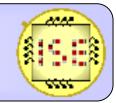


Institute of Integrated Sensor Systems



Department of Electrical and Computer Engineering

Facial Expressions Recognition Using the Emotiv EPOC Headset

Alexandru Cohal, Vitor Ribeiro Roriz, March, 2018

Prof. Dr.-Ing. Andreas König





Overview

- 1. Introduction
- 2. Objective
- 3. Data Acquisition
- 4. Data Preprocessing
- 5. Feature Extraction
- 6. Classifiers
- 7. Real-Time Recognition
- 8. Conclusions





- Multiple **Human Computer Interaction** (**HCI**) methods have been developed recently make technology available to more users with different needs and goals
- A Brain Computer Interface (BCI) a solution for HCI which uses signals captured from the brain for controlling an external activity
- BCI used in the rehabilitation of persons with limited physical control (due to a brain injury for example)
- Electroencephalography (EEG) a method for monitoring the electrical neural activity of the brain

http://wiki.cas.mcmaster.ca/index.php/Motivations_for_the_Studies_of_HCI

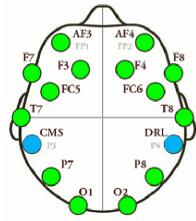
Investigating the Emotiv EPOC for cognitive control in limited training time – M. Lang, T. Mitrovic, University of Canterbury (2012)





- **Emotiv EPOC** a compact, wireless EEG device, easy to setup and use
- Has 16 sensors (electrodes): 14 for data (μV) and 2 for reference





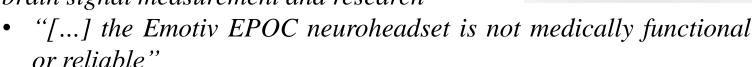
- Data is acquired with 128 Hz frequency
- A saline solution has to be used for increasing conductivity

Investigating the Emotiv EPOC for cognitive control in limited training time – M. Lang, T. Mitrovic, *University of Canterbury* (2012) https://www.emotiv.com/epoc/





- Emotiv EPOC used in many researches
- The general trend Emotiv EPOC is not suited for recording mental commands
 - "[...] only suitable for a beginner level brain signal measurement and research"



• "With noninvasive technology, the skull hinders the signals being detected by EEG"

Consumer-grade EEG devices: are they usable for control tasks? – R. Maskeliunas et al., *PeerJ* (2016)

Using the Emotiv EPOC Neuroheadset as an EEGControlled BrainComputer Interface – A. Hawkes et al., *Appalachian State University* (2015)





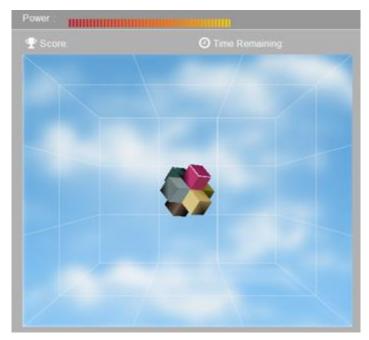
• Tests done by us ———— the Emotiv own software (Emotiv Control

Panel)

• *3* users

• 20-25 minutes of training each

- 3 classes ("Neutral" and 2 actions for moving the cube)
- Very poor classification results



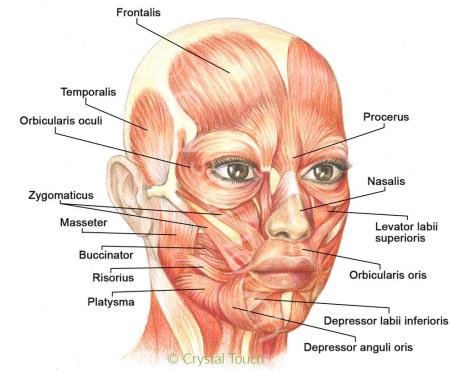
https://www.emotiv.com/brain-controlled-technology/





monitoring the electrical activity of the muscle tissue facial expressions can be detected

