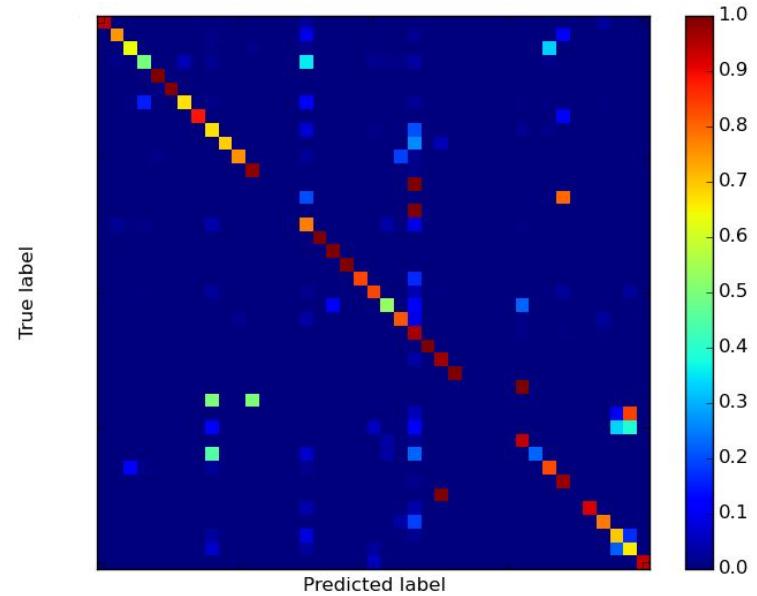
How many faces
are retrieved?



Classification performance metrics

- Accuracy = proportion of correct
- Recall (sensitivity) \approx proportion of "not missed"
 \approx "completeness" level [exhaustivité]
- Precision (specificity) \approx reliability of predicted labels
- Confusion matrix: predicted label v.s. true label

C.Matrix							ACTUAL	RECALL
	True positive	False positive	True negative	False negative				
1	339	15	5	0	0	0	359	94.43%
2	15	305	14	0	0	0	334	91.32%
3	6	10	242	0	0	0	258	93.80%
4	0	0	0	302	30	0	332	90.96%
5	0	0	0	15	368	0	383	96.08%
6	0	0	0	0	0	394	394	100.00%
PREDICTED	360	330	261	317	398	394	2060	94.43%
PRECISION	94.17%	92.42%	92.72%	95.27%	92.46%	100.00%	94.51%	94.66%

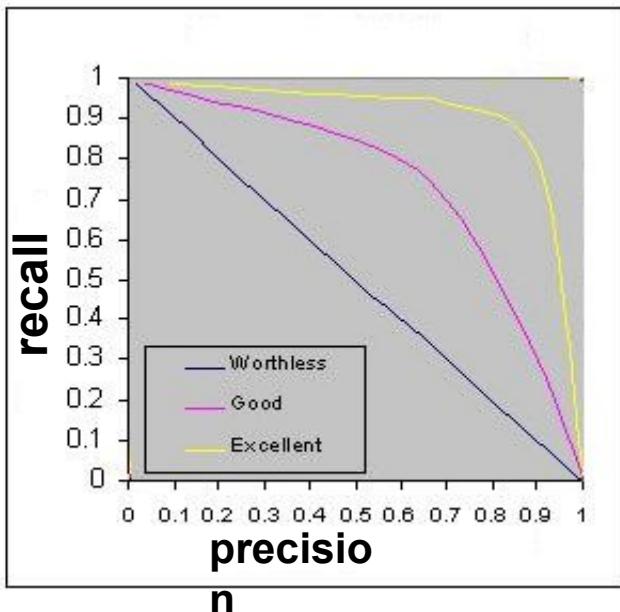


Precision-recall trade-off and curve

Classifier C1 predicts better than C2

iff C1 has better recall and precision

+ Trade-off between recall and precision



□ Compare precision-recall curves!

