Sistema de Coordenadas 2D e 3D

Modelagem e Aplicações Gráficas 3D

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Sistema de Coordenadas R^n

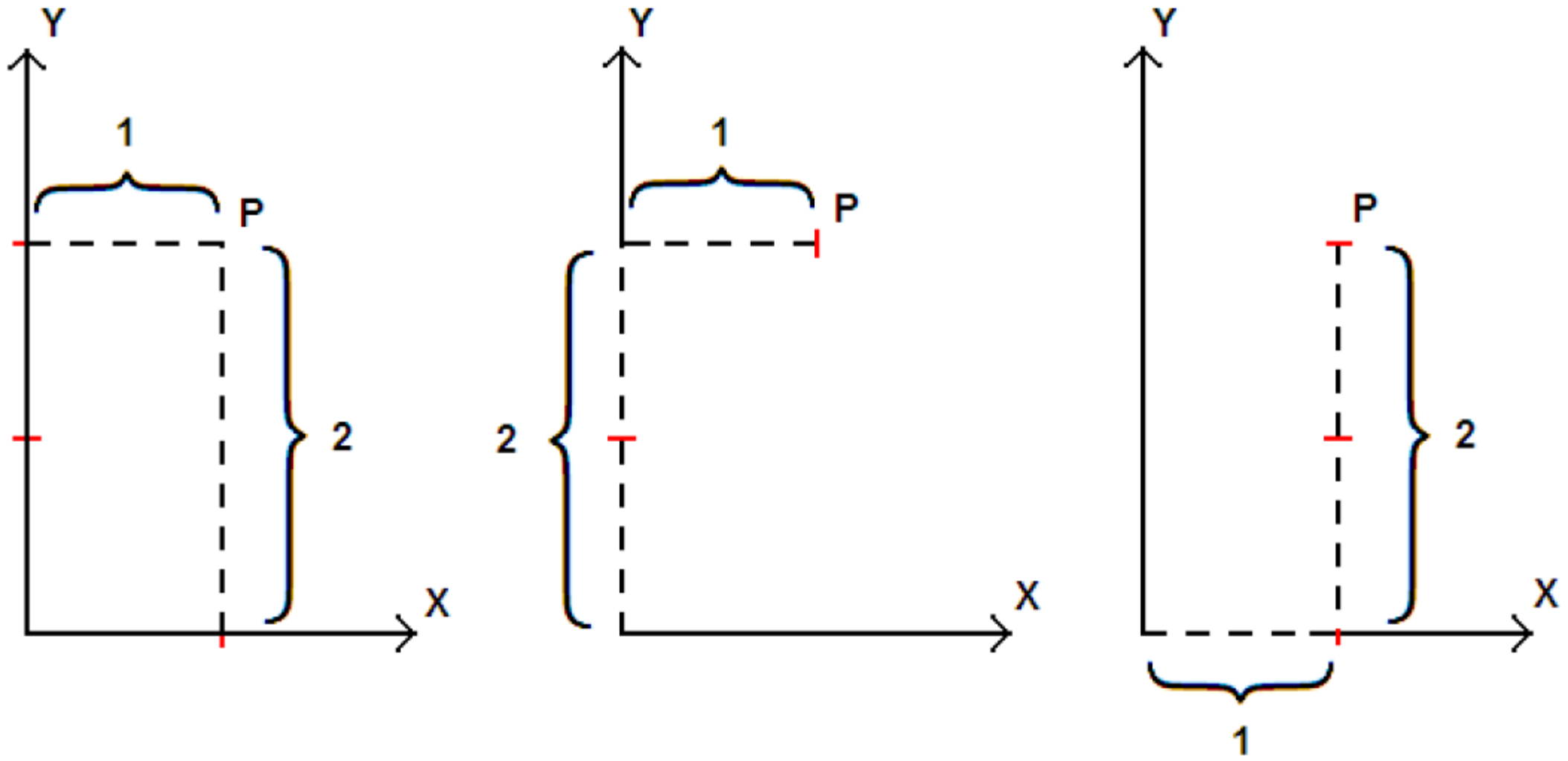
Um ponto de referência que corresponde a origem do sistema de coordenadas e seus respectivos eixos de orientação

