

Summer School Guide

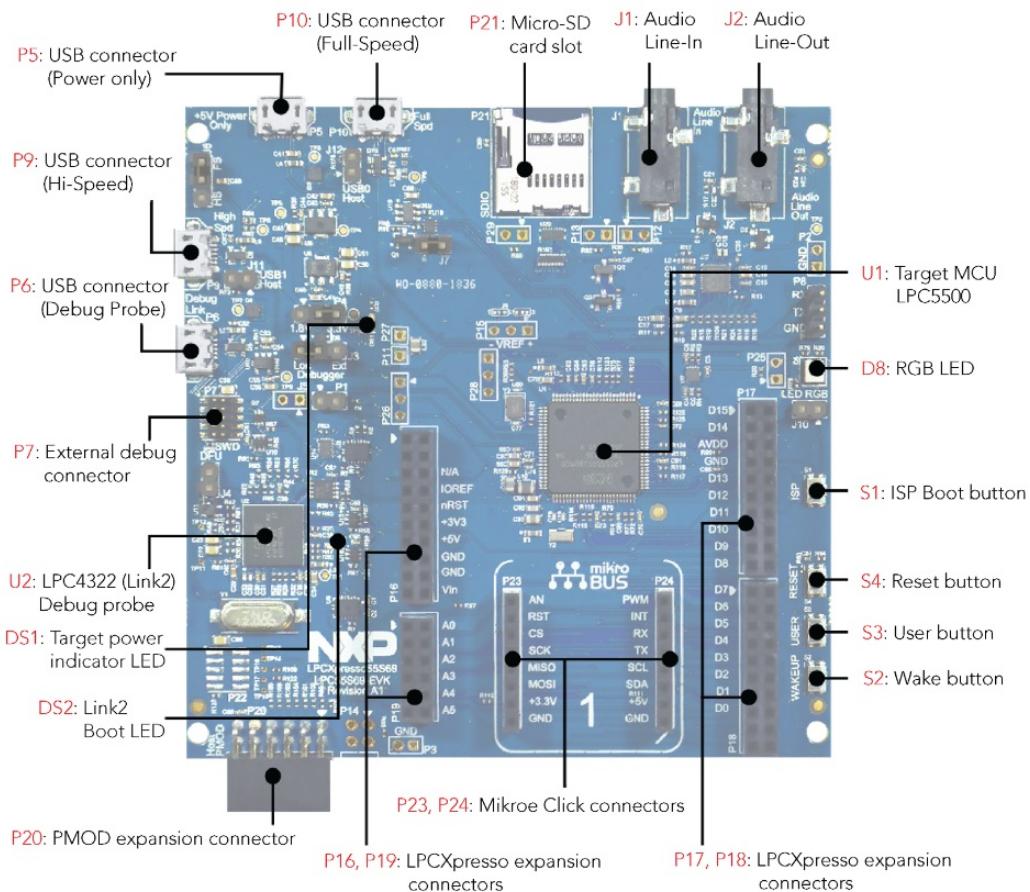
June 17, 2025

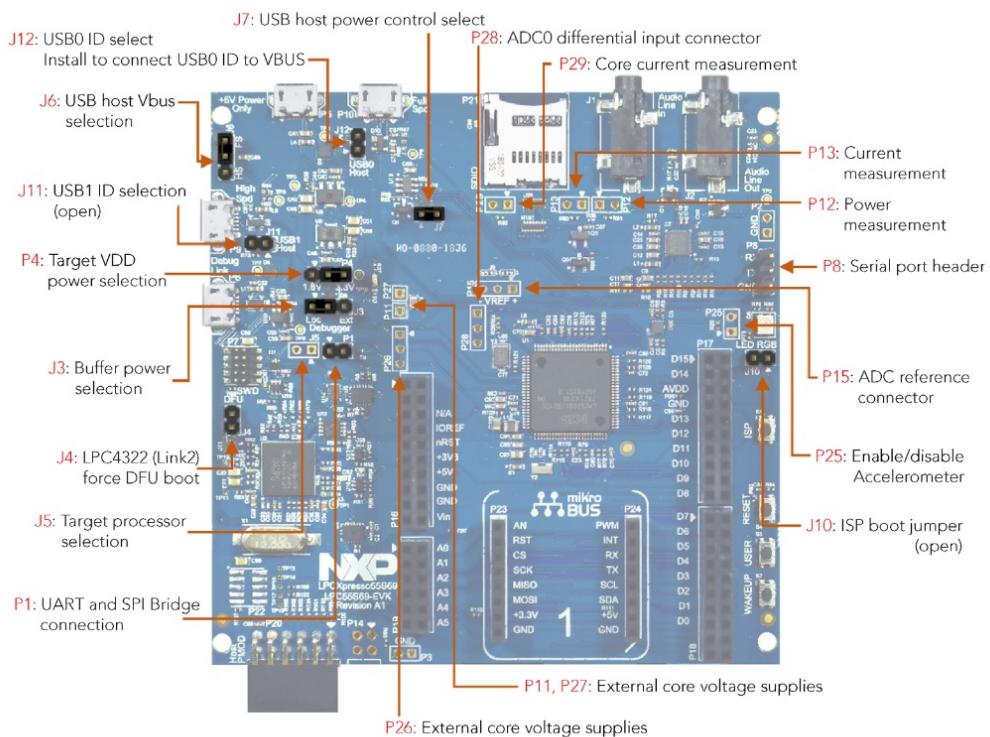
Tools

LPCXpresso55S69 Development Board

The LPCXpresso55S69 and LPCXpresso55S28 boards include the following features:

- LPC55S69 Dual Cortex-M33 core processor or LPC55S28 Cortex-M33 processor
- Onboard, high-speed USB, Link2 debug probe with CMSIS-DAP and SEGGER J-Link protocol options
- UART and SPI port bridging from LPC55Sxx target to USB via the onboard debug probe
- Optional external debug probes with trace option (10 or 20 pin Cortex-M connectors)
- RGB user LED
- Reset, ISP, User/Wakeup and user buttons
- Multiple Expansion options, including Arduino UNO, Mikroe Click and PMod
- Micro SD card slot
- NXP MMA8652FCR1 accelerometer
- Stereo audio codec with line in/out
- High / full speed USB port with micro A/B connector for the host or device functionality
- Reset button





Board Elements Overview 2

Why do we need SDKs?

- An SDK (Software Development Kit) is a collection of software tools, libraries, documentation, and sample code that developers use to create applications for specific hardware or software platforms. SDKs streamline the development process by providing the necessary components and resources in one package.
 - Hardware Abstraction - it simplifies access to hardware by offering drivers and libraries.
 - Sample Code and Documentation - provides a lot of examples that showcase the functionalities on the specific board/development kit.
