

Certified Algebraic Path Tracking with Algpah

Alexandre Guillemot

Join work with Pierre Lairez

MATHEXP, Université Paris–Saclay, Inria, France

Ouragan seminar

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Certified path tracking

F



Parametrized polynomial system

Certified homotopy continuation

Input: F

Certified path tracking

Point in \mathbb{C}^n


$$F_0(\zeta_0) = 0$$

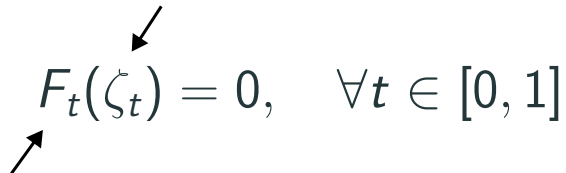
Parametrized polynomial system

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Input: F, ζ_0

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Unique continuous extension


$$F_t(\zeta_t) = 0, \quad \forall t \in [0, 1]$$

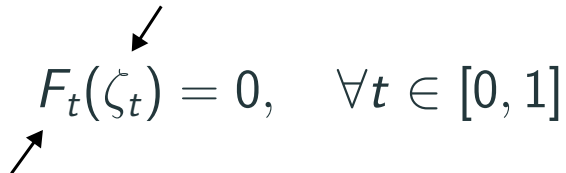
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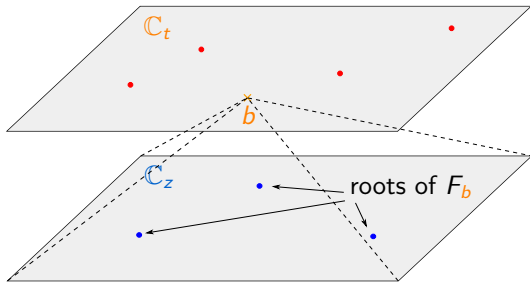
Parametrized polynomial system

Certified homotopy continuation

Input: F, ζ_0

Output: A “certified approximation” of ζ

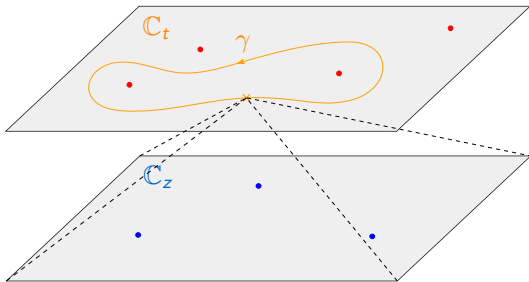
Motivation



Setup

- Let $g \in \mathbb{C}[t, z]$ ($n = \deg_z(g)$),
- define $F_t(z) = g(t, z)$.
- Let $b \in \mathbb{C} \setminus \Sigma$ be a base point,

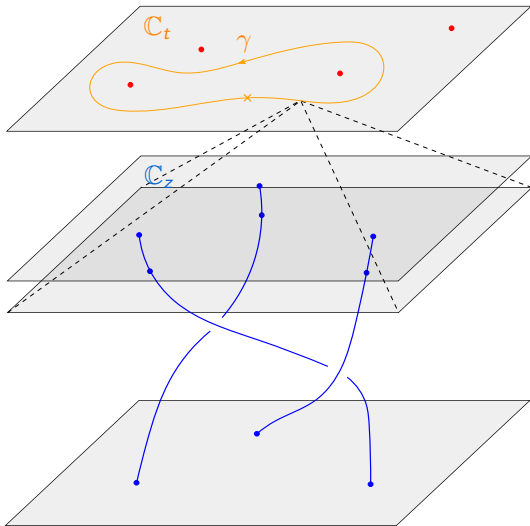
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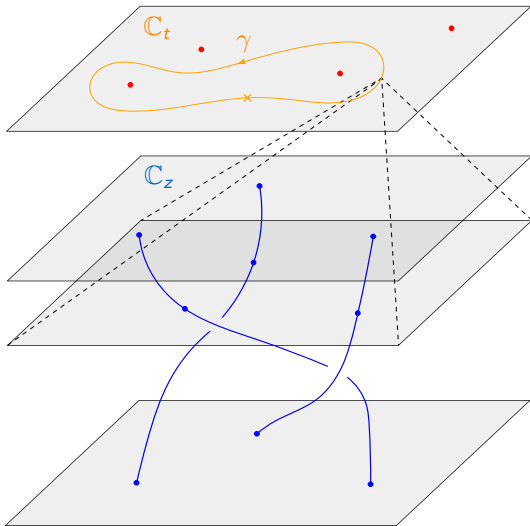
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- The displacement of all roots of F_t when t moves along γ defines a braid.