Algebricamente: R^2 e R^3

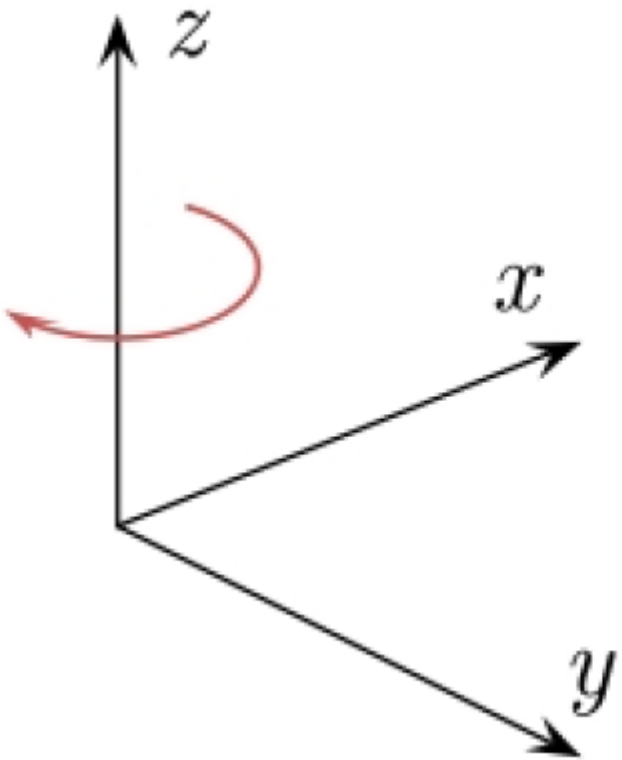
$$P = x_p \cdot X + y_p \cdot Y + O$$

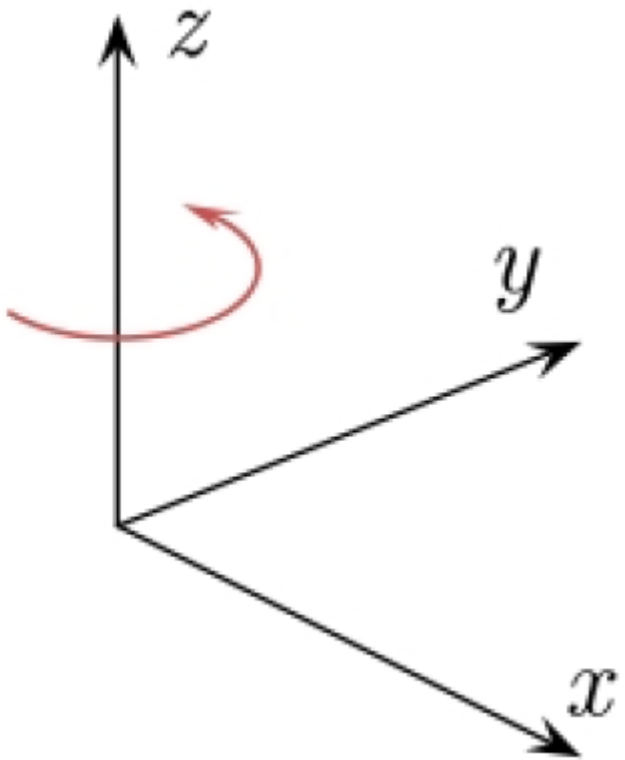
$$P = x_p \cdot X + y_p \cdot Y + z_p \cdot Z + O$$

Exemplo P = (1, 2)

