Preliminary analysis of Greenland narwhals trajectories with smoothSDE

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In this analysis, we fit SDE models to the narwhal data. In this preliminary work, the analysis is made without considering any constraints on the motion. Only the effect of the distance to the ship will be considered in the response model.

Set up

```
set.seed(42)
library(smoothSDE) #sde fit
library(ggplot2) #plots
library(dplyr)
                 #manipulate dataframes
library(tidyr)
                # same
library(plotly) # dynamic plots
library(htmlwidgets) #save dynamic plots
library(mgcv)
                # mixed models
library(here)
                # path management
library(xtable) # for latex tables
                # read shapefile for land polygons
library(sf)
library(gganimate) # animated trajectories
```

```
n_pre12=length(dataBE12$time) #nb of obs before exposure with first 12h removed
n_pre24=length(dataBE24$time) #nb of obs before exposure with first 24h removed
n_post=length(dataAE$time) #number of observations after exposure
```

Baseline CTCRW models

converged

CTCRW without random individual effects

We fit a baseline CTCRW with constant parameters (no covariates) on the data before exposure dateBE12. The mean velocity μ is fixed to (0,0) because we are not investigating a long term migration movement.

We now extract the estimated parameters and their standard deviations. These estimates are on the log-scale.

```
estimates_bas_ctcrw0=as.list(baseline_ctcrw0$tmb_rep(),what="Est")
std_bas_ctcrw0=as.list(baseline_ctcrw0$tmb_rep(),what="Std")
```

We process the results and show a table with the estimates and their standard deviations.

% latex table generated in R 4.4.0 by xtable 1.8-4 package % Mon Nov 18 10:01:07 2024

Parameter	Estimate	Std_Error
log_sigma_obs	-3.26	0.03
mu1.(Intercept)	0.00	
mu2.(Intercept)	0.00	
tau.(Intercept)	0.07	0.09
nu.(Intercept)	1.54	0.04

Table 1: Parameter Estimates and Standard Errors

From this we can obtain 95% confidence intervals for the parameters τ , ν and σ_{obs} .

We include the results in a latex table.

% latex table generated in R 4.4.0 by xtable 1.8-4 package % Mon Nov 18 10:01:07 2024

Parameter	Estimate	CI
σ_{obs}	38.58	[36.39; 40.85]
au	1.07	[0.90; 1.27]
ν	4.69	[4.35; 5.04]

Table 2: Baseline estimations

The estimate for τ is $\bar{\tau}=1.08$ h and the estimate for ν is $\bar{\nu}=4.69$ km/h. The measurement error standard deviation is estimated to $\bar{\sigma}_{obs}\simeq 38$ m. The measurement error in Fastloc GPS data mainly depends on the number of satellite that were used to compute the location. This number might change from a data point to another. However, we don't know the number of satellites that computed the position in the data. That is why we assume a constant standard deviation for the measurement error. We know from Weensveen paper, table 3, that it should be at most around 30m when only 4 satellites are involved, and then decrease as the number of satellites increases. This suggest that the measurement error might be slightly overestimated here.

Sensitivity to measurement error standard deviation

converged

converged

initial value -3779.571355 ## final value -3793.723826

To investigate the sensitivity of the parameters estimates to the measurement error, we fix σ_{obs} to different values and estimate the parameters again.

```
#fixed values for std of measurement error
sigma_obs=c(0.025,0.05,0.075,0.1)
list_baseline_ctcrw0=list()
for (i in 1:length(sigma_obs)){
  H=array(rep(sigma_obs[i]^2*diag(2),n_pre12),dim=c(2,2,n_pre12))
  baseline ctcrw0 fixed error <- SDE new (formulas = formulas, data = data BE12,
                                        type = "CTCRW",
                              response = c("x","y"),
                    par0 = par0,other_data=list("H"=H),fixpar=c("mu1","mu2"))
  baseline_ctcrw0_fixed_error$fit()
  list_baseline_ctcrw0[[i]] = baseline_ctcrw0_fixed_error
}
## initial value -3827.977217
## final value -3992.996564
## converged
## initial value -4026.998691
## final value -4035.929320
```

```
## initial value -3479.532212
## final value -3503.290946
## converged

list_baseline_ctcrw0_est=list()
list_baseline_ctcrw0_std=list()
```

```
for (i in seq_along(list_baseline_ctcrw0)) {
   estimates=as.list(list_baseline_ctcrw0[[i]]$tmb_rep(),what="Est")
   std=as.list(list_baseline_ctcrw0[[i]]$tmb_rep(),what="Std")
   list_baseline_ctcrw0_est[[i]]=estimates
   list_baseline_ctcrw0_std[[i]]=std
}

for (i in seq_along(list_baseline_ctcrw0)) {
```

```
estimates=list_baseline_ctcrw0_est[[i]]
std=list_baseline_ctcrw0_std[[i]]
# Create data frames for each set
log_sigma_obs <- combine_to_df(estimates$log_sigma_obs,</pre>
                              std$log_sigma_obs, "log_sigma_obs")
coeff_fe <- combine_to_df(estimates$coeff_fe,</pre>
                         std$coeff_fe,
                         rownames(estimates$coeff_fe))
# Combine all data frames into one
table_data <- bind_rows(log_sigma_obs, coeff_fe)</pre>
latex_table <- xtable(</pre>
 table_data,
  caption = paste(
    "Parameter Estimates and Standard Errors for fixed \\(\\sigma_{obs}=\\) ",
    sigma_obs[i]," m"),
 xtable.table.placement="H")
# Print LaTeX table
print(latex_table, type = "latex", include.rownames = FALSE,table.placement="H")
```

% latex table generated in R 4.4.0 by xtable 1.8-4 package % Mon Nov 18 10:01:11 2024

Parameter	Estimate	Std_Error
log_sigma_obs	0.00	
mu1.(Intercept)	0.00	
mu2.(Intercept)	0.00	
tau.(Intercept)	-0.36	0.07
nu.(Intercept)	1.57	0.03

Table 3: Parameter Estimates and Standard Errors for fixed $\sigma_{obs} = 0.025$ m

% latex table generated in R 4.4.0 by xtable 1.8-4 package % Mon Nov 18 10:01:11 2024

Parameter	Estimate	Std_Error
log_sigma_obs	0.00	
mu1.(Intercept)	0.00	
mu2.(Intercept)	0.00	
tau.(Intercept)	0.25	0.09
nu.(Intercept)	1.54	0.04

Table 4: Parameter Estimates and Standard Errors for fixed $\sigma_{obs} = 0.05 \text{ m}$

% latex table generated in R 4.4.0 by xtable 1.8-4 package % Mon Nov 18 10:01:11 2024

Parameter	Estimate	Std_Error
log_sigma_obs	0.00	
mu1.(Intercept)	0.00	
mu2.(Intercept)	0.00	
tau.(Intercept)	0.45	0.10
nu.(Intercept)	1.52	0.05

Table 5: Parameter Estimates and Standard Errors for fixed $\sigma_{obs}=0.075~\mathrm{m}$

% latex table generated in R 4.4.0 by xtable 1.8-4 package % Mon Nov 18 10:01:11 2024

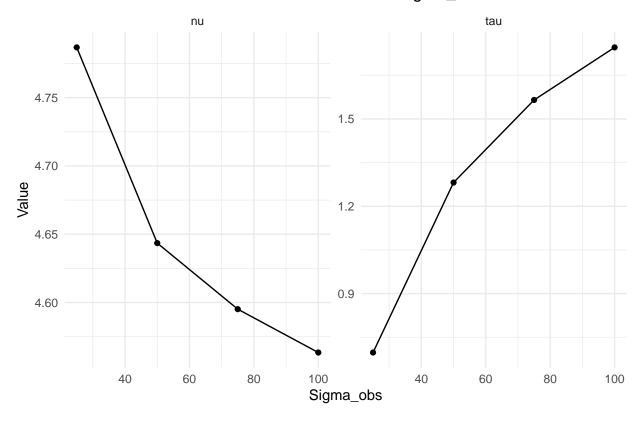
Parameter	Estimate	Std_Error
log_sigma_obs	0.00	
mu1.(Intercept)	0.00	
mu2.(Intercept)	0.00	
tau.(Intercept)	0.56	0.11
nu.(Intercept)	1.52	0.05

