

August Retrospective

What Went Well

- Jamie accepted to USU
- Good relationship w/ Jamie and family (minus hickups)
- Recorded another video and did monthly post

What Didn't Go Well

- Arguments over nothing
- Stressed

What To Work On

- Talk to Mike
- Personal/School/relationships balance

Weekly Retrospectives

August 24 - August 30

Personal

- ☒ 2 Day Rule
- ☒ Workout 5/7 Days
- ☒ Jamie Time
- ☒ Vacuum

- ☒ Bathroom

School

- ☒ Opt out of auto access book

Work

- ☒ Walk a mile a day
- ☐ 1 Hour DAU this week
- ☐ Go aggressive on TSP

Hobby

- ☒ Hobby 5 Hours
- ☐ Learn SDL

August 30 - September 6

Personal

- ☒ 2 Day Rule
- ☒ Workout 5/7 Days
- ☒ Jamie Time
- ☐ Vacuum

- ☐ Bathroom

School

- ☒ Install MATLAB
- ☒ Install MAXIMA
- ☐ Read Paper > started on it
- ☒ Get code running
- ☐ Finish lab > Just need to take quiz and upload video
- ☐ Finish HWK 1 both classes
- ☒ Watch lectures
- ☒ Assigned readings

Work

- ☒ Walk a mile a day
- ☐ 1 Hour DAR this week
- ☐ Go aggressive on TSP

Hobby

- ☐ Hobby 1 Hour >

September 7 - September 13

Personal

- ☒ 2 Day Rule
- ☒ Workout 5/7 Days
- ☒ Jamie Time
- ☐ Vacuum

- ☒ Bathroom

- ☒ Laundry

School

- ☐ Read Mobile Robotics

- ☒ Watch Lectures LMC
- ☒ Finish HWK 1 Mobile Robotics
- ☒ Read Paper
- ☒ Finish lab 1 > Upload video
- ☒ Review over HWK 1
- ☒ Look over code

Work

- ☐ Walk a mile a day
- ☐ 1 Hour DAU this week
- ☐ Go aggressive on TSP

Hobby

- ☐ Hobby 1 Hour

September 14 - September 20

Personal

- ☐ 2 Day Rule
- ☒ Workout 5/7 Days
- ☐ Jamie Time
- ☐ Vacuum
- ☒ Bathroom
- ☒ Laundry
 - ☒ Clothes
 - ☒ Bed Sheets

School

- ☒ Read
 - ☒ Mobile Robotics - [X] PA: 2.1-2.3 - [X] AI Robotics: CH 13 - [X] AI Robotics: CH 14
 - ☒ LMC
- ☐ Watch Lectures LMC
- ☒ HWK 2
 - ☒ Mobile Robotics
 - ☒ LMC
 - ☒ Try Example 2 LCM Linearization
- ☒ Lab 2: Create video

Research

- [o] Read

- ☒ Potential Field Methods
- ☐ Fixed Site Security Control Behavior
- ☒ Create lecture for Potential Field Methods (pan doc slides?)
- ☒ Figure out how to create CSV
- ☐ Run and analyze static code tools
- ☒ Get google sheets from Anthony
 - ☒ Figure out what he was trying to pull from data
 - ☒ Start thinking of ways to automate
- [o] termviz
 - ☒ Figure out how to get objects in Rviz
 - ☐ Plot multiple robots (try to get all odom data available?)

Work

- ☒ Walk a mile a day
- ☐ 1 Hour DAU this week
- ☐ Go aggressive on TSP

Hobby

- ☐ Hobby 1 Hour

September 14 - September 20

Personal

- ☒ 2 Day Rule
- ☒ Workout 5/7 Days
- ☒ Jamie Time
- ☒ Vacuum
- ☐ Bathroom
- ☐ Laundry
 - ☐ Clothes
 - ☐ Bed Sheets

School

- ☐ Watch Lectures LMC
- ☐ HWK 2
 - ☐ Mobile Robotics > Almost there
- ☒ Lab 3
 - ☒ Create publisher and subscriber
 - ☒ Create video
- ☒ Take Quizze

Research

- ☒ Read
 - ☒ Fixed Site Security Control Behavior
- ☐ Run and analyze static code tools
- ☒ Get google sheets from Anthony
 - ☒ Figure out what he was trying to pull from data
 - ☒ Start thinking of ways to automate
- ☐ Finish script to get goal analytics
- ☒ termviz
 - ☒ Plot multiple robots (try to get all odom data available?)

Work

- ☐ Walk a mile a day
- ☐ Go aggressive on TSP

Hobby

- ☐ Hobby 1 Hour

September 28 - October 4

Personal

- ☐ 2 Day Rule
- ☐ Workout 5/7 Days
- ☒ Jamie Time
- ☐ Vacuum

- ☒ Bathroom

- [o] Laundry
 - ☒ Clothes
 - ☐ Bed Sheets

School

- ☐ Watch Lectures LMC
- [o] HWK
 - ☒ Mobile Robotics : I think I'm done
 - ☐ LMC
- ☐ Lab 4 > Not due till next week
 - ☐ Complete Lab
 - ☐ Create video
- ☒ Take Quiz LMC
- ☒ Reading Mobile Robotics

Research

- ☐ Run and analyze static code tools
- ☐ Read paper
 - ☐ Taxonomy multi-robot allocation
 - ☐ Consensus-based decentralized auctions
 - ☐ Multiagent Systems
- ☐ Make Presentation
- ☒ Code
 - ☒ Start fixing up code
 - ☒ Make sure that you are running the right code
- ☐ Finish script to get goal analytics
 - Number of collisions
 - Number of visits to a location
 - Mean time between visits to a location
 - Std deviation between visits to a location
- ☐ Start working on paper
- ☐ termviz
 - ☐ Plot walls

Work

- ☒ Walk a mile a day

Hobby

- ☐ Hobby 1 Hour