Contact:	nilles2@illinois.edu
	My website
Status:	PhD Candidate
	Computer Science Department, University of Illinois at Urbana-Champaign
	Advisor: Steve LaValle
Research Interests:	Developing useful and mathematically sound abstractions for robot design and control. Applying these abstractions, and new developments in programming languages and formal methods, to robotics software tools.

EDUCATION

University of Illinois (UIUC) (Urbana-Champaign, IL)

| Degree: | PhD in Computer Science |
| Dates: | Aug 2015 - present |

Colorado School of Mines (CSM) (Golden, CO)

Degree:	B.S. in Engineering Physics
	Minor in Computational and Applied Mathematics
	Minor in Public Affairs, from McBride Honors Program
Dates:	August 2011 to May 2015
GPA:	3.93

SKILLS

Programming:	Skilled in Haskell, Python, C++, embedded programming (mBed, Arduino), MatLab, Mathematica, parallel computing, shell scripting. Comfortable learning new languages.
Experimental:	Comfortable with electronics prototype design and construction. Familiar with electronics lab equipment (oscilloscopes, multimeters, soldering, etc), safety, and troubleshooting techniques. Experienced with collection and analysis of video and motion-capture data.
Computing:	Experience in Linux (several distributions, comfortable with the command line), LaTeX, Git, Pandoc, and high performance computing clusters.
Teaching:	Paid tutor at Colorado School of Mines math learning center. Volunteer tutor at Python, Linux, and high-performance computing help sessions in the physics department.

PREVIOUS POSITIONS

Petronics internship: Development of small, agile mobile robot

| Description: | Over the summer, I worked with Petronics to develop hardware and software for their mobile platform. I helped add a wifi module to the robot which streamed data to a ROS server, which I also helped set up and configure. I wrote software for collecting and analyzing the resulting data. The goal was to compare streaming pose estimates from the robot with a ground truth from a motion capture system (also ROS-integrated), to analyze how the robot slipped on different surfaces and learn better controllers. |
| Dates: | May 2016 - August 2016 |

Complexity Sciences Center, UC Davis: Implementing Predicted Information Gain Algorithms

| Description: | While working in Dr. Jim Crutchfield's group, I successfully implemented an information-theoretic learning algorithm for exploratory robots with limited sensing capabilities. I also researched ways to include more memory in the learning algorithm. |
| Dates: | June - Aug 2014 |

Colorado School of Mines Math Learning Center

| Description: | Tutor five hours a week for all classes in Math department. Primarily calculus, differential equations, and linear algebra. |
| Dates: | Jan 2015 - May 2015 |

North American Network of Science Labs Online (NANSLO)

| Description: | Developed, monitored, and troubleshot remote-controlled robotic physics, chemistry, and biology experiments for college students in online classes. Served as a TA and equipment technician while classes were running. |
| Dates: | Feb 2012 - May 2014 |

Institute of Electrical and Electronics Engineers (IEEE)

Description:	Washington Internships for Students of Engineering (WISE) program: researched smart grid data management and policy alternatives; published an overview and policy recommendation in the *WISE Journal of Engineering and Public Policy.*
Dates:	June - Aug 2013

PROFESSIONAL ACTIVITIES

- Co-organizer for 2017 Robotic Science and Systems (RSS) full day workshop, "Minimality and Trade-offs in Automated Robot Design." July 16 2017. Website
  - Recruited and communicated with speakers, helped develop materials (The Robot Design Game, http://robot-design.org/), facilitated workshop and discussions.
- President of Computer Science Graduate Students Organization (fall 2017 - present).
  - Organize social events, communicate with department administration about graduate student needs, assist in organizing annual prospective PhD student visit weekend.
- Reviewer for IROS '17, '18, ICRA '18, EAAI '17
- Head of student committee organizing an internal Robotics@UIUC seminar (Fall 2016).
  - Recruited student speakers, advertised talks, maintained wiki with schedule and speaker slides.

AWARDS AND HONORS

- Saburo Muroga Endowed Fellowship, UIUC CS Department. 2015-2016
- Physics Faculty Distinguished Graduate Award, CSM. May 2015
- Leo Borasio Outstanding Junior Award, McBride Honors Program, CSM. May 2014
- President's Undergraduate Scholarship, CSM. 2011-2015
- ECC Women's Leadership Group Scholarship. 2011

OUTREACH AND DIVERSITY SERVICE

- Founding member of Equality Through Awareness (ETA) at CSM, a group promoting diversity in STEM through discussion, mentoring, and invited speakers.
  - personally facilitated weekly group discussions on articles and topics relevant to underrepresented minorities
  - ETA has since won the Martin Luther King Jr. Recognition Award from CSM
- Society of Physics Students - participated in outreach events such as travelling to local elementary/middle schools to do science demos and promote interest in physics

PUBLICATIONS AND POSTERS

- A. Q. Nilles, D. A. Shell, J. M. O'Kane. "Robot Design: Formalisms, Representations, and the Role of the Designer," in *Workshop on the Autonomous Design of Robots* at ICRA 2018.
- A. Q. Nilles, C. Gladish, M. Beckman, and A. LaViers. "Improv: Live Coding for Robot Motion Design," in *Proceedings of the 5th International Conference on Movement Computing*, ACM. 2018.
- A. LaViers, C. Cuan, C. Maguire, K. Bradley, K. B. Mata, A. Nilles, I. Vidrin, N. Chakraborty, M. Heimerdinger, U. Huzaifa, R. McNish, I. Pakrasi, and A. Zurawski. "Choreographic and Somatic Approaches for the Development of Expressive Robotic Systems," in *MDPI – Arts*, 2018.
- A. Q. Nilles, I. Becerra, and S. M. LaValle. "Controllable Billiards: Characterizing the Paths of Simple Mobile Robots," poster in *Dynamics Days*, 2018.
- A. Q. Nilles, I. Becerra, and S. M. LaValle. "Periodic Trajectories of Mobile Robots," in *IEEE Conference on Intelligent Robots and Systems (IROS)*, 2017.
- A. Q. Nilles, "Teaching the Smart Grid: Why Data Management is Essential to the Future of Electricity," WISE Journal of Engineering and Public Policy.
- A. Q. Nilles, "Partially Coherent Transport: Computational Analysis and Overcoming Anderson Localization," 2014 CSM Physics poster session.

TALKS

- "Interesting Trajectories of Mobile Robots in Polygons," 2017 Midwest Robotics Workshop (MWRW). May 18 2017.
- "New Developments in Combinatorial Data Structures and Algorithms for Robotic Planning, Filtering and Design," UIUC Theory Seminar, October 3 2016.
- "Case Studies in Robotics Toolchains," UIUC Robotics Seminar, September 9 2016.