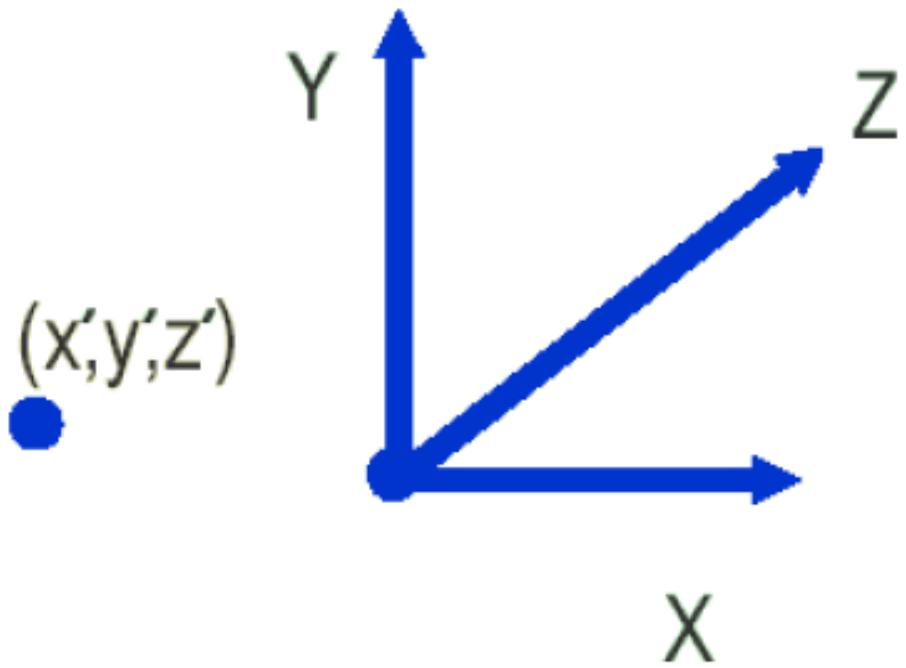


R^3 – Regra da Mão Esquerda e Direita

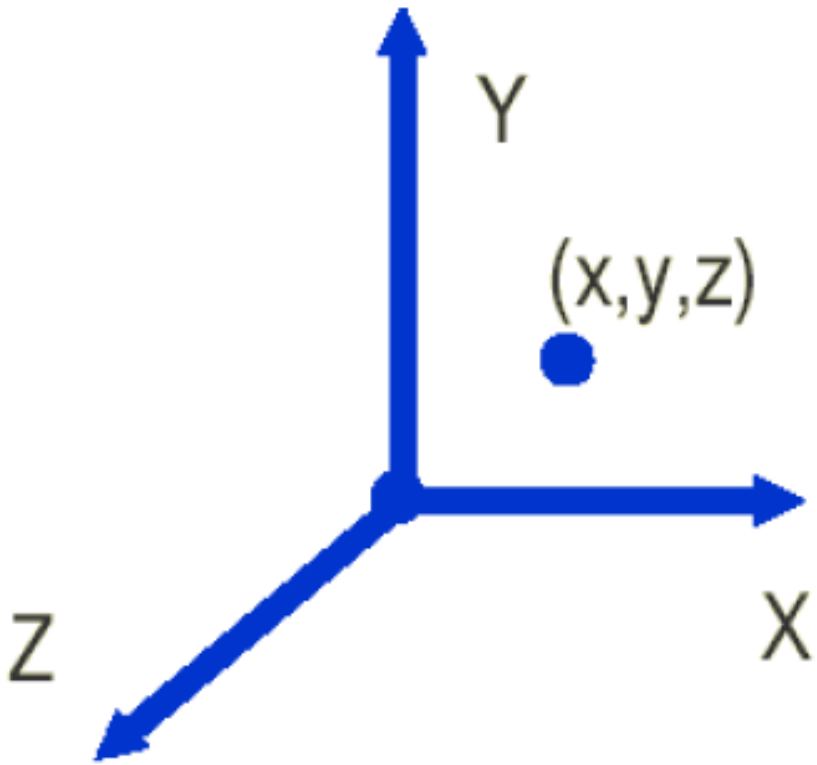