Table 6: Parameter Estimates and Standard Errors for fixed $\sigma_{obs}=0.1~\mathrm{m}$

```
tau_estimates=sapply(list_baseline_ctcrw0_est,
                     function(estimates)
                       {exp(estimates$coeff_fe["tau.(Intercept)",1])})
nu_estimates=sapply(list_baseline_ctcrw0_est,
                    function(estimates)
                      {exp(estimates$coeff_fe["nu.(Intercept)",1])})
tau_std=sapply(list_baseline_ctcrw0_std,
               function(std) {exp(std$coeff_fe["tau.(Intercept)",1])})
nu_std=sapply(list_baseline_ctcrw0_std,
              function(std) {exp(std$coeff_fe["nu.(Intercept)",1])})
df=as.data.frame(cbind(tau_estimates,nu_estimates,sigma_obs))
colnames(df)=c("tau","nu","sigma_obs")
df <- df %>%
 pivot_longer(cols = c(tau, nu), names_to = "parameter", values_to = "value")
ggplot(df, aes(x = 1000*sigma_obs, y = value)) +
  geom_point() +
  geom_line() +
  theme_minimal() +
  xlab("Sigma_obs") +
 ylab("Value") +
```

```
ggtitle("Estimated Tau and Nu as functions of fixed Sigma_obs") +
facet_wrap(~parameter, scales = "free_y") # Facet by 'parameter' (tau or nu)
```

Estimated Tau and Nu as functions of fixed Sigma_obs



We see a clear effect of the fixed measurement error on the estimates of τ , and a slight influence of ν . We also remark that as the measurement error grows, the uncertainty on the estimates of τ and ν increases. Overall, knowing or estimating precisely the measurement error will be crucial in the analysis.

CTCRW with random individual effects

converged

```
estimates_bas_ctcrw1=as.list(baseline_ctcrw1$tmb_rep(),what="Est")
std_bas_ctcrw1=as.list(baseline_ctcrw1$tmb_rep(),what="Std")
```

% latex table generated in R 4.4.0 by xtable 1.8-4 package % Mon Nov 18 10:01:12 2024

Parameter	Estimate	Std_Error
log_sigma_obs	-3.33	0.03
mu1.(Intercept)	0.00	
mu2.(Intercept)	0.00	
tau.(Intercept)	0.06	0.15
nu.(Intercept)	1.53	0.06
tau.s(ID)	2.70	0.85
nu.s(ID)	4.80	0.99
tau.s(ID).1	0.12	0.17
tau.s(ID).2	-0.07	0.18
tau.s(ID).3	0.06	0.16
tau.s(ID).4	-0.42	0.20
tau.s(ID).5	-0.01	0.18
tau.s(ID).6	0.29	0.21
nu.s(ID).1	-0.06	0.07
nu.s(ID).2	-0.03	0.07
nu.s(ID).3	0.04	0.07
nu.s(ID).4	0.12	0.08
nu.s(ID).5	-0.02	0.07
nu.s(ID).6	-0.07	0.09

Table 7: Parameter Estimates and Standard Errors

As previously, we can obtain 95% confidence intervals for the parameters τ , ν and σ_{obs} , and include the results in a latex table.

```
post_coeff_bas_ctrcw1=baseline_ctcrw1$post_coeff(n_post=10000)
post_par_bas_ctcrw1=list(
   "sigma_obs"=1000*exp(post_coeff_bas_ctrcw1$log_sigma_obs),
   "tau"=exp(post_coeff_bas_ctrcw1$coeff_fe[,"tau.(Intercept)"]),
   "nu"=exp(post_coeff_bas_ctrcw1$coeff_fe[,"nu.(Intercept)"]),
   "sigma_tau"=1/sqrt(exp(post_coeff_bas_ctrcw1$log_lambda[,"tau.s(ID)"])),
```

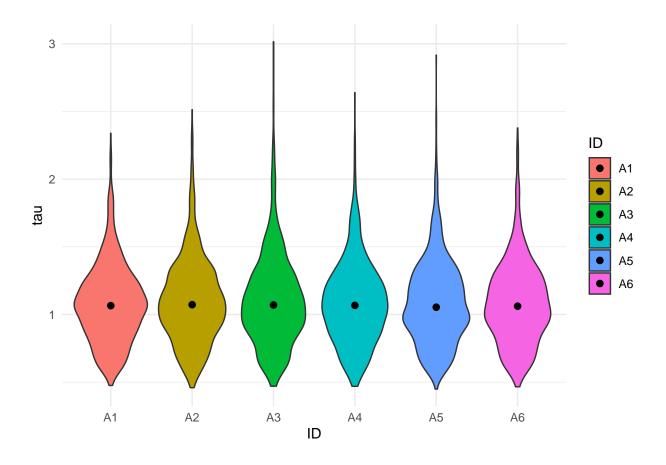
% latex table generated in R 4.4.0 by xtable 1.8-4 package % Mon Nov 18 10:01:12 2024

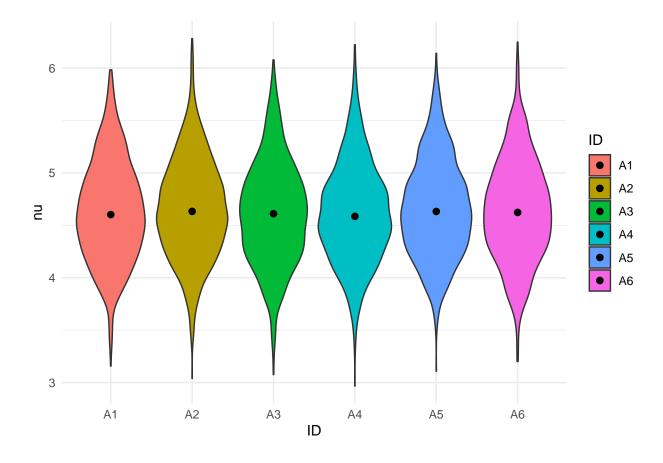
Parameter	Estimate	CI
σ_{obs}	35.83	[33.58; 38.17]
au	1.07	[0.79; 1.40]
ν	4.64	[4.15; 5.19]
$\sigma_{ au}$	0.28	[0.11; 0.59]
$\sigma_{ u}$	0.10	[0.04; 0.24]

Table 8: Baseline estimations with random effects

Note that the random effect is multiplicative and not additive since it appears in the log of the parameters. We can plot the estimates on the parameter scale for each narwhal.

```
baseline_ctcrw1$get_all_plots(baseline=NULL,show_CI="simultaneous")
```





RACVM without random individual effects

We can also test whether adding a constant rotational ω in the SDE model would make sense. For this, we fit a RACVM model.

```
## initial value -4026.998691
## iter 10 value -4078.320598
## iter 10 value -4078.320611
```

% latex table generated in R 4.4.0 by xtable 1.8-4 package % Mon Nov 18 10:01:14 2024

table_data_baseline_racvm0 <- bind_rows(log_sigma_obs, coeff_fe)

Parameter	Estimate	Std_Error
log_sigma_obs	-3.26	0.03
mu1.(Intercept)	0.00	
mu2.(Intercept)	0.00	
tau.(Intercept)	0.07	0.09
nu.(Intercept)	1.54	0.04
omega.(Intercept)	-0.00	0.08

Table 9: Parameter Estimates and Standard Errors

The estimate of ω is 0. This indicates that a **constant** parameter ω is irrelevant in the model. As a consequence, the final baseline model we keep is **baseline_ctcrw1** which corresponds to a CTCRW with constant parameters τ and ν and mean velocity fixed to zero.