- Blink
- Left wink
- Right wink
- Raise brow
- Smile
- Laugh



https://www.emotiv.com/comparison/

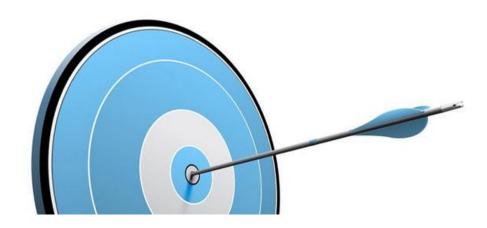
https://crystal-touch.nl/muslces-of-facial-expressions-and-how-they-work/





Objective

- Using the 14 channels data provided by the *Emotiv EPOC* headset, recognize in real-time the *Neutral* state and 5 facial expressions:
 - Left wink / blink (BL)
 - Right wink / blink (BR)
 - Strong blink (BB)
 - Open mouth (OM)
 - Full mouth (FM)



https://www.emotiv.com/comparison/





Data Acquisition

- For the training step:
 - Each recording file is composed of 100 raw data samples for each of the 14 channels ($\frac{100 \text{ samples}}{128 \text{ Hz}} = 0.78 \text{ sec}$)
 - The length was experimentally observed to be enough to capture only the behavior of the facial expression and to give enough time to the user to react
 - 20 files were recorded for each class
 - Implementation: data-acquisition.py

```
vitorroriz@vitorroriz-XPS-15-9560:~$ python data-acquisition.py v_bl_0
Prepare to act in :
3
2
1
ACTION!
Recording done.
v_bl_0.npy file saved
```





Data Acquisition

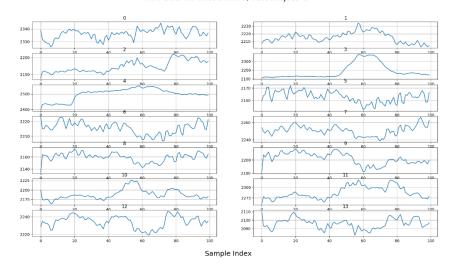
- We observed that:
 - The same facial expression is performed differently by distinct users results in different signal patterns
 - Signal patterns influenced by external factors such as:
 - positions of the headset and of the sensors
 - amount of the saline solution used, etc.
- For better results in the training / classification phase:
 - Not mixing data from different users
 - Not mixing data from different acquisition sessions
- For each utilization, new training dataset has to be build to capture the current environment conditions Large datasets are inconvenient to acquire for the users Classifiers relying on large datasets are not feasible



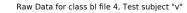


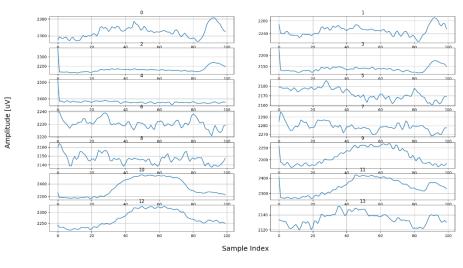
Data Acquisition

Raw Data for class bl file 7, Test subject "a"



Distinct users having different signal patterns for the "Blink Left" expression









Data Preprocessing

DC value extraction

- We observed in the frequency spectrum that all the signals have a DC component (2000 μ V)
- We extracted $1250 \,\mu\text{V}$ for some facial expressions, some signals drop below $2000 \,\mu\text{V}$ (e.g. "Open Mouth")

Filtering

• We used a Low-Pass Filter (Digital Butterworth Filter) with the cut-off frequency 50 Hz and order 15