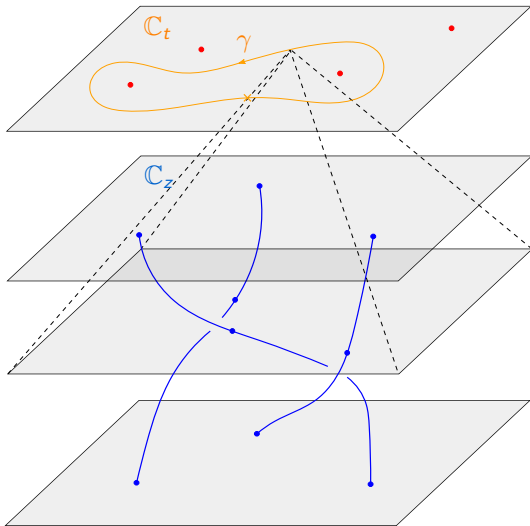
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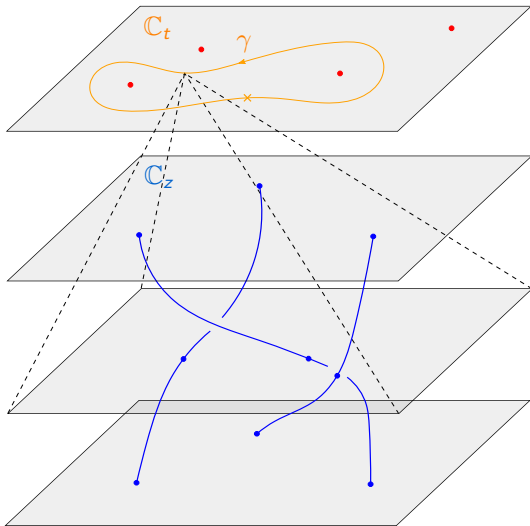
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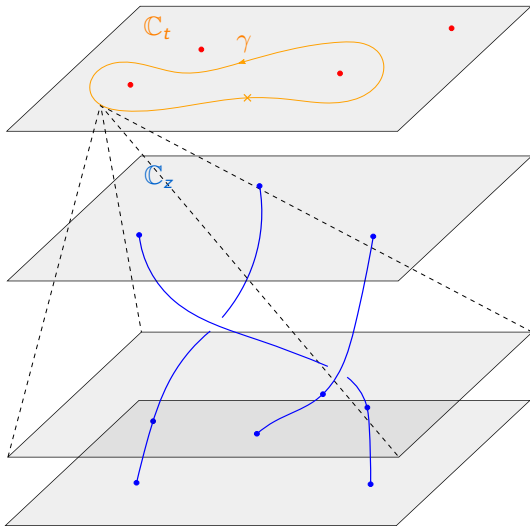
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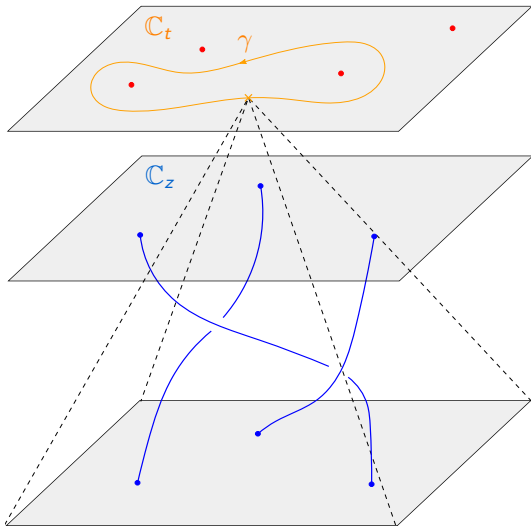
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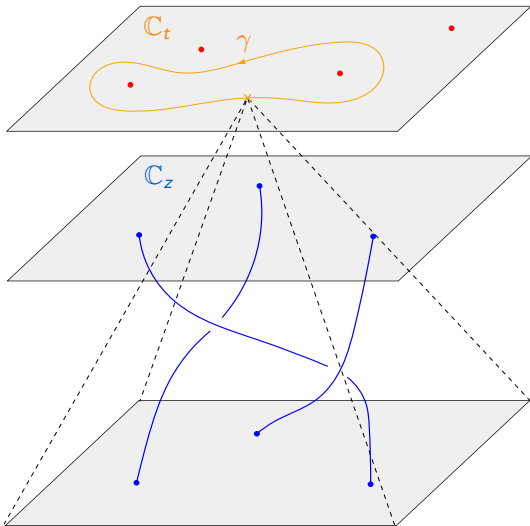
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Algorithmic goal