Sensitivity analysis of the baseline CTCRW to the tagging effect threshold

In this first analysis, we only removed 12h of data after the tagging for each narwhal. However, the narwhals might still be affected by the tagging and not behave "normally". This would invalidate all our conclusions in the response model, if the baseline model happens to be biased. Therefore, we need to assess the sensitivity of the baseline model to the time threshold we choose for the tagging effect. Here, we only repeat the fit for the model baseline_ctcrw1 with the sub dataset dataBE24 where all the data until 24h after tagging have been removed.

```
#initial parameters
par0 <- c(0,0,1,4)

#model formula
formulas <- list(mu1=~1,mu2=~1,tau =~s(ID,bs="re"),nu=~s(ID,bs="re"))

#Fit baseline with measurement error estimated from the data
baseline_ctcrw1_24h<- SDE$new(
   formulas = formulas,data = dataBE24,type = "CTCRW",
    response = c("x","y"),par0 = par0,
   other_data=list("log_sigma_obs0"=log(0.05)),</pre>
```

```
fixpar=c("mu1","mu2"))
baseline_ctcrw1_24h$fit()
## initial value -2188.786204
## iter 10 value -2210.115293
## iter 20 value -2210.505845
## final value -2210.514723
## converged
estimates_bas_ctcrw1_24h=as.list(baseline_ctcrw1_24h$tmb_rep(), what="Est")
std_bas_ctcrw1_24h=as.list(baseline_ctcrw1_24h$tmb_rep(),what="Std")
# Create data frames for each set
log_sigma_obs <- combine_to_df(</pre>
 estimates bas ctcrw1 24h$log sigma obs,
  std_bas_ctcrw1_24h$log_sigma_obs, "log_sigma_obs")
coeff_fe <- combine_to_df(estimates_bas_ctcrw1_24h$coeff_fe,</pre>
                          std_bas_ctcrw1_24h$coeff_fe,
                          rownames(estimates bas ctcrw1 24h$coeff fe))
# Combine all data frames into one
table_data_baseline_ctcrw1_24h <- bind_rows(log_sigma_obs, coeff_fe)
```

% latex table generated in R 4.4.0 by xtable 1.8-4 package % Mon Nov 18 10:01:23 2024

Parameter	Estimate	Std_Error
log_sigma_obs	-3.12	0.04
mu1.(Intercept)	0.00	
mu2.(Intercept)	0.00	
tau.(Intercept)	-0.09	0.11
nu.(Intercept)	1.46	0.06

Table 10: Parameter Estimates and Standard Errors

The standard deviations are wider due to the smaller amount of data, but also due to the fact that the measurement error is estimated higher than before. τ seems to be estimated slightly below the value we obtained for the dataset dataBE12, but the difference seems reasonable as the CI of the two estimates overlap.

```
## initial value -2182.914713
## iter 10 value -2198.359754
## final value -2198.470234
## converged
estimates_bas_ctcrw1_24h_fixed_error=as.list(
  baseline_ctcrw1_24h_fixed_error$tmb_rep(), what="Est")
std_bas_ctcrw1_24h_fixed_error=as.list(
  baseline_ctcrw1_24h_fixed_error$tmb_rep(),what="Std")
# Create data frames for each set
log_sigma_obs <- combine_to_df(</pre>
  estimates_bas_ctcrw1_24h_fixed_error$log_sigma_obs,
  std_bas_ctcrw1_24h_fixed_error$log_sigma_obs, "log_sigma_obs")
coeff_fe <- combine_to_df(</pre>
  estimates_bas_ctcrw1_24h_fixed_error$coeff_fe,
  std_bas_ctcrw1_24h_fixed_error$coeff_fe,
  rownames(estimates_bas_ctcrw1_24h_fixed_error$coeff_fe))
# Combine all data frames into one
table_data_baseline_ctcrw1_24h_fixed_error <- bind_rows(log_sigma_obs, coeff_fe)
```

% latex table generated in R 4.4.0 by xtable 1.8-4 package % Mon Nov 18 10:01:30 2024

Parameter	Estimate	Std_Error
log_sigma_obs	0.00	
mu1.(Intercept)	0.00	
mu2.(Intercept)	0.00	
tau.(Intercept)	-0.33	0.10
nu.(Intercept)	1.45	0.07

Table 11: Parameter Estimates and Standard Errors

When the measurement error is fixed to the value we initially estimated from the whole dataset dateBE12, we observe a big decrease in the estimate of τ . This indeed suggest a shift in the behavior of the whales within the time interval [12h,24h] after tagging, which might invalidate our results.

Response CTCRW models

Response CTCRW with constant parameters

First, we try to fit the exact same model as baseline_ctcrw1 on the data during exposure to assess a potential shift in the behavior due to the presence of the ship. We fix the measurement error to the value that has been estimated from the data before exposure.

```
#initial parameters
par0 <- c(0,0,1,4)

#model formula
formulas <- list(mu1=~1,mu2=~1,tau =~s(ID,bs="re"),nu=~s(ID,bs="re"))</pre>
```

```
sigma_obs=exp(estimates_bas_ctcrw1$log_sigma_obs)
H=array(rep(sigma_obs^2*diag(2),n_post),dim=c(2,2,n_post))
#Fit response with measurement error estimated from the baseline
response_ctcrw1<- SDE$new(formulas = formulas,data = dataAE,type = "CTCRW",
                          response = c("x","y"),
                          par0 = par0,
                          other data=list("H"=H),
                          fixpar=c("mu1","mu2"))
response_ctcrw1$fit()
## initial value -8140.158397
## iter 10 value -8159.892281
## final value -8159.902600
## converged
estimates_res_ctcrw1=as.list(response_ctcrw1$tmb_rep(), what="Est")
std_res_ctcrw1=as.list(response_ctcrw1$tmb_rep(), what="Std")
# Create data frames for each set
log_sigma_obs <- combine_to_df(estimates_res_ctcrw1$log_sigma_obs,</pre>
                               std res ctcrw1$log sigma obs, "log sigma obs")
coeff_fe <- combine_to_df(estimates_res_ctcrw1$coeff_fe,</pre>
                          std res ctcrw1$coeff fe,
                          rownames(estimates_res_ctcrw1$coeff_fe))
# Combine all data frames into one
table_data_response_ctcrw1 <- bind_rows(log_sigma_obs, coeff_fe)</pre>
```

% latex table generated in R 4.4.0 by xtable 1.8-4 package % Mon Nov 18 10:01:53 2024

Parameter	Estimate	Std_Error
log_sigma_obs	0.00	
mu1.(Intercept)	0.00	
mu2.(Intercept)	0.00	
tau.(Intercept)	-0.06	0.06
nu.(Intercept)	1.46	0.04

Table 12: Parameter Estimates and Standard Errors

The estimated standard deviation of the random effects can be computed with sdev method in smoothSDE.

```
response_ctcrw1$sdev()

## [,1]
## tau.s(ID) 0.06722654
## nu.s(ID) 0.07134007
```

The estimates are lower than those obtained from the data before exposure. This may happen because we have short trajectories before exposure, that may not represent the whole range of possible movement for each narwhal, and therefore there may be more varieties of movements between the different individuals. On

the contrary, the trajectories during exposure are longer so we can reasonably say that they represent better the range of possible movement. The lower standard deviation of the random effects might then indicate that on the long run, the narwhals in the study tend to have similar movement characteristics.

The estimated value for τ is slightly lower than the value we obtained from the data before exposure. The value for ν is also slightly lower. In both cases, the CI of the estimate overlaps with the CI of the estimate from the data before exposure. To better understand if this difference in the estimated values of the parameters is due to the presence of the ship, we will introduce the exposure to ship ExpShip (or E_{ship} in the paper) covariate in the model.

Response models with splines of ExpShip

The intercept of the parameters τ and ν are considered as offset in the statistical model, and fixed using the estimates we get from the baseline model baseline_ctcrw1. The measurement error is an offset 7that is fixed to the value that has been estimated from the data before exposure.