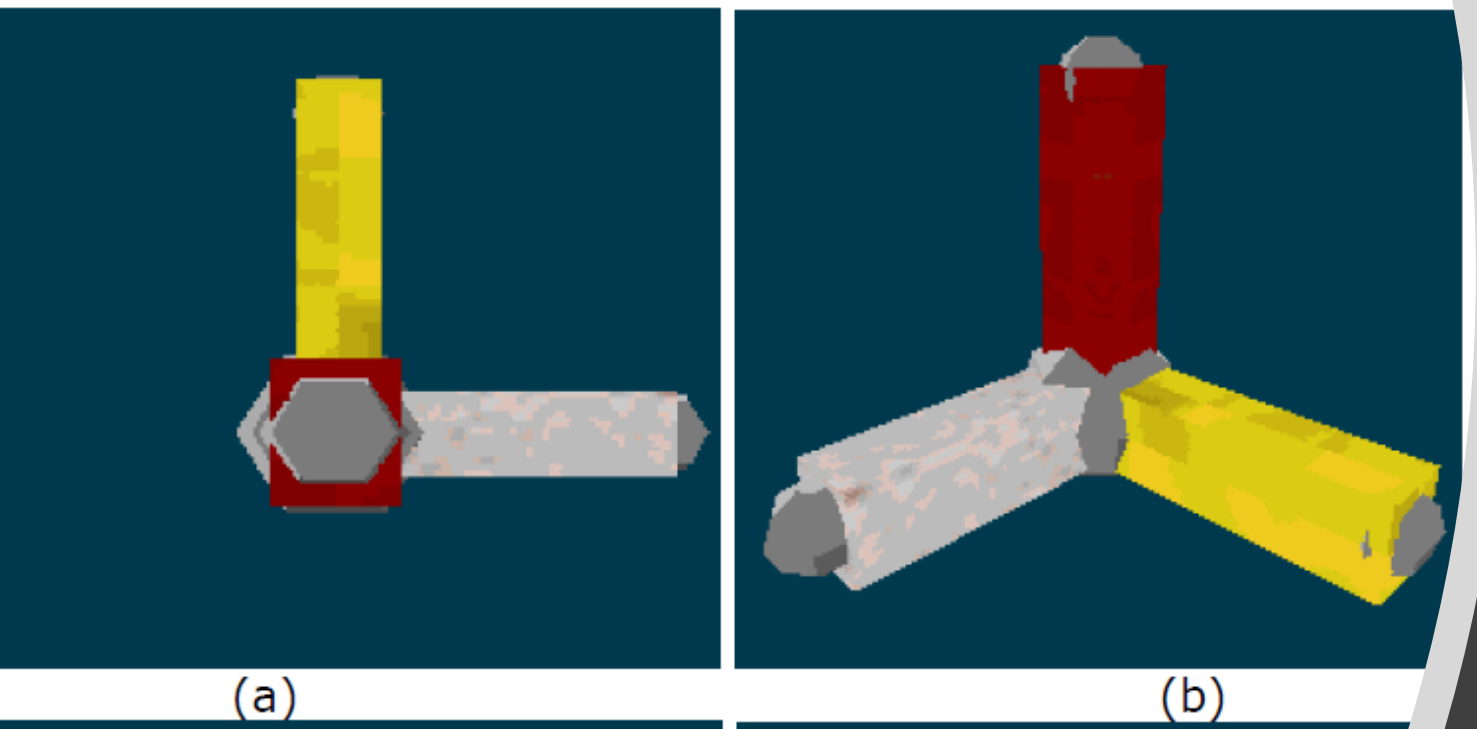
R^3 – Regra da Mão Esquerda e Direita



(a)