Input: g, γ

Output: the associated braid

Previous work

Noncertified path trackers

- PHCpack by Verschelde (1999)
- Bertini by Bates, Sommese, Hauenstein, and Wampler (2013)
- HomotopyContinuation.jl by Breiding and Timme (2018)

Certified path trackers using Smale's alpha-theory

- NAG for M2 by Beltrán and Leykin (2012, 2013)

Certified path trackers in one variable

- Marco-Buzunariz and Rodríguez (2016)
- Kranich (2016)
- Xu, Burr, and Yap (2018)

Certified path trackers using interval arithmetic

- Kearfott and Xing (1994)
- van der Hoeven (2015) *Krawczyk operator + Taylor models*
- Duff and Lee (2024) *similar to us but independent work*

Interval arithmetic

Problem

Given $f \in \mathbb{R}[x]$, I and J intervals, check $f(I) \subseteq J$.

Sufficient solution

- Define interval binary operations \boxplus and \boxtimes that take two intervals, give an interval and is such that for all $x \in I$, $y \in J$,

$$x + y \in I \boxplus J, xy \in I \boxtimes J.$$

- Write f as a composition of binary operations and replace each operation by its interval counterpart (interval extension), then plug I and check if the result is contained in J .
- ! This is only a sufficient condition.

Computational model

- Interval endpoints: \mathbb{Q} ,
- $[a, b] \boxplus [c, d] = [a + c, b + d]$,
- $[a, b] \boxtimes [c, d] = [\min\{ac, ad, bc, bd\}, \max\{ac, ad, bc, bd\}]$.

Pros and cons

- ✓ Good theoretical properties.
- ✗ Coefficient swell.

- Interval endpoints: {IEEE-754 64-bits floating-point numbers},
- $[a, b] \boxplus [c, d] = [\underline{a + c}, \overline{b + d}]$,
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Pros and cons

- ✓ Fast.
- ✗ Bad theoretical properties.
- ✗ Not enough representable numbers.

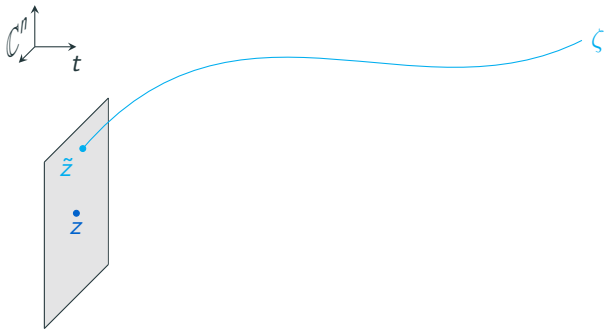
Computational model

- Interval endpoints: $\{m2^e \in \mathbb{R} : m, e \in \mathbb{Z}\}$,
- precision $P \in \mathbb{Z}_{>}$ (number of bits) that can be changed at will,
- interval operations: endpoints rounding done at precision P .

Pros and cons

- ✓ Good theoretical properties as $P \rightarrow \infty$.
- ✓ Fast when we can maintain low precision.
- ⚙ Need to carefully manage P in the algorithms to ensure termination.