In the response model, we suppose that the presence of the ship has a similar effect on all the narwhals. Therefore, we estimate a mean reaction (if any) to the presence of the ship. We are aware that a variety of reactions might be possible, depending on the narwhals habituation to noise or on the specific place where it has been approached by the ship for instance. This variety of reaction can be assessed visually by looking at a small subset of the data, but is difficult to infer statistically (see [Heide-Jorgensen2021] figure 7).

```
#model formula
formulas <- list(mu1=~1,mu2=~1,
                 tau =~s(ExpShip,k=10,bs="cs")+s(ID,bs="re"),
                 nu=~s(ExpShip,k=10,bs="cs")+s(ID,bs="re"))
# Fit response with measurement error fixed to baseline value
sigma_obs=exp(estimates_bas_ctcrw1$log_sigma_obs)
H=array(rep(sigma_obs^2*diag(2),n_post),dim=c(2,2,n_post))
response_ctcrw_sp<- SDE$new(formulas = formulas,data = dataAE,type = "CTCRW",
                            response = c("x","y"),
                    par0 = par0,other data=list("H"=H),fixpar=c("mu1","mu2"))
# fix random effects to baseline values
response_ctcrw_sp$update_coeff_re(
  c(rep(0,9),baseline_ctcrw1$coeff_re()[1:6,1],rep(0,9)
    ,baseline ctcrw1$coeff re()[7:12,1]))
response ctcrw sp$update lambda(
  c(1,baseline_ctcrw1$lambda()[1,1],1,baseline_ctcrw1$lambda()[2,1]))
response_ctcrw_sp$update_coeff_fe(baseline_ctcrw1$coeff_fe())
#use the indices of the variable in the map for TMB
#to keep the coefficients in the right order
#otherwise we may have issues in function post_coeff
response_ctcrw_sp$update_map(list(coeff_re=factor(
  c(1:9,rep(NA,6),10:18,rep(NA,6))),
  coeff_fe=factor(rep(NA,4)),
  log_lambda=factor(c(1,NA,2,NA))))
response_ctcrw_sp$fit()
```

######################

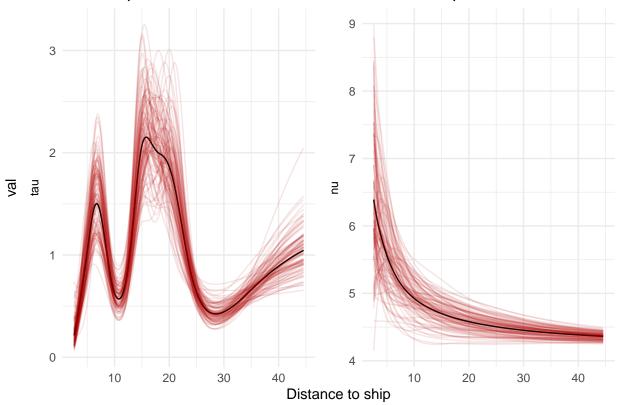
```
## ### smoothSDE model ###
## ########################
## > SDE for CTCRW model:
##
       dV(t) = beta (mu - V(t)) dt + sigma dW(t)
##
       dZ(t) = V(t) dt
## Parameterised in terms of:
## * tau = 1/beta
## * nu = sqrt(pi/beta)*sigma/2
## > Formulas for model parameters:
## * mu1 ~ fixed
## * mu2 ~ fixed
## * tau ~ s(ExpShip, k = 10, bs = "cs") +
     s(ID, bs = "re")
## * nu ~ s(ExpShip, k = 10, bs = "cs") +
     s(ID, bs = "re")
##
## initial value -8162.053737
## final value -8188.983767
## converged
estimates_res_ctcrw_sp=as.list(response_ctcrw_sp$tmb_rep(), what="Est")
std_res_ctcrw_sp=as.list(response_ctcrw_sp$tmb_rep(), what="Std")
# Create data frames for each set
log_sigma_obs <- combine_to_df(estimates_res_ctcrw_sp$log_sigma_obs,</pre>
                                std_res_ctcrw_sp$log_sigma_obs, "log_sigma_obs")
coeff_fe <- combine_to_df(estimates_res_ctcrw_sp$coeff_fe,</pre>
                           std_res_ctcrw_sp$coeff_fe,
                           rownames(estimates_res_ctcrw_sp$coeff_fe))
coeff_re <- combine_to_df(estimates_res_ctcrw_sp$coeff_re,</pre>
                           std_res_ctcrw_sp$coeff_re,
                           rownames(estimates_res_ctcrw_sp$coeff_re))
log_lambda <- combine_to_df(estimates_res_ctcrw_sp$log_lambda,</pre>
                             std_res_ctcrw_sp$log_lambda,
                             rownames(estimates_res_ctcrw_sp$log_lambda))
# Combine all data frames into one
table_data_response_ctcrw_sp <- bind_rows(</pre>
 log_sigma_obs, coeff_fe,coeff_re,log_lambda)
```

Parameter	Estimate	Std_Error
log_sigma_obs	0.00	
mu1.(Intercept)	0.00	
mu2.(Intercept)	0.00	
tau.(Intercept)	0.06	
nu.(Intercept)	1.53	
tau.s(ExpShip).1	-0.52	0.12
tau.s(ExpShip).2	-1.00	0.19
tau.s(ExpShip).3	0.10	0.22
tau.s(ExpShip).4	0.52	0.18
tau.s(ExpShip).5	0.55	0.18
tau.s(ExpShip).6	-0.49	0.17
tau.s(ExpShip).7	-0.26	0.18
tau.s(ExpShip).8	0.00	0.21
tau.s(ExpShip).9	-1.71	0.53
tau.s(ID).1	0.12	
tau.s(ID).2	-0.07	
tau.s(ID).3	0.06	
tau.s(ID).4	-0.42	
tau.s(ID).5	-0.01	
tau.s(ID).6	0.29	
nu.s(ExpShip).1	0.02	0.02
nu.s(ExpShip).2	0.03	0.02
nu.s(ExpShip).3	0.05	0.03
nu.s(ExpShip).4	0.06	0.04
nu.s(ExpShip).5	0.08	0.04
nu.s(ExpShip).6	0.10	0.05
nu.s(ExpShip).7	0.14	0.06
nu.s(ExpShip).8	0.23	0.08
nu.s(ExpShip).9	0.39	0.16
nu.s(ID).1	-0.06	
nu.s(ID).2	-0.03	
nu.s(ID).3	0.04	
nu.s(ID).4	0.12	
nu.s(ID).5	-0.02	
nu.s(ID).6	-0.07	
tau.s(ExpShip)	0.70	0.82
tau.s(ID)	2.70	
nu.s(ExpShip)	11.83	1.16
nu.s(ID)	4.80	

Table 13: Parameter Estimates and Standard Errors

```
# ELow exposure threshold
threshold <- 1 / 45 # 1/ max(distance to ship)
plot_data <- plot_data %>% filter(var > threshold)
plot_data$distance <- rep(1/plot_data$plot_data$group==1,"var"],</pre>
                          length(unique(plot_data$group)))
plot_data <- plot_data %>%
  mutate(mle= recode(mle, "#B300001A" = "no", "#000000FF" = "yes"))
plot_data <- plot_data %>%
  mutate(par= recode(par, "1" = "tau", "2" = "nu"))
pal \leftarrow c("no" = rgb(0.7, 0, 0, 0.1), "yes" = rgb(0, 0, 0, 1))
plot_smooth_par_distance=ggplot(plot_data, aes(x = distance, group = group)) +
  scale_colour_manual(values = pal, guide = "none") +
  facet_wrap(c("par"), scales = "free_y",strip.position = "left") +
  theme_minimal() + xlab("Distance to ship") +
  ggtitle("Smooth parameters as a function of distance to ship") +
  theme(strip.background = element_blank(),strip.placement = "outside",
        strip.text = element_text(colour = "black"))+
  geom_line(aes(y = val,color=mle))
plot_smooth_par_distance
```

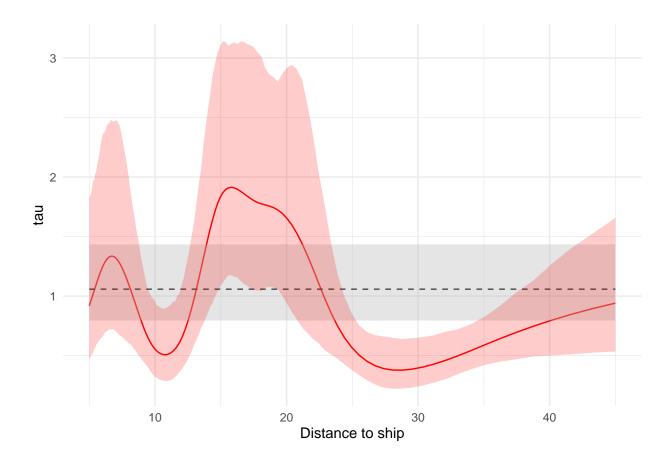
Smooth parameters as a function of distance to ship