Normalization

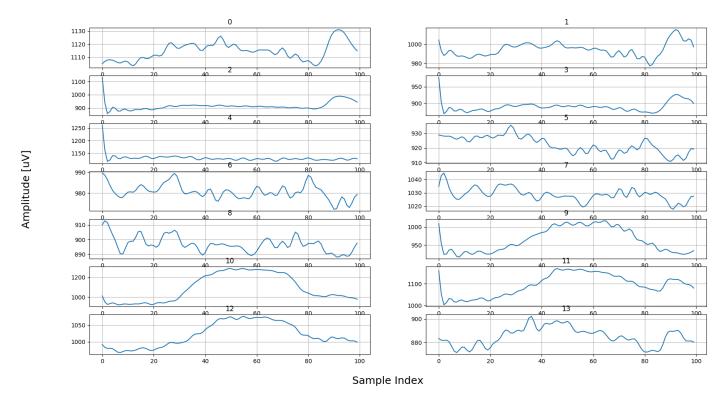
• Done for each channel individually, based on the average of 200 "Neutral" state *samples*





Data Preprocessing

Filtered Data for class bl file 4, Test subject "v"



The resulted signals of the "Blink Left" expression after filtering and DC component removal* for all the channels





Feature Extraction

Ratios for each channel

- Data was split into windows (25 samples) and overlapped (15 samples)
- $Per\ Channel\ Ratio = \frac{Average(Window\ preprocessed\ data)}{Average(Neutral\ state)}$

Hjorth parameters

• Mobility:
$$\sqrt{\frac{var(\frac{dy(t)}{dt})}{var(y(t))}}$$
 Complexity: $\frac{Mobility(\frac{dy(t)}{dt})}{Mobility(y(t))}$

Ratio between the average power of frequency spectrum bands

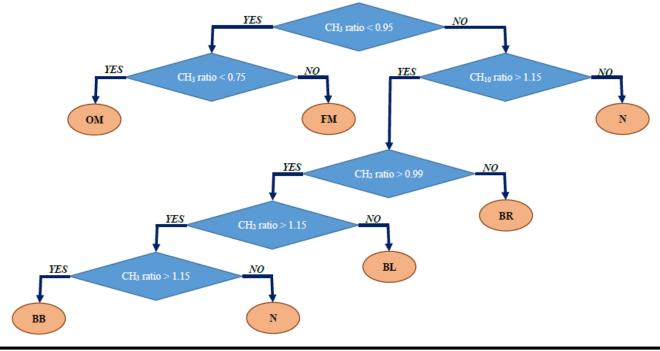
• [0, 10] Hz and [25, 45] Hz

A Novel EEG Feature Extraction Method Using Hjorth Parameter – S.-H. Oh et al., International Journal of Electrical Engineering (2014) Online Recognition of Facial Actions for Natural EEG-based BCI Applications, D. Heger et al., Affective Computing and Intelligent Interaction: Fourth International Conference (2011)





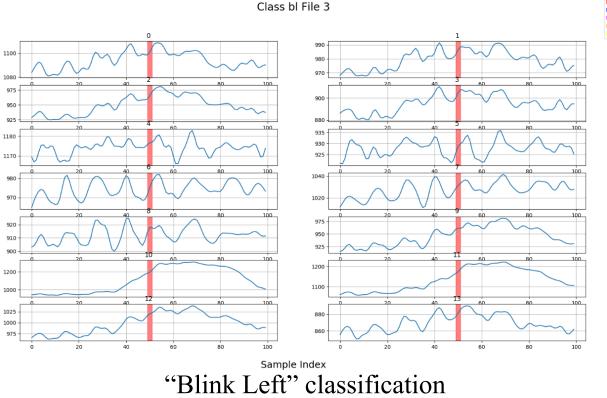
- Decision Tree classifier based on thresholds (own implementation)
 - All preprocessing steps (DC value extraction, filtering, normalization)
 - Features used: Ratios for each channels
 - "Filtering" the results of the classification







- Decision Tree classifier based on thresholds (own implementation)
 - Overall accuracy: 73.33% (for all classes)



Classifying window 0 ratios = 0.969982665519 1.05020700212 1.05159074405 CH10 smaller than 1.16 returning neutral lassifying window 25 atios = 0.994605245566 1.06739435379 1.15199260266 H3 bigger than 0.95 CH10 smaller than 1.16 eturning neutral lassifying window 50 H3 bigger than 0.95 H10 bigger than 1.16 H2 bigger than 1.01 H2 smaller than 1.15 returning bl lassifying window 75 atios = 0.985876238844 1.0607620802 1.301138085 H3 bigger than 0.95 H10 bigger than 1.16 CH2 smaller than 1.01 eturning br