The folklore meta-algorithm

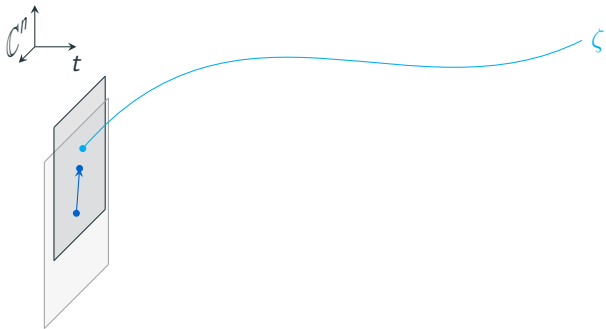


$F : \mathbb{C} \times \mathbb{C}^n \rightarrow \mathbb{C}^n$, $F_t(z) = F(t, z)$,
 m isolates a zero of F_0 .

def *track*(F, m):

```
1  $t \leftarrow 0$ ;    $L \leftarrow []$ 
2 while  $t < 1$ :
3    $m \leftarrow \text{refine}(F_t, m)$ 
4    $\delta \leftarrow \text{extend}(F, t, m)$ 
5    $t \leftarrow t + \delta$ 
6   append  $(t, m)$  to  $L$ 
7 return  $L$ 
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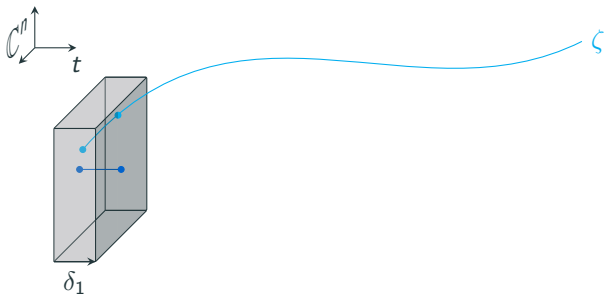


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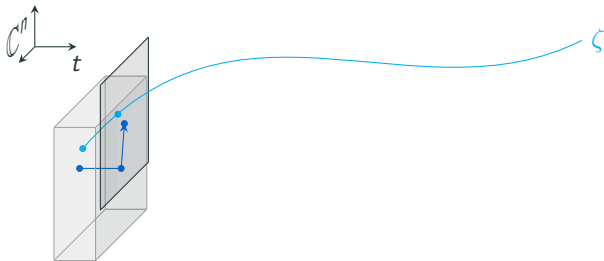


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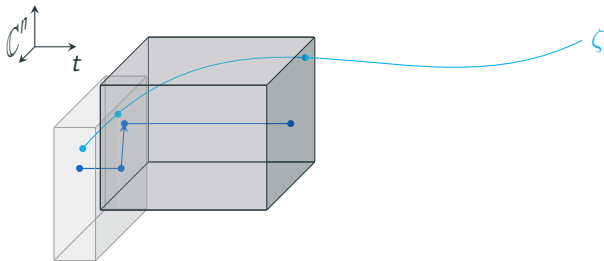


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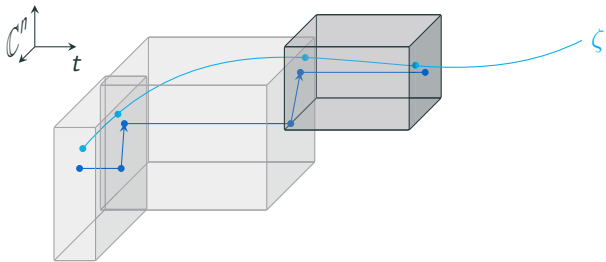


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Moore boxes, the datastructure for isolating boxes

Root isolation criterion (Krawczyk'1969, Moore'1977, Rump'1983)

- $f : \mathbb{C}^n \rightarrow \mathbb{C}^n$ polynomial, $\rho \in (0, 1)$,
- $z \in \mathbb{C}^n$, $A \in \mathbb{C}^{n \times n}$, $B \subseteq \mathbb{C}^n$ a ball of center 0,

such that for all $u, v \in B$,

$$-A \cdot f(z) + [I_n - A \cdot df(z + u)]v \in \rho B.$$

Then f has a unique zero in $z + \rho B$.

Moore boxes, the datastructure for isolating boxes

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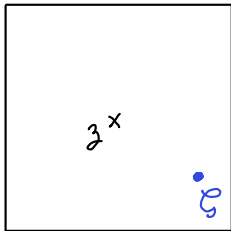
Proof sketch

We show that $\varphi : z + \rho B \rightarrow \mathbb{C}^n$ defined by $\varphi(w) = w - Af(w)$ is a ρ -contraction map with values in $z + \rho B$.

Definition

A ρ -Moore box for f is a triple (z, B, A) which satisfies Moore's criterion.

Refinement of Moore boxes

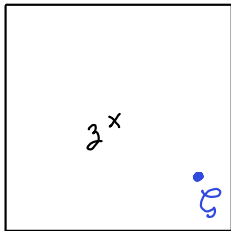


Strategy

(z, B, A) a $\frac{7}{8}$ -Moore box for f , ζ its associated zero.

$$-A \cdot f(z) + [I_n - A \cdot df(z + B)]B \subseteq \frac{7}{8}B.$$

Refinement of Moore boxes



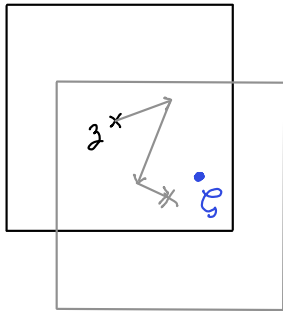
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(z, B, A) a $\frac{7}{8}$ -Moore box for f , ζ its associated zero.

We want to transform it into a $\frac{1}{8}$ -Moore box.

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Refinement of Moore boxes



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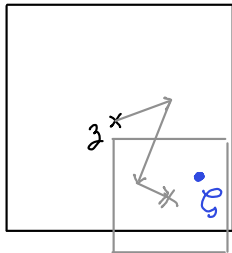
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Reduce **left term** with quasi-Newton $z \mapsto z - Af(z)$.

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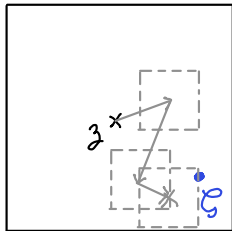
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How do we handle numerical errors?

Refinement of Moore boxes