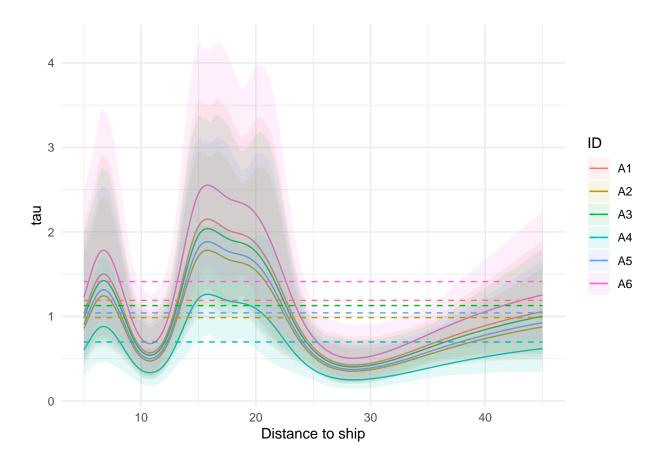


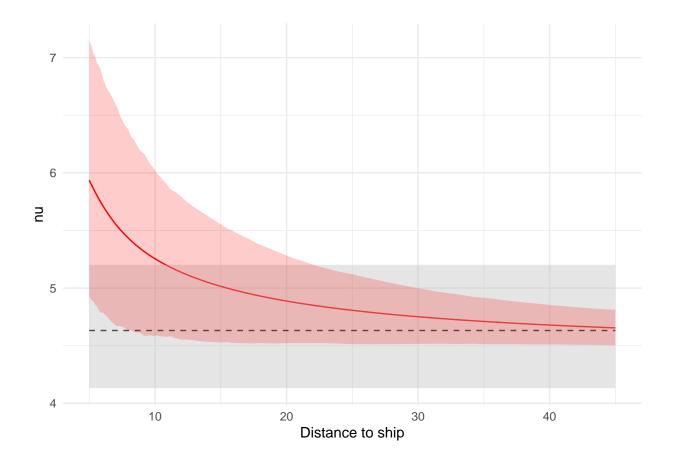
The estimated smooth functions depend on the number of knots we choose in the splines. For ν , the estimated smooth does not change as we increase gradually the degree of freedom to 10, meaning that only a few knots

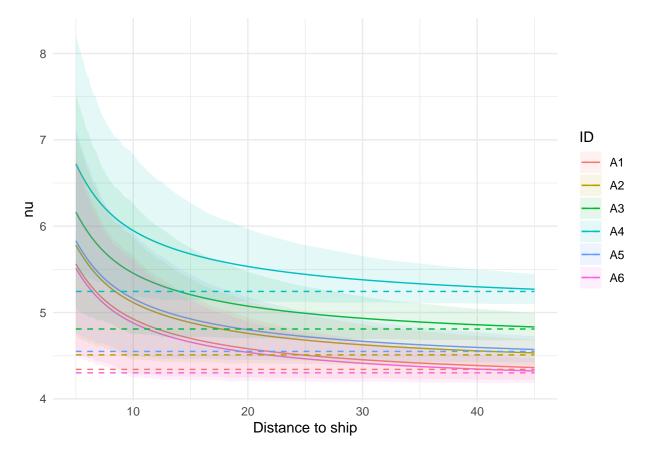
(1 or 2) are needed. The effect of the presence of the ship on the parameter ν is easily interpreted: the closer the narwhals are to the ship, the higher their velocity, likely to move away or avoid the ship. Now, the estimated smooth function for τ requires more knots and is harder to interpret. Though there seem to be a decrease in persistence close to the ship, at a medium distance around 20 km the persistence of the movement seem to increase. This is likely connected to figure 7 in [Heide-Jorgensen], where depending on how the narwhals were first exposed to the ship, they either change direction (lower persistence) or persist in their heading to flee away (higher persistence).

However, we only plot 100 posterior draws here. If we increase to $n_{post} = 1000$ posterior draws, the confidence intervals appear much wider. We now construct confidence intervals from 1000 posterior draws of the estimated coeffs and compare the smooth parameter with the baseline parameter.









Even if there seems to be an influence of ExpShip over the parameters, the confidence intervals are too wide to really conclude.

Log linear CTCRW response model with exponential of ExpShip

To simplify the analysis, instead of using spline, we now try a simpler log-linear model for the parameters τ and ν , meaning that τ and ν are exponentials of a linear function of E_{ship} .

```
response_ctcrw_exp$update_coeff_fe(
  c(baseline_ctcrw1$coeff_fe()[1:3,1],0,baseline_ctcrw1$coeff_fe()[4,1],0))
#use the indices of the variable in the map for TMB
#to keep the coefficients in the right order
#otherwise we may have issues in function post_coeff
response_ctcrw_exp$update_map(list(coeff_re=factor(rep(NA,12)),
                             coeff_fe=factor(c(rep(NA,3),1,NA,2)),
                             log lambda=factor(c(NA,NA))))
response_ctcrw_exp$fit()
## ######################
## ### smoothSDE model ###
## ######################
## > SDE for CTCRW model:
       dV(t) = beta (mu - V(t)) dt + sigma dW(t)
##
##
       dZ(t) = V(t) dt
## Parameterised in terms of:
## * tau = 1/beta
## * nu = sqrt(pi/beta)*sigma/2
## > Formulas for model parameters:
## * mu1 ~ fixed
## * mu2 ~ fixed
## * tau ~ ExpShip +
     s(ID, bs = "re")
## * nu ~ ExpShip +
   s(ID, bs = "re")
##
## initial value -8040.865772
## final value -8098.734460
## converged
estimates_res_ctcrw_exp=as.list(response_ctcrw_exp$tmb_rep(), what="Est")
std_res_ctcrw_exp=as.list(response_ctcrw_exp$tmb_rep(), what="Std")
```

% latex table generated in R 4.4.0 by xtable 1.8-4 package % Mon Nov 18 10:02:04 2024

Parameter	Estimate	Std_Error
log_sigma_obs	0.00	
mu1.(Intercept)	0.00	
mu2.(Intercept)	0.00	
tau.(Intercept)	0.06	
tau.ExpShip	-2.69	0.67
nu.(Intercept)	1.53	
nu.ExpShip	0.70	0.28

Table 14: Parameter Estimates and Standard Errors

We can also compute 95% CI for the coefficients in the log-linear model.

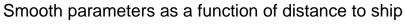
% latex table generated in R 4.4.0 by xtable 1.8-4 package % Mon Nov 18 10:02:04 2024

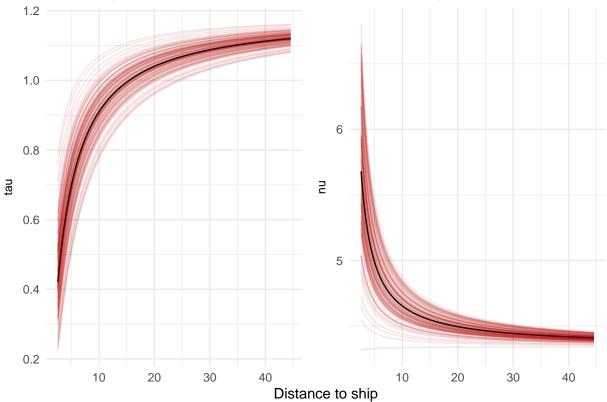
Parameter	Estimate	CI
α_{τ}	-2.67	[-4.00; -1.40]
α_{ν}	0.70	[0.16; 1.25]

Table 15: Response log linear estimations

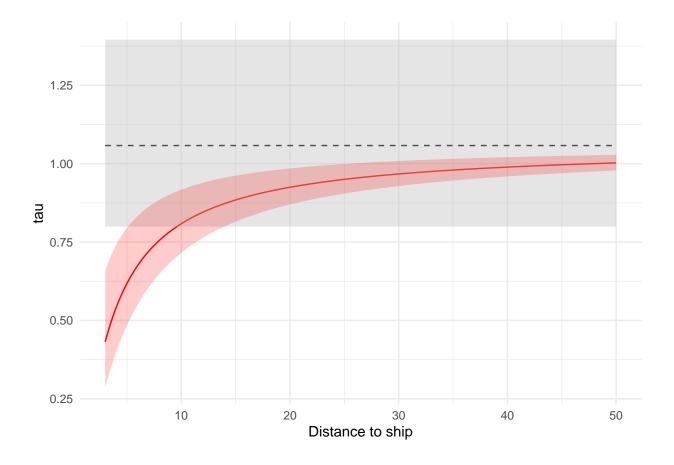
We can now plot the estimated smooth parameters.