Blink Both
Full Mouth
Open Mouth





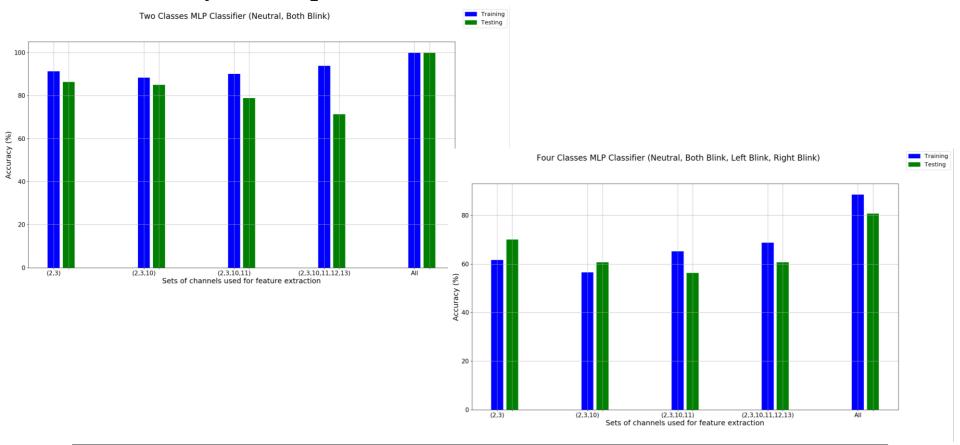
Multi-Layer Perceptron

- Preprocessing steps: DC value extraction, filtering
- Features used: Ratios for each channels
- Classification with different sets of classes based on different sets of channels
- One hidden layer with more neurons when using more channels (number of neurons between 5 and 17)
- Logistic activation function used





• Multi-Layer Perceptron



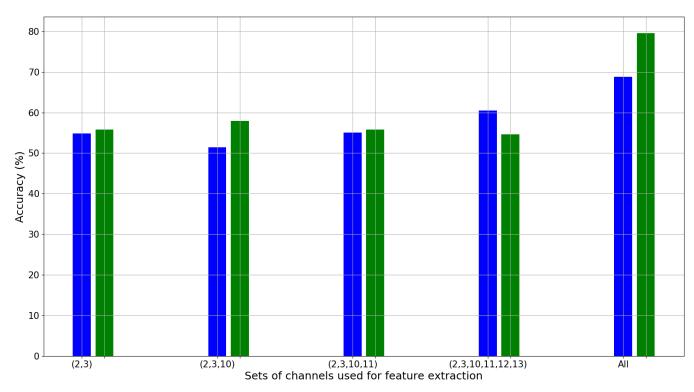




Multi-Layer Perceptron

All Classes MLP Classifier (Neutral, Both Blink, Left Blink, Right Blink, Open Mouth, Full Mouth)







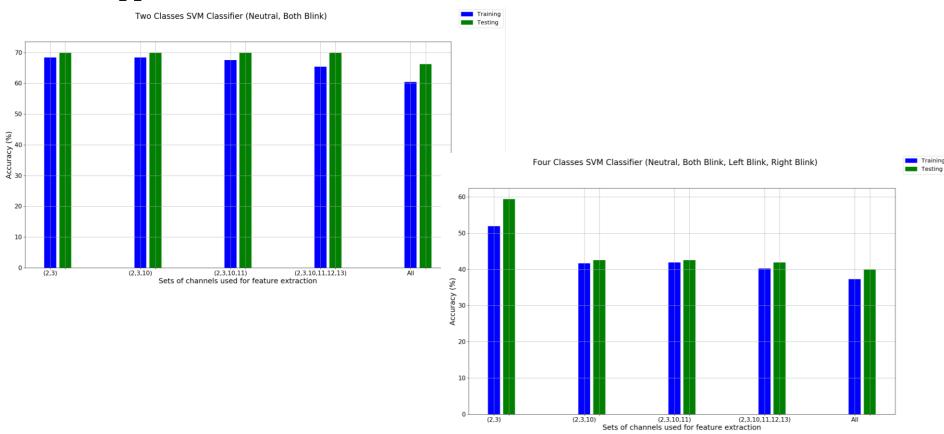


- Support Vector Machine
 - Preprocessing steps: DC value extraction, filtering
 - Features used: Ratios for each channels
 - Classification with different sets of classes based on different sets of channels