For numeric comparison (or if curves cross each other),
Area Under Curve (AUC)

- Quality measure for a learnt model h :

$$Q(h) = E(L(h(x), y))$$

where $L(h(x), y)$ is the « *LOSS function* »
often = $\|h(x) - y\|^2$

- What optimum for h ?

h^* *absolute optimum* = $\text{argMin}_h(E(h))$

h^* *optimum within H family* = $\text{argMin}_{h \in H}(E(h))$

$h^*_{H,n}$ *optimum in H from finite set of examples* =
 $\text{argMin}_{h \in H}(E_n(h))$

where $E_n(h) = (1/N) \sum_i (L(h(x_i), y_i))$

$$E(h^*_{H,n}) - E(h^*) = [E(h^*_{H,n}) - E(h^*)_H] + [E(h^*)_H - E(h^*)]$$

ESTIMATION error *MODEL error*

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Formal definition of SUPERVISED LEARNING

"LEARNING = APPROXIMATE + GENERALIZE"

Given a FINITE set of examples $(\mathbf{x}_1, \mathbf{y}_1), (\mathbf{x}_2, \mathbf{y}_2), \dots, (\mathbf{x}_n, \mathbf{y}_n)$
 where $\mathbf{x}_i \in \mathbb{R}^d$ = input vectors, and $\mathbf{y}_i \in \mathbb{R}^s$ = target values
 (given by the "teacher"), find a function h which
"approximates AND GENERALIZES as best as possible"
 the underlying function such that $\mathbf{y}_i = f(\mathbf{x}_i) + \text{noise}$

⇒ goal = to minimize the GENERALIZATION error

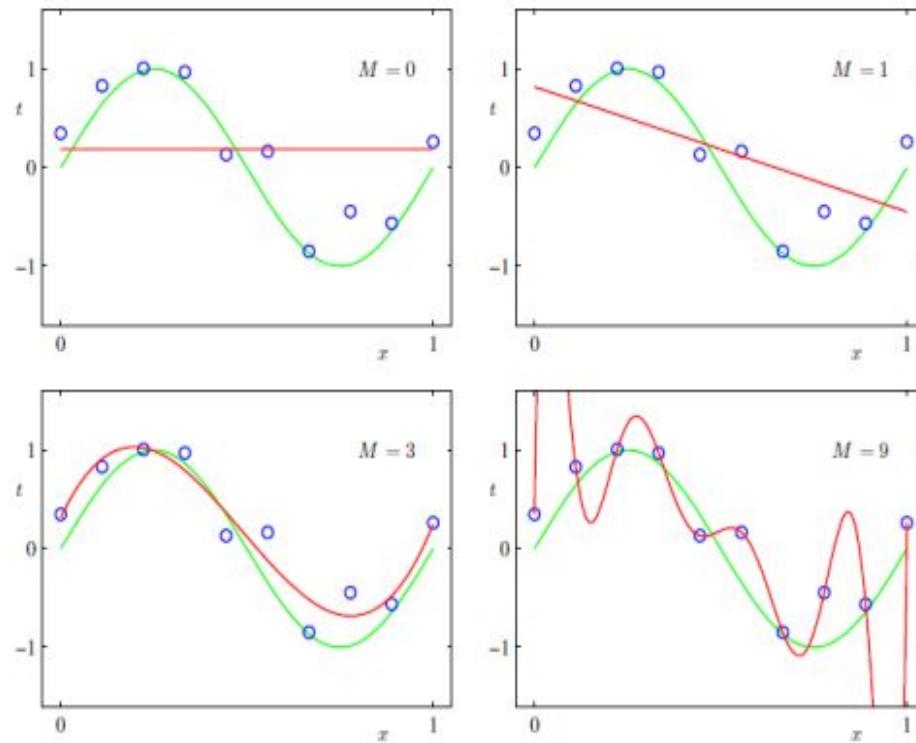
$$E_{\text{gen}} = \int \|h(\mathbf{x}) - f(\mathbf{x})\|^2 p(\mathbf{x}) d\mathbf{x}$$

(where $p(\mathbf{x})$ = probability distribution of \mathbf{x})