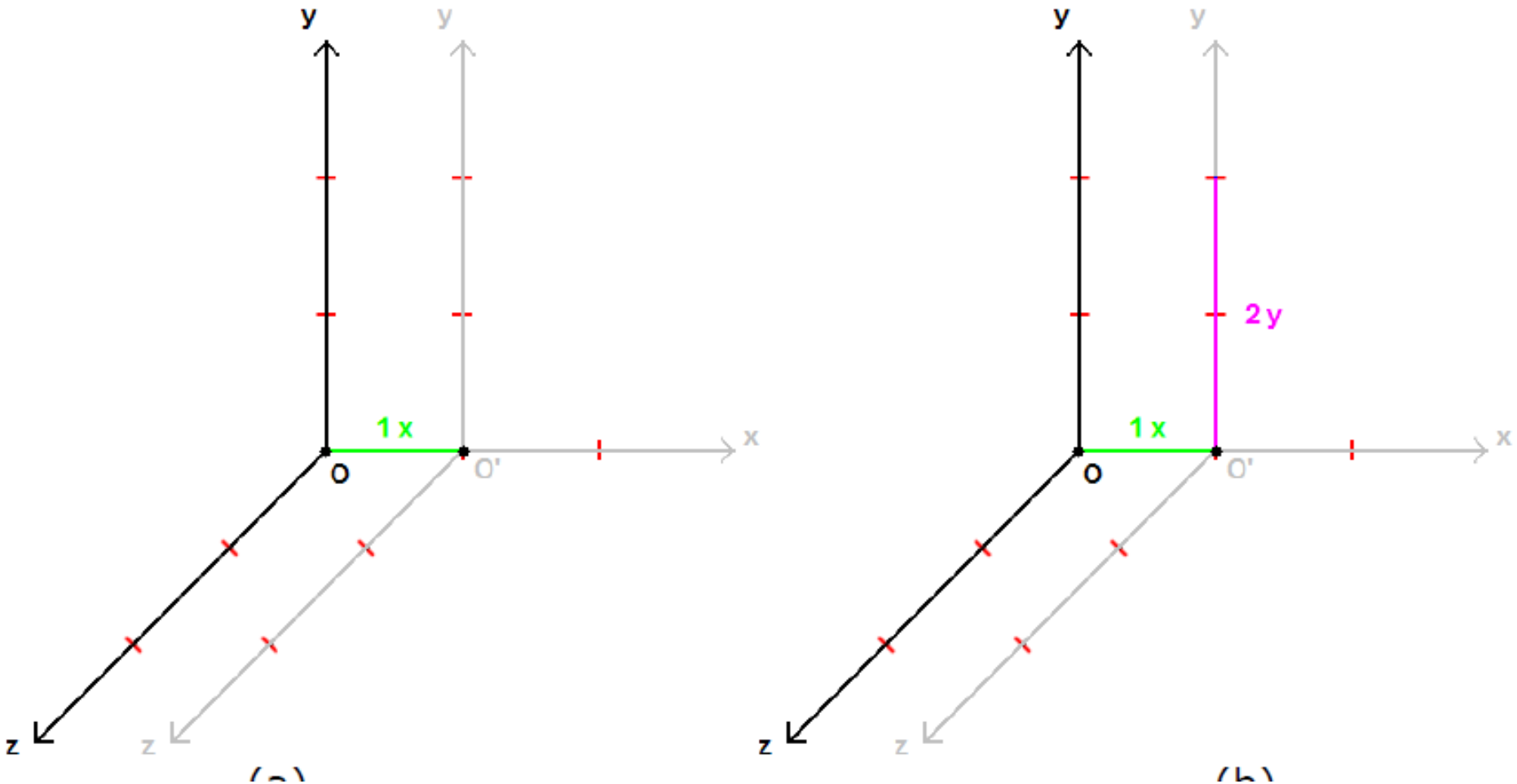


(b)