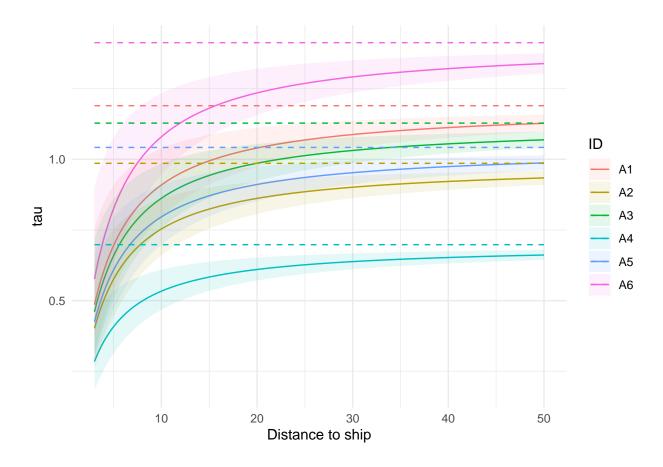
```
plot_smooth_par=response_ctcrw_exp$plot_par(var="ExpShip",
                                             par_names=c("tau","nu"),n_post=100)
#get data for the plot
plot_data <- ggplot_build(plot_smooth_par)$data[[1]]</pre>
#rename columns
colnames(plot_data)[1:5]=c("mle","val","var","group","par")
# ELow exposure threshold
threshold <- 1 / 45 # 1/ max(distance to ship)
plot_data <- plot_data %>% filter(var > threshold)
plot_data$distance <- rep(1/plot_data[plot_data$group==1,"var"],</pre>
                          length(unique(plot_data$group)))
plot_data <- plot_data %>%
  mutate(mle= recode(mle, "#B300001A" = "no", "#000000FF" = "yes"))
plot_data <- plot_data %>%
  mutate(par= recode(par, "1" = "tau", "2" = "nu"))
pal \leftarrow c("no" = rgb(0.7, 0, 0, 0.1), "yes" = rgb(0, 0, 0, 1))
plot_smooth_par_distance=ggplot(plot_data, aes(x = distance, group = group)) +
  scale colour manual(values = pal, guide = "none") +
  facet_wrap(c("par"), scales = "free_y",strip.position = "left") +
                theme_minimal() + xlab("Distance to ship") + ylab(NULL) +
  ggtitle("Smooth parameters as a function of distance to ship") +
  theme(strip.background = element_blank(), strip.placement = "outside",
        strip.text = element_text(colour = "black"))+
  geom_line(aes(y = val,color=mle))
plot_smooth_par_distance
```

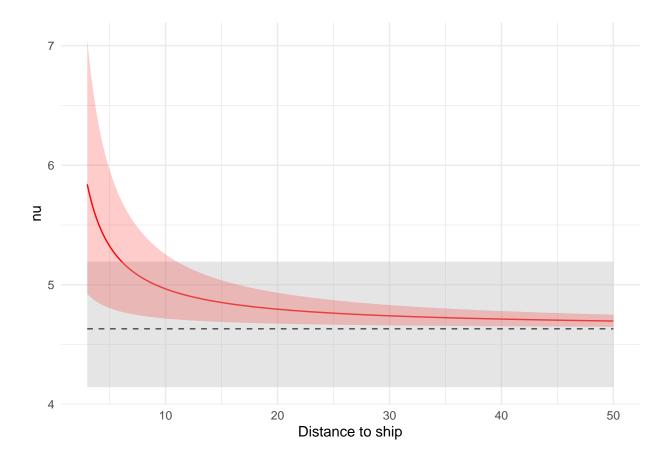


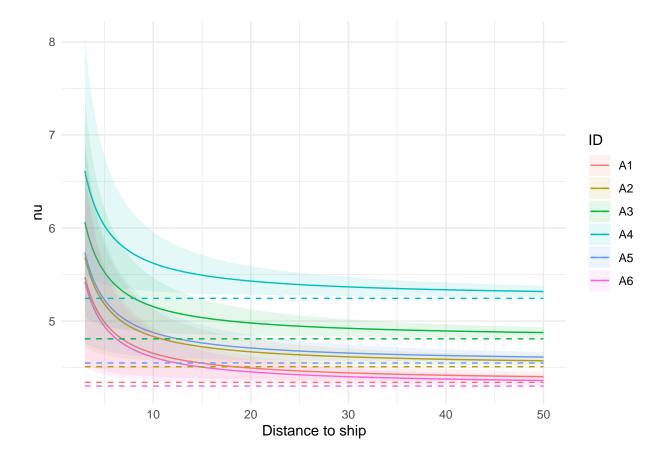


The results are indeed similar to what we obtain using cubic splines with a low degree of freedom.









Baseline uncertainty propagation

In the foregoing, offset of the parameters are fixed to the baseline estimate. We did not propagate the uncertainty from the baseline estimate to the response model. To do this, we can draw values from the estimated distribution of the baseline parameters, and estimate the response for each drawn value.

```
#posterior samples of the baseline model coefficients
post_coeff=baseline_ctcrw1$post_coeff(n_post=200)

post_coeff_re=post_coeff$coeff_re
post_coeff_fe=post_coeff$coeff_fe
post_coeff_lambda=exp(post_coeff$log_lambda)
post_coeff_sigma_obs=exp(post_coeff$log_sigma_obs)

# Fit response for each draw of baseline coefficients

formulas <- list(mu1=~1,mu2=~1,tau =~ExpShip,nu=~ExpShip)

alpha_estimates=matrix(rep(0,2*nrow(post_coeff_fe)),ncol=2)
alpha_std=matrix(rep(0,2*nrow(post_coeff_fe)),ncol=2)
models_list=list()</pre>
```

```
for (i in 1:nrow(post_coeff_fe)) {
    formulas <- list(mu1=~1,mu2=~1,tau =~ExpShip+s(ID,bs="re"),
                 nu=~ExpShip+s(ID,bs="re"))
    sigma obs=post coeff sigma obs[i,1]
   H=array(rep(sigma_obs^2*diag(2),n_post),dim=c(2,2,n_post))
   response_ctcrw_exp_i<- SDE$new(formulas = formulas,data = dataAE,</pre>
                                   type = "CTCRW",
                                   response = c("x","y"),
                                   par0 = par0,
                                   other data=list("H"=H),fixpar=c("mu1","mu2"))
   response_ctcrw_exp_i$update_map(list(coeff_re=factor(rep(NA,12)),
                             coeff_fe=factor(c(rep(NA,3),1,NA,2)),
                             log_lambda=factor(c(NA,NA))))
   new_coeff_fe=c(post_coeff_fe[i,1:3],0,post_coeff_fe[i,4],0)
   response_ctcrw_exp_i$update_coeff_fe(new_coeff_fe)
   response_ctcrw_exp_i$update_lambda(post_coeff_lambda[i,])
   response_ctcrw_exp_i$update_coeff_re(post_coeff_re[i,])
   response_ctcrw_exp_i$fit()
    est_alpha=as.list(response_ctcrw_exp_i$tmb_rep(),
                      what="Est")$coeff_fe[c("tau.ExpShip","nu.ExpShip"),1]
    std_alpha=as.list(response_ctcrw_exp_i$tmb_rep(),
                      what="Std")$coeff_fe[c("tau.ExpShip","nu.ExpShip"),1]
    alpha_estimates[i,]=est_alpha
    alpha_std[i,]=std_alpha
    models_list[[i]]=response_ctcrw_exp_i
}
colnames(alpha_estimates)=c("tau.ExpShip", "nu.ExpShip")
colnames(alpha_std)=c("tau.ExpShip","nu.ExpShip")
```

