ECE/MAE 5310 Stability More Examples

Chap. 5 Maderial

Stability

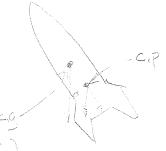
We will work from the definition of stability

as a bounded input produces a bounded output

Your book uses a come to illustrate stability. Canes are boring rockets are interesting. We'll use a rocket, read about the cone.

c.g. P

forces on the body



(3 row rocket de moust ration)

perturbed rockel



the rocket is instable if the c.p is in front of the c.g. stable if it is behind the c.g. and neutral if it is co-located.

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The rocket illustrates bounded input/bounded output or BIBO stability. When the cig. is in front of the center of pressure.

A linear system is stable only if all the poles of the system (closed loop) have negative real parts

Almear system is marginally stable if it has poles on the jw-axis (oscillatory)

$$T(5) = 100$$
 stable $(5+5)(5+20)(5+1)$

$$T(5) = 100$$
 unstable PHP pole $5=5$ (5-5)(5+20)(5+1)



ECE/MAE 5310 Stability Extra Examples Chap. 5 Material The denominator of T(6) is called the

The denominator of T(6) is called the characteristic equation of T(6). The closed loop system poles are the zeros of the denominator of T(5)

$$T(5) = 100$$
 $(5+5)(5+20)(5+1)$

q(s)= (5+5)(5+20)(5+1) is the characteristic equation this one is factored and it is easy to tell stability q(s)=0 = (5+5)(5+20)(5+1) when 5=-5, 5=-20, 5=-1

It is more difficult to know stability when it is not factored.

or when one of the coefficient is a variable rather than a number

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This was such a problem that Horwitz found a solution, realized that Routh had found it 90 yes, earlier and was adult enough to put his name first.

The criterion requires the manipolation of a special array that allows you to determine yestern stability

given a general characteristic equation $q(s) = a_n s^n + a_{n-1} s^{n-1} + a_{n-2} s^{n-2} + \dots + a_1 s + a_0 = 0$

you form the trouth array as follows



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$$5^{n}$$
 a_{n} a_{n-2} a_{n-4} a_{n-3} a_{n-5} a_{n-5} a_{n-1} a_{n-3} a_{n-5} a_{n-5}

$$b_{n-1} = \frac{(a_{n-1})(a_{n-2}) - (a_n)(a_{n-3})}{a_{n-1}}$$

$$b_{n-3} = \frac{(q_{n-1})(q_{n-4}) - (q_{n})(q_{n-5})}{q_{n-1}}$$



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$$C_{n-1} = \frac{(b_{n-1})(a_{n-3}) - (a_{n-1})(b_{n-3})}{b_{n-1}}$$

what's Cn-3

$$C_{n-3} = \frac{(b_{n-1})(a_{n-5}) - (a_{n-1})(b_{n-5})}{b_{n-1}}$$

Routh-Hurwitz Criterion

"the number of roots of 960) with positive real parts is equal to the number of sign changes in the first column of the treath array.

Case I No element in the column is zero

Example 1.1
$$q(s) = s^2 + 5s + 6$$

$$=\frac{30-0}{5}=6$$

5° [6] stable no sign changes



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$$\frac{1}{1}$$
 $\frac{1}{1}$ $\frac{1}$

for a second order system to be stable 911 the coefficients must be positive (or all negative)

Example 1,3 General Third Order

$$b_1 = ? \qquad a_2 q_1 - q_3 q_0$$

$$C_1 = b_1 Q_0 - 0 = Q_0$$



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to be stable a third order system must have all coefficients positive and

929,79390

Zeros in the first column cause trouble because they are used in division so

Case 2: There is a zero in the first column but non-zero elements in the row containing the zero.

Examples			
9(5)=	55-1254,	253+45	+115+10

55	1 2 11
54	2 4 10
53	0.6
52	replace W/E
51	
<i>5</i> °	

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5° 1 2 11 5° 2 4 10 5° 2 6 0 5° 10

$$D = \frac{4\varepsilon - 12}{\varepsilon} = \frac{4 - 12}{\varepsilon} \quad \text{bot } \quad \text{ε is small}$$



$$\triangle = 0$$

$$0 = \frac{-12(6) - 10\varepsilon}{\frac{2}{5}} = 36 \text{ back to}$$

$$\frac{-12/\varepsilon}{\frac{2}{5}}$$

2 signalayes

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Case 3 There is a zero in the first column and all the elements in the row are also zero.

$$5^{3}$$
 | 24
 5^{2} | 2 | K | for K = 8 we
 5^{1} | 8-14 0 | have a zero
 5^{0} | K | row

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Then the row above the zero row contains a polynomial P.110513 whos roots are poles of q(6). It is called the auxillary polynomial. In this example

$$U(s) = 2s^2 + 8 = 0$$

$$S+4=0$$
 $S=\pm j2$ $(6+j2)(S-j2)$ are roots of $q(S)$ and system poles

check by synthetic division

$$\begin{array}{r}
 \frac{1}{25^{2}+8} \overline{)5^{3}+25^{2}+45+8} \\
 \underline{5^{3}+05^{2}+45} \\
 \underline{25^{2}+8}
\end{array}$$

(5+2) is the other mot

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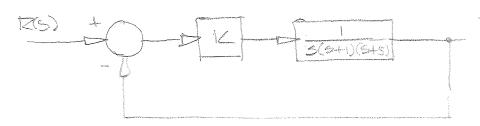
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Case 4 respected jou roots ::

Routh does indicate instability
indicates marginal stability

Example

Given a system



Determine the range of K for which the system is stable

$$T(5) = \frac{K}{5(5^2 + 45 + 5) + K} = \frac{K}{5^3 + 45^2 + 55 + K}$$

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Forming the Booth array 9,60=?

$$q(5) = 5^3 + 65^2 + 55 + 16$$

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