```
def refine( $f, z, B, A$ ):
```

```
1  $U \leftarrow A; B \leftarrow 2B$   
2 while not  $-A \cdot f(z) + [I - A \cdot df(z + B)] B \subseteq \frac{1}{8}B$   
3   if  $-Uf(z) \subseteq \frac{1}{512}B$ : # left term is small  
4      $B \leftarrow \frac{1}{2}B$   
5   else: # left term is big  
6      $z \leftarrow z - Uf(z)$   
7    $A \leftarrow Jf(z)^{-1}$  # unchecked arithmetic  
8 return  $z, B, A$ 
```

Input

- $f : \mathbb{C}^n \rightarrow \mathbb{C}^n$ polynomial,
- z, B, A a $\frac{7}{8}$ -Moore box for f .

Output

A $\frac{1}{8}$ -Moore box for f with same associated zero as z, B, A .

Refinement of Moore boxes

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def refine( $f, z, B, A$ ):
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4           $B \leftarrow \frac{1}{2}B; \text{shrink\_cnt} \leftarrow \text{shrink\_cnt} + 1$ 
5          if shrink_cnt > 8:
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8           $\delta \leftarrow Uf(z)$ 
9          if  $\text{width}(z - \delta) > \frac{1}{40} \text{mag}(\delta)$ :
10             increase working precision
11         else:
12              $z \leftarrow \text{mid}(z - \delta);$ 
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- z, B, A a $\frac{7}{8}$ -Moore box for f .

Output

A $\frac{1}{8}$ -Moore box for f with same associated zero as z, B, A .

Proposition

refine terminates and is correct.

Step validation

Input

- $F : \mathbb{C} \times \mathbb{C}^n \rightarrow \mathbb{C}^n$,
- $t \in [0, 1]$,
- (z, B, A) a $\frac{1}{8}$ -Moore box for F_t , returned by refine.

recall $F_s(z) = F(s, z)$

Output

$\delta > 0$ s.t. for all $s \in [t, t + \delta]$,
 (z, B, A) is a $\frac{7}{8}$ -Moore box for F_s .

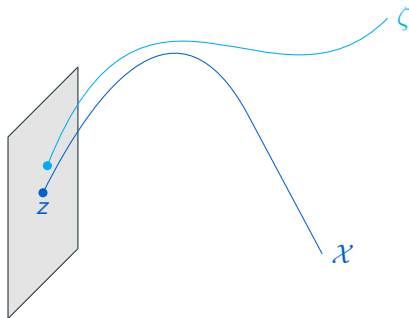
```
def extend( $F, t, \delta_{\text{hint}}, z, B, A$ )
```