We can get new and more reliable confidence intervals for the coefficients in the log-linear model.

```
parameter_names <- names(mean_alpha)
estimates <- mean_alpha
conf_intervals <- sapply(parameter_names, function(param) {
    sprintf("$[%.2f; %.2f]$", quant_alpha[[param]][1],</pre>
```

```
quant_alpha[[param]][2])
})

table_data <- data.frame(
  Parameter =
      c("$\\alpha_{\\tau}$","$\\alpha_{\\nu}$"),
      Estimate = sprintf("$%.2f$", mean_alpha),
      CI = conf_intervals,
      stringsAsFactors = FALSE
)</pre>
```

% latex table generated in R 4.4.0 by xtable 1.8-4 package % Mon Nov 18 10:02:10 2024

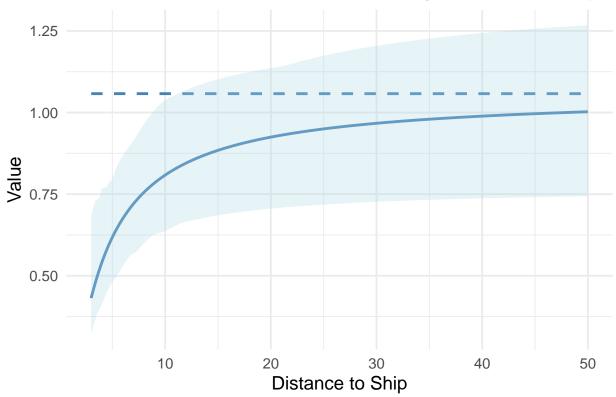
Parameter	Estimate	CI
α_{τ}	-2.55	[-3.86; -0.83]
$\alpha_{ u}$	0.78	[0.28; 1.42]

Table 16: Response log linear estimations with propagated uncertainty

```
# Extract data for each estimated smooth parameter
tau_CI_data <- lapply(CI_plots, function(plot) {</pre>
  ggplot_build(plot$fe_tau_ExpShip)$data[[1]][,c("x","y")]
nu_CI_data <- lapply(CI_plots, function(plot) {</pre>
  ggplot_build(plot$fe_nu_ExpShip)$data[[1]][,c("x","y")]
})
# Get confidence intervals as quantiles of estimated parameters
# Combine the x columns from all data frames into a matrix
x_matrix_tau <- do.call(cbind, lapply(tau_CI_data, function(df) df$y))</pre>
x_matrix_nu <- do.call(cbind, lapply(nu_CI_data, function(df) df$y))</pre>
# Compute the 5% and 95% quantiles row-wise
quantiles_tau <- apply(x_matrix_tau, 1,</pre>
                        function(row) quantile(row, probs = c(0.025, 0.975)))
quantiles_nu <- apply(x_matrix_nu, 1,
                       function(row) quantile(row, probs = c(0.025, 0.975)))
# Transpose and format the results into a data frame
quantiles_tau <- as.data.frame(t(quantiles_tau))</pre>
colnames(quantiles_tau) <- c("low", "up")</pre>
quantiles_nu <- as.data.frame(t(quantiles_nu))</pre>
colnames(quantiles_nu) <- c("low", "up")</pre>
# Add the "true" estimated smooth
plots=response_ctcrw_exp$get_all_plots(
  baseline=baseline ctcrw1,xmin=xmin,xmax=xmax,
  link=link,xlabel=xlabel,show_CI="pointwise")
```

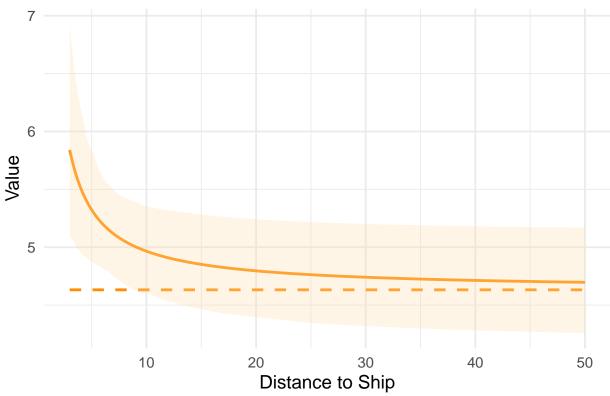
```
est_tau=ggplot_build(plots$fe_tau_ExpShip)$data[[1]][,c("x","y")]
est_nu=ggplot_build(plots$fe_nu_ExpShip)$data[[1]][,c("x","y")]
est_tau=cbind(est_tau,quantiles_tau)
est_nu=cbind(est_nu,quantiles_nu)
est_tau$baseline=ggplot_build(plots$fe_tau_ExpShip)$data[[2]][,"y"]
est_nu$baseline=ggplot_build(plots$fe_nu_ExpShip)$data[[2]][,"y"]
plot_tau_response_exp <- ggplot(data = est_tau) +</pre>
  geom_line(aes(x = x, y = y), color = "steelblue", size = 1) +
  geom_line(aes(x=x,y=baseline),color="steelblue",size=1,linetype="dashed")+
  geom ribbon(aes(x = x, ymin = low, ymax = up),
              fill = "lightblue", alpha = 0.3) +
 labs(
   x = "Distance to Ship",
   y = "Value",
   title = "Smooth Tau Estimates with propagated uncertainty"
  theme_minimal(base_size = 14) +
  theme(
   legend.position = "none",
   plot.title = element_text(hjust = 0.5, face = "bold", size = 16)
  )
## Warning: Using 'size' aesthetic for lines was deprecated in ggplot2 3.4.0.
## i Please use 'linewidth' instead.
## This warning is displayed once every 8 hours.
## Call 'lifecycle::last_lifecycle_warnings()' to see where this warning was
## generated.
# Enhanced plot for nu
plot_nu_response_exp <- ggplot(data = est_nu) +</pre>
  geom_line(aes(x = x, y = y), color = "darkorange", size = 1) +
  geom_line(aes(x,baseline),color="darkorange",size=1,linetype="dashed")+
  geom_ribbon(aes(x = x, ymin = low, ymax = up),
              fill = "navajowhite", alpha = 0.3) +
 labs(
   x = "Distance to Ship",
   y = "Value",
   title = "Smooth Nu Estimates with propagated uncertainty"
  theme_minimal(base_size = 14) +
  theme(
   legend.position = "none",
   plot.title = element_text(hjust = 0.5, face = "bold", size = 16)
  )
```

Smooth Tau Estimates with propagated uncertainty



plot_nu_response_exp





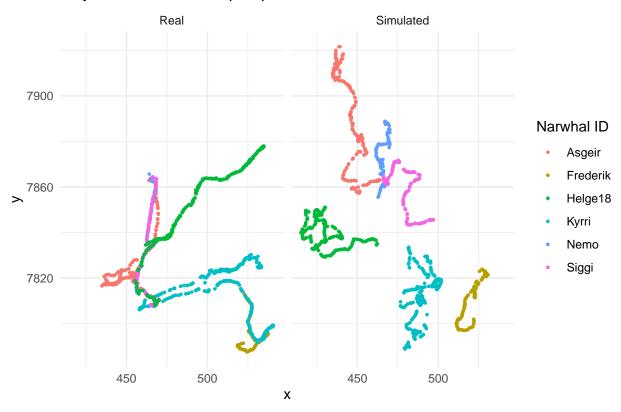
Simulation from the baseline and response models

We know want to investigate how the fitted model match the actual observations. To fo this, we simulate trajectories from the fitted model before and during exposure. First, we ignore that the narwhals move in a restricted area and only look at the shape of the trajectories.