About over-fitting

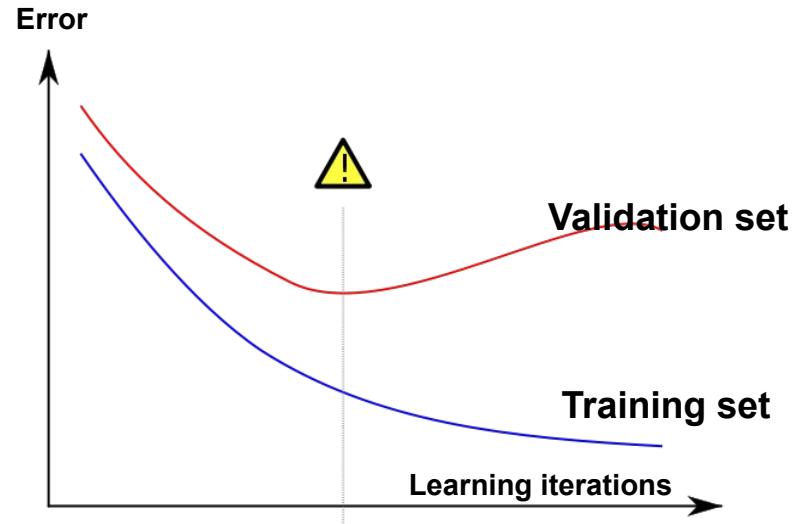
The generalization error cannot be directly measured, only empirical error on examples can be estimated:

$$E_{\text{emp}} = \left(\sum_i \|h(x_i) - y_i\|^2 \right) / n$$



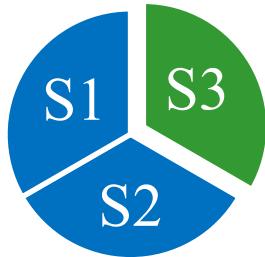
Fitting a data set to different orders of polynomials
 [from Bishop, "Pattern Recognition and Machine Learning"]

Detection of over-fitting
 for an iterative algorithm



To avoid over-fitting and maximize generalization, absolutely essential to use some VALIDATION estimation, for optimizing training hyper-parameters (and stopping criterion):

- either use a *separate validation dataset* (random split of data into Training-set + Validation-set)
- or use CROSS-VALIDATION:
 - Repeat k times: train on $(k-1)/k$ proportion of data + estimate error on remaining $1/k$ portion
 - Average the k error estimations



3-fold cross-validation:

- Train on $S_1 \cup S_2$ then estimate err_{S_3} error on S_3
- Train on $S_1 \cup S_3$ then estimate err_{S_2} error on S_2
- Train on $S_2 \cup S_3$ then estimate err_{S_1} error on S_1
- Average validation error: $(\text{err}_{S_1} + \text{err}_{S_2} + \text{err}_{S_3})/3$

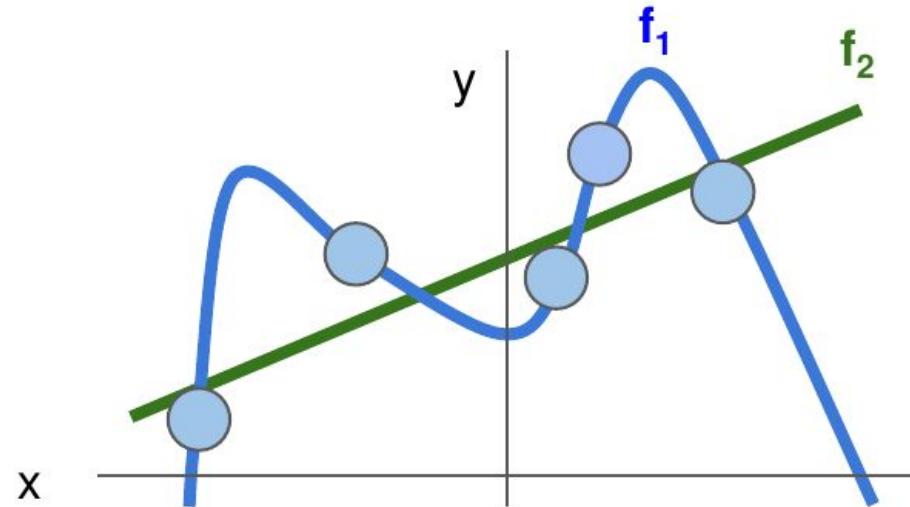
Regularization

Want to find:

- “Simplest” h
- Often, add term to loss
- Consider:
 - Loss L
 - Weights W
 - Function f

$$L(W) = \frac{1}{N} \sum_{i=1}^N L_i(f(x_i, W), y_i)$$

Data loss: Model predictions
should match training data



From: Lecture 3: Regularization and Optimization, Fei-Fei Li, Ehsan Adeli, Zane Durante

Regularization

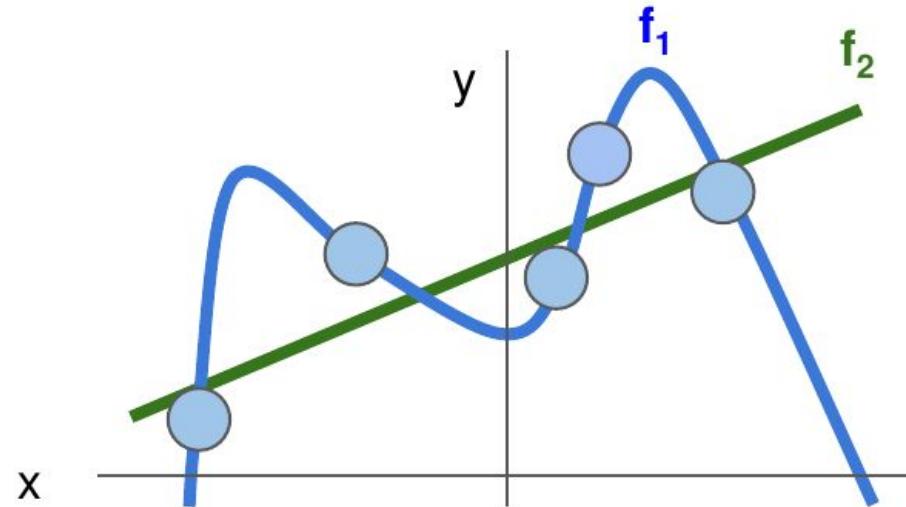
Want to find:

- “Simplest” h
- Often, add term to loss
- Consider:
 - Loss L
 - Weights W
 - Function f
 - Regularization R

$$L(W) = \underbrace{\frac{1}{N} \sum_{i=1}^N L_i(f(x_i, W), y_i)}_{\text{Data loss: Model predictions}} + \lambda \underbrace{R(W)}_{\text{Regularization}}$$