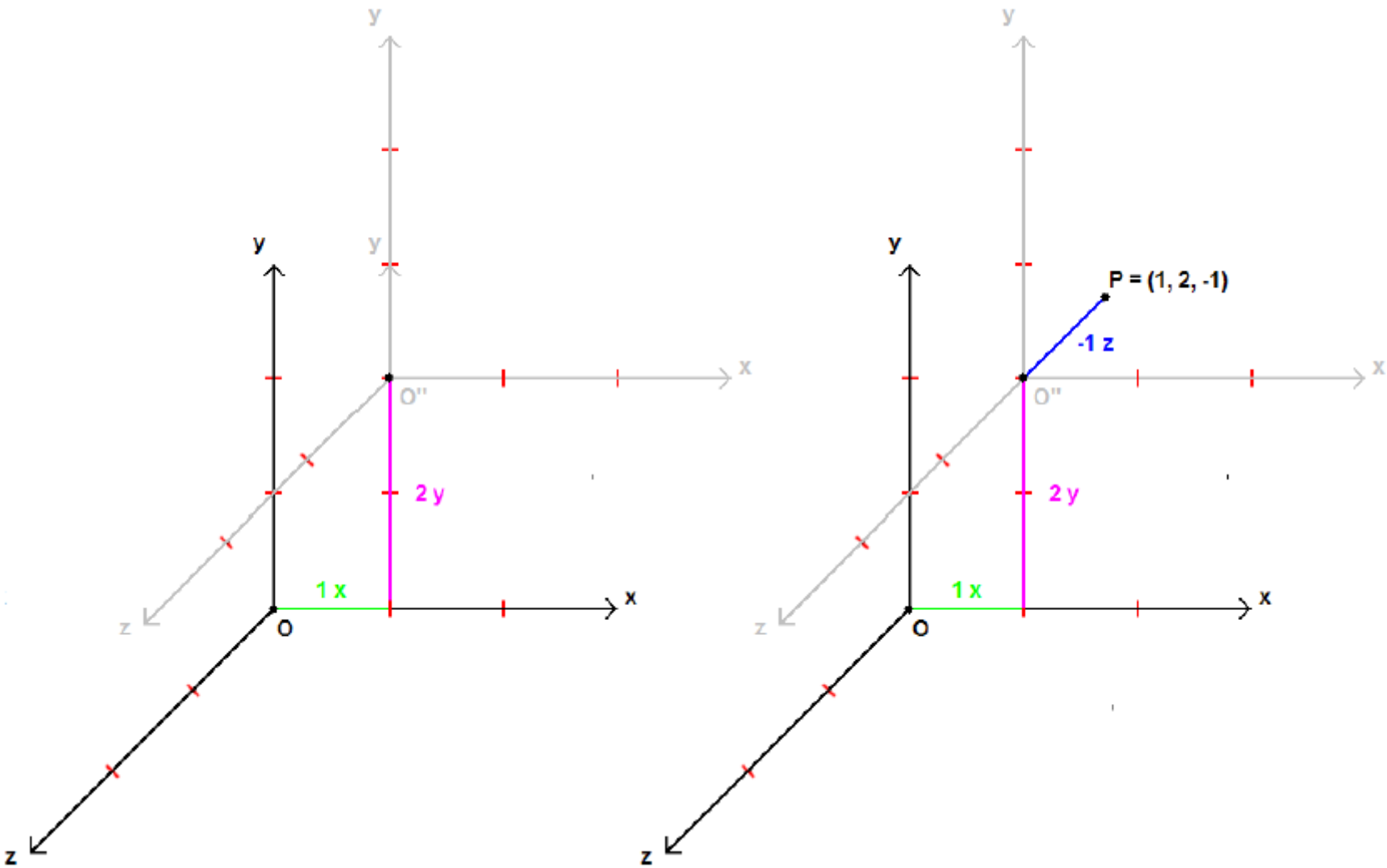


Perspectiva do Observador

Exemplo P = (1, 2, -1)



Exemplo P = (1, 2, -1)



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