Without land constraints

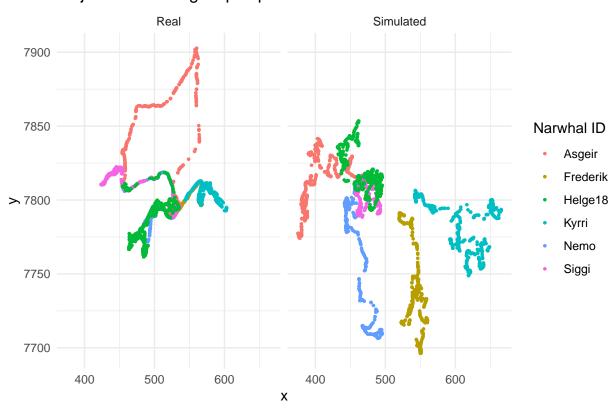
```
# Plot both in a single plot with facets
ggplot(baseline_trajectories) +
  geom_point(aes(x = x, y = y, color = ID), size = 0.6) +
  facet_wrap(~ data_type) +
  ggtitle("Trajectories before ship exposure") +
  theme_minimal() +
  labs(color = "Narwhal ID")
```

Trajectories before ship exposure



```
ggtitle("Trajectories during ship exposure") +
theme_minimal() +
labs(color = "Narwhal ID")
```

Trajectories during ship exposure



The simulated trajectories appear less persistent than the observed ones. We probably miss something in the model.

```
# Basic ggplot setup
plot_trajectories <- ggplot(</pre>
  response_trajectories, aes(x = x, y = y, color =ExpShip,group=ID)) +
  geom_path(size = 1, lineend = "round",alpha=0.1) +
  geom_point(aes(shape=ID), size =4 ) +
  scale_color_gradient(low = "blue", high = "red") + #
  labs(title = "Narwhal Trajectories with Ship Exposure",
       subtitle = "Time : {frame_along} h",
       x = "X Position",
       y = "Y Position") +
  theme_minimal() +
  facet_wrap(~ data_type)
# Animation setup with transition_reveal for one-point-at-a-time appearance
anim <- plot_trajectories +</pre>
  transition_reveal(along = time) +
  labs(subtitle = "Time: {round(frame_along,1)} hours")
```

The baseline model seems to match better the observations than the response model. In both cases, the simulated trajectories appear less persistent than the actual observations. Indeed, the persistence in the movement is linked to the highly constrained environment in which the narwhals move. We want to add this effect of the shoreline on the movement.

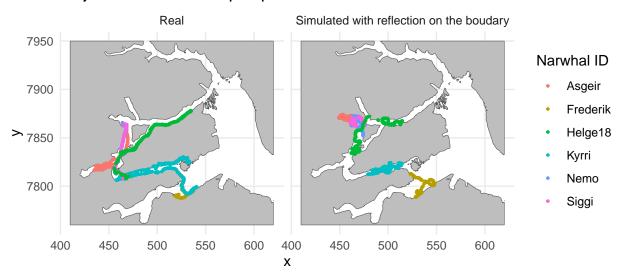
With land reflection

To illustrate, we simulate trajectories of the fitted model and project the points that reach land on the shoreline. This is equivalent to simulating from the reflected version of the fitted SDE, that is the fitted SDE with an additional term with bounded variations that keeps the process within the water domain.

```
# Set the path to the directory containing the data
par dir=here()
greenland_data_path <- file.path(par_dir, "Data",</pre>
                                  "preprocessed_data", "greenland")
#get the coastline geometry from the geojson file
land<-st_read(file.path(greenland_data_path,</pre>
                         "updated_scoresby_sound_utm.shp"))
## Reading layer 'updated_scoresby_sound_utm' from data source
##
     '/home/delporta/Documents/Research/Projects/narwhals_smoothSDE/Data/preprocessed_data/greenland/up
     using driver 'ESRI Shapefile'
## Simple feature collection with 64 features and 1 field
## Geometry type: MULTIPOLYGON
## Dimension:
                  XY
## Bounding box: xmin: 410000 ymin: 7760000 xmax: 620000 ymax: 7950000
## Projected CRS: WGS 84 / UTM zone 26N
land <- st transform(land, crs = "+init=EPSG:32626 +units=km")</pre>
baseline_ctcrw_sim_land=baseline_ctcrw1$simulate(z0 = z0_BE,
                                             data=baseline_ctcrw1$data(),
                                             sd_noise=sigma_obs,land=land)
# Add a label to each dataset for plotting
baseline_ctcrw_sim_land <- baseline_ctcrw_sim_land %>%
  mutate(data_type = "Simulated with reflection on the boudary")
dataBE12 <- dataBE12 %>% mutate(data_type = "Real")
# Combine both datasets
baseline_trajectories_land <- bind_rows(baseline_ctcrw_sim_land, dataBE12)</pre>
# Plot both in a single plot with facets
ggplot(baseline_trajectories_land) +geom_sf(data=land$geometry,fill="grey")+
  coord sf(datum=st crs("+init=EPSG:32626 +units=km"))+
  geom_point(aes(x = x, y = y, color = ID), size = 0.6) +
```

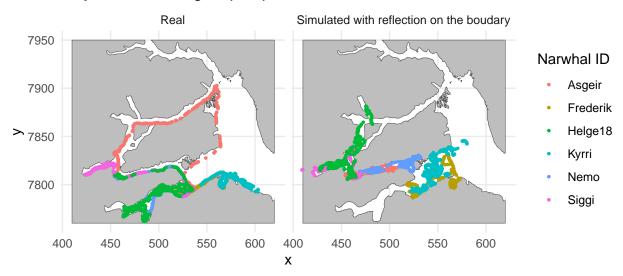
```
facet_wrap(~ data_type) +
ggtitle("Trajectories before ship exposure") +
theme_minimal() +
labs(color = "Narwhal ID")
```

Trajectories before ship exposure



```
response ctcrw sim land=response ctcrw exp$simulate(z0 = z0 AE,
                                            data=response_ctcrw_exp$data(),
                                            sd noise=sigma obs,land=land)
# Add a label to each dataset for plotting
response_ctcrw_sim_land <- response_ctcrw_sim_land %>%
  mutate(data_type = "Simulated with reflection on the boudary")
dataAE <- dataAE %>% mutate(data type = "Real")
# Combine both datasets
response_trajectories_land <- bind_rows(response_ctcrw_sim_land, dataAE)
# Plot both in a single plot with facets
ggplot(response_trajectories_land) +geom_sf(data=land$geometry,fill="grey")+
  coord_sf(datum=st_crs("+init=EPSG:32626 +units=km"))+
  geom_point(aes(x = x, y = y, color = ID), size = 0.6) +
  facet_wrap(~ data_type) +
  ggtitle("Trajectories during ship exposure") +
  theme_minimal() +
  labs(color = "Narwhal ID")
```

Trajectories during ship exposure



```
# Basic ggplot setup
plot_trajectories_land <- ggplot() +</pre>
  geom_sf(data=land$geometry,fill="grey")+
  coord_sf(datum=st_crs("+init=EPSG:32626 +units=km"))+
  geom_path(data=response_trajectories_land,
            aes(x = x, y = y, color =ExpShip,group=ID),size = 1,
            lineend = "round",alpha=0.15) +
  geom_point(data=response_trajectories_land,
             aes(x = x, y = y, color = ExpShip,group=ID,shape=ID),size = 4) +
  scale_color_gradient(low = "blue", high = "red") +
  labs(title = "Narwhal Trajectories with Ship Exposure",
       subtitle = "Time : {frame_along} h",
       x = "X Position",
       y = "Y Position") +
  theme_minimal() +
  facet_wrap(~ data_type)
anim <- plot_trajectories_land +
  transition_reveal(along = time) +
  labs(subtitle = "Time: {round(frame_along,1)} hours")
# Save the animation
animate(anim, nframes = 100, fps = 5, width = 800, height = 600,
        renderer = gifski_renderer("response_trajectories_land.gif"))
```

In the real data, the trajectories seem to follow more the shoreline and be more persistent than in the simulated data. To better integrate this phenomenon in the model, we will need to use new covariates.