 - Consistency and Efficiency - provides standardized interfaces and already follows coding guidelines.
 - Support and Updates - ongoing support provided by the manufacturer/community.

An SDK can be downloaded by searching for the development board name and accessing the development board main page (provided below) or by accessing the NXP portal, MCUXpresso SDK Builder and searching for the board we need the toolkit for.

Useful Links:

- [Development Board Purchase details, and documentation](#)
- [IDE: Extensions for VS Code](#)
- [MCUXpresso SDK Builder](#)

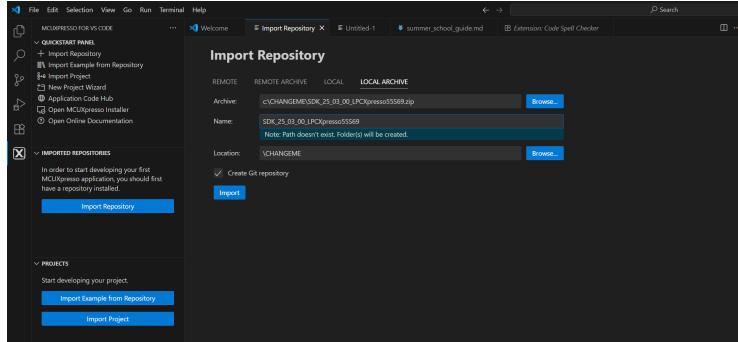
MCUXpresso For VS Code

MCUXpresso for Visual Studio Code (VS Code) provides an optimized embedded developer experience for code editing and development. MCUXpresso for VS Code supports NXP MCUs based on Arm® Cortex®-M cores including MCX, LPC, Kinetis and i.MX RT. MCUXpresso for VS Code allows developers the flexibility to work on projects from Zephyr, or MCUXpresso SDK in conjunction with Open-CMSIS-Packs.

The VS Code extension organizes relevant information including installed SDK repositories, available debug probes, user projects and links to help get started. A popular QuickStart panel provides access to the most popular actions. Intellisense improves upon standard auto-complete and auto-format features. The debug view provides access to breakpoints, variable/register views, call stack and thread awareness while using normal debug controls to step through the code.