Data loss: Model predictions should match training data

Regularization: Prevent the model from doing *too well* on training data



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Simple examples

$$\text{L2 regularization: } R(W) = \sum_k \sum_l W_{k,l}^2$$

$$\text{L1 regularization: } R(W) = \sum_k \sum_l |W_{k,l}|$$

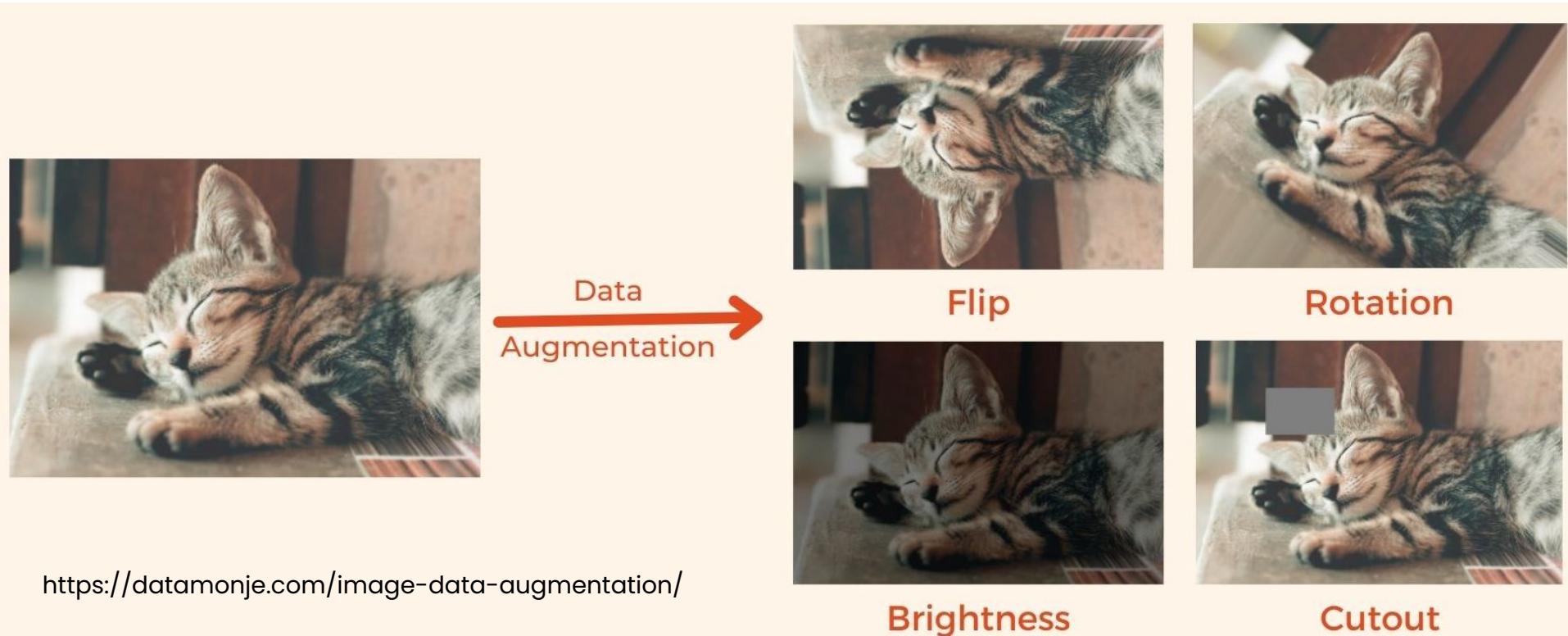
$$\text{Elastic net (L1 + L2): } R(W) = \sum_k \sum_l \beta W_{k,l}^2 + |W_{k,l}|$$

Regularization: Prevent the model from doing *too well* on training data

Data augmentation (for classification)

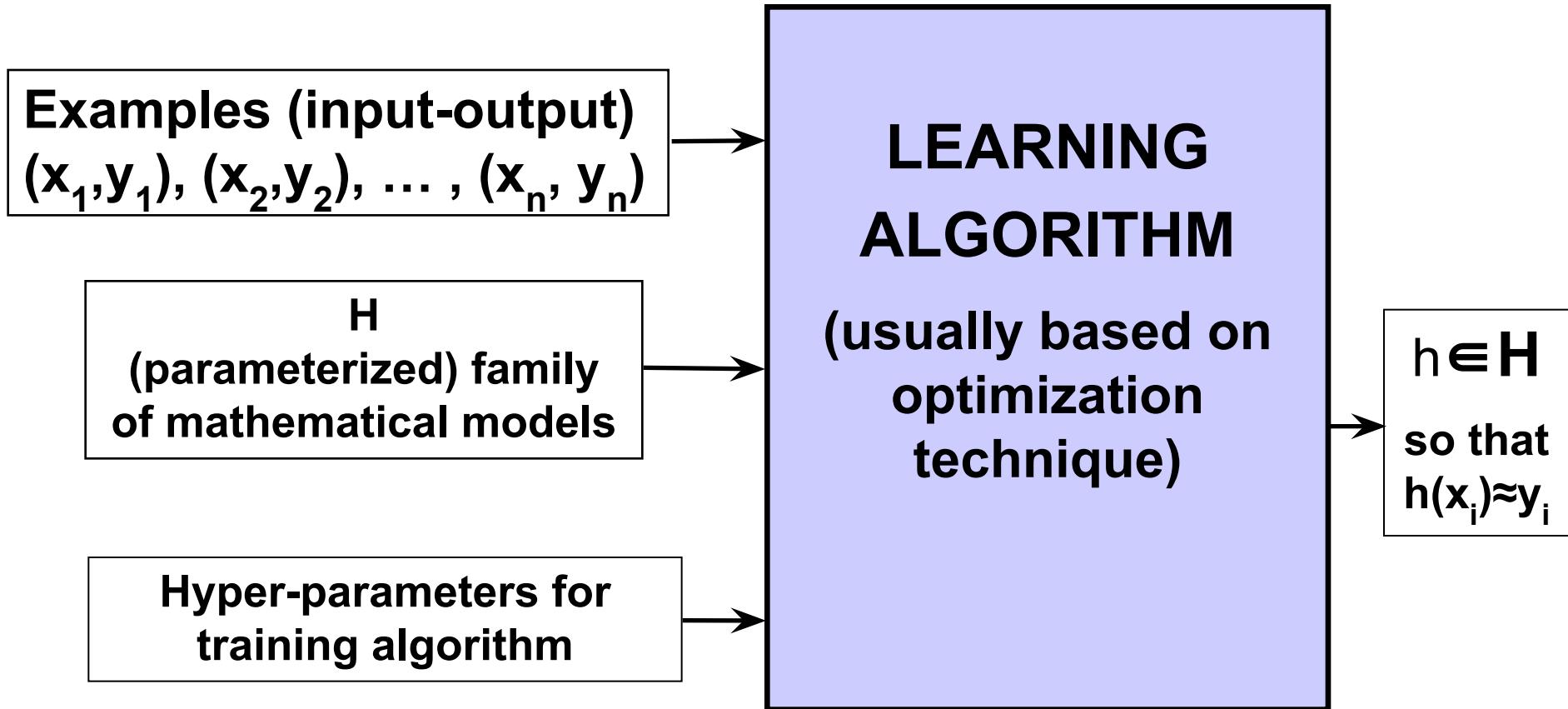
In the case of CLASSIFICATION, over-fitting avoidance and better generalization can also be favored by DATA AUGMENTATION:

for each labelled example in training set, generate several slightly *distorted* variants which shall have the same label



Synthesis on various algorithms for SUPERVISED Machine-Learning

Supervised learning



Typology of classification methods

- By *similarity* Nearest Neighbors (kNN)
- By *succession of elementary tests* Decision Trees
- By *probabilistic computations* (using hypothesis on distribution of classes) Bayesian methods
- By *error minimization* (gradient descent, etc...)
 - Neural Networks, etc...
- Idem + "*margin*" maximization
 - Support Vector Machines (SVM)
- By *voting committee (ensemble methods)*:
 - using trees Random Forests
 - using successive weightings of examples Boosting

- **Decision trees:** naturally adapted to symbolic inputs, very fast, good scaling for very high number of classes, "white" box; BUT **noise sensitive**
- **Multi-layer neural networks:** universal approximators, good generalization, easy handling of multi-class; BUT optimum model NOT guaranteed, many critical hyper-parameters (# hidden neurons, weight init., learning rate, # training epochs,...)
- **Support Vector Machines:** maths-guaranteed optimal separation, possible handling of structured input (graphs, etc...) via kernel; BUT not very efficient for multi-class (K times 1-vs-all SVMs, or at least $\log(K)$ times Ci-vs-Cj), training computation rises quickly with input dim and # of examples $O(\max(N, D) * \min(N, D)^2)$
- **Boosting of « weak » classifiers:** simple algo, can build strong classifier from any weak classifier, can select features during training; BUT not very efficient for multi-class (n times 1-vs-all)
- **Random forests:** OK for symbolic input, robustness to noise, very fast to compute, efficient for large # of classes and high input dim; BUT **training sometimes long**

Model type choice criteria for SUPERVISED learning

	MLP Neural Network	ConvNets	SVM	Boosting	Decision Tree	Random Forest
Many classes	+	+	--	--		++
High dimension of input			-		+	++
Many examples		REQUIRED (except if transfer-lear- ning)	-			
Interpretability ("white" box)	-	--			YES	
Data OTHER than vectors of values		Only "grid" data	Structured (string, graph)		symbolic	symbolic
Robustness to noise and erroneous labels	+	+	++		--	++
Ease/speed of training	-	---	+		++	+
Handling of features		Learn them		Automated selection		
Execution time		-			+++	+

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