```
1  $\delta \leftarrow \delta_{\text{hint}}; \quad \textcolor{red}{T} \leftarrow [t, t + \delta]$   
2 while not  $-AF_{\textcolor{red}{T}}(z) + [I - AdF_{\textcolor{red}{T}}(z + B)] B \subseteq \frac{7}{8}B$ :  
3    $\delta \leftarrow \frac{\delta}{2}; \quad \textcolor{red}{T} \leftarrow [t, t + \delta]$   
4   if  $\delta < 2^{-P}$ : #  $P$  working precision in bits  
5     increase working precision  
6 return  $\delta$ 
```

Proposition

extend terminates and is correct.

Extending along a predictor

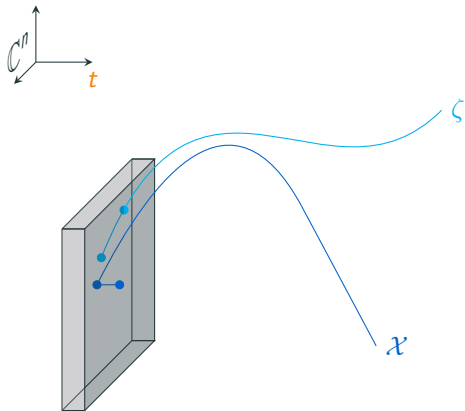


Predictor

A map $\mathcal{X} : \mathbb{R} \rightarrow \mathbb{C}^n$ such that $\mathcal{X}(0) = z$.

In practice, one should have $\mathcal{X}(s) \approx \zeta(t + s)$ around 0.

Extending along a predictor



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How to extend?

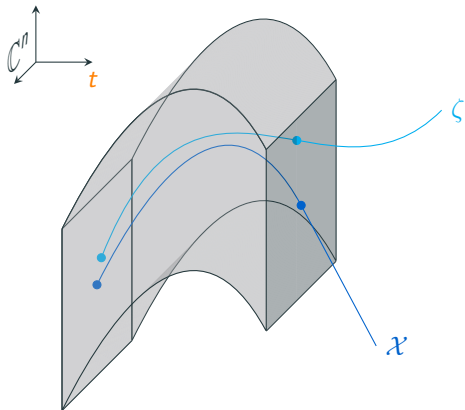
Pb: check that for all $s \in [0, \delta]$, (z, B, A) is a ρ -Moore box for F_{t+s} .

Soln: try

$$-AF_{t+\mathcal{S}}(z) + [1 - \text{Ad}F_{t+\mathcal{S}}(z + B)]B \subseteq \rho B$$

where $\mathcal{S} = [0, \delta]$.

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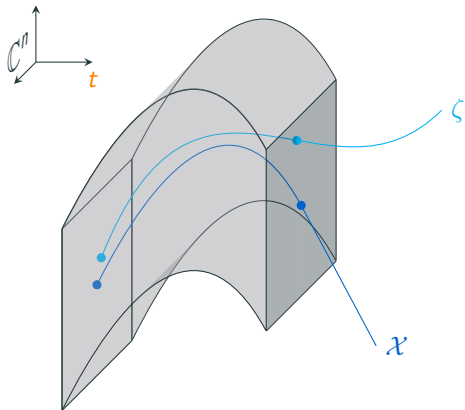
Pb: check that for all $s \in [0, \delta]$, $(\mathcal{X}(s), B, A)$ is a ρ -Moore box for F_{t+s} .

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$$-AF_{t+s}(\mathcal{X}(S)) + [1 - \text{Ad}F_{t+s}(\mathcal{X}(S) + B)]B \subseteq \rho B$$

where $S = [0, \delta]$.

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This is too strong! Way around the dependency problem: **Taylor models**

Taylor models with relative remainder

Definition

- A real interval S containing zero,
- a polynomial $P(\eta) = A_0 + A_1\eta + \cdots + A_{d+1}\eta^{d+1}$ where A_i is a (complex) interval.

d is the order of the Taylor model.

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A Taylor model (S, P) of degree d encloses a function $\mathcal{X} : \mathbb{R} \rightarrow \mathbb{C}$ if

$$\forall s \in S, \forall i \in 0, \dots, d+1, \exists a_i \in A_i \text{ s.t. } \mathcal{X}(s) = a_0 + a_1s + \cdots + a_{d+1}s^{d+1}.$$

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Remark

If $J \subseteq S$, we have $\mathcal{X}(J) \subseteq P(J)$ (where $P(J)$ is computed using interval arithmetic).

Reduction