• Support Vector Machine



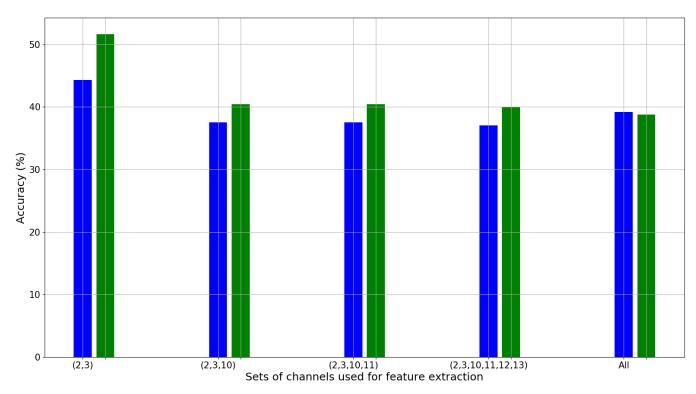




• Support Vector Machine

All Classes SVM Classifier (Neutral, Both Blink, Left Blink, Right Blink, Open Mouth, Full Mouth)









K-Nearest Neighbours

- Preprocessing steps: DC value extraction, filtering
- Features used: Ratios for each channels, Hjorth parameters*, Average power of frequency bands*
 - * Poor results
- Classification with different sets of classes based on different sets of channels





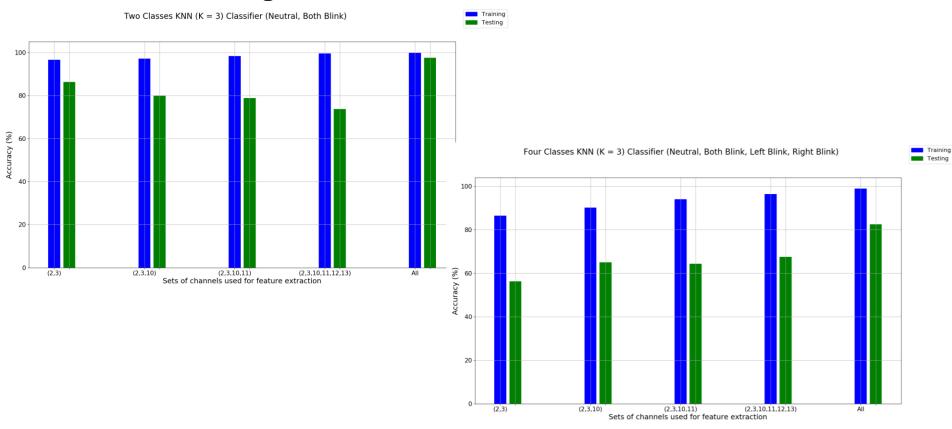
K-Nearest Neighbours

- Using only Hjorth parameters, the overall accuracy for all classes recognition using all channels is 46.67%
- Using Hjorth parameters and Average power of frequency bands, the overall accuracy for all classes recognition using all channels is 27.08%





