

Linear-Time-Invariant System

$$a \frac{dx}{dt} + b = 0 \quad \text{has the form of}$$

An LTI system is stable if all poles are in the left hand plane.

$$G(s) = \frac{n(s)}{d(s)}$$

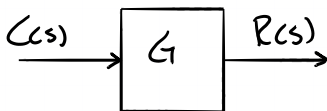
$d(s) = 0$ if all s 's that solve $d(s) = 0$ are negative, the system is stable.

You only need one pole to be positive to make the entire system unstable.

Given a transfer function

$$G(s) = \frac{1}{s^5 + 2s^4 + 3s^3 + 4s^2 + 5s + 10}$$

There is no real way of solving this. Especially if we want to find the range for which a is stable.



Bounded Input / Bounded Output

BIBO

Example

$$G(s) = \frac{10}{(s+1)(s+10)}$$

$$R(s) = \frac{1}{s}$$

$$C(s) = \frac{10}{s(s+1)(s+10)}$$

Use tables to find $\mathcal{L}^{-1}\{C(s)\}$

$$c(t) = \underline{u(t)} \left[1 - \frac{10}{9}e^{-t} + \frac{1}{9}e^{-10t} \right]$$

↳ The unit step function is implied in the book so we have to add it.

Example

$$G(s) = \frac{1}{(s+1)(s-1)}$$

$$R(s) = \frac{1}{s}$$

$$C(s) = \frac{1}{s(s+1)(s-1)}$$

This function is not stable because there is a positive root.

$$c(t) = u(t) \left[-1 + \frac{1}{2}e^{-t} + \frac{1}{2}e^t \right]$$

Routh Stability Criterion

Used to find stability of equations without having to factor the characteristic equation.

1) Forming Routh Array

$$a_n s^n + a_{n-1} s^{n-1} + \dots + a_1 s + a_0 = 0$$



If there are sign changes in the characteristic equation, we know by looking at it that it is unstable. If they are all positive, it may be stable, but it is not guaranteed.

s^n	a_n	a_{n-1}	\dots
s^{n-1}	a_{n-1}	a_{n-3}	\dots
s^{n-2}	b_1	b_2	b_3
\vdots			
s^0	c_1	c_2	c_3

$$b_1 = - \frac{\begin{vmatrix} a_n & a_{n-2} \\ a_{n-1} & a_{n-3} \end{vmatrix}}{a_{n-1}}$$

$$b_2 = - \frac{\begin{vmatrix} a_n & a_{n-4} \\ a_{n-1} & a_{n-5} \end{vmatrix}}{a_{n-1}}$$

$$C_1 = - \frac{\begin{vmatrix} a_{n-1} & a_{n-3} \\ b_1 & b_2 \end{vmatrix}}{b_1}$$

$$C_2 = - \frac{\begin{vmatrix} a_{n-1} & a_{n-5} \\ b_1 & b_3 \end{vmatrix}}{b_1}$$

The number of sign changes in the first column of the array is the number of positive roots in the system.

Example

$$G(s) = \frac{1}{s^3 + 2s^2 + 2s + 6}$$

Find range of stability of a .

$$- \frac{6 - 2a}{2}$$

$$-3 + a > 0$$

$$\Rightarrow \underline{a > 3}$$

The ensures the system will be stable.

s^3	1	2	0
s^2	2	6	0
s^1	$-3+a$	0	
s^0	6	0	
	0		

When we let the s^0 row to be 0 (by setting $a = 3$ in this case) we can write the auxiliary equation

$$2s^2 + 6 = 0 \Rightarrow s^2 = -3$$

$$s = \pm j\sqrt{3}$$

Example: $T(s) = \frac{10}{s^5 + 2s^4 + 3s^3 + 6s^2 + 5s + 3}$

↳ What you do when you divide by 0

- Choose ϵ to be positive. It is still 0, but we can now see the sign of the values

$$s^2 \rightarrow \frac{6(0) - 7}{0} \rightarrow (-)$$

- Now Choose ϵ to be negative

$$\begin{array}{ccccccc} + & + & - & + & + & + & \\ \hline \end{array}$$

+	s^5	1	3	5	
+	s^4	2	6	3	
+	s^3	0	$7/2$		
-	s^2	$\frac{6\epsilon - 7}{\epsilon}$			
+	s^1	$\frac{42\epsilon - 49 - 6\epsilon^2}{12\epsilon - 14}$			
+	s^0	3			

Replace w/ ϵ

Reciprocal Root

$3s^5 + 5s^4 + 6s^3 + 3s^2 + 2s + 1 \rightarrow$ Place opposite values together

$s^5 a_0 + s^4 a_1 + \dots$

Gives the same results as above.

s^5	3	6	2
s^4	5	3	1
s^3	$2/5$	$7/5$	
s^2	$4/3$	1	
s^1	$-7/4$		
s^0	1		