Let (S, P) be a Taylor model of order d .

Goal : reduce its order to $d - 1$, s.t. if (S, P) encloses a function, so does its reduction.

Solution : replace $A_d \eta^d + A_{d+1} \eta^{d+1}$ by $[A_d \boxplus (A_{d+1} \boxtimes S)] \eta^d$.

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Let (S, P) and (S, Q) be Taylor models of order d .

Sum

Component-wise sum of P and Q using \boxplus . Compatible with sums of enclosed functions.

Product

Usual product formula with P and Q , gives a Taylor model of order $2d + 1$, then reduce it to make it of order d . Compatible with products of enclosed functions.

Back to our problem

- (z, B, A) is a $\frac{1}{8}$ -Moore box for F_t ,
- $\mathcal{X} : \mathbb{R} \rightarrow \mathbb{C}^n$ polynomial s.t. $\mathcal{X}(0) = z$.

We want to check that for all $s \in [0, \delta]$, $(\mathcal{X}(s), B, A)$ is a $\frac{7}{8}$ -Moore box for F_{t+s} . i.e.

$$-A \cdot F_{t+s}(\mathcal{X}(s)) + [1 - A \cdot dF_{t+s}(\mathcal{X}(s) + B)]B \subseteq \frac{7}{8}B.$$

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Solution using Taylor models

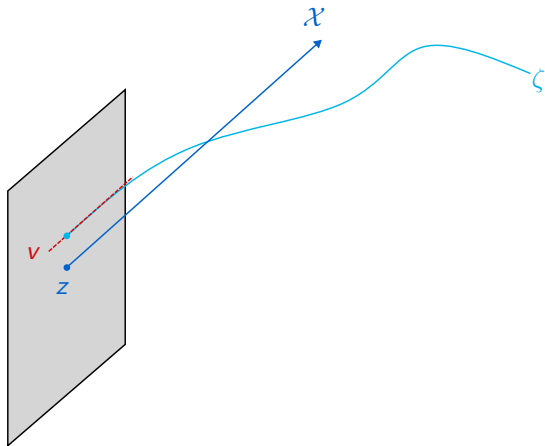
- Compute an order d Taylor model \mathcal{K} on $[0, \delta]$ enclosing

$$s \mapsto -A \cdot F_{t+s}(\mathcal{X}(s)) + [1 - A \cdot dF_{t+s}(\mathcal{X}(s) + B)]B.$$

This is just Taylor model arithmetic !

- Check that $\mathcal{K}([0, \delta]) \subseteq \frac{7}{8}B$ (interval arithmetic).

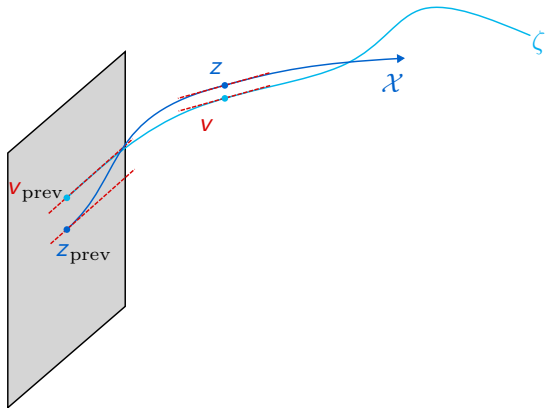
Choosing the right predictor



Tangent predictor

Idea: $-A \cdot \frac{\partial F}{\partial t}(t, z)$ is a good approximation of $\zeta'(t)$. Use it to do a order 1 correction.

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Hermite predictor

Idea: use previous point z_{prev} and previous tangent vector v_{prev} , z and v to do a Hermite cubic spline approximation.

Features

- **Rust** implementation,
- available at <https://gitlab.inria.fr/numag/algpath>,
- **SIMD double precision interval arithmetic** following Lambov (2008),
- **adaptive precision** using **Arb**¹,
- **mixed precision** between double precision and Arb **without overhead**.

¹Johansson, 2017.

Adaptive precision, in practice

Precision decreases

The algorithm presented only increases precision.

⚠ High precision is computationally costly.

Can we introduce precision decreases?