Getting started with the MCUXpresso IDE

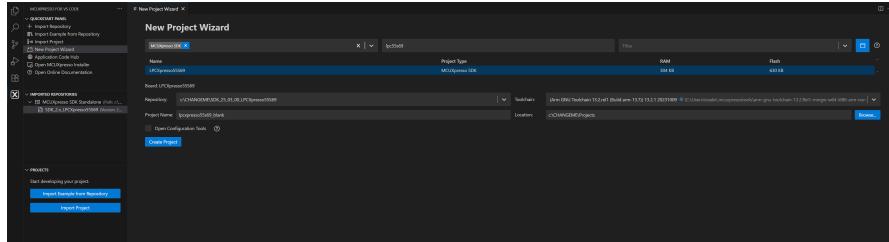
1. Select the **MCUXpresso for VS Code** in the sidebar and click on **Import Repository**. Please use the folder specified by the Lab assistants on this step, the CHANGEME folder is a placeholder.



Select Workspace

2. Click on **New Project Wizard**

Select in the first dropdown **MCUXpresso SDK**. Select in the second dropdown our board: Ipc55s69. Select in the repository the only entry available(the one we just installed). Select in the toolchain the only entry available. Select in the ProjectName: *yourname_dayx_exy*, for example: toader_day1_ex1 Select in location: the temporary location you will use for these project, will be communicated by the lab assistants.



Welcome Page

Hit create project

The project structure is presented below. Thye project can be downloaded(to the board) and debugged with the green play byutton highlighted in the red square. The main two parts of interest for files are **Project Files** and **Repository**.

The screenshot shows the MCUXpresso for VS Code interface. On the left, the sidebar displays the 'QUICKSTART PANEL' with options like Import Repository, Import Project, and New Project Wizard. Below that is the 'IMPORTED REPOSITORIES' section, which lists 'MCUxpresso SDK Standalone'. The 'PROJECTS' section shows the selected project 'lpcxpresso55s69_blank'. The 'Project Files' tree view on the left highlights several files: 'main.c' (which is also selected in the code editor), 'mcux.config.h', 'new_project_cm33_core_v3_15.xml', 'new_project.mex', 'peripherals.c', 'peripherals.h', and 'pin_mux.c'. The code editor on the right contains the 'main.c' file with its source code. The status bar at the bottom indicates 'No problems have been detected in the workspace'.

In **Project Files** will find all the filkes corresponding to your project. All the changes we will make in our exercises will be here. In the **Repository** we will find all the drivers that we will need throughout the days. To be more precise in `Repository/devices/LPC55S69/drivers/fsl_gpio.h` we will find the gpio driver header with doxygen documentation for each function. We will not change any code in **Repository** this is just a collection of drivers we need!

The screenshot shows the code editor displaying the `fsl_gpio.h` header file. The code is annotated with Doxygen comments explaining the functions and their parameters. The code editor's status bar at the bottom shows line numbers from 109 to 137.

```

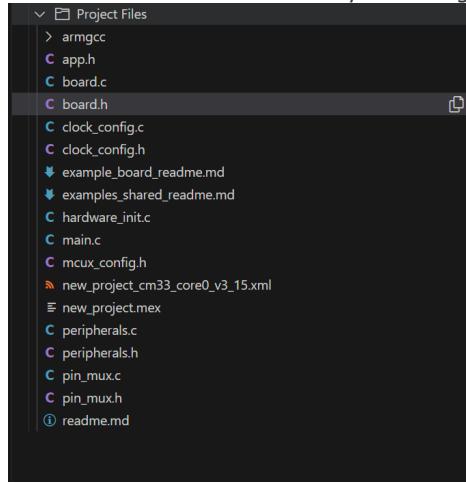
109 * @brief Initializes a GPIO pin used by the board.
110 *
111 * To initialize the GPIO, define a pin configuration, either input or output, in the user file.
112 * Then, call the GPIO_PinInit() function.
113 *
114 * This is an example to define an input pin or output pin configuration:
115 * @code
116 * Define a digital input pin configuration,
117 * @endcode
118 * @param config
119 * {
120 *   kGPIO_DigitalInput,
121 *   0,
122 * }
123 * Define a digital output pin configuration,
124 * @param config
125 * {
126 *   kGPIO_DigitalOutput,
127 *   0,
128 * }
129 * @endcode
130 *
131 * @param base GPIO peripheral base pointer(Typically GPIO)
132 * @param port GPIO port number
133 * @param pin GPIO pin number
134 * @param config GPIO pin configuration pointer
135 */
136 void GPIO_PinInit(GPIO_Type *base, uint32_t port, uint32_t pin, const gpio_pin_config_t *config);
137

```

Some useful tips:

- the `main` function (our application entry point) will be inside **Project Files**.