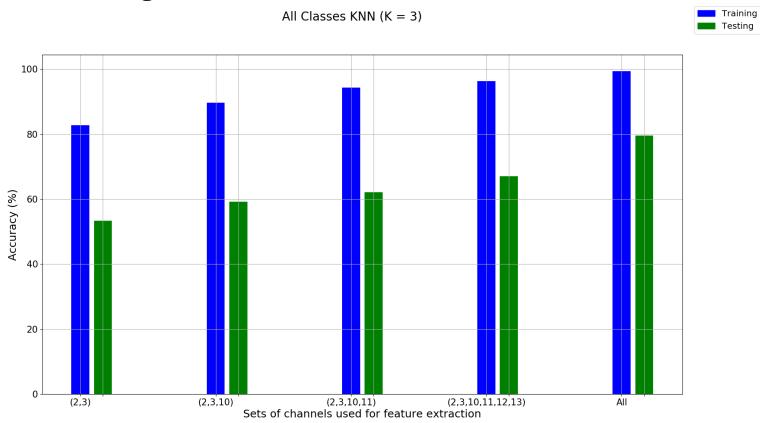
• K-Nearest Neighbours







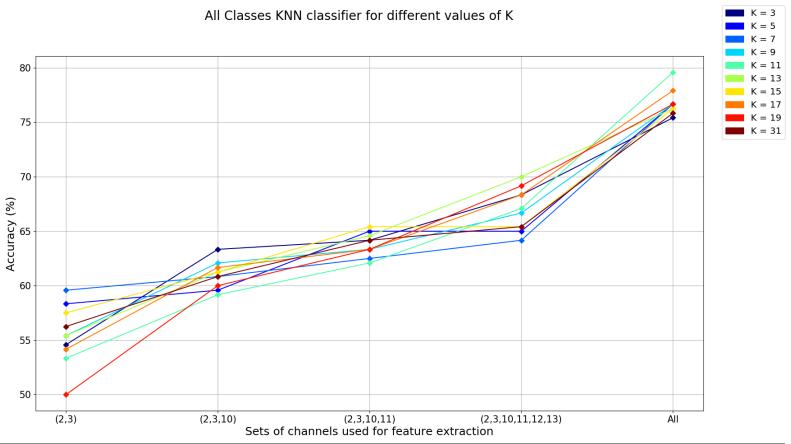
• K-Nearest Neighbours







• K-Nearest Neighbours







Real - Time

Setup

- Calibration of the Neutral state —— calculation of the mean value of each channel for 10 windows of 25 samples each
- Capturing the data for each class 10 recordings for each class, each recording having 10 windows of 25 samples each
- Training* of the KNN classifier

Loop

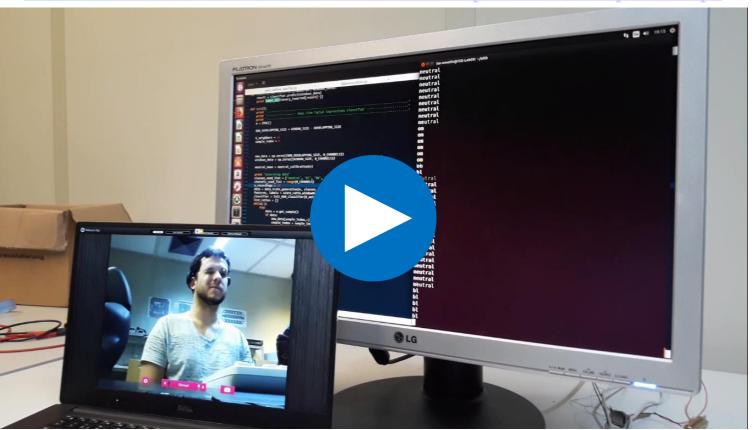
- Real-time acquisition of data split into windows of 25 samples with an overlapping of 15 samples
- Classification for each window





Real - Time

<u>Link to the Video of the entire Real-Time process (Setup + Loop)</u>







Conclusions

- We successfully classified in Real-Time the "Neutral" state and 5 facial expressions:
 - Left wink / blink
 - Right wink / blink
 - Strong blink
 - Open mouth
 - Full mouth
- The best classifier was KNN (K = 11)
- Due to the window size of 25 samples and the overlapping of 15 samples, a new classification result can be delivered every 0.07 seconds





Thank you!

Danke!

Obrigado!

Mulțumim!









