

B-splines

B-splines basis

$$P(u) = \sum_{i=0}^n P_i N_i^d(u)$$

- The basis functions N_i^d are piecewise polynomials
- Have a *compact support* + satisfy partition of the unity
- The continuity is defined at the basis function's level.

- The number of control points is fixed by the relation

$$n+1 = m - d$$


Last knot number

B-splines

- The functions are such as : (recurrence formula of Cox – de Boor)

$$N_i^0(u) = \begin{cases} 1 & \text{if } u_i \leq u < u_{i+1} \\ 0 & \text{otherwise} \end{cases}$$

$$N_i^d(u) = \frac{u - u_i}{u_{i+d} - u_i} N_i^{d-1}(u) + \frac{u_{i+d+1} - u}{u_{i+d+1} - u_{i+1}} N_{i+1}^{d-1}(u)$$

- Where $u_{i+d} - u_i = 0$, necessarily $N_i^{d-1}(u) \equiv 0$

By convention, we set in this case $\frac{0}{0} = 0$ when the limit is undefined.

B-splines

- (simplified) Cox-de Boor's Algorithm :

Determine the interval of u : $u \in [u_i, u_{i+1}[$
Initialization of P_j^0 $i \in \{d, d+1, \dots, m-d-1\}$
For k from 1 to d
 For j from i to $i-d+k$

$$P_j^k = \left(\frac{u - u_j}{u_{j+d+1-k} - u_j} \right) P_j^{k-1} + \left(\frac{u_{j+d+1-k} - u}{u_{j+d+1-k} - u_{j-1}} \right) P_{j-1}^{k-1}$$

 Endfor
Endfor
 P_i^d is the point that is sought.

- What is its complexity ?

- quadratic in function of the degree d .

B-spline and the Cox-de Boor algorithm ?

For u in $[u_i, u_{i+1}[$

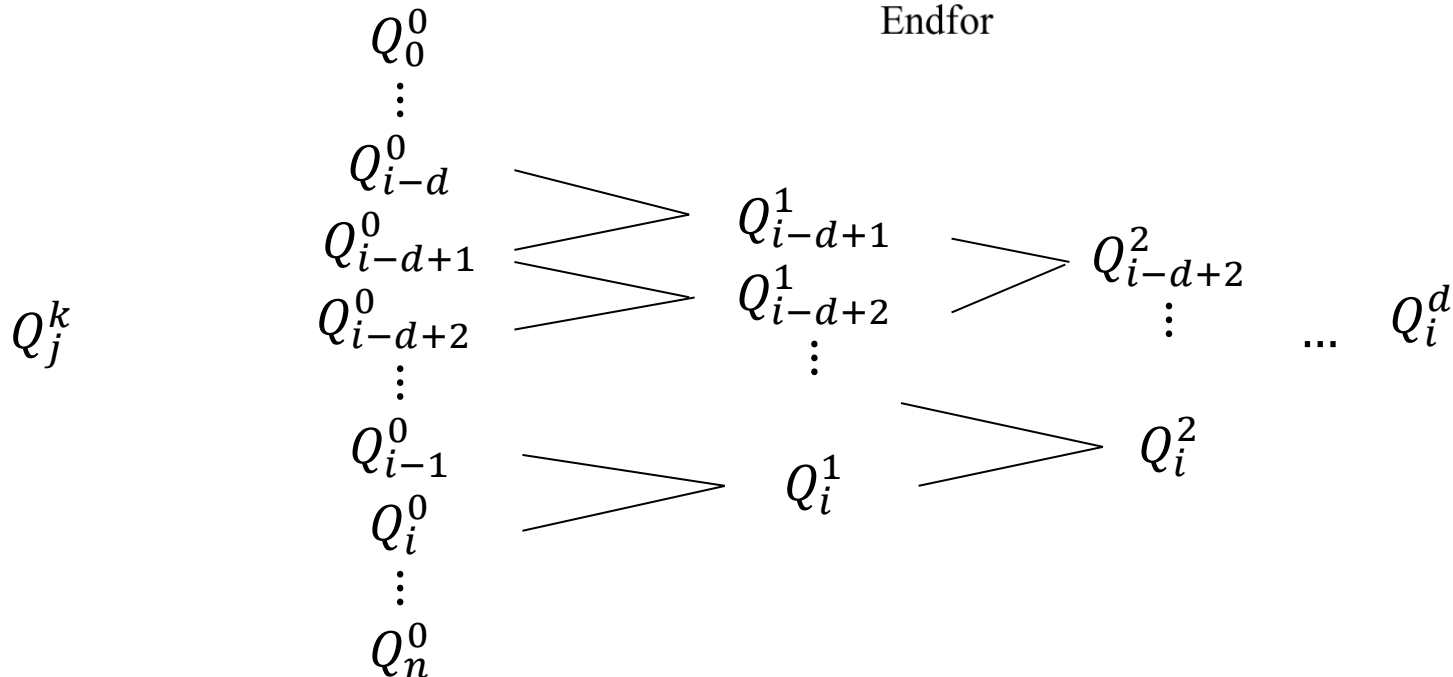
For k from 1 to d

For j from i to $i-d+k$

$$P_j^k = \left(\frac{u - u_j}{u_{j+d+1-k} - u_j} \right) P_j^{k-1} + \left(\frac{u_{j+d+1-k} - u}{u_{j+d+1-k} - u_{j-1}} \right) P_{j-1}^{k-1}$$

Endfor

Endfor



B-splines

- Types of nodal sequence...

- Uniform – The gap between two successive knots is constant

$$U = \{u_0, u_1, \dots, u_{m-d-1}\} \quad , \quad u_{i+1} - u_i = k$$

- Periodic - The gap between the knots at the start of a nodal sequence is identical to the one at the end of the nodal sequence

$$U = \left\{ \underbrace{u_0, \dots, u_d}_{d+1}, u_{d+1}, \dots, u_{m-d-1}, \underbrace{u'_0, \dots, u'_d}_{d+1} \right\} \quad , \quad u'_i - u_i = k$$

- Non uniform, interpolating – first and last control point are interpolated

$$U = \left\{ \underbrace{a, \dots, a}_{d+1}, u_{d+1}, \dots, u_{m-d-1}, \underbrace{b, \dots, b}_{d+1} \right\}$$