```
def track( $F, m$ ):
```

```
1   $t \leftarrow 0$ ;    $L \leftarrow []$ 
```

```
2  while  $t < 1$ :
```

```
3      decrease  $P$  by 1?
```

```
4       $m \leftarrow \text{refine}(F_t, m)$ 
```

```
5       $\delta \leftarrow \text{extend}(F, t, m)$ 
```

```
6       $t \leftarrow t + \delta$ 
```

```
7      append  $(t, m)$  to  $L$ 
```

```
8  return  $L$ 
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Computational model, again

- Precision is managed globally,
- a change of precision induces **no changes on data, only operations are changed**,
- precision of data is indirectly changed by performing operations on it.

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1   $t \leftarrow 0$ ;    $L \leftarrow []$   
2  while  $t < 1$ :  
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6       $t \leftarrow t + \delta$   
7      append  $(t, m)$  to  $L$   
8  return  $L$ 
```

Mixed precision

Double precision SIMD interval arithmetic is faster than Arb, but it lacks the ability to manage precision. . .

Goal

Use double precision when possible, else use Arb. We want to have no overhead over double precision only.

💡 Data can either be double precision or Arb balls. Operations manage arithmetic switch depending on precision

! Overhead

! Challenging implementation

```
enum MixedRI {  
    Fast(F64RI),  
    Accurate(Arb),  
}
```

Spacing arithmetic switches

One iteration of the main loop

```
1 def one_step( $F, m$ ): #  $m$  isolating box
2     try:
3         convert  $m$  to double precision
4         perform a corrector-predictor round at double precision
5     except:
6         convert  $m$  to Arb
7         perform a corrector-predictor round using Arb
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```

Can we always convert m to Arb?

Can we always convert m to double precision when the working precision is 53?

Exact conversions

Exact conversions fail both ways !

Consider double precision interval $[-2^{-50}, 2]$. The exact ball associated is $[(1 - 2^{-51}) \pm (1 + 2^{-51})]$. $1 + 2^{-51}$ cannot be represented by a mag_t!

Remark

- Recall: a moore box is a triple (z, B, A) where $z \in \mathbb{C}^n$, $A \in \mathbb{C}^{n \times n}$ and B is given by its radius $r > 0$. In practice, represented by singleton intervals.
- Conversions of singleton intervals behave as expected!

name	dim.	max deg	algp _{ath}	algp _{ath} (fixed precision)
			time (s)	time (s)
dense	1	100	0.4	0.4
katsura	16	2	42 min	41 min
dense	2	50	588	588

Implementation details

We would like to avoid writing the algorithm for each arithmetic.

Challenges

- Rust is statically typed,
- our functions depend on the type of intervals (double precision, Arb balls) but also on higher level types (e.g. complex intervals, interval matrices),
- Rust's generics are interface based.

Still we tried

- + Very little code duplication.
- + Easy to integrate additional arithmetics.
- Lots of complicated interfaces trying to avoid “where clause” swell.
- High level generic functions require heavy setup for only a few lines of code.

Conclusion

Features

- Rust implementation available at <https://gitlab.inria.fr/numag/algpath>,
- **certified** corrector-predictor loop,
- relies on **interval arithmetic** and **Krawczyk's method**,
- **SIMD double precision interval arithmetic**,
- **adaptive precision** using **Arb**,
- **mixed precision** between double precision and Arb **without overhead**.

Todos

- Interface with Sage or Julia
- Avx512?

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