No map
No location information

. . .

Full map
Full tracking
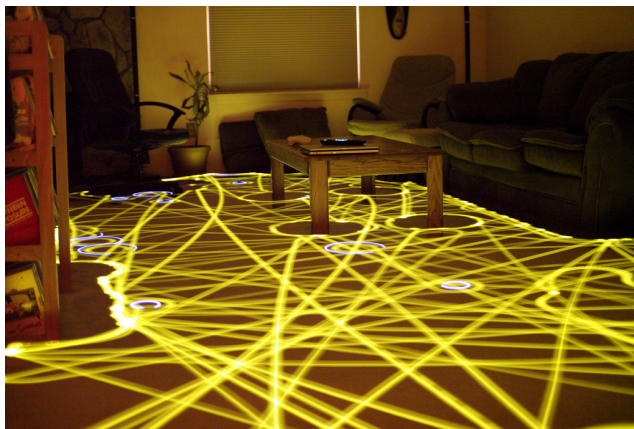
Image Credit: Chris Bartle

Image Credit: iRobot

Minimalist Robot Navigation and Coverage using a Dynamical System Approach

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Periodic Trajectories of Mobile Robots

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Toward the Design and Analysis of Blind, Bouncing Robots

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Planning for provably reliable navigation
using an unreliable, nearly sensorless robot

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