- the `board` header file provides information and API interfaces for board-specific components, such as on-board LEDs, buttons, and communication interfaces. The macro definitions within these files map out the connections to these components, which can also be verified by referring to the board's schematic.



```

58  #define BOARD_CODEC_I2C_INSTANCE 4
59  #ifndef BOARD_LED_RED_GPIO
60  #define BOARD_LED_RED_GPIO GPIO
61  #endif
62  #define BOARD_LED_RED_GPIO_PORT 1U
63  #ifndef BOARD_LED_RED_GPIO_PIN
64  #define BOARD_LED_RED_GPIO_PIN 6U
65  #endif
66
67  #ifndef BOARD_LED_BLUE_GPIO
68  #define BOARD_LED_BLUE_GPIO GPIO
69  #endif
70  #define BOARD_LED_BLUE_GPIO_PORT 1U
71  #ifndef BOARD_LED_BLUE_GPIO_PIN
72  #define BOARD_LED_BLUE_GPIO_PIN 4U
73  #endif
74
75  #ifndef BOARD_LED_GREEN_GPIO
76  #define BOARD_LED_GREEN_GPIO GPIO
77  #endif
78  #define BOARD_LED_GREEN_GPIO_PORT 1U
79  #ifndef BOARD_LED_GREEN_GPIO_PIN
80  #define BOARD_LED_GREEN_GPIO_PIN 7U
81  #endif
82

```

- the `drivers` folder provides the drivers for all included components, such as the USART driver.

- header:** Repository/devices/LPC55S69/drivers/fsl_usart.h - contains macro definitions and functions prototypes.
- source:** Repository/devices/LPC55S69/drivers/fsl_usart.c - contains C implementation for internal and external functionalities.
- useful C functions:**

```

status_t USART_ReadBlocking(USART_Type *base, uint8_t*data, size_t length);
status_t USART_WriteBlocking(USART_Type *base, const uint8_t*data, size_t length);

```

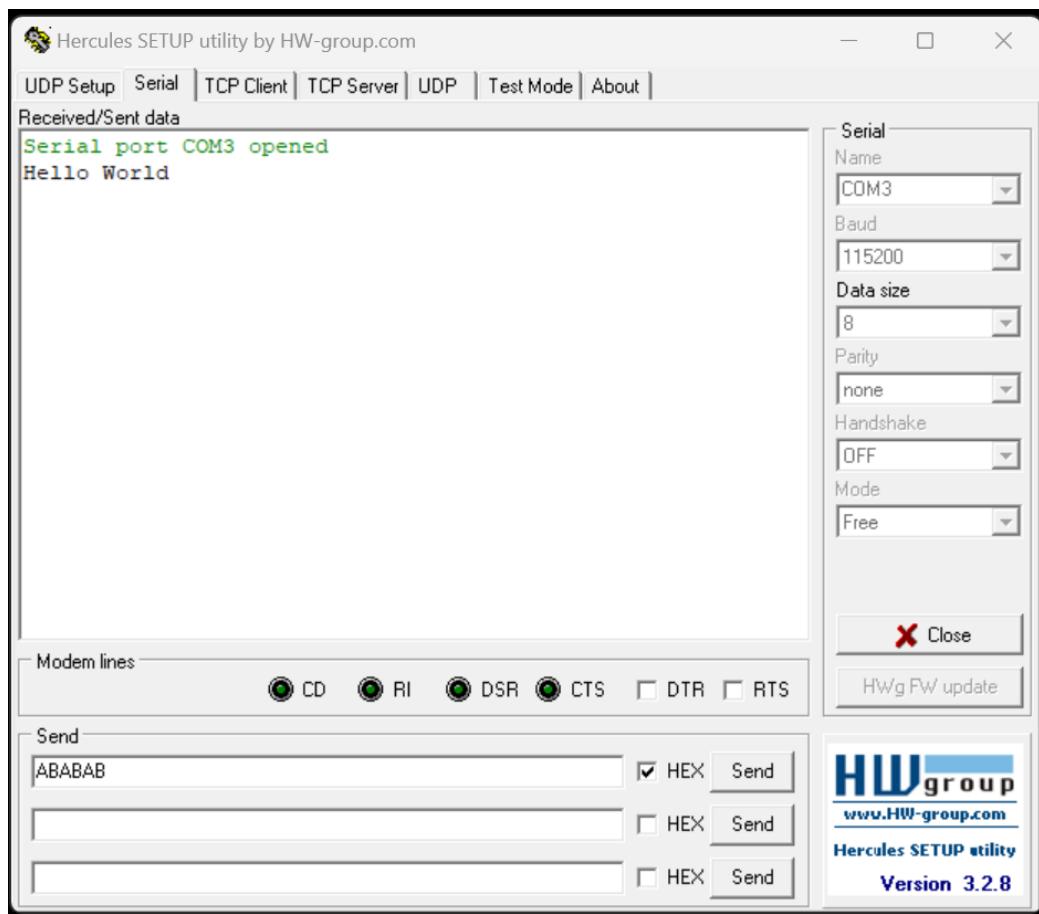
Useful Links:

- [Getting Started Guide](#)

Hercules

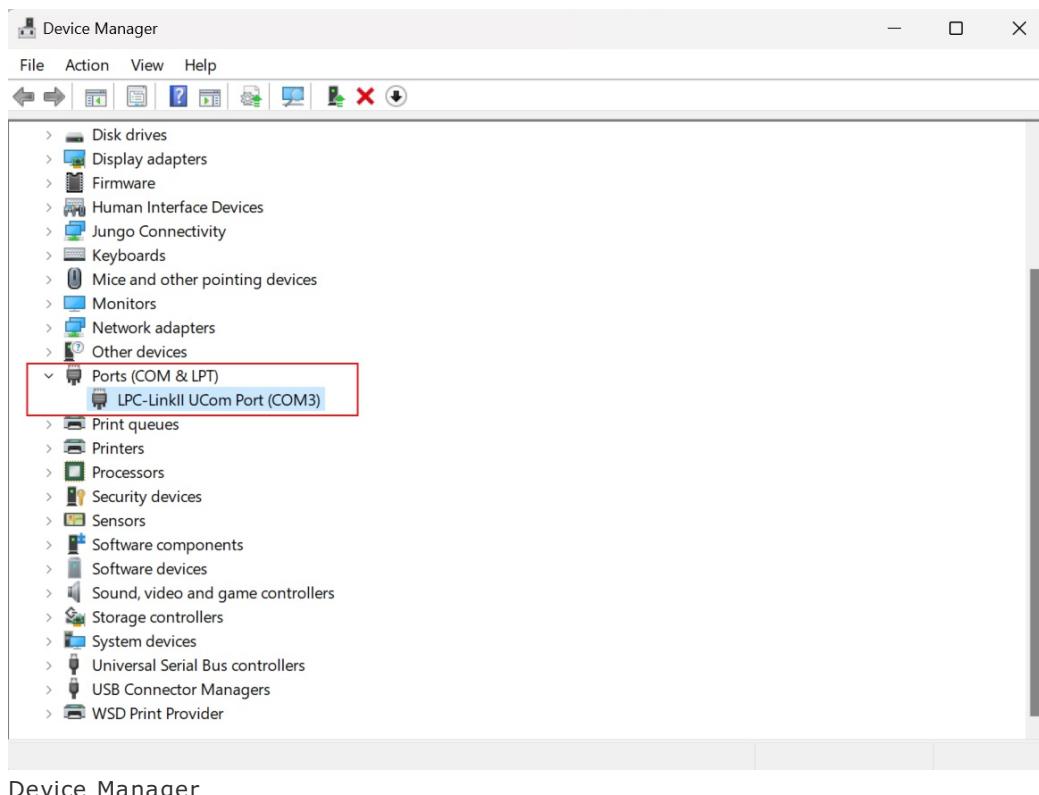
Hercules SETUP utility is a useful serial port terminal (RS-485 or RS-232 terminal). This terminal application will be used for serial communication through UART.

This is the output we will receive when running the default `main` function generated when creating new projects. Additionally, we can send ASCII characters. By checking the `HEX` box, we can send hexadecimal strings to the device.



Hello World

To identify the COM port of the device, open Device Manager.



Device Manager

Useful Links:

- [Download Hercules](#)